# VB-GROUPOIDS COCYCLES AND THEIR APPLICATIONS TO MULTIPLICATIVE STRUCTURES 

Leandro Ginés Egea<br>Advisor: Prof. Henrique Bursztyn<br>Co-Advisor: Prof. Thiago Drummond (UFRJ) IMPA

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Dedicado a
mi familia

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#### Abstract

This thesis concerns the study of VB-groupoids and their cocycles (i.e., groupoid cocycles with additional linearity properties). We provide a description of VB-groupoid cocycles at the infinitesimal level, i.e., in terms of the underlying algebroid data. As an application, we use our results in the general study of multiplicative geometric structures on Lie groupoids. We pursue the viewpoint that such structures can be regarded as cocycles on suitable VB-groupoids. This approach gives a unifying framework to several multiplicative structures of interest, such as multiplicative forms, multivectors, and subbundles. In fact, with this point of view we treat general multiplicative tensors taking values in VB-groupoids. In particular, we establish a Lie theory for multiplicative tensors with coefficients in a (2-term) representation up to homotopy.


## Resumo

A presente tese versa sobre o estudo de VB-grupoides e seus cociclos (ou seja, cociclos em grupoides com propriedades lineares adicionais). Obtemos uma descrição de cociclos em VB-grupoides num nível infinitesimal, ou seja, em termos de dados do algebroide associado. Como uma aplicação, usamos nossos resultados no estudo geral de estruturas geométricas multiplicativas em grupoides de Lie. Seguimos o ponto de vista que tais estruturas podem ser vistas como cociclos num VB-grupoide apropiado. Esta abordagem permite colocar no mesmo contexto varias das estruturas multiplicativas de interesse, tais como formas diferenciais, multivectores, subfibrados multiplicativos, e tratar-las conjuntamente de maneira uniforme. De fato, com este ponto de vista, tratamos tensores multiplicativos gerais tomando valores em VB-grupoides. Em particular, estabelecemos uma teoria de Lie para tensores multiplicativos com coeficientes numa representação a menos de homotopia (2-termos)

## Contents

Acknowledgements ..... III
Abstract ..... V
Resumo ..... VII
Introduction ..... XI
1 Background ..... 1
1.1 Lie groupoids and Lie algebroids ..... 1
1.2 Multiplicative functions ..... 3
1.2.1 Cohomology of Lie groupoids and Lie algebroids ..... 4
1.3 VB-groupoids and representations up to homotopy ..... 5
1.3.1 VB-groupoids ..... 6
1.3.2 Representations up to homotopy ..... 11
1.3.3 Representations up to homotopy vs VB-groupoids ..... 14
1.4 VB-algebroids and representation up to homotopy ..... 14
1.4.1 VB-algebroids ..... 15
1.4.2 Representations up to homotopy ..... 21
1.4.3 Representations up to homotopy vs. VB-algebroids ..... 23
2 VB-groupoid cocycles and their infinitesimal data ..... 25
2.1 Linear cocycles ..... 25
2.2 Infinitesimal linear cocycles ..... 30
2.3 Multilinear cocycles ..... 35
2.3.1 Bilinear cocycles ..... 35
2.3.2 Multilinear cocycles ..... 40
2.4 Infinitesimal bilinear cocycles ..... 42
2.4.1 Infinitesimal multilinear cocycles ..... 47
3 Applications to multiplicative structures on Lie groupoids ..... 49
3.1 Core and linear sections ..... 50
3.1.1 Core sections ..... 52
3.1.2 Linear sections ..... 56
3.2 IM equations ..... 58
3.3 Multiplicative $k$-forms with coefficients in a representation up to ho- motopy ..... 63
4 Applications to VB-subalgebroids ..... 73
4.1 Double vector subbundles ..... 73
4.1.1 Linear distributions ..... 78
4.1.2 Double vector subbundles of $T A \oplus T^{*} A$ ..... 82
4.2 Double vector subalgebroids ..... 84
4.2.1 Infinitesimal-global correspondence ..... 91
4.3 IM-Dirac structures ..... 92
4.3.1 Dirac structures ..... 92
4.3.2 IM-Dirac structures ..... 99
Appendix ..... 109
A Linear vector fields ..... 109
B Module structure on the space of linear sections ..... 110
C Compatibility of multiplication ..... 111
D Dull algebroids and Dorfman connections ..... 114
References ..... 117

## Introduction

In recent years Lie groupoids have played an increasing role in several areas of mathematics, such as non-commutative geometry [16], foliations [21, 35], singular spaces $[23,34]$, Poisson geometry $[12,13,41]$, etc. Just as Lie groups have Lie algebras as their infinitesimal counterparts, the infinitesimal version of a Lie groupoid is a Lie algebroid, and the Lie theory relating them is very rich (see e.g. [11]); in particular, in contrast with Lie algebras, there are nontrivial obstructions to the integration of Lie algebroids [13].

An area where Lie groupoids have become a central tool is Poisson geometry. Any Poisson manifold is naturally associated with a Lie algebroid structure on its cotangent bundle, and the Lie groupoids arising in this context come equipped with compatible symplectic forms, known as multiplicative [41]. These symplectic groupoids naturally arise in the study of symmetries as well as in quantization problems, see e.g. [4]. On the other hand, multiplicative Poisson structures on Lie groups define the so-called Poisson-Lie groups, which are semi-classical limits of quantum groups.

The study of symplectic groupoids, Poisson-Lie groups, or more general Poisson groupoids [42] is the starting point for considering multiplicative geometric structures on a Lie groupoid $\mathcal{G}$, that is, geometric structures on $\mathcal{G}$ that are compatible with the multiplication on $\mathcal{G}$, and their description in terms of infinitesimal data obtained from the Lie algebroid $A=\operatorname{Lie}(\mathcal{G})$ of $\mathcal{G}$. The simplest multiplicative structures are multiplicative functions, which are just cocycles on the Lie groupoid. Other types of multiplicative structures have drawn much attention in recent years, including multiplicative differential forms [7,14], multivector fields [24,33], distributions and foliations [22,27], complex structures [28], etc. In all these contexts, a central issue is always finding the infinitesimal description of, and proving an integration theorem for, the multiplicative object. This infinitesimal-global correspondence recovers some classical results, such as the correspondence between Lie bialgebras and Poisson-Lie groups, Poisson structures and symplectic groupoids, and many others.

This thesis fits into this general program, bringing in an additional feature: the study of multiplicative tensors, such as forms and multivectors, with values in vector bundles, or representations. Here "vector bundles" and "representations" should be understood in the realm of Lie groupoids. While the representation of a Lie group realizes it as the automorphisms of a vector space, Lie groupoids are naturally
represented on vector bundles: each arrow of the groupoid is sent to an isomorphism between fibers of the vector bundle. A difficulty in the theory is that, while Lie groups have natural adjoint and coadjoint representations, Lie groupoids do not. And in order to make sense of such natural objects, one is forced to go a step further and consider representations up to homotopy $[1,2]$.

Representations up to homotopy of Lie groupoids and Lie algebroids generalize their representations on vector bundles to representations on graded vector bundles, or complexes. In fact, one can make sense of the (co-)adjoint representation as a 2-term representation up to homotopy. Recently, it has been shown in [19, 20] that 2-term representations up to homotopy can be geometrically described by certain double structures, known as VB-groupoids (VB-algebroids), which are (categorified) vector-bundle objects in the contexts of Lie groupoids (algebroids). Prototypical examples are the tangent and cotangent bundles of a Lie groupoid (algebroid). More precisely, a $V B$-groupoid is a commutative diagram

where the vertical sides are Lie groupoids, the horizontal sides are vector bundles and the two structures on $\mathcal{E}$ are compatible in a suitable way. A VB-algebroid is defined similarly. It is proven in $[19,20]$ that there is a one-to-one correspondence between isomorphism classes of VB-groupoids $(\mathcal{E}, E ; \mathcal{G}, M)$ (resp. VB-algebroids $(\mathcal{A}, E ; A, M)$ ) and isomorphism classes of 2-term representations up to homotopy of $\mathcal{G}$ (resp. $A$ ) on $C_{[0]} \oplus E_{[1]}$, where $C$ is the so-called core bundle.

The Lie theory underlying VB-algebroids and VB-groupoids has been recently explained in $[5,8]$. Building on these results and using the infinitesimal-global correspondence for cocycles on general VB-groupoids developed in the first part of this thesis, we prove a general infinitesimal-global correspondence for multiplicative structures unifying the cases previously known, and including new ones.

One of the initial motivations for this thesis was the work [14], where the authors consider the notion of multiplicative forms on a Lie groupoid $\mathcal{G} \rightrightarrows M$ with coefficients in an (ordinary) representation $E \longrightarrow M$, and described their infinitesimal counterpart, the so-called E-valued Spencer operators. The kernels of multiplicative 1 -form with coefficients give rise to multiplicative distribution on $\mathcal{G}$, that is, subbundles of $T \mathcal{G}$ which are Lie subgroupoids of the tangent groupoid $T \mathcal{G} \rightrightarrows T M$, with the particularity that the base manifold is the whole space $T M$. In trying to extend this viewpoint to general multiplicative distributions (i.e., those covering a subbundle of $T M$, as considered in $[17,27]$ ), one realizes that one should consider (2-term) representations up to homotopy as coefficients.

In order to make sense of multiplicative forms with these more general coefficients, it is convenient to have the following interpretation of the usual multiplicativity
condition, which extends the approach in [7] for the case of trivial coefficients. A representation $E \longrightarrow M$ of a Lie groupoid $\mathcal{G}$ has an associated VB-groupoid $\mathbf{s}^{*} E \rightrightarrows E$ over $\mathcal{G}$ with trivial core bundle (the action VB-groupoid), where $\mathbf{t}$ is the target map of $\mathcal{G}$ (see [19] or Subsection 1.3.1 below). Then a $k$-form $\omega \in \Omega^{k}\left(\mathcal{G}, \mathbf{s}^{*} E\right)$ with coefficients in $E$ is multiplicative (as in [14]) if and only if the natural map

$$
\omega: \bigoplus_{k} T \mathcal{G} \longrightarrow \mathrm{~s}^{*} E,
$$

defined by evaluation, is a morphism of Lie groupoids, where $\bigoplus_{k} T \mathcal{G}$ is the Whitney sum of the tangent groupoid over $\mathcal{G}$ (see Subsection 3.3). This viewpoint can now be extended by replacing $\mathrm{s}^{*} E$ by a general VB-groupoid, in particular those arising from representations up to homotopy.

Actually, it is a general fact that multiplicative geometric structures on a Lie groupoid can be viewed as a morphism of appropriate Lie groupoids. This observation goes back to [33], where it is shown that a Poisson structure $\pi \in \Gamma\left(\wedge^{2} T \mathcal{G}\right)$ on a Lie groupoid is multiplicative if and only if the induced map $\pi^{\sharp}: T^{*} \mathcal{G} \longrightarrow T \mathcal{G}$ is a morphism of Lie groupoids. This viewpoint is further explored in [7,9,10]. Moreover, since these geometric structures have some linear conditions, the morphisms which determine them are actually morphism between VB-groupoids satisfying additional linear properties. And since we can dualize VB-groupoids, those morphisms can be seen as cocycles in suitable VB-groupoids. With this in mind, we can extend the discussion to more general geometric structures and allow them to have general coefficients.

Given a VB-groupoid $\mathcal{E}$, the central idea we pursue is then to view an $\mathcal{E}$-valued multiplicative $(p, q)$-tensor on a Lie groupoid $\mathcal{G}$,

$$
\tau \in \Gamma\left(\bigotimes^{p} T^{*} \mathcal{G} \otimes \bigotimes^{q} T \mathcal{G} \otimes \mathcal{E}\right)
$$

as a cocycle

$$
c_{\tau}:\left(\oplus_{p} T \mathcal{G}\right) \oplus\left(\oplus_{q} T^{*} \mathcal{G}\right) \oplus \mathcal{E}^{*} \longrightarrow \mathbb{R}
$$

defined on the Whitney sums of its tangent and cotangent bundles and the dual of $\mathcal{E}$, making use of tangent and cotangent groupoid structures (Definition 3.2).

This viewpoint has some nice features:

- It allows us to work with functions (cocycles) instead of more complicated structures. Moreover, the characterization of groupoid cocycles in terms of infinitesimal data is simple.
- It allows us to put many geometric structures of interest in a common framework.
- It provides simpler proofs even of known results, besides giving new ones.

An important particular case of multiplicative tensors with coefficients are differential forms with values in a representation up to homotopy $\omega \in \Omega^{q}(\mathcal{G}, \mathcal{E})$, where $\mathcal{E}$ is the VB-groupoid associated with the representation. In this thesis, we obtain an infinitesimal-global correspondence for these objects extending the result in [14], which we recover when $\mathcal{E}$ is an ordinary representation (with a different proof). Moreover, when $q=1$ the $\operatorname{kernel} \operatorname{ker}(\omega)$ is a (general) multiplicative subbundle, and we recover the description of multiplicative tangent distributions and foliations in $[14,17,27]$; we also use our methods to treat multiplicative Dirac structures [36], giving an alternative viewpoint to results in [25,26]. Our methods are also well suited for other classes of multiplicative structures, such as Nijenhuis structures on Courant algebroids, that we plan to explore in the future.

Outline of the Thesis. This thesis is organized as follows.
In Chapter 1 we recall the definitions of Lie groupoids, and Lie algebroids, VBgroupoids and VB-algebroids, as well as representations up to homotopy. We recall some basic results for these objects which are relevant for subsequent chapters.

Chapter 2 is dedicated to the study of cocycles on VB-groupoids and on VBalgebroids. We provide a description of cocycles on a VB-groupoid, satisfying additional linearity conditions, in terms of VB-algebroid data and prove an infinitesimalglobal correspondence:


In order to simplify the discussion, we first treat linear cocycles, and then bilinear cocycles in detail, and finally we extend the results to multilinear cocycles. The main results in this chapter are:

- Theorem 2.15, which says that linear cocycles on a VB-groupoid $\mathcal{E} \rightrightarrows E$ with core bundle $C$ over a source-simply-connected Lie groupoid $\mathcal{G}$ are in natural one-to-one correspondence with pairs $(\mathbf{D}, \sigma)$, where $\mathbf{D}: \Gamma_{\text {lin }}\left(A_{\mathcal{E}}, E\right) \longrightarrow \Gamma\left(E^{*}\right)$ is a $C^{\infty}(M)$-linear operator defined on the space of linear section of the Lie $\operatorname{algebroid} A_{\mathcal{E}}$ of $\mathcal{E}, \sigma$ is an element in $\Gamma\left(C^{*}\right)$, satisfying suitable compatibility conditions.
- Theorem 2.30, which states that bilinear cocycles on a VB-groupoid $\mathcal{E}_{1} \oplus$ $\mathcal{E}_{2}$ over a source-simply-connected Lie groupoid $\mathcal{G}$ are in natural one-to-one correspondence with triples ( $\mathbf{D}, \sigma_{1}, \sigma_{2}$ ), where
$-\mathbf{D}: \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}_{1}}, E_{1}\right) \times_{\Gamma(A)} \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}_{2}}, E_{2}\right) \longrightarrow \Gamma\left(E_{1}^{*} \otimes E_{2}^{*}\right)$ is a $C^{\infty}(M)$-linear operator,
$-\sigma_{1}: C_{1} \longrightarrow E_{2}^{*}$ and $\sigma_{2}: C_{2} \longrightarrow E_{1}^{*}$ are vector bundle maps,
satisfying suitable compatibility conditions.

In Chapter 3 we apply the theory of VB-groupoid cocycles to study multiplicative $(p, q)$-tensor fields on a Lie groupoid $\mathcal{G}$ with coefficients on a VB-groupoid $\mathcal{E}$. The componentwise linear function $c_{\tau} \in C^{\infty}\left(\left(\oplus_{p} T \mathcal{G}\right) \oplus\left(\oplus_{q} T^{*} \mathcal{G}\right) \oplus \mathcal{E}^{*}\right)$ associated to $\tau$ will be a multilinear cocycle. As an example we describe multiplicative forms with coefficients in a representation up to homotopy.

Our main theorem is:

- Theorem 3.17, which says that multiplicative $\mathcal{E}$-valued $(p, q)$-tensors on a source-simply-connected Lie groupoid $\mathcal{G}$ are in one-to-one correspondence with quadruples $(\mathbf{D}, l, r, \sigma)$ which define $A_{\mathcal{E}}$-valued $(p, q)$-tensors on $A$, see Def. 3.14 for an explicit description of the infinitesimal objects.
For the trivial representation, this recovers the infinitesimal description of multiplicative differential forms, multivector fields etc, as in [10]. This result can be specialized to the case of differential forms with coefficients on representations up to homotopy, leading to:
- Theorem 3.25, which establishes a one-to-one correspondence between multiplicative $k$-forms on a source-simply-connected Lie groupoid with values in a representation up to homotopy and triples $(\mathbb{D}, l, \theta)$, where
$-\mathbb{D}: \Gamma(A) \longrightarrow \Omega^{k}(M, C)$ satisfies a derivation rule,
$-l: A \longrightarrow \wedge^{k-1} T^{*} M \otimes C$ is a linear map,
$-\theta \in \Omega^{k}(M, E)$,
satisfying suitable compatibility equations (see (3.34)-(3.39)).
For ordinary representations, this recovers the result in [14].
In Chapter 4, we use the techniques developed to treat $(p, q)$-tensor fields with coefficients to consider VB-subgroupoids, or multiplicative subbundles. We consider subbundles arising as kernels of linear and bilinear cocycles, and then we apply the theory of Chapter 2. We describe the particular cases of tangent distributions and subbundles of $T \mathcal{G} \oplus T^{*} \mathcal{G}$. We use this approach to study multiplicative Dirac structures, recovering results about their infinitesimal description from a new viewpoint. We work out explicitly the examples of multiplicative presymplectic form and multiplicative Poisson structures. The main result here is
- Theorem 4.26, which says that, for a VB-groupoid $\mathcal{E} \rightrightarrows E$ with core bundle $C$, over a source-simply-connected Lie groupoid $\mathcal{G} \rightrightarrows M$, there is a natural one-toone correspondence between VB-subgroupoids $\mathcal{H} \rightrightarrows H$ of $\mathcal{E}$, with core bundle $K$, and operators $\mathcal{D}: \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}, E\right) \longrightarrow \Gamma\left(H^{*} \otimes C / K\right)$ satisfying compatibility conditions described by Equations (4.11)-(4.14).


## Chapter 1

## Background

In this chapter we recall some definitions and results which will be useful throughout this thesis, and we fix some notation. For Lie groupoids and Lie algebroids we follow mostly [13], for VB-groupoids, VB-algebroids [19, 20] and for representation up to homotopy we rely on $[1,2,19,20]$. These references contain the proofs of results omitted here.

### 1.1 Lie groupoids and Lie algebroids

A Lie groupoid consists of two manifolds, $\mathcal{G}$ and $M$, called the space of arrows and the space of objects, respectively, together with the following structure maps

- surjective submersions $\mathbf{s}, \mathbf{t}: \mathcal{G} \longrightarrow M$, called source and target maps,
- a smooth map $\mathbf{m}: \mathcal{G}^{(2)} \longrightarrow \mathcal{G}$, called the multiplication, where

$$
\mathcal{G}^{(2)}=\{(g, h) \in \mathcal{G} \times \mathcal{G}: \mathbf{s}(g)=\mathbf{t}(h)\},
$$

is the space of composable arrows,

- smooth maps, $1: M \longrightarrow \mathcal{G}$ and $\iota: \mathcal{G} \longrightarrow \mathcal{G}$, the unit map and the inversion map,
satisfying suitable compatibility conditions: $\mathcal{G}$ is a category over $M$ where all morphisms are invertible. We denote a Lie groupoid by $\mathcal{G} \rightrightarrows M$.

Example 1.1. Trivial examples. These first examples show how Lie groupoids are generalizations of different spaces. A Lie group $G$ is a Lie groupoid over a point. Given a manifold $M$, we can see it as the Lie groupoid $M \rightrightarrows M$ where the source and target maps are the identity. Finally, every vector bundle $\pi: E \longrightarrow M$ is a Lie groupoid, where $\mathbf{s}=\mathbf{t}=\pi$, and the multiplication is the addition on the fibers.

Example 1.2. The pair groupoid. Let $M$ be a manifold. The direct product $M \times M$ is a Lie groupoid over $M$, where the source map is the projection in the first component, and the target map is the projection on the second component. The multiplication is $(y, z)(x, y)=(x, z)$. This Lie groupoid is called the pair groupoid.

Example 1.3. General linear groupoid. Let $E \longrightarrow M$ be a vector bundle. The general linear groupoid of E is the Lie groupoid whose arrows are all linear isomorphisms $E_{x} \longrightarrow E_{y}$, for $x, y \in M$, and the space of objects is $M$. Given an isomorphism $g: E_{x} \longrightarrow E_{y}$, the source is $\mathbf{s}(g)=x$ and the target is $\mathbf{t}(g)=y$. The multiplication is given by composition of linear maps. We denote this Lie groupoid by $\mathcal{G}(E)$. This is a generalization of the general linear group $G L(V)$ for a vector space $V$. For details of the smooth structure of $\mathcal{G}(E)$ see e.g. [32], Chapter 1, Example 1.1.12.

Example 1.4. The fundamental groupoid. Assume that $M$ is a connected manifold. The fundamental groupoid of $M$, denoted by $\Pi_{1}(M) \rightrightarrows M$, consists of homotopy classes of paths with fixed end points. The multiplication is the concatenation of paths.

Example 1.5. The action groupoid. Let $G \times M \longrightarrow M$ be an action of a Lie group on a manifold $M$. The action groupoid over $M$ has as space of arrows the direct product $G \times M$. For $(g, x),(h, y) \in G \times M$, the source, target and multiplication are

$$
\mathbf{s}(g, x)=x, \quad \mathbf{t}(g, x)=g \cdot x, \quad(g, x)(h, y)=(g h, y)
$$

Definition 1.6. Let $\mathcal{G} \rightrightarrows M$ and $\mathcal{H} \rightrightarrows N$ be two Lie groupoids. A morphism of Lie groupoids between $\mathcal{G}$ and $\mathcal{H}$ consists of maps $F: \mathcal{G} \longrightarrow \mathcal{H}$ and $f: M \longrightarrow N$ which are compatible with all the structure maps, i.e., a morphism of Lie groupoids is a functor.

A Lie algebroid is a vector bundle $A \longrightarrow M$ together with a vector bundle map $\rho: A \longrightarrow T M$, called the anchor map, and a Lie bracket on the space of sections $\Gamma(A)$ such that the following Leibniz rule holds:

$$
[a, f b]=f[a, b]+\mathcal{L}_{\rho(a)} f b
$$

for all $a, b \in \Gamma(A)$ and $f \in C^{\infty}(M)$.
Example 1.7. A Lie algebra $\mathfrak{g}$ is a Lie algebroid where $M=\{*\}$ is a point. The tangent bundle $T M \longrightarrow M$ of a manifold $M$ is a Lie algebroid, where the Lie bracket is the Lie bracket of vector fields and the anchor map is the identity Id : TM $\longrightarrow T M$.

Example 1.8. Poisson Manifolds. Let $(M, \pi)$ be a Poisson manifold. Its cotangent bundle $T^{*} M \longrightarrow M$ inherits a natural Lie algebroid structure, where the anchor map $\pi^{\sharp}: T^{*} M \longrightarrow T M$ is $\pi^{\sharp}(\alpha):=\pi(\alpha, \cdot)$, and the Lie bracket is determined by the Poisson bracket: $[\mathrm{d} f, \mathrm{~d} g]:=\mathrm{d}\{f, g\}$ together with a Leibniz rule.

Example 1.9. Let $\mathcal{F} \subseteq T M$ be an involutive distribution on $M$, i.e. a (smooth) linear subbundle of $T M$ whose space of sections is closed under the usual bracket of vector fields. Then $\mathcal{F} \longrightarrow M$ is a Lie algebroid with bracket the restriction of Lie brackets of vector fields, and where the anchor map is the inclusion $\iota: \mathcal{F} \longrightarrow T M$.

Example 1.10. The Lie algebroid of a Lie groupoid. Let $\mathcal{G} \rightrightarrows M$ be a Lie groupoid with $\mathbf{s}, \mathbf{t}$ the source and target maps. Let $A:=\left.\operatorname{Ker}(T \mathbf{s})\right|_{M}$. Since the source map is a surjective submersion, $A$ is a vector bundle over $M$. The anchor map $\rho: A \longrightarrow T M$ is defined by $\rho\left(a_{p}\right)=(T \mathbf{t})_{p} a \in T_{p} M$. Similarly to the Lie algebra case, one can identify the space of sections of $A$ with vector fields on $\mathcal{G}$ which are invariant by right multiplication (see e.g. [13]):

$$
\vec{a}_{g}=T R_{g}\left(a_{\mathbf{t}(g)}\right) \quad \text { for } a \in \Gamma(A)
$$

where $T R_{g}$ is the differential map of the right multiplication by $g \in \mathcal{G}$. Under this identification, the Lie bracket on $\Gamma(A)$ is determined by

$$
\overrightarrow{[a, b]}:=[\vec{a}, \vec{b}]_{\mathfrak{X}(\mathcal{G})} .
$$

### 1.2 Multiplicative functions

Our approach to study multiplicative structures on a Lie groupoid $\mathcal{G}$ is to regard them as multiplicative functions in some Lie groupoid $\mathbb{G}$. We recall here a characterization of this kind of functions in terms of an infinitesimal data, and their relation with cohomology of Lie groupoids and Lie algebroids.

Given a Lie groupoid $\mathcal{G} \rightrightarrows M$, a function $F \in C^{\infty}(\mathcal{G})$ is called multiplicative if

$$
\begin{equation*}
F\left(g_{1} \cdot g_{2}\right)=F\left(g_{1}\right)+F\left(g_{2}\right) \tag{1.1}
\end{equation*}
$$

for all composable pair $\left(g_{1}, g_{2}\right) \in \mathcal{G}^{(2)}$.
An immediate consequence of the definition is that

$$
\begin{equation*}
\left.F\right|_{M}=0 \tag{1.2}
\end{equation*}
$$

For a function $F: \mathcal{G} \longrightarrow \mathbb{R}$ its infinitesimal counterpart is the differential of $F$ restricted to the Lie algebroid $A$ :

$$
A F: A \longrightarrow \mathbb{R}, \quad\langle A F, a\rangle=\mathrm{d} F(a) \quad \text { for all } a \in A
$$

The following result characterizes multiplicative functions and its proof can be found in [10]. We use this proposition in Chapter 2 to describe infinitesimally cocycles in VB-groupoids.

Proposition 1.11. Let $F$ be a smooth function in a Lie groupoid $\mathcal{G} \rightrightarrows M$. Let $A$ be the Lie algebroid of $\mathcal{G}$. If $F$ is multiplicative then

$$
\begin{equation*}
\mathcal{L}_{\vec{a}} F=\boldsymbol{t}^{*}\langle A F, a\rangle \quad \forall a \in \Gamma(A) . \tag{1.3}
\end{equation*}
$$

Moreover if a function $F \in C^{\infty}(\mathcal{G})$ satisfies (1.3) and (1.2), and $\mathcal{G}$ is source connected then $F$ is a multiplicative function.

Example 1.12. Every function $f \in C^{\infty}(M)$ defines a multiplicative function on $\mathcal{G}$ as follows

$$
F:=\mathbf{t}^{*} f-\mathbf{s}^{*} f .
$$

Since $F$ is multiplicative, the infinitesimal counterpart satisfies

$$
\mathbf{t}^{*}\langle A F, a\rangle=\mathcal{L}_{\vec{a}}\left(\mathbf{t}^{*} f-\mathbf{s}^{*} f\right)=\mathbf{t}^{*} \mathcal{L}_{\rho(a)} f,
$$

for all $a \in \Gamma(A)$, where $\rho: A \longrightarrow T M$ is the anchor map. Note that we used

$$
\mathcal{L}_{\vec{a}}\left(\mathbf{s}^{*} f\right)(p)=\left.\frac{d}{d r}\right|_{r=0} f\left(\mathbf{s}\left(\varphi_{r}^{a}(p)\right)\right)=0
$$

because $\mathbf{s}\left(\varphi_{r}^{a}(p)\right)=p$, where $\varphi_{r}^{a}$ is the flow of the vector field of $\vec{a}$. Therefore

$$
\langle A F, a\rangle=\mathcal{L}_{\rho(a)} f .
$$

When $\mathcal{G}=M \times M \rightrightarrows M$ is the pair groupoid, functions of the form

$$
F(x, y)=f(x)-f(y) \quad \text { for } f \in C^{\infty}(M)
$$

are always multiplicative.

### 1.2.1 Cohomology of Lie groupoids and Lie algebroids

Given a Lie groupoid $\mathcal{G}$, denote by $\mathcal{G}^{(k)}, k>0$, the space of $k$-composable arrows:

$$
\mathcal{G}^{(k)}=\left\{\left(g_{1}, \ldots, g_{k}\right) \in \mathcal{G}^{k}: \mathbf{s}\left(g_{i}\right)=\mathbf{t}\left(g_{i+1}\right), i=1, \ldots, k-1\right\}
$$

and $\mathcal{G}^{(0)}=M$. The space of smooth groupoid k-cochains is $C^{k}(\mathcal{G})=C^{\infty}\left(\mathcal{G}^{(k)}\right)$. There is a coboundary operator $\delta: C^{\bullet}(\mathcal{G}) \longrightarrow C^{\bullet+1}(\mathcal{G})$ defined as follows: for $k=0$

$$
\delta(f)(g)=f(\mathbf{s}(g))-f(\mathbf{t}(g)),
$$

and for $k>0$

$$
\begin{align*}
(\delta f)\left(g_{0}, \ldots, g_{k}\right)= & f\left(g_{1}, \ldots, g_{k}\right)+\sum_{i=1}^{k}(-1)^{i} f\left(g_{0}, \ldots, g_{i-1} g_{i}, \ldots, g_{k}\right)  \tag{1.4}\\
& +(-1)^{k+1} f\left(g_{0}, \ldots, g_{k-1}\right)
\end{align*}
$$

where $f \in C^{k}(\mathcal{G})$. The coboundary operator satisfies $\delta^{2}=0$, and the cohomology of the complex $\left(C^{\bullet}(\mathcal{G}), \delta\right)$ is referred to as cohomology of the Lie groupoid.

Remark 1.13. Note that for $F \in C^{\infty}(\mathcal{G})$ the coboundary operator is

$$
(\delta F)\left(g_{1}, g_{2}\right)=F\left(g_{2}\right)-F\left(g_{1} g_{2}\right)+F\left(g_{1}\right)
$$

Then $F$ is multiplicative if and only if $\delta F=0$, i.e., $F$ is a cocycle on $\mathcal{G}$.
Given a Lie algebroid $A$, let

$$
d_{A}: \Omega^{k}(A)=\Gamma\left(\wedge^{k} A^{*}\right) \longrightarrow \Omega(A)^{k+1}
$$

be the Lie algebroid differential associated to the complex $\Omega(A)=\Gamma\left(\wedge A^{*}\right)$ given by the Koszul formula

$$
\begin{align*}
d_{A}(\omega)\left(a_{1}, \ldots, a_{k+1}\right)= & \sum_{i<j}(-1)^{i+j} \omega\left(\left[a_{i}, a_{j}\right], \ldots, \widehat{a_{i}}, \ldots, \widehat{a_{j}}, \ldots, a_{k+1}\right)  \tag{1.5}\\
& +\sum_{i}(-1)^{i+1} \mathcal{L}_{\rho\left(a_{i}\right)} \omega\left(a_{1}, \ldots, \widehat{a_{i}}, \ldots, a_{k+1}\right)
\end{align*}
$$

This operator satisfies $d_{A}^{2}=0$ and the following derivation rule

$$
d_{A}(\omega \eta)=d_{A}(\omega) \eta+(-1)^{k} \omega d_{A}(\eta)
$$

for $\omega \in \Omega^{k}(A)$ and $\eta \in \Omega^{k+1}(A)$. The cohomology of the complex $\left(\Omega(A), d_{A}\right)$ is called the cohomology of the Lie algebroid $A$.

Remark 1.14. A function $f \in C^{\infty}(A)$ is a morphism of Lie algebroid or a cocycle if

$$
d_{A}(f)(X, Y):=f([X, Y])-\mathcal{L}_{\rho(X)} f(Y)+\mathcal{L}_{\rho(Y)} f(X)=0
$$

for all sections $X, Y \in \Gamma(A)$.

### 1.3 VB-groupoids and representations up to homotopy

Representations up to homotopy of Lie groupoids generalize their representations on vector bundles to representations on graded vector bundles, or complexes. It has been shown in [19] that 2-term representations up to homotopy can be geometrically described by certain double structures, known as VB-groupoids, which are the natural vector-bundle objects in the context of Lie groupoids. Prototypical examples are the tangent and cotangent groupoids. We recall here briefly VB-groupoids, representations up to homotopy and their relation. We follow mostly [19].

### 1.3.1 VB-groupoids

A VB-groupoid ( [37]) is a commutative diagram

such that the vertical sides are Lie groupoids, the horizontal sides are vector bundles and the two structures on $\mathcal{E}$ are compatible:

- $\bar{s}, \bar{t}: \mathcal{E} \longrightarrow E$ are vector bundle morphisms over $s, t: \mathcal{G} \longrightarrow M$, respectively.
- $Q: \mathcal{E} \longrightarrow \mathcal{G}$ is a Lie groupoid morphism over $q_{E}: E \longrightarrow M$.
- For all $\eta_{1}, \eta_{2}, \eta_{3}, \eta_{4} \in \mathcal{E}$ such that $Q\left(\eta_{1}\right)=Q\left(\eta_{3}\right), Q\left(\eta_{2}\right)=Q\left(\eta_{4}\right)$ and $\left(\eta_{1}, \eta_{2}\right)$ and $\left(\eta_{3}, \eta_{4}\right)$ composable pair, then

$$
\left(\eta_{1}+\eta_{3}\right) \cdot\left(\eta_{2}+\eta_{4}\right)=\eta_{1} \cdot \eta_{2}+\eta_{3} \cdot \eta_{4} .
$$

This is known as the interchange law.
Remark 1.15. There is an equivalent definition using actions. An $(\mathbb{R}, \cdot)$-action $h$ on the space of arrows of a Lie groupoid $\mathcal{E} \rightrightarrows E$ is called multiplicative if $h_{\lambda}: \mathcal{E} \longrightarrow \mathcal{E}$ is a morphism of Lie groupoids for every $\lambda \in \mathbb{R}$ (see [8]). Bursztyn, Cabrera, and del Hoyo proved in [8] that there is a one-to-one correspondence between VB-groupoids and regular multiplicative actions.

Given a VB-groupoid there is a canonical vector bundle over $M$, called (right-) core bundle which is defined as follows:

$$
C=1^{*}(\operatorname{Ker}(\bar{s}))
$$

where $1: M \longrightarrow \mathcal{G}$ is the unit map. The core is important in the structure of a VB-groupoid: there is a short exact sequence of vector bundles over $\mathcal{G}$, called the (right-) core exact sequence,

$$
\begin{equation*}
0 \longrightarrow \mathbf{t}^{*} C \longrightarrow \mathcal{E} \longrightarrow \mathbf{s}^{*} E \longrightarrow 0 \tag{1.7}
\end{equation*}
$$

where the maps are $\mathbf{t}^{*} C \longrightarrow \mathcal{E},(g, c) \longrightarrow c \cdot 0_{g}$, and $\mathcal{E} \longrightarrow \mathbf{s}^{*} E, \eta \longrightarrow(Q(\eta), \bar{s}(\eta))$, and any splitting of this sequence induces a decomposition of the VB-groupoid as $\mathcal{E}=\mathbf{t}^{*} C \oplus \mathbf{s}^{*} E$ (see [19]).

We give now some important examples of VB-groupoids that we will use later. We do this in detail because most of the applications we present in this thesis are related with these VB-groupoids.

Example 1.16. Tangent groupoid. Given a Lie groupoid $\mathcal{G} \rightrightarrows M$ with structure maps ( $\mathbf{s}, \mathbf{t}, \mathbf{m}, 1, \iota$ ), it induces a Lie groupoid structure on $T \mathcal{G}$ over $T M$ where the structure maps are $\mathrm{Ts}, \mathrm{Tt}, \mathrm{T} m, \mathrm{~T} \epsilon$ and $\mathrm{T} \iota$, the differentials of the structure maps of $\mathcal{G}$. Explicitly, the multiplication $\bar{m}=\mathrm{Tm}: T\left(\mathcal{G}^{(2)}\right) \simeq T \mathcal{G}^{(2)} \longrightarrow T \mathcal{G}$ is given as follows: for $X \in T_{g}\left(\mathcal{G}_{\mathbf{s}(g)}\right), Y \in T_{h}\left(\mathcal{G}_{\mathbf{t}(h)}\right)$ we have (see [32] § 1.1)

$$
\begin{equation*}
\bar{m}_{(g, h)}(X, Y)=\left(\mathrm{T} R_{h}\right)_{g}(X)+\left(\mathrm{T} L_{g}\right)_{h}(Y) \tag{1.8}
\end{equation*}
$$

where $(g, h) \in \mathcal{G}^{(2)}, R_{h}$ and $L_{g}$ are the right and left multiplication, respectively, and where

$$
\mathcal{G}_{\mathbf{s}(g)}=\{\widetilde{g} \in \mathcal{G} / \mathbf{s}(\widetilde{g})=\mathbf{s}(g)\} \quad \text { and } \quad \mathcal{G}_{\mathbf{t}(h)}=\{\widetilde{h} \in \mathcal{G} / \mathbf{t}(\widetilde{h})=\mathbf{t}(h)\} .
$$

The Lie groupoid $T \mathcal{G} \rightrightarrows T M$ is called tangent groupoid of $\mathcal{G}$. Moreover, considering the linear structure of the tangent bundle,

is a VB-groupoid with core bundle $A$, and we refer to it as the tangent VB-groupoid.
Remark 1.17. Using Formula (1.8), a right invariant vector field $\vec{a} \in \mathfrak{X}(\mathcal{G})$, with $a \in \Gamma(A)$ can be write as

$$
\begin{equation*}
\vec{a}(g)=a(\mathbf{t}(g)) \cdot 0_{g} \tag{1.9}
\end{equation*}
$$

where the multiplication is in the tangent groupoid.
Example 1.18. Cotangent groupoid. Let $\mathcal{G} \rightrightarrows M$ be a Lie groupoid and let $A$ its Lie algebroid. Denote by $A^{*}$ the dual vector bundle of $A$ with respect to $M$. We will define a Lie groupoid structure on $T^{*} \mathcal{G} \rightrightarrows A^{*}$. The source and target maps $\widetilde{s}, \widetilde{t}: T^{*} \mathcal{G} \longrightarrow A^{*}$ are characterized by:

$$
\langle\widetilde{s}(\eta), a\rangle=-\left\langle\eta, 0_{g} \cdot T \iota(a)\right\rangle \quad \text { and } \quad\langle\widetilde{t}(\eta), b\rangle=\left\langle\eta, b \cdot 0_{g}\right\rangle,
$$

for $g \in \mathcal{G}, \eta \in T_{g}^{*} \mathcal{G}, a \in A_{\mathbf{s}(g)}$ and $b \in A_{\mathbf{t}(g)}$. In particular, for a section $a \in \Gamma(A)$ we have

$$
\left\langle\widetilde{s}(\eta), a_{(\mathbf{s}(g))}\right\rangle=-\left\langle\eta, \overleftarrow{a}_{g}\right\rangle \quad \text { and } \quad\left\langle\widetilde{t}(\eta), a_{(\mathbf{t}(g))}\right\rangle=\left\langle\eta, \vec{a}_{g}\right\rangle
$$

The multiplication is given by:

$$
\begin{equation*}
\langle\eta \cdot \mu, X \cdot Y\rangle=\langle\eta, X\rangle+\langle Y, \mu\rangle, \tag{1.10}
\end{equation*}
$$

for $\eta \in T_{g}^{*} \mathcal{G}, \mu \in T_{h}^{*} \mathcal{G}$ with $\widetilde{s}(\eta)=\widetilde{t}(\mu)$, and where $X \in T_{g} \mathcal{G}, Y \in T_{h} \mathcal{G}$ are composable vectors. With this structure maps $T^{*} \mathcal{G} \rightrightarrows A^{*}$ is Lie groupoid, called the cotangent groupoid. Moreover

is a VB-groupoid, where the vector bundle structures are the usual ones, and where its core bundle is $T^{*} M$. We call it the cotangent VB-groupoid.

Another important type of example comes from representations of Lie groupoids. Recall that a representation of a Lie groupoid $\mathcal{G}$ is a vector bundle $E \longrightarrow M$ such that for every $g: x \longrightarrow y \in \mathcal{G}$ there is a linear isomorphism $g \cdot: E_{x} \longrightarrow E_{y}$ satisfying $g \cdot(h \cdot e)=(g h) \cdot e$ for composable arrows, and $x \cdot=\left.I d\right|_{E_{x}}$, for every unit $x \in M$. Note that when $\mathcal{G}=G$ is a Lie group, $E$ is a vector space, and a representation of this Lie groupoid is indeed a usual representation of a Lie group on the vector space $E$. Moreover a representation of Lie groups on a vector space $V$ can be seen as a morphism of Lie groups $G \longrightarrow G L(V)$. Is straightforward to check that in the case of Lie groupoids, a representation on $E \longrightarrow M$ is equivalent to the existence of a Lie groupoid morphism $\Delta: \mathcal{G} \longrightarrow \mathcal{G}(E)$. We denote $(E \longrightarrow M, \Delta)$ a representation of $\mathcal{G}$ on the vector bundle $E$.
Example 1.19. Action groupoid associated to a representation. Let $E \longrightarrow$ $M, \Delta)$ be a representation of $\mathcal{G}$. Take now the pull back of $E$ by the source map

$$
\mathbf{s}^{*}(E)=\left\{(e, g) \in E \times \mathcal{G}: e \in E_{\mathbf{s}(g)}\right\}
$$

There is a Lie groupoid structure on $\mathbf{s}^{*}(E)$ over $E$, where the structure maps are

$$
\begin{aligned}
\bar{s}(e, g) & =e \\
\bar{t}(e, g) & =g \cdot e \\
\left(g_{1}, g_{2} \cdot e_{2}\right)\left(g_{2}, e_{2}\right) & =\left(g_{1} g_{2}, e_{2}\right)
\end{aligned}
$$

This Lie groupoid is denoted by $E * \mathcal{G} \rightrightarrows E$ and is called the action groupoid for the representation. Moreover

is a VB-groupoid with zero core bundle, called the action VB-groupoid.
As an example of this VB-groupoid, consider an orbit $\mathcal{O} \subseteq M$ of a Lie groupoid $\mathcal{G} \rightrightarrows M$, i.e.,

$$
\mathcal{O}=M / \mathcal{G}=\left\{\mathcal{O}_{x}: x \in M\right\}
$$

where $\mathcal{O}_{x}=\left\{\mathbf{t}(g): g \in \mathbf{s}^{-1}(x)\right\}$ is the orbit through $x$. Restringing $\mathcal{G}$ to $\mathcal{O}$ we get a Lie groupoid $\mathcal{G}_{\mathcal{O}} \rightrightarrows \mathcal{O}$. The normal bundle is the quotient

$$
N_{\mathcal{G}_{\mathcal{O}}}=\frac{T \mathcal{G}}{T \mathcal{G}_{\mathcal{O}}}
$$

and it is a Lie groupoid over $N_{\mathcal{O}}=T M / T \mathcal{O}$. This defines a VB-groupoid

with core bundle $C=0$. That means that this VB-groupoid comes from a representation de $\mathcal{G}_{\mathcal{O}}$ on $N_{\mathcal{O}}$. This is the normal representation, which appears in the theorem of linearization $[15,43,45]$.
Example 1.20. Semi-direct product. Let $(C \longrightarrow M, \Delta)$ be a representation of $\mathcal{G}$. Consider the vector bundle over $\mathcal{G}$ given by the pull back of $C$ by the target map

$$
\mathbf{t}^{*}(C)=\left\{(c, g) \in C \times \mathcal{G}: c \in C_{\mathbf{t}(g)}\right\} .
$$

There is a Lie groupoid structure on $\mathbf{t}^{*}(C)$ over $M$ : the source, target and multiplication are

$$
\begin{aligned}
\widetilde{s}(c, g) & =\mathbf{s}(g) \\
\widetilde{t}(c, g) & =\mathbf{t}(g) \\
\left(c_{1}, g_{1}\right) \cdot\left(c_{2}, g_{2}\right) & =\left(c_{1}+\Delta_{g_{1}} c_{2}, g_{1} g_{2}\right) .
\end{aligned}
$$

This Lie groupoid is called semi-direct product of $C$ and $\mathcal{G}$ and it is denoted by $C \rtimes \mathcal{G} \rightrightarrows M$. Moreover, the semi-direct product is a VB-groupoid

with core bundle $C$, and we call it the semi-direct product VB-groupoid.
Example 1.21. Dual of a VB-groupoid. (See [19], $\S 4$ for more details.) Consider a VB-groupoid as (1.6). Let $\mathcal{E}^{*}$ be the dual vector bundle of $\mathcal{E}$ over $\mathcal{G}$. There is a Lie groupoid structure on $\mathcal{E}^{*} \rightrightarrows C^{*}$. The source and target map $\widehat{s}, \widehat{t}$ are determined by:

$$
\langle\widehat{s}(\epsilon), c\rangle=-\left\langle\epsilon, 0_{g} \cdot c^{-1}\right\rangle \quad \text { and } \quad\langle\widehat{t}(\epsilon), d\rangle=\left\langle\epsilon, d \cdot 0_{g}\right\rangle,
$$

where $\epsilon \in \mathcal{E}_{g}^{*}, c \in C_{\mathbf{s}(g)}$ and $d \in C_{\mathbf{t}(g)}$. The multiplication is: for $\left(\epsilon_{1}, \epsilon_{2}\right) \in\left(\mathcal{E}^{*}\right)^{(2)}$ where $\epsilon_{i} \in \mathcal{E}_{g_{i}}^{*}$,

$$
\left\langle\epsilon_{1} \cdot \epsilon_{2}, \eta_{1} \cdot \eta_{2}\right\rangle=\left\langle\epsilon_{1}, \eta_{1}\right\rangle+\left\langle\epsilon_{2}, \eta_{2}\right\rangle,
$$

with $\eta_{i} \in \mathcal{E}_{g_{i}}$. With these structure maps and the usual vector bundle structures $\mathcal{E}^{*} \longrightarrow \mathcal{G}$ and $C^{*} \longrightarrow M$,

is a VB-groupoid with core bundle $E^{*}$.
Remark 1.22. The cotangent VB-groupoid is the dual of the tangent VB-groupoid. Also, semi-direct products and action groupoids are in duality. That means that the dual VB-groupoid of the semi-direct product VB-groupoid $C \rtimes \mathcal{G}$ is the action VB-groupoid $C^{*} * \mathcal{G}$. Conversely, the dual of the action VB-groupoid $E * \mathcal{G}$ is the semi-direct product VB-groupoid $E^{*} \rtimes \mathcal{G}$ (see [19]).

The next examples are related with operations in the category of VB-groupoid over a fix Lie groupoids $\mathcal{G} \rightrightarrows M$. They are important because we will use them in Chapters 3 and 4. Recall that the structure maps of the Lie groupoid $\mathcal{E} \rightrightarrows E$ are denoted by $(\bar{s}, \bar{t}, \bar{m}, \bar{\iota}, \bar{\epsilon})$.

Example 1.23. Sum. Let $\mathcal{E}_{i} \longrightarrow E_{i}$ be two VB-groupoids over $\mathcal{G} \longrightarrow M$ with core bundles $C_{i}$. The direct product $\mathcal{E}_{1} \times \mathcal{E}_{2}$ is a Lie groupoid over $E_{1} \times E_{2}$ where the structure maps are component to component. Also, since $\mathcal{E}_{1} \times \mathcal{E}_{2}$ is a vector bundle over $\mathcal{G}$,

is a VB-groupoid over $\mathcal{G}$, where the core bundle is $C_{1} \oplus C_{2} \longrightarrow M$.
Example 1.24. VB-subgroupoid. Let $\mathcal{E} \rightrightarrows E$ be a VB-groupoid over $\mathcal{G}$ with core bundle $C$. Recall that a Lie subgroupoid of $\mathcal{E}$ is a pair $(\mathcal{H}, i)$ where $\mathcal{H}$ is a Lie groupoid and $i: \mathcal{H} \longrightarrow \mathcal{E}$ is an injective Lie groupoid morphism ([32]). A VB-subgroupoid is a VB-groupoid

such that $\mathcal{H} \rightrightarrows H$ is a Lie subgroupoid of $\mathcal{E} \rightrightarrows E$ and $\mathcal{H}$ is a vector subbundle of $\mathcal{E}$ over $\mathcal{G}$. Note that, in particular, the side bundle $H$ is a vector subbundle of $E$, and the core bundle $K$ is a vector subbundle of $C$.

Example 1.25. Quotient. Let $\mathcal{H} \rightrightarrows H$ be a VB-subgroupoid of $\mathcal{E} \rightrightarrows E$, and consider the vector bundle $\mathcal{E} / \mathcal{H}$ over $\mathcal{G}$. There exists a Lie groupoid structure on $\mathcal{E} / \mathcal{H}$ over $E / H$. The source map $\widehat{s}: \mathcal{E} / \mathcal{H} \longrightarrow E / H$ is: for $[\eta] \in \mathcal{E} / \mathcal{H}$,

$$
\widehat{s}([\eta]):=[\bar{s}(\eta)] .
$$

This map is well defined. Indeed, if $\eta^{\prime} \in[\eta]$ there exists an element $\tau \in \mathcal{H}$ such that $\eta^{\prime}=\eta+{ }_{\mathcal{G}} \tau$. Then

$$
\bar{s}\left(\eta^{\prime}\right)=\bar{s}\left(\eta+{ }_{\mathcal{G}} \tau\right)=\bar{s}(\eta)+\bar{s}(\tau)
$$

because $\bar{s}$ is linear, and since $\mathcal{H}$ is a subgroupoid, $\bar{s}(\tau) \in H$, which means that $\left[\bar{s}\left(\eta^{\prime}\right)\right]=[\bar{s}(\eta)]$. In the same way, we define the target map $\widehat{t}: \mathcal{E} / \mathcal{H} \longrightarrow E / H$. Let now $[\eta],[\mu] \in \mathcal{E} / \mathcal{H}$ such that $\widehat{s}([\eta])=\widehat{t}([\mu])$.

Lemma 1.26. There exist elements $\eta^{\prime} \in[\eta]$ and $\mu^{\prime} \in[\mu]$ such that $\left(\eta^{\prime}, \mu^{\prime}\right) \in \mathcal{E}^{(2)}$. Moreover, if $\widetilde{\eta} \in[\eta]$ and $\widetilde{\mu} \in[\mu]$ are also composable, then $\left[\eta^{\prime} \cdot \mu^{\prime}\right]=[\widetilde{\eta} \cdot \widetilde{\mu}]$.

Proof. Since $\widehat{s}([\eta])=\widehat{t}([\mu])$ follows that there is $e \in H$ such that $\bar{s}(\eta)=\bar{t}(\mu)+_{E} e$. Since $\left.\bar{t}\right|_{\mathcal{H}}$ is onto over $H$, there exist $\tau \in \mathcal{H}$ such that $\bar{t}(\tau)=e$. By linearity of $\bar{t}$, we have $\bar{s}(\eta)=\bar{t}(\mu+\tau)$. Hence $\mu^{\prime}=\mu+\tau \in[\mu]$ and $\left(\eta, \mu^{\prime}\right) \in \mathcal{E}^{(2)}$. Suppose now that $\widetilde{\eta} \in[\eta]$ and $\widetilde{\mu} \in[\mu]$ are also composable. There exist $\tau_{1}, \tau_{2} \in \mathcal{H}$ such that

$$
\widetilde{\eta}=\eta+\tau_{1}, \quad \widetilde{\mu}=\mu^{\prime}+\tau_{2} .
$$

In particular we have that $\left(\tau_{1}, \tau_{2}\right)$ is a composable pair:

$$
\bar{s}(\widetilde{\eta})=\bar{t}(\widetilde{\mu}) \Longrightarrow \bar{s}(\eta)+\bar{s}\left(\tau_{1}\right)=\bar{t}\left(\mu^{\prime}\right)+\bar{t}\left(\tau_{2}\right) \Longrightarrow \bar{s}\left(\tau_{1}\right)=\bar{t}\left(\tau_{2}\right)
$$

because $\bar{s}(\eta)=\bar{t}\left(\mu^{\prime}\right)$. Then by the interchange law

$$
\widetilde{\mu} \cdot \widetilde{\mu}=\left(\eta+\tau_{1}\right) \cdot\left(\mu^{\prime}+\tau_{2}\right)=\eta \cdot \mu^{\prime}+\tau_{1} \cdot \tau_{2},
$$

with $\tau_{1} \cdot \tau_{2} \in \mathcal{H}$. Therefore $\left[\eta \cdot \mu^{\prime}\right]=[\widetilde{\eta} \cdot \widetilde{\mu}]$.
Hence the multiplication $[\eta] \cdot[\mu]:=[\eta \cdot \mu]$ is well defined. The unit map $\widehat{1}:$ $E / H \longrightarrow \mathcal{E} / \mathcal{H}$ and the inversion map $\widehat{\imath}: \mathcal{E} / \mathcal{H} \longrightarrow \mathcal{E} / \mathcal{H}$ are

$$
\widehat{1}([e])=[\overline{1}(e)], \quad \text { and } \quad \widehat{\iota}([\eta])=[\bar{\iota}(\eta)] .
$$

Therefore $\mathcal{E} / \mathcal{H} \rightrightarrows E / H$ is a Lie groupoid. And moreover

is a VB-groupoid with core bundle $C / K$.

### 1.3.2 Representations up to homotopy

Even when representations of Lie groupoids are natural extensions of those of Lie groups, they are too restrictive, in the sense that not always exists a such representation in a given vector bundle, and because there is not a good definition of adjoint representation. The adjoint representation is an important object in the study of the cohomology of classifying spaces, and in the Lie algebroid setting, for deformation cohomology. To solve this situation, Arias-Abad and Crainic [1], introduced the concept of representation up to homotopy, where Lie groupoids are represented in a complex of vector bundles, rather than in vector bundles. These allows more flexibility, for example, there is not a requirement for the associativity condition.

In this thesis we only use representation up to homotopy on a 2 -term graded vector bundle $C_{[0]} \oplus E_{[1]}$ over $M$, where $C$ sits in degree zero, and $E$ in degree one. To define representations up to homotopy, we recall an equivalent definition for representations of Lie groupoids on a vector bundle, which allows a natural extension
to the graded case. We also give an equivalent definition of representations up to homotopy which is more conceptual. We follow [1] and [19] for this part.

Let $E \longrightarrow M$ be a vector bundle over $M$. Define the map $\pi_{0}^{k}: \mathcal{G}^{(k)} \longrightarrow M$ by $\pi_{0}^{k}\left(g_{1}, \ldots, g_{k}\right)=\mathbf{t}\left(g_{1}\right)$, for $k>0$, and the identity for $k=0$. Consider now the following vector bundle over $\mathcal{G}^{(k)}$ :

and denote by

$$
C^{k}(\mathcal{G}, E)=\Gamma\left(\left(\pi_{0}^{k}\right)^{*} E\right)
$$

its space of sections. The space $C^{\bullet}(\mathcal{G}, E)=\oplus_{k} C^{k}(\mathcal{G}, E)$ has a right graded module structure over $C^{\bullet}(\mathcal{G})$ : for $\eta \in C^{k}(\mathcal{G}, E)$ and $f \in C^{l}(\mathcal{G})=C^{\infty}\left(\mathcal{G}^{(l)}\right)$

$$
(\eta \star f)\left(g_{1}, \ldots, g_{k+l}\right)=(-1)^{k l} \eta\left(g_{1}, \ldots, g_{k}\right) f\left(g_{k+1}, \ldots, g_{k+l}\right) .
$$

Theorem 1.27. [19] There is a one-to-one correspondence between representations of a Lie groupoid $\mathcal{G}$ on a vector bundle $E \longrightarrow M$ and degree one operators

$$
D: C^{\bullet}(\mathcal{G}, E) \longrightarrow C^{\bullet+1}(\mathcal{G}, E)
$$

such that

$$
D(\eta \star f)=D(\omega) \star f+(-1)^{|\eta|} \eta \star \delta(f),
$$

preserve normalized functions, and $D^{2}=0$, where $\delta$ is the groupoid coboundary operator, see (1.4).

Proof. (Sketch) Given a representation $(E \longrightarrow M, \Delta)$ define an operator

$$
D: C^{0}(\mathcal{G}, E)=\Gamma(E) \longrightarrow C^{1}(\mathcal{G}, E)=\Gamma\left(\mathbf{t}^{*} E\right)
$$

as follows

$$
D(e)(g):=g \cdot e_{\mathbf{s}(g)}-e_{\mathbf{s}(g)},
$$

for $e \in \Gamma(E)$, and then extend by Leibniz rule to higher degrees. Conversely, given an operator $D: C^{\bullet}(\mathcal{G}, E) \longrightarrow C^{\bullet+1}(\mathcal{G}, E)$, define the representation by:

$$
g: E_{\mathbf{s}(g)} \longrightarrow E_{\mathbf{t}(g)} \quad g \cdot e_{\mathbf{s}(g)}=D(e)(g)+e_{\mathbf{s}(g)} \quad \text { for } e \in \Gamma(E)
$$

The property $D^{2}=0$ is equivalent to the flatness condition of the representation.
This point of view to representations can be naturally extended to the graded case. Let $V=C_{[0]} \oplus E_{[1]}$ be a graded vector bundle over $M$, with $C$ sits in degree zero and $E$ in degree one. Consider $C(\mathcal{G}, V)$ to be a graded (right) $C^{\bullet}(\mathcal{G})$-module with respect to the total grading

$$
C(\mathcal{G}, V)^{k}=\Gamma\left(\left(\pi_{0}^{k}\right)^{*} C\right) \oplus \Gamma\left(\left(\pi_{0}^{k-1}\right)^{*} E\right)
$$

Definition 1.28. A representation up to homotopy of a Lie groupoid $\mathcal{G} \rightrightarrows M$ is a 2-term-graded vector bundle $V=C_{[0]} \oplus E_{[1]}$ over $M$ together with a degree one operator

$$
D: C(\mathcal{G}, V)^{\bullet} \longrightarrow C(\mathcal{G}, V)^{\bullet+1}
$$

such that

$$
D(\omega \star f)=D(\omega) \star f+(-1)^{|\omega|} \omega \star \delta(f),
$$

where $\delta$ is the coboundary operator, $D^{2}=0$ and preserves normalized functions.
For a more conceptual interpretation, remember that we want to represent a Lie groupoid in a complex $\partial: C \longrightarrow E$. For an element $g \in \mathcal{G}$ we expect that it acts as a map of complexes

$$
g: V_{\mathbf{s}(g)}^{\bullet} \longrightarrow V_{\mathbf{t}(g)}^{\bullet} .
$$

That means we would have linear maps $g^{0}: C_{\mathbf{s}(g)} \longrightarrow C_{\mathbf{t}(g)}$ and $g^{1}: E_{\mathbf{s}(g)} \longrightarrow E_{\mathbf{t}(g)}$ which commute with $\partial$ :

$$
g^{1} \circ \partial=\partial \circ g^{0} .
$$

Also, since there is not a requirement about associativity, if $(g, h)$ is a composable pair, $g^{0} \circ h^{0}$ and $(g h)^{0}$ do not need to be equal; and the same with $g^{1} \circ h^{1}$ and $(g h)^{1}$. We summarize this in the following theorem, which is proven in [1] for a general representation up to homotopy, and in [19] for the particular case of representation up to homotopy on a 2 -term graded vector bundle.

Theorem 1.29. A representation up to homotopy of $\mathcal{G}$ on a 2-term graded vector bundle $V=C_{[0]} \oplus E_{[1]}$ over $M$ is equivalent to a quadruple $\left(\Delta^{0}, \Delta^{1}, \partial, \Omega\right)$, where

- $\Delta^{0}$ and $\Delta^{1}$ are unital quasi-actions of $\mathcal{G} \rightrightarrows M$ on $C$ and $E$, respectively. That means for each $g \in \mathcal{G}$ we have linear maps (not necessary invertible) $\Delta_{g}^{0}: C_{s(g)} \longrightarrow C_{t(g)}$ and $\Delta_{g}^{1}: E_{s(g)} \longrightarrow E_{t(g)}$ (quasi-action), and for all $p \in M$, the linear map $\Delta_{p}^{0}: C_{p} \longrightarrow C_{p}$ and $\Delta_{p}^{1}: E_{p} \longrightarrow E_{p}$ are the identity (unital).
- $\partial: C \longrightarrow E$ is a vector bundle map over the identity of $M$
- $\Omega \in C^{2}(\mathcal{G} ; E \longrightarrow C)=\Gamma\left(\mathcal{G}^{(2)}, \operatorname{Hom}\left(s^{*}(E), t^{*}(C)\right)\right)$ is a normalized operator satisfying the following equations:

$$
\begin{align*}
\Delta_{g}^{1} \partial-\partial \Delta_{g}^{0} & =0,  \tag{1.11}\\
\Delta_{g_{1}}^{0} \Delta_{g_{2}}^{0}-\Delta_{g_{1} g_{2}}^{0}+\Omega_{g_{1}, g_{2}} \partial & =0,  \tag{1.12}\\
\Delta_{g_{1}}^{1} \Delta_{g_{2}}^{1}-\Delta_{g_{1} g_{2}}^{1}+\partial \Omega_{g_{1}, g_{2}} & =0,  \tag{1.13}\\
\Delta_{g_{1}}^{0} \Omega_{g_{2}, g_{3}}-\Omega_{g_{1} g_{2}, g_{3}}+\Omega_{g_{1}, g_{2} g_{3}}-\Omega_{g_{1}, g_{2}} \Delta_{g_{3}}^{1} & =0 \tag{1.14}
\end{align*}
$$

for $\left(g_{1}, g_{2}, g_{3}\right) \in \mathcal{G}^{(3)}$.
Remark 1.30. When we say representation up to homotopy, we mean the quadruple $\left(\Delta^{0}, \Delta^{1}, \partial, \Omega\right)$.

### 1.3.3 Representations up to homotopy vs VB-groupoids

There is an equivalence between classes of representations up to homotopy and classes of VB-groupoids. We show here, briefly this correspondence.

Let $\left(\Delta^{0}, \Delta^{1}, \partial, \Omega\right)$ be a representation up to homotopy of a Lie groupoid $\mathcal{G} \rightrightarrows M$ on $C_{[0]} \oplus E_{[1]}$. We will associate to this data a VB-groupoid. Consider the vector bundle over $\mathcal{G}$, given by $\mathbf{t}^{*} C \oplus \mathbf{s}^{*} E$. This space has a Lie groupoid structure over $E$ : for $(g, c, e),\left(g_{i}, c_{i}, e_{i}\right) \in \mathbf{t}^{*} C \oplus \mathbf{s}^{*} E, i=1,2$ we define

$$
\begin{aligned}
\widetilde{s}(g, c, e) & =e \\
\widetilde{t}(g, c, e) & =\partial c+\Delta_{g}^{1} e \\
\left(g_{1}, c_{1}, e_{1}\right) \cdot\left(g_{2}, c_{2}, e_{2}\right) & =\left(g_{1} g_{2}, c_{1}+\Delta_{g_{1}}^{0} c_{2}-\Omega_{g_{1}, g_{2}} e_{2}, e_{2}\right),
\end{aligned}
$$

when $e_{1}=\partial c_{2}+\Delta_{g_{2}}^{1} e_{2}$. Conversely, if $\mathcal{E} \rightrightarrows E$ is a VB-groupoid over $\mathcal{G}$ with core bundle $C$, we can associate a representation up to homotopy. Let $h: \mathrm{s}^{*} E \longrightarrow \mathcal{E}$ be a horizontal lift, i.e., a section of the short exact sequence (1.7) covering the identity of $\mathcal{G}$ such that

$$
h\left(e, 1_{x}\right)=\widetilde{1}_{e} .
$$

This horizontal lift always exists [19]. Then we define the quadruple ( $\Delta^{0}, \Delta^{1}, \partial, \Omega$ ) by

$$
\begin{aligned}
\partial c & =\widetilde{t}(c) \\
\Delta_{g}^{0} c & \left.=h_{g} \widetilde{t}(c)\right) \cdot c \cdot \widetilde{0}_{g^{-1}} \\
\Delta_{g}^{1} e & =\widetilde{t}\left(h_{g}(e)\right) \\
\Omega_{g_{1}, g_{2}} e & =\left(h_{g_{1} g_{2}}(e)-h_{g_{1}}\left(\widetilde{t}\left(h_{g_{2}}(e)\right)\right) \cdot h_{g_{2}}(e)\right) \cdot \widetilde{0}_{\left(g_{1} g_{2}\right)^{-1}}
\end{aligned}
$$

Remark 1.31. The isomorphism class of the VB-groupoid associated to a representation up to homotopy is independent of the choice of the horizontal lift (see [19]).

The previous correspondence between 2-terms representations up to homotopy of $\mathcal{G} \rightrightarrows M$ and VB-groupoids over $\mathcal{G}$ together with a horizontal lift is one-to-one, and it is proved in [19]. Moreover they also proved that there is a one-to-one correspondence between isomorphism classes of VB-groupoids over $\mathcal{G}$ and isomorphism classes of 2-terms representation up to homotopy of $\mathcal{G}$.

### 1.4 VB-algebroids and representation up to homotopy

As in the Lie groupoid case, representations up to homotopy of Lie algebroids generalize their representations on vector bundles to representations on graded vector bundles or complexes. The particular case of 2 -terms representations up to homotopy can be geometrically described by VB-algebroids, which are the natural vector-bundle
objects in the context of Lie algebroids. In this section we recall the definitions, some properties and the relation between VB-algebroids and representations up to homotopy. The material of this part can be found in [20].

### 1.4.1 VB-algebroids

Consider a commutative square

where all sides are vector bundles.
Definition 1.32. A commutative square (1.15) is called a double vector bundle if the two linear structures in $\mathcal{A}$ are compatible. Explicitly, if the following conditions hold:

1. $Q\left(\eta_{1}+{ }_{A} \eta_{2}\right)=Q\left(\eta_{1}\right)+Q\left(\eta_{2}\right)$ for $\eta_{1}, \eta_{2} \in \mathcal{A}_{a}$ for some $a \in A$.
2. $\Psi\left(\eta+_{E} \mu\right)=\Psi(\eta)+\Psi(\mu)$ for $\eta, \mu \in \mathcal{A}_{e}$ for some $e \in E$.
3. For $\eta_{1}, \eta_{2}, \mu_{1}, \mu_{2} \in \mathcal{A}$ such that $Q\left(\eta_{i}\right)=Q\left(\mu_{i}\right), i=1,2$ and $\Psi\left(\eta_{1}\right)=\Psi\left(\eta_{2}\right)$ and $\Psi\left(\mu_{1}\right)=\Psi\left(\mu_{2}\right)$ we have

$$
\begin{equation*}
\left(\eta_{1}+_{E} \mu_{1}\right)+_{A}\left(\eta_{2}+_{E} \mu_{2}\right)=\left(\eta_{1}+_{A} \eta_{2}\right)+_{E}\left(\mu_{1}+_{A} \mu_{2}\right) \tag{1.16}
\end{equation*}
$$

This last equation is called the interchange law.
Remark 1.33. A double vector bundle is just a VB-groupoid, where the groupoid structures $\mathcal{A} \rightrightarrows E$ and $A \rightrightarrows M$ are as in Example 1.1 (vector bundles as Lie groupoids).

Remark 1.34. We also write a double vector bundle (1.15) as $(\mathcal{A}, E ; A, M)$, and we say that $\mathcal{A} \longrightarrow E$ is a double vector bundle over $A \longrightarrow M$. An element $\eta \in \mathcal{A}$ will be written as

or $(\eta, e ; a, p)$, where $e=Q(\eta) \in E$ and $a=\Psi(\eta) \in A$.
Remark 1.35. We follow the definition of double vector bundle of [20]. Nevertheless, there is an equivalent definition in [18] in terms of scalar multiplication.

There is a canonical vector bundle over $M$ associated to a double vector bundle: the core bundle $C \longrightarrow M$ is the intersection of the kernels of the projections $Q$ : $\mathcal{A} \longrightarrow E$ and $\Psi: \mathcal{A} \longrightarrow A:$


To every section $c \in \Gamma(C)$ of the core bundle we associate a section $S_{c}: E \longrightarrow \mathcal{A}$ of $E$ over $\mathcal{A}$ defined by:

where $\bar{c}$ is the element $c$ viewed as an element of $\mathcal{A}$. This kind of section is called core section. We denote by $\Gamma_{\text {cor }}(\mathcal{A}, E)$ the space of core sections.

Now we give some initial examples.
Example 1.36. The prolonged tangent bundle. Let $q: A \longrightarrow M$ be a vector bundle then its tangent groupoid (seeing the vector bundle as a Lie groupoid)

is a double vector bundle with core bundle $A$, called the prolonged tangent bundle. Explicitly, the vertical linear structure $T A \longrightarrow T M$ is defined as follows: for a curve $\gamma(t) \subseteq A$, consider the vector $\left.\frac{d}{d t}\right|_{t=0} \gamma(t) \in T_{\gamma(0)} A$, so

$$
T q\left(\left.\frac{d}{d t}\right|_{t=0} \gamma(t)\right)=\left.\frac{d}{d t}\right|_{t=0} q(\gamma(t)) \quad \in T_{q(\gamma(0))} M
$$

then

$$
\left.\frac{d}{d t}\right|_{t=0} \gamma(t)+\left._{T M} \frac{d}{d t}\right|_{t=0} \sigma(t)=\left.\frac{d}{d t}\right|_{t=0}(\gamma(t)+\sigma(t))
$$

for $\gamma(t), \sigma(t) \subseteq A$ with $\gamma(0)=\sigma(0)$.
Example 1.37. Trivial double vector bundle. Let $q_{A}: A \longrightarrow M, q_{C}: C \longrightarrow M$ and $q_{E}: E \longrightarrow M$ be vector bundles over $M$ and consider $\mathcal{A}=A \oplus C \oplus E$. We define a double vector bundle structure on $\mathcal{A}$ over $A$ and over $E$ as follows:

$$
\begin{aligned}
\left(a, c_{1}, e_{1}\right)+_{A}\left(a, c_{2}, e_{2}\right) & =\left(a, c_{1}+c_{2}, e_{1}+e_{2}\right) \\
\left(a_{1}, c_{1}, e\right)+_{E}\left(a_{2}, c_{2}, e\right) & \text { over } A \\
\left(a_{1}+a_{2}, c_{1}+c_{2}, e\right) & \text { over } E,
\end{aligned}
$$

i.e., the linear structure over $A$ is $q_{A}^{*} *(E \oplus C) \longrightarrow A$, and over $E$ is $q_{E}^{*}(A \oplus C) \longrightarrow E$. We call $\mathcal{A}$ the trivial double vector bundle with side bundles $E$ and $A$, and core bundle $C$.

Example 1.38. Dual of a double vector bundle. Let $(\mathcal{A}, E ; M, A)$ be a double vector bundle. Take the dual of $\mathcal{A}$ over $A$, which we denote by $\mathcal{A}^{*}$. We will show that

has a double vector bundle structure with core bundle $E^{*}$. For a complete description and more details see [32]. The horizontal structure $\mathcal{A}^{*} \longrightarrow A$ is the usual one. With respect to the vertical side, the projection $q^{*}: \mathcal{A}^{*} \longrightarrow C^{*}$ is defined by

$$
\left\langle q^{*}(\eta), c\right\rangle=\left\langle\eta, 0_{a}+_{E} \bar{c}\right\rangle
$$

where $c \in C_{p}, \eta \in \mathcal{A}_{a}^{*}$, and $a \in A_{p}$. The addition in $\mathcal{A}^{*} \longrightarrow C^{*}$ is defined by:

$$
\left\langle\eta_{1}+C_{C^{*}} \eta_{2}, d\right\rangle=\left\langle\eta_{1}, d_{1}\right\rangle+\left\langle\eta_{2}, d_{2}\right\rangle
$$

for $\left(\eta_{1}, \xi, a_{1}, p\right),\left(\eta_{2}, \xi, a_{2}, p\right) \in \mathcal{A}_{\xi}^{*}$, and where $d=d_{1}+_{E} d_{2}$.
Example 1.39. Cotangent double vector bundle. Let $A \longrightarrow M$ be a vector bundle. The cotangent double vector bundle associated to $A$ is obtained by dualization of its prolonged tangent bundle ( $T A, T M ; A, M$ ):

with core bundle $T^{*} M \longrightarrow M$.

There is another type of sections on a double vector bundles, called linear.
Definition 1.40. A linear section of $E$ over $\mathcal{A}$ is a section $\chi: E \longrightarrow A$ which is a vector bundle morphism over some section $a: M \longrightarrow A$. The space of linear sections is denoted by $\Gamma_{\text {lin }}(\mathcal{A}, E)$.

The following proposition can be found in [31].
Proposition 1.41. The space of sections of $\mathcal{A}$ over $E$ is a $C^{\infty}(E)$-module generated by $\Gamma_{\text {lin }}(\mathcal{A}, E)$ and $\Gamma_{\text {cor }}(\mathcal{A}, E)$. Moreover if $\left(\mathcal{A}_{i}, E_{i} ; A, M\right)$ are $k$ double vector bundles over $A$ with core bundles $C_{i}$, then the space of sections of $\mathcal{A}=\oplus_{i=1}^{k} \mathcal{A}_{i}$ over $E=$ $\oplus_{i=1}^{k} E_{i}$ is generated by

- $\left(X_{1}, \ldots, X_{k}\right)$, where $X_{i} \in \Gamma_{\text {lin }}\left(\mathcal{A}_{i}, E_{i}\right)$ are linear sections, all of them covering the same section $a \in \Gamma(A)$, and
- $S^{i}\left(\xi_{i}\right)=(0, \ldots, \underbrace{S_{\xi_{i}}}_{i}, \ldots, 0)$ with $\xi_{i} \in \Gamma\left(C_{i}\right)$, for $i=1, \ldots, k$.

The core bundle has an important role in the structure of a double vector bundle: there is a canonical short exact sequence of sections of vector bundles over $M$,

$$
\begin{equation*}
0 \longrightarrow \Gamma(\operatorname{Hom}(E, C)) \longrightarrow \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \longrightarrow \Gamma(A) \longrightarrow 0 \tag{1.20}
\end{equation*}
$$

where for $T \in \Gamma(\operatorname{Hom}(E, C))$ we associate the linear section covering the zero section of $\Gamma(A)$ given by

$$
S_{T}(e)=0_{e}+{ }_{A} \overline{T(e)} .
$$

The space of linear sections of a double vector bundle is isomorphic to the space of sections of some vector bundle $\widehat{A}$ over $M$ (see [20]). Hence this short exact sequence is $C^{\infty}(M)$-linear, which means that (1.20) is an exact sequence is of vector bundles over $M$. There exists always a splitting of this exact sequence to level of vector bundles, and any splitting of this sequence gives a decomposition of the double vector bundle as $\mathcal{A}=A \oplus C \oplus E$ (see [17,20]).

Remark 1.42. In some examples there exists a canonical splitting which is not $C^{\infty}(M)$-linear, like the case when $\mathcal{A}=T A$, the prolonged tangent bundle: the core exact sequence of vector bundles is

$$
0 \longrightarrow T^{*} M \otimes A \longrightarrow J^{1} A \longrightarrow A \longrightarrow 0
$$

and at level of section it is

$$
0 \longrightarrow \Omega^{1}(M) \otimes \Gamma(A) \longrightarrow \Gamma\left(J^{1} A\right) \longrightarrow \Gamma(A) \longrightarrow 0
$$

which has a canonical splitting $j^{1}: \Gamma(A) \longrightarrow \Gamma\left(J^{1} A\right)$ which is not $C^{\infty}(M)$-linear. Here $J^{1} A$ is the first jet bundle associated to $A$.

Definition 1.43. A morphism of double vector bundles between $\left(\mathcal{A}_{i}, E_{i} ; A_{i}, M_{i}\right), i=$ 1,2 is a quadruple $\left(F, F_{v e r} ; F_{h o r}, f\right)$ of maps such that in the following diagram are all vector bundle maps


Definition 1.44. A VB-algebroid is a double vector bundle

where the $\mathcal{A} \longrightarrow E$ is a Lie algebroid, and the following compatibility conditions hold: the anchor map $\rho_{\mathcal{A}}: \mathcal{A} \longrightarrow T E$ is a vector bundle morphism over a map $\rho: A \longrightarrow T M$ and the Lie bracket satisfies

- $\left[\Gamma_{\operatorname{lin}}(\mathcal{A}, E), \Gamma_{\operatorname{lin}}(\mathcal{A}, E)\right] \subseteq \Gamma_{\operatorname{lin}}(\mathcal{A}, E)$
- $\left[\Gamma_{\mathrm{lin}}(\mathcal{A}, E), \Gamma_{\mathrm{cor}}(\mathcal{A}, E)\right] \subseteq \Gamma_{\mathrm{cor}}(\mathcal{A}, E)$
- $\left[\Gamma_{\text {cor }}(\mathcal{A}, E), \Gamma_{\text {cor }}(\mathcal{A}, E)\right]=0$.

Remark 1.45. In [8] it is proved an equivalent definition of VB-algebroids in terms of scalar multiplication.

As a consequence of the definition, follows that the vector bundle $A \longrightarrow M$ inherits a Lie algebroid structure with anchor map $\rho$ and Lie bracket given by

$$
[a, b]:=\Psi\left(\left[\chi_{a}, \chi_{b}\right]\right)
$$

where $\chi_{a}, \chi_{b} \in \Gamma_{\text {lin }}(\mathcal{A}, E)$ are any linear sections covering $a$ and $b$, respectively.
The space of linear sections of a VB-algebroid which is isomorphic to the space of sections of some vector bundle $\widehat{A}$ over $M$, has a Lie algebroid structure over $M$ : its Lie bracket and anchor map are the restriction of the structure of $\mathcal{A}$ to $\Gamma_{\text {lin }}(\mathcal{A}, E)$. This Lie algebroid $\widehat{A} \longrightarrow M$ has canonical representations on $E^{*}$ and $C$ :

- $\left(\nabla^{1}\right)^{*}: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \times \Gamma\left(E^{*}\right) \longrightarrow \Gamma\left(E^{*}\right)$ such that $\left(\nabla^{1}\right)_{X}^{*}$ is the derivation in $E^{*}$ corresponding to the vector field $\rho_{\mathcal{A}}(X)$, that is

$$
\begin{equation*}
\ell_{\left(\nabla^{1}\right)_{X}^{*}(\varphi)}=\rho_{\mathcal{A}}(X)\left(\ell_{\varphi}\right), \quad \varphi \in \Gamma\left(E^{*}\right) \tag{1.21}
\end{equation*}
$$

where $\ell_{\varphi} \in C^{\infty}(E)$ is the linear function defined by $\ell_{\varphi}\left(e_{p}\right)=\left\langle\varphi_{p}, e_{p}\right\rangle$.

- $\nabla^{0}: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \times \Gamma(C) \longrightarrow \Gamma(C)$ characterized by

$$
\begin{equation*}
S_{\nabla_{X} \zeta}=\left[X, S_{\zeta}\right] . \tag{1.22}
\end{equation*}
$$

There is a canonical vector bundle map $\partial: C \longrightarrow E$ defined as follows: since the anchor $\operatorname{map} \rho_{\mathcal{A}}: \mathcal{A} \longrightarrow T E$ is a morphism of double vector bundle from $(\mathcal{A}, E ; A, M)$ to ( $T E, T M ; E, M$ ), it restricts to the core bundles, hence

$$
\begin{equation*}
\partial:=\left.\rho_{\mathcal{A}}\right|_{C}: C \longrightarrow E . \tag{1.23}
\end{equation*}
$$

We call $\partial$ by core anchor map.

Example 1.46. Tangent algebroid. Let $(A \longrightarrow M, \rho,[\cdot, \cdot])$ be a Lie algebroid and consider the prolonged tangent bundle ( $T A, T M ; A, M$ ) (Example 1.36). We will define a Lie algebroid structure over $T A \longrightarrow T M$. For linear sections $T a, T b \in$ $\Gamma_{\mathrm{lin}}(T A, T M)$ and core sections $S_{c}, S_{d} \in \Gamma_{\mathrm{cor}}(T A, T M)$ with $a, b, c, d \in \Gamma(A)$ we define:

- $[T a, T b]=T[a, b]$
- $\left[T a, S_{c}\right]=S_{[a, b]}$
- $\left[S_{c}, S_{d}\right]=0$.

The anchor map $\rho_{T A}: T A \longrightarrow T(T M)$ is

- $\rho_{T A}(T a)$ is the linear vector in $\mathfrak{X}(T M)$ corresponding to the usual derivation $\mathcal{L}_{\rho(a)} \in \operatorname{Der}(\Omega(M))$ of 1-forms.
- $\rho_{T A}\left(S_{c}\right)=\rho(c)^{\uparrow}$ is the vertical vector field corresponding to the section $\rho(c)$, i.e., the vector field given by

$$
\rho(c)^{\uparrow}\left(X_{p}\right):=\left.\frac{d}{d t}\right|_{t=0}\left(X_{p}+t \rho(c)(p)\right)
$$

Example 1.47. Cotangent algebroid. The cotangent algebroid is the vector bundle $T^{*} A \longrightarrow A^{*}$, where the anchor $\rho^{*}: T^{*} A \longrightarrow T A^{*}$ is determined by

- $\rho^{*}\left(R_{a}\right)=H_{a}$ is the Hamiltonian lift of $a \in \Gamma(A)$, i.e.,

$$
H_{a}=\pi_{\operatorname{lin}}^{\sharp}\left(\ell_{a}\right)
$$

where $\pi_{\mathrm{lin}} \in \Gamma\left(\wedge^{2} T A^{*}\right)$ is the linear Poisson structure of $A^{*}$; with $R_{a}: A^{*} \longrightarrow$ $T^{*} A$ is given by

$$
\begin{equation*}
R_{a}(\xi)=\left(\mathrm{d} \ell_{\xi}\right)_{a}+q^{*} \mathrm{~d}\langle\xi, a\rangle, \tag{1.24}
\end{equation*}
$$

where $q: A \longrightarrow M$,

- $\rho^{*}\left(S_{\theta}\right)=\rho_{A}^{*}(\theta)^{\uparrow}$, for $\theta \in \Omega^{1}(M)$.

The Lie bracket is determined by

$$
\left[R_{a}, R_{b}\right]=R_{[a, b]} \quad\left[R_{a}, S_{\theta}\right]=S_{\mathcal{L}_{\rho(a)}(\theta)} \quad\left[S_{\theta_{1}}, S_{\theta_{2}}\right]=0
$$

Example 1.48. VB-algebroid associated to a VB-groupoid. Given a VBgroupoid $\mathcal{E} \rightrightarrows E$ over $\mathcal{G} \rightrightarrows M$, then the Lie algebroid $A_{\mathcal{E}} \longrightarrow E$ of $\mathcal{E} \rightrightarrows E$ is a VBalgebroid over $A \longrightarrow M$. The compatibility conditions follow by the compatibility structures on $\mathcal{E}$. We refer the reader to [8] for more details.

Example 1.49. Sum. Given two VB-algebroids $\mathcal{A}_{i} \longrightarrow E_{i}$ over $A$ with core bundles $C_{i}$. Let $\mathcal{A}=\mathcal{A}_{1} \times{ }_{A} \mathcal{A}_{2}$ and $E=E_{1} \times_{M} E_{2}$. Then $\mathcal{A} \longrightarrow E$ is a VB-algebroid over $A$, with core bundle $C_{1} \times{ }_{M} C_{2}$. The Lie bracket is induced by the Lie bracket in each component:

$$
\left[\left(X_{1}, X_{2}\right),\left(Y_{1}, Y_{2}\right)\right]=\left(\left[X_{1}, Y_{1}\right],\left[X_{2}, Y_{2}\right]\right),
$$

and the anchor map is $\rho=\left(\rho_{1}, \rho_{2}\right)$.

Example 1.50. Dual of a VB-algebroid. Fix a VB-algebroid

with core bundle $C \longrightarrow M$, and dualize it with respect to $A$. We get the double vector bundle

with core bundle $E^{*}$ (see Example 1.38). The VB-algebroid structure is determined by (see [17], APPENDIX A, for more details):

- Using the one-to-one correspondence between

$$
\begin{aligned}
\Gamma_{\operatorname{lin}}\left(\mathcal{A}^{*}, C^{*}\right) & \longleftrightarrow \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \\
X^{\perp} & \longleftrightarrow X,
\end{aligned}
$$

we define

$$
\left[X^{\perp}, Y^{\perp}\right]:=[X, Y]^{\perp}
$$

- If $S_{\eta} \in \Gamma_{\text {cor }}\left(\mathcal{A}^{*}, C^{*}\right)$ for some $\eta \in \Gamma\left(E^{*}\right)$, then $\left[X^{\perp}, S_{\eta}\right]$ is the core section such that

$$
\ell_{\left[X^{\perp}, S_{\eta}\right]}=\rho_{\mathcal{A}}(X)\left(\ell_{\eta}\right) .
$$

### 1.4.2 Representations up to homotopy

One of the problems of representations of Lie algebroids is that there is not a good definition of adjoint representation, in the sense that we expect that it controls the deformation of the structure, as in the Lie algebra case. For this reason, and others, Arias-Abad and Crainic introduced in [2] representations up to homotopy. In this subsection, we first recall the definition of representation of Lie algebroids and we give an equivalent definition which allows a natural extension to the graded case. We follow $[2,20]$.

Let $A \longrightarrow M$ be a Lie algebroid. Recall that a representation of $A$ is a vector bundle $E \longrightarrow M$ together with a flat $A$-connection $\nabla: \Gamma(A) \times \Gamma(E) \longrightarrow \Gamma(E)$.

Given an $A$-connection $\nabla: \Gamma(A) \times \Gamma(E) \longrightarrow \Gamma(E)$, let $\Omega(A, E)=\Gamma\left(\wedge A^{*} \otimes E\right)$ be the space of $E$-valued $A$-differential forms. We have a degree one operator $d_{\nabla}$ acting on this space induced by the Koszul formula: for $\omega \in \Omega^{k}(A, E)=\Gamma\left(\wedge^{p} A^{*} \otimes E\right)$

$$
\begin{aligned}
d_{\nabla} \omega\left(a_{1}, \ldots, a_{k+1}\right)= & \sum_{i<j}(-1)^{i+j} \omega\left(\left[a_{i}, a_{j}\right], \ldots, \widehat{a_{i}}, \ldots, \widehat{a_{j}}, \ldots, a_{k+1}\right. \\
& +\sum_{i}(-1)^{i+1} \nabla_{a_{i}} \omega\left(a_{1}, \ldots, \widehat{a_{i}}, \ldots, a_{k+1}\right)
\end{aligned}
$$

satisfying the following derivation rule:

$$
\begin{equation*}
d_{\nabla}(\alpha \wedge \omega)=d_{A}(\alpha) \wedge \omega+(-1)^{k} \alpha \wedge d_{\nabla}(\omega) \tag{1.25}
\end{equation*}
$$

for $\alpha \in \Omega^{k}(A)$, where $d_{A}: \Omega^{\bullet}(A) \longrightarrow \Omega^{\bullet+1}(A)$ is the Lie algebroid differential, see (1.5). The next result can be found in [2].

Proposition 1.51. Let $A \longrightarrow E$ be a Lie algebroid and let $E \longrightarrow M$ be a vector bundle. There is a natural one-to-one correspondence between flat $A$-connections on $E$ and degree one operators $d$ on $\Omega(A, E)$ satisfying the derivation rule (1.25) and $d^{2}=0$.

Consider now a 2-term graded vector bundle $V=C_{[0]} \oplus E_{[1]}$ over $M$. The space of $V$-valued $A$-differential forms is $\Omega(A ; V)=\Gamma\left(\wedge A^{*} \otimes V\right)$. This space has a grading given by

$$
\Omega(A ; V)_{k}=\Gamma\left(\wedge^{k} A^{*} \otimes C\right) \oplus \Gamma\left(\wedge^{k-1} A^{*} \otimes E\right)
$$

and it is a (naturally graded) module over the algebra $\Gamma(A)=\Gamma\left(\wedge^{\bullet} A^{*}\right)$.
Definition 1.52. A 2-term representation up to homotopy of a Lie algebroid $A$ is a 2-term-graded vector bundle $V=C_{[0]} \oplus E_{[1]}$ over $M$ together with a degree one operator $d: \Omega(A ; V) \bullet \longrightarrow \Omega(A ; V)_{\bullet}+1$ such that $d^{2}=0$ and satisfies the derivation rule

$$
d(\alpha \wedge \omega)=d_{A}(\alpha) \wedge \omega+(-1)^{k} \alpha \wedge d(\omega)
$$

for $\alpha \in \Omega^{k}(A)$, where $d_{A}: \Omega^{\bullet}(A) \longrightarrow \Omega^{\bullet+1}(A)$ is the Lie algebroid differential.
Remark 1.53. A representation up to homotopy can be defined on any graded vector bundle (see e.g. [2,17]). For this thesis, we only are interested in representations up to homotopy in 2-term-graded vector bundles. When we write representation up to homotopy we are talking about of this particular case.

As in the Lie groupoid case, there is an equivalence of this definition in terms of structure operators.

Theorem 1.54 ( $[17,20]$ ). A representation up to homotopy of a Lie algebroid on $C_{[0]} \oplus E_{[1]}$ is equivalent to the following data: A-connections $\nabla^{0}$ and $\nabla^{1}$ on $C$ and $E$, respectively, a vector bundle map $\partial: C \longrightarrow E$ and a section $\Omega \in \Gamma\left(\wedge^{2} A^{*} \otimes\right.$ $\operatorname{Hom}(E, C))$ satisfying the following
(i) $\partial \circ \nabla^{0}=\nabla^{1} \circ \partial$
(ii) $d_{\nabla \operatorname{End} d} \Omega=0$
(iii) The following diagram commutes

where $R_{\nabla^{0}}$ and $R_{\nabla^{1}}$ are the curvatures corresponding to the connections on $C$ and $E$, respectively.

### 1.4.3 Representations up to homotopy vs. VB-algebroids

Here we explain briefly the correspondence between representations up to homotopy and VB-algebroids. This correspondence will allow us to pass from multiplicative tensors with coefficients in a representation up to homotopy to multiplicative functions.

Let $\left(\nabla^{0}, \nabla^{1}, \partial, \Omega\right)$ be a representation up to homotopy of $A$ on the 2-term graded vector bundle $C \oplus E$ over $M$. We will construct the corresponding VB-algebroid associated to this representation. The underlying double vector bundle is the trivial double vector bundle

with core bundle $C$. Let $h: \Gamma(A) \longrightarrow \Gamma_{\operatorname{lin}}(\mathcal{A}, E)$ be the canonical horizontal lift given by

$$
h(a)(e):=(a, 0, e) \quad \text { for } e \in E \text {. }
$$

The anchor map $\rho: \mathcal{A} \longrightarrow T E$ is:

- for a linear section $h(a)$, the linear vector field $\rho(h(a))$ is the one that corresponds to the derivation $\left(\nabla_{a}^{1}\right)^{*}: \Gamma\left(E^{*}\right) \longrightarrow \Gamma\left(E^{*}\right)$, that means

$$
\rho(h(a))\left(\ell_{\eta}\right)=\ell_{\left(\left(\nabla_{a}^{1}\right)^{*} \eta\right)} \quad \text { for } \eta \in \Gamma\left(E^{*}\right),
$$

where $\left(\nabla_{a}^{1}\right)^{*}$ is the dual connection of $\nabla^{1}$.

- For a core section $S_{c}$,

$$
\rho\left(S_{c}\right)=\partial(c)^{\uparrow}
$$

The Lie bracket is characterized by:

- $\left[S_{c_{1}}, S_{c_{2}}\right]=0$
- $\left[h(a), S_{c}\right]=S_{\nabla_{a}^{0} c}$
- $[h(a), h(b)]=h([a, b])+S_{\Omega(a, b)}$.

Conversely, let $(\mathcal{A}, E ; A, M)$ be a VB-algebroid with core bundle $C$ and with a horizontal lift $h: \Gamma(A) \longrightarrow \Gamma_{\text {lin }}(\mathcal{A}, E)$. Let

- $\partial: C \longrightarrow E$
- $\nabla^{0}: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \times \Gamma(C) \longrightarrow \Gamma(C)$
- $\left(\nabla^{1}\right)^{*}: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \times \Gamma\left(E^{*}\right) \longrightarrow \Gamma\left(E^{*}\right)$
the associated canonical operators. We define:
- $\widetilde{\nabla}^{0}: \Gamma(A) \times \Gamma(C) \longrightarrow \Gamma(C) \quad$ by $\quad \widetilde{\nabla}_{a}^{0} c:=\nabla_{h(a)}^{0} c$,
- $\widetilde{\nabla}^{1}: \Gamma(A) \times \Gamma(E) \longrightarrow \Gamma(E) \quad$ by $\quad \widetilde{\nabla}_{a}^{1} e:=\left(\nabla_{h(a)}^{1}\right)^{*} e$,
- $\Omega \in \Gamma\left(\wedge^{2} A^{*} \otimes \operatorname{Hom}(E, C)\right) \quad$ by $\quad \Omega(a, b)=h([a, b])-[h(a), h(b)]$.

Then the quadruple ( $\widetilde{\nabla}^{0}, \widetilde{\nabla}^{1}, \partial, \Omega$ ) defines a representation up to homotopy of $A$ on the 2-term graded vector bundle $C_{[0]} \oplus E_{[1]}$.

This correspondence between VB-algebroids over $A$ together with a horizontal lift, and representations up to homotopy of $A$ is one-to-one, and it is proved in [20].

## Chapter 2

## VB-groupoid cocycles and their infinitesimal data

Let $\mathcal{G} \rightrightarrows M$ be a Lie groupoid and let $\tau$ be a multiplicative structure on $\mathcal{G}$, that is, a geometric structure which is compatible with the multiplication on $\mathcal{G}$. Our approach to study this structure is look at it as a cocycle $F_{\tau}$ on some Lie groupoid $\mathcal{E} \rightrightarrows E$. For the multiplicative structures that we are interested, their associated cocycles $F_{\tau}$ are actually defined in a VB-groupoid $\mathcal{E} \rightrightarrows E$ over $\mathcal{G}$.

In this chapter we fix a Lie groupoid $\mathcal{G} \rightrightarrows M$ and we consider VB-groupoids $\mathcal{E} \rightrightarrows E$ over $\mathcal{G}$ and cocycles $F \in C^{\infty}(\mathcal{E})$ satisfying different linear conditions with respect to the linear structure $\mathcal{E} \longrightarrow \mathcal{G}$. We characterize (multi-)linear cocycles and infinitesimal (multi-)linear cocycles. Moreover we establish a correspondence of these global objects with an infinitesimal data, see Theorems 2.15, 2.30 and 2.35.

### 2.1 Linear cocycles

Let

be a VB-groupoid over $\mathcal{G} \rightrightarrows M$ with core bundle $C$.
Definition 2.1. A function $F: \mathcal{E} \longrightarrow \mathbb{R}$ is called a linear $\mathcal{E}$-cocycle if it is multiplicative with respect to the groupoid structure and linear with respect to the vector bundle structure over $\mathcal{G}$. That means

- $F\left(\eta_{1} \cdot \eta_{2}\right)=F\left(\eta_{1}\right)+F\left(\eta_{2}\right)$ for all $\left(\eta_{1}, \eta_{2}\right) \in \mathcal{E}^{(2)}$, and
- $F(\lambda \eta+\mu)=\lambda F(\eta)+F(\mu)$ for all $\eta, \mu \in \mathcal{E}_{g}=Q^{-1}(g)$ and $\lambda \in \mathbb{R}$.

We say too that $F$ is a linear cocycle on $\mathcal{E}$. And when there is not risk of confusion about the VB-groupoid considered, we just write linear cocycle.

Remark 2.2. Let $\eta_{i} \in \mathcal{E}$ for $i=1,2,3,4$ such that $\left(\eta_{1}, \eta_{3}\right),\left(\eta_{2}, \eta_{4}\right) \in \mathcal{E}^{(2)}$, and $Q\left(\eta_{1}\right)=Q\left(\eta_{2}\right)$ and $Q\left(\eta_{3}\right)=Q\left(\eta_{4}\right)$. Then

$$
\begin{aligned}
F\left(\left(\eta_{1}+\eta_{3}\right) \cdot\left(\eta_{2}+\eta_{4}\right)\right) & =F\left(\eta_{1}+\eta_{3}\right)+F\left(\eta_{2}+\eta_{4}\right) \quad(F \text { multiplicative }) \\
& =F\left(\eta_{1}\right)+F\left(\eta_{3}\right)+F\left(\eta_{2}\right)+F\left(\eta_{4}\right) \quad(F \text { linear }) \\
& =F\left(\eta_{1} \cdot \eta_{2}\right)+F\left(\eta_{3} \cdot \eta_{4}\right) \quad(F \text { multiplicative }) \\
& =F\left(\eta_{1} \cdot \eta_{2}+\eta_{3} \cdot \eta_{4}\right) \quad(F \text { linear }),
\end{aligned}
$$

which means that a linear $\mathcal{E}$-cocycle is compatible with the interchange law.
Example 2.3. Let $f \in C_{\operatorname{lin}}^{\infty}(E)$ be a linear function. The function $F \in C^{\infty}(\mathcal{E})$ defined by

$$
F=\bar{t}^{*} f-\bar{s}^{*} f
$$

is a linear cocycle on $\mathcal{E}$, where $\bar{s}, \bar{t}: \mathcal{E} \longrightarrow E$ are the source and target maps.
Multiplicative functions $F \in C^{\infty}(\mathcal{E})$ satisfy $\mathcal{L}_{\vec{Y}} F=\bar{t}^{*}\langle A F, Y\rangle$ (Eq. (1.3)) for all sections $Y \in \Gamma\left(A_{\mathcal{E}}\right)$, where $A_{\mathcal{E}}=\operatorname{Lie}(\mathcal{E})$ and $A F: A_{\mathcal{E}} \longrightarrow \mathbb{R}$ is the infinitesimal part of $F$. Since $\mathcal{E}$ is a VB-groupoid over $\mathcal{G}$ its Lie algebroid $A_{\mathcal{E}}$ is a VB-algebroid over $A$. Then the space of sections $\Gamma\left(A_{\mathcal{E}}, E\right)$ of $A_{\mathcal{E}}$ over $E$ can be generated by its linear and core sections. Therefore we only have to check Equation (1.3) for these two kinds of sections. Hence we obtain the main result of this subsection, which characterizes linear cocycles on VB-groupoids.

Proposition 2.4. Let $\mathcal{E} \rightrightarrows E$ be a VB-groupoid over a source-connected Lie groupoid $\mathcal{G} \rightrightarrows M$. A function $F \in C^{\infty}(\mathcal{E})$ is a linear $\mathcal{E}$-cocycle if and only if

$$
\left.F\right|_{E}=0
$$

and there exist a $C^{\infty}(M)$-linear map $\mathbf{D}_{F}: \Gamma_{l i n}\left(A_{\mathcal{E}}, E\right) \longrightarrow \Gamma\left(E^{*}\right)$ and a section $\sigma \in \Gamma\left(C^{*}\right)$ such that

$$
\left\{\begin{array}{l}
\mathcal{L}_{\vec{X}} F=\ell_{\mathcal{T}\left(\mathbf{D}_{F}(X)\right)}  \tag{2.1}\\
\mathcal{L}_{\overrightarrow{S_{c}}} F=\langle\sigma, c\rangle \circ \mathbf{t} \circ Q .
\end{array}\right.
$$

For the proof of this proposition we need some results about right invariant vector fields coming from core and linear sections. We start with core sections.

Define the maps:

$$
\mathcal{T}, \mathcal{S}: \Gamma(C) \longrightarrow \Gamma(\mathcal{E})
$$

by

$$
\begin{array}{r}
\mathcal{T}(c)(g):=c(\mathbf{t}(g)) \cdot 0_{g} \\
\mathcal{S}(c)(g):=-0_{g} \cdot c(\mathbf{s}(g)) \tag{2.3}
\end{array}
$$

where $\cdot$ is the multiplication on $\mathcal{E}$.

Remark 2.5. The source and target of the zero section $0_{g} \in \mathcal{E}_{g}$ are, respectively, $0_{\mathbf{s}(g)} \in E_{\mathbf{s}(g)}$ and $0_{\mathbf{t}(g)} \in E_{\mathbf{t}(g)}$, and since $c(\mathbf{t}(g))$ is an element of the core, then $\bar{s}(c(\mathbf{t}(g)))=0_{t(g)} \in E_{\mathbf{t}(g)}$. Therefore we can multiply them. Moreover, $\mathcal{T}(c)(g) \in \mathcal{E}_{g}$ because

$$
Q\left(c(\mathbf{t}(g)) \cdot 0_{g}\right)=Q\left(c(\mathbf{t}(g)) \cdot Q\left(0_{g}\right)=1_{\mathbf{t}(g)} \cdot g=g\right.
$$

where we used that $Q$ is a morphism of Lie groupoids.
Remark 2.6. We will always use the notation $\mathcal{T}, \mathcal{S}$ for these kind of maps from the core bundle to the Lie groupoid, independent of the VB-groupoid that we are considering.

Let $\mathcal{E}^{*}$ be the dual VB-groupoid of $\mathcal{E}$ over $\mathcal{G}$ and let $\mathcal{T}, \mathcal{S}: \Gamma\left(E^{*}\right) \longrightarrow \Gamma\left(\mathcal{E}^{*}\right)$ defined as before.

Proposition 2.7. The pull-back maps $\bar{t}^{*}, \bar{s}^{*}: C^{\infty}(E) \longrightarrow C^{\infty}(\mathcal{E})$ satisfy

$$
\begin{align*}
\bar{t}^{*}\left(\ell_{\varphi}\right) & =\ell_{\mathcal{T}(\varphi)}  \tag{2.4}\\
\bar{s}^{*}\left(\ell_{\varphi}\right) & =\ell_{\mathcal{S}(\varphi)} \tag{2.5}
\end{align*}
$$

for all $\varphi \in \Gamma\left(E^{*}\right)$.
Proof. First we show that $\bar{t}^{*}\left(\ell_{\varphi}\right)$ is a linear function on $\mathcal{E}$. If $\eta, \mu \in \mathcal{E}_{g}$, then

$$
\bar{t}^{*}\left(\ell_{\varphi}\right)(\eta+\mu)=\ell_{\varphi}(\bar{t}(\eta+\mu))=\ell_{\varphi}(\bar{t}(\eta)+\bar{t}(\mu))=\ell_{\varphi}(\bar{t}(\eta))+\ell_{\varphi}(\bar{t}(\mu)),
$$

where we used that $\bar{t}$ is a linear map. For the second part, on one hand we have

$$
\ell_{\varphi}(\bar{t}(\eta))=\langle\varphi(\mathbf{t}(g)), \bar{t}(\eta)\rangle .
$$

On the other hand

$$
\ell_{\mathcal{T}(\varphi)}(\eta)=\langle\mathcal{T}(\varphi), \eta\rangle(g)=\left\langle\varphi(\mathbf{t}(g)) \cdot 0_{g}, \eta_{g}\right\rangle=\langle\varphi(\mathbf{t}(g)), \bar{t}(\eta)\rangle
$$

where the last equation follows by definition of the target map in the dual VBgroupoid. In the same way, we get the condition about the source.

Also, a section $c \in \Gamma(C)$ defines a core section of the algebroid $A_{\mathcal{E}}$ given by

$$
S_{c}(e)=0_{e}+{ }_{A} \overline{c(p)}=\left.\frac{d}{d r}\right|_{r=0}\left(e+r c\left(q_{E}(e)\right)\right)
$$

Proposition 2.8. For any section $c: M \longrightarrow C$ of the core bundle we have that

$$
\begin{equation*}
\overrightarrow{S_{c}}=\mathcal{T}(c)^{\uparrow} \tag{2.6}
\end{equation*}
$$

where the LHS is the right invariant vector field associated to the core section $S_{c}$ and the RHS is the vertical lift of the section $\mathcal{T}(c)$.

Proof. Let $\eta \in \mathcal{E}$ and let $g=Q(\eta) \in \mathcal{G}$ and $e=\bar{t}(\eta) \in E_{t(g)}$. Then

$$
\begin{aligned}
\vec{S}_{c}(\eta)=d R_{\eta}\left(S_{c}(e)\right) & =\left.\frac{d}{d r}\right|_{r=0} R_{\eta}\left(e+r c\left(q_{E}(e)\right)\right) \\
& =\left.\frac{d}{d r}\right|_{r=0}\left(\left(e+r c\left(q_{E}(e)\right)\right) \cdot \eta\right) \\
& =\left.\frac{d}{d r}\right|_{r=0}\left(\left(e+r c\left(q_{E}(e)\right)\right) \cdot\left(\eta+0_{g}\right)\right) \\
\text { interchange law } & =\left.\frac{d}{d r}\right|_{r=0}\left(e \cdot \eta+r c\left(q_{E}(e)\right) \cdot 0_{g}\right) \\
& =\left.\frac{d}{d r}\right|_{r=0}(\eta+r \mathcal{T}(c)(g)) \\
& =(\mathcal{T}(c))^{\uparrow}(\eta) .
\end{aligned}
$$

Now we describe the action of a linear cocycle on right invariant vector field coming from core sections.

Proposition 2.9. For any linear cocycle $F \in C^{\infty}(\mathcal{E})$ we have that

$$
\begin{equation*}
\mathcal{L}_{\overrightarrow{S_{c}}} F=F \circ c \circ \mathbf{t} \circ Q \tag{2.7}
\end{equation*}
$$

for all $c \in \Gamma(C)$. Moreover, there exists a section $\sigma \in \Gamma\left(C^{*}\right)$ such that

$$
\begin{equation*}
\left\langle A F, S_{c}\right\rangle=q_{E}^{*}\langle\sigma, c\rangle \tag{2.8}
\end{equation*}
$$

for all $c \in \Gamma(C)$.
Proof. Let $c \in \Gamma(C)$ and let $S_{c}$ be its corresponding core section of $A_{\mathcal{E}}$. Considering the right invariant vector field $\overrightarrow{S_{c}}$, then for $\eta \in \mathcal{E}_{g}$ we have

$$
\begin{aligned}
\mathcal{L}_{\vec{S}_{c}} F(\eta) & =\left.\frac{d}{d t}\right|_{0} F(\eta+t \mathcal{T}(c)(g)) \\
& =F(\mathcal{T}(c)(g)) \quad \text { by the linearity of } F \\
& =F\left(c(\mathbf{t}(g)) \cdot 0_{g}\right) \\
& =F(c(\mathbf{t}(g))) \quad \text { by multiplicativity and linearity of } F .
\end{aligned}
$$

Then Equation (2.7) follows. Now taking units $e \in E$ we have that

$$
\mathcal{L}_{\overrightarrow{S_{c}}} F(e)=F\left(c\left(q_{E}(e)\right)\right) .
$$

We define $\sigma: M \longrightarrow \Gamma\left(C^{*}\right)$ by $\langle\sigma, c\rangle(p)=F(c(q(e)))$ for any $e \in E_{p}$, and together with the property $\mathcal{L}_{\vec{S}_{c}} F=\bar{t}^{*}\left\langle A F, S_{c}\right\rangle$ since $F$ is multiplicative, we get (2.8).

Now let $X \in \Gamma_{\text {lin }}\left(A_{\mathcal{E}}, E\right)$ be a linear section. Since $A F$ is linear with respect to $A$, it follows that $\langle A F, X\rangle$ is a linear function on $E$. Then there exists a section $\mathbf{D}_{F}(X) \in \Gamma\left(E^{*}\right)$ such that

$$
\langle A F, X\rangle=\ell_{\mathbf{D}_{F}(X)}
$$

Proposition 2.10. For any linear $\mathcal{E}$-cocycle $F \in C^{\infty}(\mathcal{E})$ there exists a $C^{\infty}(M)$ linear map $\mathbf{D}_{F}: \Gamma_{\text {lin }}\left(A_{\mathcal{E}}, E\right) \longrightarrow \Gamma\left(E^{*}\right)$ such that

$$
\begin{equation*}
\mathcal{L}_{\vec{X}} F=\ell_{\mathcal{T}\left(\mathbf{D}_{F}(X)\right)} \tag{2.9}
\end{equation*}
$$

Proof. Since the function $\langle A F, X\rangle$ is linear in $E$, there exists a section $\mathbf{D}_{F}(X) \in$ $\Gamma\left(E^{*}\right)$ such that

$$
\langle A F, X\rangle=\ell_{\mathbf{D}_{F}(X)}
$$

Then the multiplicativity condition together with Proposition 2.7 imply

$$
\mathcal{L}_{\vec{X}} F=\bar{t}^{*}\langle A F, X\rangle=\bar{t}^{*}\left(\ell_{\mathbf{D}_{F}(X)}\right)=\ell_{\mathcal{T}\left(\mathbf{D}_{F}(X)\right)},
$$

Take now $h \in C^{\infty}(M)$. Then

$$
\begin{aligned}
\ell_{\mathcal{T}\left(\mathbf{D}_{F}\left(\left(h \circ q_{E}\right) X\right)\right)} & =\mathcal{L}_{\left(h \circ q_{E}\right) X} F \\
& =\bar{t}^{*}\left(h \circ q_{E}\right) \mathcal{L}_{\vec{X}} F \\
& =\bar{t}^{*}\left(h \circ q_{E}\right) \ell_{\mathcal{T}\left(\mathbf{D}_{F}(X)\right)} \\
& =\ell_{\mathcal{T}\left(h \circ q_{E}\right) \mathcal{T}\left(\mathbf{D}_{F}(X)\right)} \\
& =\ell_{\mathcal{T}\left(\left(h \circ q_{E}\right) \mathbf{D}_{F}(X)\right)}
\end{aligned}
$$

Since $\mathcal{T}$ is injective we have the identity.
We need one more result, which one can find in [10].
Proposition 2.11. Let $\mathcal{E}=\mathcal{E}_{1} \oplus \cdots \oplus \mathcal{E}_{k}$ the Whitney sum (as vector bundles over $\mathcal{G}$ ) of the VB-groupoids $\mathcal{E}_{i} \rightrightarrows E_{i}, i=1, \ldots k$ over $\mathcal{G}$, and consider its Lie algebroid $A_{\mathcal{E}}$, which naturally splits as a Whitney sum $A_{\mathcal{E}_{1}} \oplus \cdots \oplus A_{\mathcal{E}_{k}}$ over $A$. If $F: \mathcal{E} \longrightarrow \mathbb{R}$ is a componentwise linear function, that is, for any $g \in \mathcal{G}, F: \mathcal{E}_{g} \longrightarrow \mathbb{R}$ is a multilinear map, then its infinitesimal counterpart $A F: A_{\mathcal{E}} \longrightarrow \mathbb{R}$ is also componentwise linear function. Reciprocally, if $\mathcal{G}$ is source simply connected, then any Lie algebroid cocycle $\Lambda: A_{\mathcal{E}} \longrightarrow \mathbb{R}$ which is componentwise linear integrates to a unique componentwise linear function $F: \mathcal{E} \longrightarrow \mathbb{R}$ such that $A F=\Lambda$. Moreover in the case $\mathcal{E}_{1}=\cdots=\mathcal{E}_{j}, j \leq k, \Lambda$ is symmetric (resp. skew-symmetric) is the first $j$ components if and only if $F$ is also.

Proof. Proposition 2.4. If $F$ is a linear $\mathcal{E}$-cocycle, by Propositions 2.9 and 2.10 there exists a pair $\left(\mathbf{D}_{F}, \sigma\right)$ satisfying the condition (2.1). Conversely, we want to prove that given a pair $(\mathbf{D}, \sigma)$ satisfying condition (2.1), implies that $F$ is a linear cocycle.

We define a function $\mu: A_{\mathcal{E}} \longrightarrow \mathbb{R}$ which will be the infinitesimal counterpart of $F$. Define

$$
\begin{aligned}
\langle\mu, X\rangle & =\ell_{\mathbf{D}(X)} \\
\left\langle\mu, S_{c}\right\rangle & =\langle\sigma, c\rangle \circ q_{E}
\end{aligned}
$$

for $X \in \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}\right)$ and $c \in \Gamma(C)$. By hypothesis about the pair $(\mathbf{D}, \sigma)$, and by Proposition 2.7, we have that

$$
\begin{align*}
\mathcal{L}_{\vec{X}} F & =\ell_{\mathcal{T}(\mathbf{D}(X))}=\bar{t}^{*}\left(\ell_{\mathbf{D}(X)}\right)=\bar{t}^{*}\langle\mu, X\rangle  \tag{2.10}\\
\mathcal{L}_{\overrightarrow{S_{c}}} F & =\sigma(c) \circ \mathbf{t} \circ Q=\bar{t}^{*}\left(\sigma(c) \circ q_{E}\right)=\bar{t}^{*}\left\langle\mu, S_{c}\right\rangle . \tag{2.11}
\end{align*}
$$

Remember that the space of sections $\Gamma\left(A_{\mathcal{E}}, E\right)$ is generated as $C^{\infty}(E)$-module by its linear and core sections, so by the equations (2.10) and (2.11), we get a well defined map at the level of sections $\mu: \Gamma\left(A_{\mathcal{E}}, E\right) \longrightarrow C^{\infty}(E)$. Moreover, the equations (2.10) and (2.11) imply too that $\mu$ is $C^{\infty}(E)$-linear. Therefore $\mu: A_{\mathcal{E}} \longrightarrow \mathbb{R}$ is well defined map and linear over $E$. It follows too that $\mu$ satisfies

$$
\mathcal{L}_{\vec{Y}} F=\bar{t}^{*}\langle\mu, Y\rangle
$$

for all section $Y \in \Gamma\left(A_{\mathcal{E}}\right)$. Since $\mathcal{E}$ is source connected there exists a multiplicative function $F_{\mu} \in C^{\infty}(\mathcal{E})$ such that $A F_{\mu}=\mu$. Then we have that $\mathcal{L}_{\vec{Y}} F=\mathcal{L}_{\vec{\gamma}} F_{\mu}$ for all $Y \in \Gamma\left(A_{\mathcal{E}}\right)$. Since $\mathcal{E}$ has connected $\bar{s}$-fibers, it follows that $F-F_{\mu}$ is constant along the $\bar{s}$-fibers. Finally $\left.\left(F-F_{\mu}\right)\right|_{E}=0$, which means that $\left(F-F_{\mu}\right)=0$ everywhere. Then $F=F_{\mu}$. Now we have to check the linearity over $A$. Let $\alpha_{i} \in A_{\mathcal{E}}, i=1,2$, projectable over $a \in A$ and over $e_{i} \in E$. Let $X \in \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}, E\right)$ such that $X\left(e_{1}\right)=\alpha_{1}$. Then $\alpha_{2}=X\left(e_{2}\right)+_{E} S_{c}\left(e_{2}\right)$ for some section $c \in \Gamma(C)$. Then

$$
\begin{aligned}
\mu\left(\alpha_{1}+_{A} \alpha_{2}\right) & =\mu\left(X\left(e_{1}\right)+_{A}\left(X\left(e_{2}\right)+{ }_{E} S_{c}\left(e_{2}\right)\right)\right) \\
& =\mu\left(\left(X\left(e_{1}\right)+_{A} X\left(e_{2}\right)\right)+_{E} S_{c}\left(e_{2}\right)\right) \quad \text { by interchange law } \\
& =\mu\left(X\left(e_{1}+e_{2}\right)+_{E} S_{c}\left(e_{2}\right)\right) \quad \text { by linearity of } X \\
& =\mu\left(X\left(e_{1}+e_{2}\right)\right)+\mu\left(S_{c}\left(e_{2}\right)\right) \quad \text { by linearity of } \mu \text { w.r.t } E \\
& =\left\langle\mathbf{D}(X), e_{1}+e_{2}\right\rangle+\mu\left(S_{c}\left(e_{2}\right)\right) \\
& =\left\langle\mathbf{D}(X), e_{1}\right\rangle+\left\langle\mathbf{D}(X), e_{2}\right\rangle+\mu\left(S_{c}\left(e_{2}\right)\right) \\
& =\mu\left(X\left(e_{1}\right)\right)+\mu\left(X\left(e_{2}\right)\right)+\mu\left(S_{c}\left(e_{2}\right)\right) \\
& =\mu\left(\alpha_{1}\right)+\mu\left(X\left(e_{2}\right)+_{E} S_{c}\left(e_{2}\right)\right) \\
& =\mu\left(\alpha_{1}\right)+\mu\left(\alpha_{2}\right) .
\end{aligned}
$$

Hence $\mu=d F$ is linear with respect to $A$. Then by Proposition 2.11 it follows that $F$ is linear over $\mathcal{G}$.

### 2.2 Infinitesimal linear cocycles

In this section we characterize and describe functions defined on a VB-algebroid $\mathcal{A}$ over $A$, which are cocycles with respect to the Lie algebroid structure, and linear with
respect to the vector bundle structure $\mathcal{A} \longrightarrow A$. We will prove that this description is the infinitesimal counterpart of linear cocycles on VB-groupoids.

Let

be a VB-algebroid over $A$ with core bundle $C \longrightarrow M$. Recall the canonical operator associated to a VB-algebroid: the flat connections $\nabla^{0}: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \times \Gamma(C) \longrightarrow \Gamma(C)$ (1.22) and $\left(\nabla^{1}\right)^{*}: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \times \Gamma\left(E^{*}\right) \longrightarrow \Gamma\left(E^{*}\right)(1.21)$, and the core anchor map $\partial: C \longrightarrow E(1.23)$.

Definition 2.12. A function $f \in C^{\infty}(\mathcal{A})$ is a linear $\mathcal{A}$-cocycle if it is a cocycle on $\mathcal{A}$ which is linear with respect to the vector bundle structure $\mathcal{A} \longrightarrow A$.

We describe now these functions in terms of their actions on linear and core sections.

Proposition 2.13. Let $f \in C^{\infty}(\mathcal{A})$ be a linear $\mathcal{A}$-cocycle. Then there exist $a$ $C^{\infty}(M)$-linear map $\mathbf{D}: \Gamma_{l i n}(\mathcal{A}) \longrightarrow \Gamma\left(E^{*}\right)$ and a section $\sigma \in \Gamma\left(C^{*}\right)$ such that

$$
\begin{align*}
\mathbf{D}\left(S_{T}\right) & =\langle\sigma, T\rangle \quad \text { for all } T \in \Gamma(\operatorname{Hom}(E, C))  \tag{2.13}\\
\mathbf{D}([X, Y]) & =\left(\nabla^{1}\right)_{X}^{*} \mathbf{D}(Y)-\left(\nabla^{1}\right)_{Y}^{*} \mathbf{D}(X)  \tag{2.14}\\
\left\langle\mathbf{D}\left(X_{a}\right), \partial(c)\right\rangle & =\mathcal{L}_{\rho_{A}(a)} \sigma(c)-\sigma\left(\nabla_{X}^{0} c\right) . \tag{2.15}
\end{align*}
$$

Conversely, a pair $(\mathbf{D}, \sigma)$ satisfying (2.13), (2.14) and (2.15) defines an linear cocycle on $\mathcal{A}$.

Proof. Let $f: \mathcal{A} \longrightarrow \mathbb{R}$ be a linear cocycle. Consider $f$ as a map at the level of sections $f: \Gamma(\mathcal{A}, E) \longrightarrow C^{\infty}(E)$, i.e., for a section $X \in \Gamma(\mathcal{A}, E)$ we associated the function $f \circ X: E \longrightarrow \mathbb{R}$. Take a core section $S_{c}$ then

$$
\left\langle f, S_{c}\right\rangle(e)=f\left(0_{e}+_{A} \overline{c(p)}\right)=f(\overline{c(p)})
$$

for $e \in E_{p}$, where we used the linearity of $f$ with respect to the vector bundle structure over $A$. This means that the function $\left\langle f, S_{c}\right\rangle \in C^{\infty}(E)$ is basic. So, define $\sigma \in \Gamma\left(C^{*}\right)$ such that $q_{E}^{*}(\langle\sigma, c\rangle)=\left\langle f, S_{c}\right\rangle$. On the other hand, define $\mathbf{D}:=\left.f\right|_{\Gamma_{\operatorname{lin}(\mathcal{A}, E)}}$. Since $f$ is a cocycle then

$$
\langle f,[Y, Z]\rangle=\mathcal{L}_{\rho_{\mathcal{A}}(Y)}\langle f, Z\rangle-\mathcal{L}_{\rho_{\mathcal{A}}(Z)}\langle f, Y\rangle
$$

for all $Y, Z \in \Gamma(\mathcal{A})$. Remember that if $X$ be a linear section then

$$
\ell_{\left(\nabla^{1}\right)_{X}^{*} \eta}=\rho_{\mathcal{A}}(X)\left(\ell_{\eta}\right) .
$$

Hence $\ell_{\left(\nabla^{1}\right)_{X}^{*} \mathbf{D}(Y)}=\rho_{\mathcal{A}}(X)\left(\ell_{\mathbf{D}(Y)}\right)=\mathcal{L}_{\rho_{\mathcal{A}}(X)}\langle f, Y\rangle$. This implies that the condition (2.14) for $\mathbf{D}$ holds. Now suppose that $X$ covers the section $a \in \Gamma(A)$. Recall that the Lie bracket $\left[X, S_{c}\right]=S_{\nabla_{X}^{0} c}$. Then

$$
\left\langle f,\left[X, S_{c}\right]\right\rangle=\sigma\left(\nabla_{X}^{0} c\right) \circ q_{E} .
$$

In the other side

$$
\mathcal{L}_{\rho_{\mathcal{A}}(X)}\left(\sigma(c) \circ q_{E}\right)=\left(\mathcal{L}_{\rho_{A}(a)} \sigma(c)\right) \circ q_{E}
$$

and

$$
\mathcal{L}_{\rho_{\mathcal{A}}\left(S_{c}\right)} l_{\mathbf{D}(X)}=\mathcal{L}_{(\partial(c))^{\uparrow}} \ell_{\mathbf{D}(X)}=\langle\mathbf{D}(X), \partial(c)\rangle \circ q_{E}
$$

So the third equation holds. By definition of $\mathbf{D}$ we have that $\mathbf{D}(h X)=h \mathbf{D}(X)$ for all $h \in C^{\infty}(M)$. Finally, the first equation, the compatibility between $\mathbf{D}$ and $\sigma$ holds:

$$
\mathbf{D}\left(S_{T}\right)=f \circ S_{T}=\langle\sigma, T\rangle
$$

Therefore the pair $(\mathbf{D}, \sigma)$ satisfies Equations (2.13), (2.14) and (2.15). Conversely, given a pair $(\mathbf{D}, \sigma)$ satisfying these conditions, define $\mu: \Gamma(\mathcal{A}) \longrightarrow C^{\infty}(E)$ by:

$$
\begin{align*}
\langle\mu, X\rangle & =\ell_{\mathbf{D}(X)}  \tag{2.16}\\
\left\langle\mu, S_{c}\right\rangle & =\sigma(c) \circ q_{E} . \tag{2.17}
\end{align*}
$$

The compatibility of $\mathbf{D}$ and $\sigma$ implies that $\mu$ is well define on core linear sections. Moreover we have that

$$
\mu\left(q_{E}^{*}(h) X\right)=q_{E}^{*}(h) \mu(X) \quad \text { and } \quad \mu\left(q_{E}^{*}(h) S_{c}\right)=q_{E}^{*}(h) \mu\left(S_{c}\right)
$$

for all $h \in C^{\infty}(M)$. Then we extend $\mu$ to all sections $\Gamma(\mathcal{A}, E)$ by $C^{\infty}(E)$-linearity. Therefore $\mu: \mathcal{A} \longrightarrow \mathbb{R}$ is a well defined linear map with respect to the linear structure $\mathcal{A} \longrightarrow E$. The equations (2.14) and (2.15) satisfied by $\mathbf{D}$ and $\sigma$ imply that $\mu$ is a morphism of Lie algebroid. Now, to check the linearity over $A$, let $\alpha_{i} \in \mathcal{A}, i=1,2$, projectable over $a \in A$ and over $e_{i} \in E$. Let $X \in \Gamma_{\text {lin }}(\mathcal{A}, E)$ such that $X\left(e_{1}\right)=\alpha_{1}$. Then $\alpha_{2}=X\left(e_{2}\right)+_{E} S_{c}\left(e_{2}\right)$ for some section $c \in \Gamma(C)$. Then

$$
\begin{aligned}
\mu\left(\alpha_{1}+{ }_{A} \alpha_{2}\right) & =\mu\left(X\left(e_{1}\right)+_{A}\left(X\left(e_{2}\right)+{ }_{E} S_{c}\left(e_{2}\right)\right)\right) \\
& =\mu\left(\left(X\left(e_{1}\right)+_{A} X\left(e_{2}\right)\right)+_{E} S_{c}\left(e_{2}\right)\right) \quad \text { by interchange law } \\
& =\mu\left(X\left(e_{1}+e_{2}\right)+_{E} S_{c}\left(e_{2}\right)\right) \quad \text { by linearity of } X \\
& =\mu\left(X\left(e_{1}+e_{2}\right)\right)+\mu\left(S_{c}\left(e_{2}\right)\right) \quad \text { by linearity of } \mu \text { w.r.t } E \\
& =\left\langle\mathbf{D}(X), e_{1}+e_{2}\right\rangle+\mu\left(S_{c}\left(e_{2}\right)\right) \\
& =\left\langle\mathbf{D}(X), e_{1}\right\rangle+\left\langle\mathbf{D}(X), e_{2}\right\rangle+\mu\left(S_{c}\left(e_{2}\right)\right) \\
& =\mu\left(X\left(e_{1}\right)\right)+\mu\left(X\left(e_{2}\right)\right)+\mu\left(S_{c}\left(e_{2}\right)\right) \\
& =\mu\left(\alpha_{1}\right)+\mu\left(X\left(e_{2}\right)+_{E} S_{c}\left(e_{2}\right)\right) \\
& =\mu\left(\alpha_{1}\right)+\mu\left(\alpha_{2}\right) .
\end{aligned}
$$

Hence $\mu$ is linear with respect to $A$.

Definition 2.14. Let $\mathcal{A} \longrightarrow E$ be a VB-algebroid over $A$ with core bundle $C$. A pair $(\mathbf{D}, \sigma)$ satisfying (2.13), (2.14) and (2.15) is called the infinitesimal components of a linear cocycle.

Now we are in condition to state the global-infinitesimal correspondence between linear cocycles and infinitesimal linear cocycles.

Theorem 2.15. Let $\mathcal{E} \rightrightarrows E$ be a VB-groupoid over $\mathcal{G}$. Then every linear cocycle $F \in$ $C^{\infty}(\mathcal{E})$ induces a pair $(\mathbf{D}, \sigma)$ satisfying (2.13), (2.14) and (2.15) on $A_{\mathcal{E}}$. Moreover, if $\mathcal{G}$ is source simply connected, there is a one-to-one correspondence between linear cocycles on $\mathcal{E}$ and such pairs given by

$$
\begin{aligned}
\mathcal{L}_{\vec{X}} F & =\ell_{\mathcal{T}(\mathbf{D}(X))} \\
\mathcal{L}_{\vec{S}_{c}} F & =\langle\sigma, c\rangle \circ \mathbf{t} \circ Q .
\end{aligned}
$$

Proof. Let $F \in C^{\infty}(\mathcal{E})$ be linear cocycle. By Proposition 2.4 there exist $C^{\infty}(M)$ linear map $\mathbf{D}_{F}: \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}, E\right) \longrightarrow \Gamma\left(E^{*}\right)$ and a section $\sigma \in \Gamma\left(C^{*}\right)$ such that

$$
\begin{aligned}
\mathcal{L}_{\vec{X}} & =\ell_{\mathcal{T}(\mathbf{D}(X))} \\
\mathcal{L}_{\overrightarrow{S_{c}}} F & =\sigma(c) \circ \boldsymbol{t} \circ Q .
\end{aligned}
$$

Note that for $T \in \Gamma(\operatorname{Hom}(E, C)), \overrightarrow{S_{T}}$ is a core linear vector field, which implies that $\mathbf{D}_{F}\left(S_{T}\right)=\sigma \circ T$. Moreover the operator $\mathbf{D}_{F}$ satisfies

$$
\ell_{\mathbf{D}_{F}(X)}=\langle A F, X\rangle \forall X \in \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}, E\right) \quad \text { i.e. } \quad \mathbf{D}_{F}=\left.A F\right|_{\Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}, E\right)} .
$$

Since $A F$ is an infinitesimal linear cocycle follows that $\mathbf{D}_{F}$ satisfies Equation (2.14). On the other hand we have that $\left\langle A F, S_{c}\right\rangle=\langle\sigma, c\rangle \circ q_{E}$, then by Proposition 2.13 follows that Equation (2.15) holds. Conversely, let $\mu \in C^{\infty}\left(A_{\mathcal{E}}\right)$ be the linear cocycle obtained from the pair $(\mathbf{D}, \sigma)$. Since $\mathcal{G}$ is source simply connected, there exists a (unique) function $F \in C^{\infty}(\mathcal{E})$ integrating $\mu$, which is multiplicative and linear.

Remark 2.16. There is an alternative proof of this theorem. It is using the properties of the Lie derivate $\mathcal{L}_{\vec{X}} F$ with respect to the Lie bracket of vector fields, taking only vector fields coming from linear and core sections.

Proof. Let $F \in C^{\infty}(\mathcal{E})$ be linear cocycle. By Proposition (2.4) there exist $C^{\infty}(M)$ linear map $\mathbf{D}: \Gamma_{l i n}\left(A_{\mathcal{E}}\right) \longrightarrow \Gamma\left(E^{*}\right)$ and a section $\sigma \in \Gamma\left(C^{*}\right)$ such that

$$
\begin{aligned}
\mathcal{L}_{\vec{X}} F & =\ell_{\mathcal{T}(\mathbf{D}(X))} \\
\mathcal{L}_{\vec{S}_{c}} F & =\sigma(c) \circ \boldsymbol{t} \circ Q .
\end{aligned}
$$

Note that for $T \in \Gamma(\operatorname{Hom}(E, C)), \overrightarrow{S_{T}}$ is a core linear vector field, which implies that $\mathbf{D}\left(S_{T}\right)=\sigma \circ T$. Now, if $X, Y \in \Gamma_{\text {lin }}\left(A_{\mathcal{E}}\right)$ their Lie bracket $[X, Y] \in \Gamma_{\text {lin }}\left(A_{\mathcal{E}}\right)$, then

$$
\mathcal{L}_{[\vec{X}, \vec{Y}]} F=\ell_{\mathcal{T}(\mathbf{D}([X, Y]))}=\bar{t}^{*}\left(\ell_{\mathbf{D}([X, Y])}\right) .
$$

On the other side, we have that

$$
\begin{aligned}
\mathcal{L}_{[\vec{X}, \vec{Y}]} F & =\mathcal{L}_{\vec{X}} \mathcal{L}_{\vec{Y}} F-\mathcal{L}_{\vec{Y}} \mathcal{L}_{\vec{X}} F \\
& =\mathcal{L}_{\vec{X}}\left(\ell_{\mathcal{T}(\mathbf{D}(Y))}\right)-\mathcal{L}_{\vec{Y}}\left(\ell_{\mathcal{T}(\mathbf{D}(X))}\right) \\
& \left.\left.=\mathcal{L}_{\vec{X}} \vec{t}^{*}\left(\ell_{\mathbf{D}(Y)}\right)\right)-\mathcal{L}_{\vec{Y}} \vec{t}^{*}\left(\ell_{\mathbf{D}(X)}\right)\right) \\
& =\bar{t}^{*}\left(\mathcal{L}_{\rho(X)} \ell_{\mathbf{D}(Y)}\right)-\bar{t}^{*}\left(\mathcal{L}_{\rho(Y)} \ell_{\mathbf{D}(X)}\right) .
\end{aligned}
$$

Since the pullback map $\vec{t}^{*}: C^{\infty}(E) \longrightarrow C^{\infty}(\mathcal{E})$ is injective, follows

$$
\mathbf{D}([X, Y])=\left(\nabla^{1}\right)_{X}^{*} \mathbf{D}(Y)-\left(\nabla^{1}\right)_{Y}^{*} \mathbf{D}(X)
$$

Let $c \in \Gamma(C)$, then $\left[X, S_{c}\right]=S_{\nabla_{X}^{0} c}$, so

$$
\mathcal{L}_{\left[\vec{X}, \overrightarrow{\left.S_{c}\right]}\right.} F=\mathcal{L}_{\overrightarrow{\bar{S}_{\nabla^{c}}^{c}}} F=\bar{t}^{*}\left(\sigma\left(\nabla_{X}^{0} c\right) \circ q_{E}\right) .
$$

In the other side, we have

$$
\left.\mathcal{L}_{\vec{X}} \mathcal{L}_{\overrightarrow{S_{c}}} F=\mathcal{L}_{\vec{X}} \bar{t}^{*}\left(\sigma(c) \circ q_{E}\right)\right)=\bar{t}^{*}\left(\mathcal{L}_{\rho(X)}\left(\sigma(c) \circ q_{E}\right)\right)=\bar{t}^{*}\left(\left(\mathcal{L}_{\rho_{A}(a)} \sigma(c)\right) \circ q_{E}\right),
$$

and

$$
\mathcal{L}_{\overrightarrow{S_{c}}} \mathcal{L}_{\vec{X}} F=\mathcal{L}_{\overrightarrow{S_{c}}}\left(\bar{t}^{*}\left(\ell_{\mathbf{D}(X)}\right)\right)=\bar{t}^{*}\left(\mathcal{L}_{\rho\left(S_{c}\right)} \ell_{\mathbf{D}(X)}\right)=\bar{t}^{*}\left(\langle\mathbf{D}(X), \partial(c)\rangle \circ q_{E}\right) .
$$

Hence

$$
\left\langle\mathbf{D}\left(X_{a}\right), \partial(c)\right\rangle=\mathcal{L}_{\rho_{A}(a)} \sigma(c)-\sigma\left(\nabla_{X}^{0} c\right)
$$

Therefore the pair $(\mathbf{D}, \sigma)$ is the infinitesimal components of a linear cocycle on $A_{\mathcal{E}}$. Conversely, let $\mu \in C^{\infty}\left(A_{\mathcal{E}}\right)$ be the linear cocycle obtained from the pair $(\mathbf{D}, \sigma)$ Since $\mathcal{G}$ is source simply connected, there exists a (unique) function $F \in C^{\infty}(\mathcal{E})$ integrating $\mu$, which is multiplicative and linear.

Corollary 2.17. Let $\mathcal{G} \rightrightarrows M$ be source simply connected Lie groupoid, and let $E \longrightarrow M$ be a representation. Then linear cocycles on the action VB-groupoid $E * \mathcal{G}$ (1.19) are in one-to-one correspondence with $C^{\infty}(M)$-linear operators $\mathbf{D}$ : $\Gamma_{\text {lin }}\left(A_{\mathcal{E}}\right) \longrightarrow \Gamma\left(E^{*}\right)$ such that

$$
\mathbf{D}([X, Y])=\left(\nabla^{1}\right)_{X}^{*} \mathbf{D}(Y)-\left(\nabla^{1}\right)_{Y}^{*} \mathbf{D}(X)
$$

Corollary 2.18. Let $\mathcal{G} \rightrightarrows M$ be source simply connected Lie groupoid, and let $C \longrightarrow M$ be a representation. Then linear cocycles on the semidirect product $C \rtimes \mathcal{G}$ (1.20) are in one-to-one correspondence with sections $\sigma \in \Gamma\left(C^{*}\right)$ satisfying

$$
\mathcal{L}_{\rho(a)}\langle\sigma, c\rangle=\left\langle\sigma, \nabla_{a} c\right\rangle .
$$

Example 2.19. Let $f \in C_{\text {lin }}^{\infty}(E)$ be a linear function and let $F=\bar{t}^{*} f-\bar{s}^{*} f \in C^{\infty}(\mathcal{E})$ as in Example 2.3. Since $F$ is a linear cocycle, consider its infinitesimal components $(\mathbf{D}, \sigma)$. Let $X \in \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}, E\right)$ be a linear section. Then

$$
\mathcal{L}_{\vec{X}} F=\mathcal{L}_{\vec{X}} \vec{t}^{*} f=\bar{t}^{*}\left(\mathcal{L}_{\rho_{A_{\mathcal{E}}}(X)} f\right),
$$

which implies that $\mathbf{D}(X)=\left(\nabla^{1}\right)_{X}^{*} f$, where here we are seeing $f \in C_{\operatorname{lin}}^{\infty}(E) \simeq \Gamma\left(E^{*}\right)$. Taking now a core section $S_{c}$, then

$$
\mathcal{L}_{\vec{S}_{c}} F=f \circ \bar{t} \circ c \circ t \circ Q
$$

which means

$$
\sigma(c)=f \circ \bar{t} \circ c=f \circ \partial \circ c,
$$

hence $\sigma=\partial^{*}(f)$. Since the connection $\left(\nabla^{1}\right)^{*}: \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}, E\right) \times \Gamma\left(E^{*}\right) \longrightarrow \Gamma\left(E^{*}\right)$ is flat, it follows that $\mathbf{D}$ satisfies Equation (2.14). On the other hand, if $X$ is a linear section covering $a \in \Gamma(A)$ and $c \in \Gamma(C)$, we have

$$
\begin{aligned}
\langle\mathbf{D}(X), \partial(c)\rangle & =\left\langle\left(\nabla^{1}\right)_{X}^{*} f, \partial(c)\right\rangle \\
& =\mathcal{L}_{\rho(a)}\langle f, \partial(c)\rangle-\left\langle f, \nabla_{X}^{1} \partial(c)\right\rangle \\
& =\mathcal{L}_{\rho(a)}\left\langle\partial^{*}(f), c\right\rangle-\left\langle f, \partial \circ \nabla_{X}^{0} c\right\rangle \\
& =\mathcal{L}_{\rho(a)}\left\langle\partial^{*}(f), c\right\rangle-\left\langle\partial^{*} f, \nabla_{X}^{0} c\right\rangle,
\end{aligned}
$$

hence Equation (2.15) holds. Conversely, given a function $f \in C_{\operatorname{lin}}^{\infty}(E)$ define $\mathbf{D}(X)=$ $\left(\nabla^{1}\right)_{X}^{*} f$ and $\sigma=\partial^{*}(f)$. The pair $(\mathbf{D}, \sigma)$ is an infinitesimal component of a linear cocycle on $A$, and by uniqueness, the function $F \in C^{\infty}(\mathcal{E})$ which integrates this infinitesimal data is $F=\bar{t}^{*} f-\bar{s}^{*} f$.

### 2.3 Multilinear cocycles

Many of the multiplicative structures on a Lie groupoid $\mathcal{G}$ which matters for us, when viewed as functions, are defined in a Whitney sum (as vector bundles over $\mathcal{G}$ ) of VB-groupoids $\mathcal{E}_{i} \rightrightarrows E_{i}$ over $\mathcal{G}$. In this section we study functions $F$ defined on a Whitney sum of VB-groupoids which are multiplicative and multilinear, and we describe them infinitesimally. The case of bilinear cocycles is done in details and then we extend to the general case.

### 2.3.1 Bilinear cocycles

Let $\mathcal{E}_{i} \rightrightarrows E_{i}$ be two VB-groupoids over $\mathcal{G} \rightrightarrows M$ with core bundles $C_{i}, i=1,2$. We take the VB-groupoid sum:


Definition 2.20. A bilinear cocycle on $\mathcal{E}$ is a function $F \in C^{\infty}(\mathcal{E})$ such that it is multiplicative with respect to the groupoid structure and it is bilinear with respect to the vector bundle structure.

This means that the maps

are multiplicative and bilinear, respectively.
We know that the space of sections $\Gamma\left(A_{\mathcal{E}}, E\right)$ is generated, as $C^{\infty}(E)$-module, by the following sections (see Proposition 1.41):

- $\left(X_{1}, X_{2}\right)$, where $X_{i} \in \Gamma_{\text {lin }}\left(A_{\mathcal{E}_{i}}, E_{i}\right)$ are linear sections covering the same section $a \in \Gamma(A)$,
- $S_{c_{1}}^{1}=\left(S_{c_{1}}, 0\right)$ and $S_{c_{2}}^{2}=\left(0, S_{c_{2}}\right)$, where $c_{i} \in \Gamma\left(C_{i}\right)$.

Hence, bilinear cocycles can be characterized by their action on right invariant vector fields, coming from these three types of sections.

Theorem 2.21. Let $\mathcal{E}_{i} \rightrightarrows E_{i}, i=1,2$ be two VB-groupoids over a source connected Lie groupoid $\mathcal{G} \rightrightarrows M$ and consider the $V B$-groupoid sum $\mathcal{E}=\mathcal{E}_{1} \oplus \mathcal{E}_{2}$. Then a function $F \in C^{\infty}(\mathcal{E})$ is a bilinear cocycle if and only if

$$
\left.F\right|_{E_{1} \oplus E_{2}}=0
$$

and there exist a $C^{\infty}(M)$-linear map $\mathbf{D}: \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}_{1}}, E_{1}\right) \times_{\Gamma(A)} \Gamma_{l i n}\left(A_{\mathcal{E}_{2}}, E_{2}\right) \longrightarrow \Gamma\left(E_{1}^{*} \otimes\right.$ $\left.E_{2}^{*}\right)$, and vector bundle morphisms $\sigma_{1}: C_{1} \longrightarrow E_{2}^{*}$ and $\sigma_{2}: C_{2} \longrightarrow E_{1}^{*}$ covering the identity of $M$ such that

$$
\left\{\begin{array}{l}
\mathcal{L}_{\left(\overrightarrow{\left.X_{1}, \overrightarrow{X_{2}}\right)}\right.} F=\ell_{\mathcal{T}\left(D\left(X_{1}, X_{2}\right)\right)}  \tag{2.18}\\
\mathcal{L}_{\overrightarrow{S_{c_{1}, 0}}} F=\ell_{\mathcal{T}\left(\sigma_{1}\left(c_{1}\right)\right)} \circ \pi_{2} \\
\mathcal{L}_{\overrightarrow{S_{0, c_{2}}}} F=\ell_{\left.\mathcal{T}\left(\sigma_{2}\left(c_{2}\right)\right)\right)}^{\circ} \circ \pi_{1}
\end{array}\right.
$$

where $\pi_{1}: \mathcal{E}_{1} \oplus \mathcal{E}_{2} \longrightarrow \mathcal{E}_{1}$ and $\pi_{2}: \mathcal{E}_{1} \oplus \mathcal{E}_{2} \longrightarrow \mathcal{E}_{2}$ are the projections over the first and second component, respectively.

Again we first start with core sections. Let $c_{i} \in \Gamma\left(C_{i}\right)$ be sections of the core bundles and let $S_{c_{1}, c_{2}}=\left(S_{c_{1}}, S_{c_{2}}\right)$ be a core section of $A_{\mathcal{E}}$. Then for $\left(\eta_{1}, \eta_{2}\right) \in \mathcal{E}_{g}$

$$
\begin{aligned}
\mathcal{L}_{\stackrel{S_{c_{1}, c_{2}}}{ }} F\left(\eta_{1}, \eta_{2}\right) & =\left.\frac{d}{d t}\right|_{0} F\left(\eta_{1}+t \mathcal{T}\left(c_{1}\right)(g), \eta_{2}+t \mathcal{T}\left(c_{2}\right)(g)\right) \\
& =F\left(\eta_{1}, \mathcal{T}\left(c_{2}\right)(g)\right)+F\left(\mathcal{T}\left(c_{1}\right)(g), \eta_{2}\right) \quad \text { by bilinearity of } F .
\end{aligned}
$$

Hence,

$$
\begin{aligned}
& \mathcal{L}_{\overrightarrow{S_{1}, 0}} F\left(\eta_{1}, \eta_{2}\right) \\
&=F\left(\mathcal{T}\left(c_{1}\right)(g), \eta_{2}\right) \\
& \mathcal{L}_{\overrightarrow{S_{0, c_{2}}}} F\left(\eta_{1}, \eta_{2}\right)
\end{aligned}=F\left(\eta_{1}, \mathcal{T}\left(c_{2}\right)(g)\right) .
$$

By the multiplicativity of $F$, taking units we have

$$
\begin{aligned}
& \left\langle A F, S_{c_{1}, 0}\right\rangle\left(e_{1}, e_{2}\right)=F\left(c_{1}(p), e_{2}\right) \\
& \left\langle A F, S_{0, c_{2}}\right\rangle\left(e_{1}, e_{2}\right)=F\left(e_{1}, c_{2}(p)\right)
\end{aligned}
$$

Proposition 2.22. Let $F \in C^{\infty}(\mathcal{E})$ be a bilinear cocycle. Then there exist vector bundle maps $\sigma_{i}: C_{i} \longrightarrow E_{j}^{*}$, with $i, j=1,2, i \neq j$, over the identity of $M$ such that

$$
\begin{align*}
\ell_{\sigma_{1}\left(c_{1}\right)} \circ \gamma^{1} & =\left\langle A F, S_{c_{1}}^{1}\right\rangle  \tag{2.19}\\
\ell_{\sigma_{2}\left(c_{2}\right)} \circ \gamma^{2} & =\left\langle A F, S_{c_{2}}^{2}\right\rangle \tag{2.20}
\end{align*}
$$

where $\gamma^{1}: E_{1} \oplus E_{2} \longrightarrow E_{2}$ and $\gamma^{2}: E_{1} \oplus E_{2} \longrightarrow E_{1}$ are the forgetful projections:

$$
\gamma^{1}\left(e_{1}, e_{2}\right)=e_{2} \quad \text { and } \quad \gamma^{2}\left(e_{1}, e_{2}\right)=e_{1} .
$$

Proof. Take $c_{1} \in \Gamma\left(C_{1}\right)$. Since $F$ is bilinear the map $\left\langle A F, S_{c_{1}}\right\rangle\left(e_{1}, e_{2}\right)=F\left(c_{1}(p), e_{2}\right)$ is a linear function on $E_{2}$. Then there exists a map $\sigma_{1}: \Gamma\left(C_{1}\right) \longrightarrow \Gamma\left(E_{2}^{*}\right)$ such that $\left\langle A F, S_{c_{1}}^{1}\right\rangle=\ell_{\sigma_{1}\left(c_{1}\right)} \circ \gamma^{2}$. In the same way, there exists a map $\sigma_{2}: \Gamma\left(C_{2}\right) \longrightarrow \Gamma\left(E_{1}^{*}\right)$ such that $\left\langle A F, S_{c_{2}}^{2}\right\rangle=\ell_{\sigma_{2}\left(c_{2}\right)} \circ \gamma^{1}$.

Now we work with linear sections. Let $X=\left(X_{1}, X_{2}\right)$ be a linear section of $A_{\mathcal{E}}$ with $X_{i} \in \Gamma_{\text {lin }}\left(A_{\mathcal{E}_{i}}, E_{i}\right)$ covering the same section $a \in \Gamma(A)$. Let $\vec{X}=\left(\overrightarrow{X_{1}}, \overrightarrow{X_{2}}\right)$ be the corresponding right invariant vector field, and denote by $\phi_{t}^{i}$ their flows. Note that the flows $\phi_{t}^{i}: \mathcal{E}_{i} \longrightarrow \mathcal{E}_{i}$ are linear over $\mathcal{G}$ because the vector fields $\vec{X}_{i}$ are linear. Then

$$
\begin{aligned}
\mathcal{L}_{\left(\overrightarrow{X_{1}}, \overrightarrow{X_{2}}\right)} F\left(\eta_{1}+\mu_{1}, \eta_{2}\right) & =\left.\frac{d}{d t}\right|_{t=0} F\left(\phi_{t}^{1}\left(\eta_{1}+\mu_{1}\right), \phi_{t}^{2}\left(\eta_{2}\right)\right) \\
& =\left.\frac{d}{d t}\right|_{t=0} F\left(\phi_{t}^{1}\left(\eta_{1}\right)+\phi_{t}^{1}\left(\mu_{1}\right), \phi_{t}^{2}\left(\eta_{2}\right)\right) \\
& =\left.\frac{d}{d t}\right|_{t=0}\left(F\left(\phi_{t}^{1}\left(\eta_{1}\right), \phi_{t}^{2}\left(\eta_{2}\right)\right)+F\left(\phi_{t}^{1}\left(\mu_{1}\right), \phi_{t}^{2}\left(\eta_{2}\right)\right)\right) \\
& =\mathcal{L}_{\left(\overrightarrow{X_{1}}, \overrightarrow{X_{2}}\right)} F\left(\eta_{1}, \eta_{2}\right)+\mathcal{L}_{\left(\overrightarrow{X_{1}}, \overrightarrow{X_{2}}\right)} F\left(\mu_{1}, \eta_{2}\right) .
\end{aligned}
$$

Also we have

$$
\mathcal{L}_{\left(\overrightarrow{X_{1}}, \overrightarrow{X_{2}}\right)} F\left(\eta_{1}, \eta_{2}+\mu_{2}\right)=\mathcal{L}_{\left(\overrightarrow{X_{1}}, \overrightarrow{X_{2}}\right)} F\left(\eta_{1}, \eta_{2}\right)+\mathcal{L}_{\left(\overrightarrow{X_{1}}, \overrightarrow{X_{2}}\right)} F\left(\eta_{1}, \mu_{2}\right) .
$$

Hence $\mathcal{L}_{\left(\overrightarrow{X_{1}}, \overrightarrow{X_{2}}\right)} F \in C_{b i l}^{\infty}\left(\mathcal{E}_{1} \oplus \mathcal{E}_{2}\right) \simeq \Gamma\left(\mathcal{E}_{1}^{*} \otimes \mathcal{E}_{2}^{*}\right)$. Since $F$ is multiplicative, taking units we obtain $\left\langle A F,\left(X_{1}, X_{2}\right)\right\rangle \in C_{b i l}^{\infty}\left(E_{1} \oplus E_{2}\right)$.

Proof. Theorem 2.21. Since $F$ is bilinear and multiplicative $\left\langle A F,\left(X_{1}, X_{2}\right)\right\rangle \in C_{\text {bil }}^{\infty}\left(E_{1} \oplus\right.$ $E_{2}$ ). Define

$$
\mathbf{D}: \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}_{1}}\right) \times_{\Gamma(A)} \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}_{2}}\right) \longrightarrow \Gamma\left(E_{1}^{*} \otimes E_{2}^{*}\right)
$$

by

$$
\ell_{\mathbf{D}\left(X_{1}, X_{2}\right)}=\left\langle A F,\left(X_{1}, X_{2}\right)\right\rangle .
$$

Then

$$
\mathcal{L}_{\left(\overrightarrow{X_{1}}, \overrightarrow{X_{2}}\right)} F=\widehat{t}^{*}\left\langle A F,\left(X_{1}, X_{2}\right)\right\rangle=\widehat{t}^{*}\left(\ell_{\mathbf{D}\left(X_{1}, X_{2}\right)}\right)=\ell_{\mathcal{T}\left(\mathbf{D}\left(X_{1}, X_{2}\right)\right)},
$$

where $\widehat{t}: \mathcal{E} \longrightarrow E$ is the target map. Let $h \in C^{\infty}(M)$ and let $X_{i} \in \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}_{i}}\right)$. Then $q_{i}^{*}(h) X_{i} \in \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}_{i}}\right)$. Then

$$
\begin{aligned}
\left\langle\mathbf{D}\left(q_{1}^{*}(h) X_{1}, q_{2}^{*}(h) X_{2}\right),\left(e_{1}, e_{2}\right)\right\rangle & =A F\left(h(p) X_{1}\left(e_{1}\right), h(p) X_{2}\left(e_{2}\right)\right) \\
& =h(p) A F\left(X_{1}\left(e_{1}\right), X_{2}\left(e_{2}\right)\right)
\end{aligned}
$$

which implies that $\mathbf{D}$ is a $C^{\infty}(M)$-linear. The other two equations follow by Proposition (2.22). Conversely, define an operator $\mu$ as follow:

$$
\begin{align*}
\left\langle\mu,\left(X_{1}, X_{2}\right)\right\rangle & =\ell_{\mathbf{D}\left(X_{1}, X_{2}\right)}  \tag{2.21}\\
\left\langle\mu, S_{c_{i}}\right\rangle & =\ell_{\sigma\left(c_{i}\right)} \circ \gamma^{j} \tag{2.22}
\end{align*}
$$

for $X_{i} \in \Gamma_{\text {lin }}\left(A_{\mathcal{E}_{i}}, E_{i}\right)$ and $c_{i} \in \Gamma\left(C_{i}\right), i, j=1,2, i \neq j$. If $T_{i} \in \Gamma\left(\operatorname{Hom}\left(E_{i}, C_{i}\right)\right)$ and we consider its associated core linear right invariant vector field ( $S_{T_{1}}, S_{T_{2}}$ ), then by conditions (2.18) $\mu$ is well defined on all linear section. The equations (2.18) together with the $C^{\infty}(M)$-linearity of $\mathbf{D}$ allow to extend $\mu$ by $C^{\infty}(E)$-linearity to all sections in $\Gamma\left(A_{\mathcal{E}}, E\right)$. Then the map $\mu: A_{\mathcal{E}} \longrightarrow \mathbb{R}$ is well defined and linear. Since the space of sections $\Gamma\left(A_{\mathcal{E}}, E\right)$ is generated as $C^{\infty}(E)$-module by the linear and core sections, the equations (2.18) also imply that $\mathcal{L}_{\vec{Y}} F=\bar{t}^{*}\langle\mu, Y\rangle$ for every section $Y$. Then $\mu$ is a Lie algebroid function which we can integrate to a multiplicative function $F_{\mu} \in C^{\infty}(\mathcal{E})$. By a similar argument on Theorem 2.4 we get $F=F_{\mu}$. Finally we prove that $\mu$ is bilinear with respect to $A$. Let $\alpha_{1}, \beta_{1} \in A_{\mathcal{E}_{1}}$ be projectable over $e_{1}, d_{1} \in E_{1}$, respectively, and over $a \in A$, and let $\alpha_{2} \in A_{\mathcal{E}_{2}}$ be projectable over $e_{2} \in E_{2}$ and over $a \in A$. Take $\left(X_{1}, X_{2}\right) \in \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}, E\right)$ such that

$$
\begin{aligned}
\alpha_{1} & =X_{1}\left(e_{1}\right) \\
\beta_{1} & =X_{1}\left(d_{1}\right)+E_{1} \bar{c}_{1} \\
\alpha_{2} & =X_{2}\left(e_{2}\right) .
\end{aligned}
$$

Then

$$
\begin{aligned}
\mu\left(\alpha_{1}+{ }_{A} \beta_{1}, \alpha_{2}\right) & =\mu\left(X_{1}\left(e_{1}\right)+{ }_{A}\left(X_{1}\left(d_{1}\right)+_{E_{1}} S_{\xi}\left(d_{1}\right)\right), X_{2}\left(e_{2}\right)\right) \\
& =\mu\left(\left(X_{1}\left(e_{1}\right)+{ }_{A} X_{1}\left(d_{1}\right)\right)++_{E} S_{\xi}\left(d_{1}\right), X_{2}\left(e_{2}\right)\right) \quad \text { by interchange law } \\
& =\mu\left(X_{1}\left(e_{1}+d_{1}\right)+E_{1} S_{\xi}\left(d_{1}\right), X_{2}\left(e_{2}\right)\right) \quad \text { by linearity of } X_{1} \\
& =\mu\left(\left(X_{1}\left(e_{1}+d_{1}\right), X_{2}\left(e_{2}\right)\right)+_{E}\left(S_{\xi}\left(d_{1}\right), 0\right)\right) \\
& =\mu\left(X_{1}\left(e_{1}+d_{1}\right), X_{2}\left(e_{2}\right)\right)+\mu\left(S_{\xi}\left(d_{1}\right), 0\right) \quad \text { by linearity of } \mu \text { r.t } E \\
& =\left\langle\mathbf{D}\left(X_{1}, X_{2}\right),\left(e_{1}+d_{1}, e_{2}\right)\right\rangle+\mu\left(S_{\xi}\left(d_{1}\right), 0\right) \\
& =\left\langle\mathbf{D}\left(X_{1}, X_{2}\right),\left(e_{1}, e_{2}\right)\right\rangle+\left\langle\mathbf{D}\left(X_{1}, X_{2}\right),\left(d_{1}, e_{2}\right)\right\rangle+\mu\left(S_{\xi}\left(d_{1}\right), 0\right) \\
& =\mu\left(X_{1}\left(e_{1}\right), X_{2}\left(e_{2}\right)\right)+\mu\left(X_{1}\left(d_{1}\right), X_{2}\left(e_{2}\right)\right)+\mu\left(S_{\xi}\left(d_{1}\right), 0\right) \\
& \left.=\mu\left(\alpha_{1}\right)+\mu\left(X_{1}\left(d_{1}\right)+_{E_{1}} S_{\xi}\left(d_{1}\right), X_{2}\left(e_{2}\right)\right)+_{E_{2}} 0\right) \\
& =\mu\left(\alpha_{1}, \alpha_{2}\right)+\mu\left(\beta_{1}, \alpha_{2}\right) .
\end{aligned}
$$

Hence $\mu$ is bilinear over $A$, and by Proposition 2.11 it follows that $F$ is bilinear over $\mathcal{G}$.

If we consider, for example a symplectic form $\omega \in \Omega^{2}(\mathcal{G})$ or a Poisson structure $\pi \in \Gamma\left(\wedge^{2} T^{*} \mathcal{G}\right)$ on a Lie groupoid $\mathcal{G}$, when we look at them as functions $F_{\omega}: T \mathcal{G} \oplus$ $T \mathcal{G} \longrightarrow \mathbb{R}$ and $F_{\pi}: T^{*} \mathcal{G} \oplus T^{*} \mathcal{G} \longrightarrow \mathbb{R}$, respectively, they are skew-symmetric. The next proposition consider bilinear cocycles which are symmetric or skew-symmetric.

Proposition 2.23. Let $\mathcal{E} \rightrightarrows E$ be a VB-groupoid over a source 1-connected Lie groupoid $\mathcal{G} \rightrightarrows M$. Let $\mathcal{E}^{2}$ be the VB-groupoid sum of two copies of $\mathcal{E}$. Then a symmetric (resp. skew-symmetric) function $F \in C^{\infty}\left(\mathcal{E}^{2}\right)$ is a bilinear groupoid function if and only if

$$
\left.F\right|_{E \oplus E}=0
$$

and there exists a $C^{\infty}(M)$-linear map $\mathbf{D}: \Gamma_{\text {lin }}\left(A_{\mathcal{E}}, E\right) \longrightarrow \Gamma\left(E^{*} \otimes E^{*}\right)$ and a vector bundle morphism $\sigma: C \longrightarrow E^{*}$ such that

- $\ell_{\mathbf{D}(X)} \in C^{\infty}(E \oplus E)$ is symmetric (resp. skew-symmetric)
and such that

$$
\left\{\begin{array}{l}
\mathcal{L}_{(\vec{X}, \vec{X})} F=\ell_{\mathcal{T}(\mathbf{D}(X))}  \tag{2.23}\\
\iota_{\mathcal{T}(c)} F=\mathcal{T}(\sigma(c)) \quad\left(\text { resp. } \quad \iota_{\mathcal{T}(c)} F=-\mathcal{T}(\sigma(c))\right)
\end{array}\right.
$$

Proof. Since $F$ is a bilinear multiplicative function follows by Theorem 2.21 that there exist a triple ( $\widetilde{\mathbf{D}}, \sigma_{1}, \sigma_{2}$ ) where

- $\widetilde{\mathbf{D}}: \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}, E\right) \times_{\Gamma(A)} \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}, E\right) \longrightarrow \Gamma\left(E^{*} \otimes E^{*}\right)$
- $\sigma_{1}, \sigma_{2}: C \longrightarrow E^{*}$.

Since it suffices to take linear sections of the form $(X, X)$ with $X \in \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}}, E\right)$, the operator $\mathbf{D}$ is defined by

$$
\mathbf{D}(X)=\widetilde{\mathbf{D}}(X, X)
$$

The linear maps $\sigma_{i}$ are determined by

$$
\mathcal{L}_{\overrightarrow{S_{c, 0}}} F=\ell_{\mathcal{T}\left(\sigma_{1}(c)\right)} \circ \pi_{2} \quad \text { and } \quad \mathcal{L}_{\overrightarrow{S_{0, c}}} F=\ell_{\mathcal{T}\left(\sigma_{2}(c)\right)} \circ \pi_{1}
$$

If $F$ is symmetric then

$$
\begin{aligned}
\ell_{\mathcal{T}\left(\sigma_{1}(c)\right)} \circ \pi_{2}\left(\eta_{1}, \eta_{2}\right) & =\mathcal{L}_{\overrightarrow{S_{c, 0}}} F\left(\eta_{1}, \eta_{2}\right)=F\left(\mathcal{T}(c)(g), \eta_{2}\right) \\
& =F\left(\eta_{2}, \mathcal{T}(c)(g)\right)=\mathcal{L}_{\overrightarrow{S_{0, c}}} F\left(\eta_{2}, \eta_{1}\right) \\
& =\ell_{\mathcal{T}\left(\sigma_{2}(c)\right)} \circ \pi_{1}\left(\eta_{2}, \eta_{1}\right)
\end{aligned}
$$

and since $\mathcal{T}$ is injective follow that $\sigma_{1}=\sigma_{2}=: \sigma$. Moreover the equation

$$
\iota_{\mathcal{T}(c)} F=\mathcal{T}(\sigma(c))
$$

holds. Conversely, defining a map $\mu: \Gamma\left(A_{\mathcal{E}^{2}}\right) \longrightarrow C^{\infty}\left(E^{2}\right)$ by

$$
\begin{aligned}
\langle\mu,(X, X)\rangle & =\ell_{\mathbf{D}(X)} \\
\left\langle\mu, S_{c, 0}\right\rangle & =\ell_{\sigma(c)} \circ \gamma^{2} \\
\left\langle\mu, S_{0, c}\right\rangle & =\ell_{\sigma(c)} \circ \gamma^{1}
\end{aligned}
$$

it follows by similar arguments as in Theorem 2.21 that $\mu$ is a well defined infinitesimal cocycle which integrates to $F$. By the properties of $\mathbf{D}$ and $\sigma$ it follows that $\mu$ is symmetric. Hence by Proposition 2.11 we get that $F$ symmetric. The skewsymmetric case is analogous.

### 2.3.2 Multilinear cocycles

We now extend the previous discussion to the case of a Whitney sum of $k$ VBgroupoids over $\mathcal{G}$.

Let

be $k$ VB-groupoids over $\mathcal{G} \rightrightarrows M$ with core bundles $C_{i}$. Let $\mathcal{E}:=\mathcal{E}_{1} \oplus \cdots \oplus \mathcal{E}_{k}$ be the Whitney sum of vector bundles over $\mathcal{G}$, which is a Lie groupoid over the Whitney $\operatorname{sum} E:=E_{1} \oplus \cdots \oplus E_{k}$.

Definition 2.24. A function $F \in C^{\infty}(\mathcal{E})$ is called a $k$-linear cocycle if it is a multiplicative function with respect to the groupoid structure, and if it is a $k$-linear map with respect to the vector bundle structure $\mathcal{E} \longrightarrow \mathcal{G}$.

This means that

- $F\left(\left(\eta_{1}, \ldots, \eta_{k}\right) \cdot\left(\mu_{1}, \ldots, \mu_{k}\right)\right)=F\left(\eta_{1}, \ldots, \eta_{k}\right)+F\left(\mu_{1}, \ldots, \mu_{k}\right)$ for all composable elements, and
- $F\left(\eta_{1}, \ldots, \eta_{i}+\mu_{i}, \ldots, \eta_{k}\right)=F\left(\eta_{1}, \ldots, \eta_{i}, \ldots, \eta_{k}\right)+F\left(\eta_{1}, \ldots, \mu_{i}, \ldots, \eta_{k}\right)$, for $\eta_{j} \in$ $\left(\mathcal{E}_{j}\right)_{g}, \mu_{i} \in\left(\mathcal{E}_{i}\right)_{g}$, for all $i$.

Remark 2.25. Notation. To simplify we adopt the following notation: if $c_{i} \in \Gamma\left(C_{i}\right)$ then $\mathcal{T}\left(c_{i}\right) \in \Gamma\left(\mathcal{E}_{i}\right)$, hence

$$
\iota_{\mathcal{T}\left(c_{i}\right)} F:=F(\cdot, \ldots, \overbrace{\mathcal{T}\left(c_{i}\right)}^{i}, \ldots, \cdot) \quad \in \Gamma\left(\mathcal{E}_{1}^{*} \otimes \cdots \otimes \widehat{\mathcal{E}_{i}^{*}} \otimes \cdots \otimes \mathcal{E}_{k}^{*}\right)
$$

Proposition 2.26. If $\mathcal{G}$ is a source connected Lie groupoid, then a function $F \in$ $C^{\infty}(\mathcal{E})$ is a $k$-linear cocycle if and only if

$$
\left.F\right|_{E}=0
$$

and there exist a $C^{\infty}(M)$-linear map

$$
\mathbf{D}: \Gamma_{l i n}\left(A_{\mathcal{E}_{1}}, E_{1}\right) \times_{\Gamma(A)} \cdots \times_{\Gamma(A)} \Gamma_{l i n}\left(A_{\mathcal{E}_{k}}, E_{k}\right) \longrightarrow \Gamma\left(E_{1}^{*} \otimes \cdots \otimes E_{k}^{*}\right)
$$

and vector bundle maps $\sigma_{i}: C_{i} \longrightarrow E_{1}^{*} \otimes \cdots \otimes \widehat{E_{i}^{*}} \otimes \cdots \otimes E_{k}^{*}$ over the identity of $M$, for $i=1, \ldots, k$, such that

$$
\left\{\begin{array}{l}
\mathcal{L}_{\vec{X}} F=\ell_{\mathcal{T}(D(X))}  \tag{2.24}\\
\iota_{\mathcal{T}\left(c_{i}\right)} F=\mathcal{T}\left(\sigma_{i}\left(c_{i}\right)\right) \quad i=1, \ldots, k
\end{array}\right.
$$

Proof. Since $F$ is $k$-linear by an analogous argument of the bilinear case it follows that

$$
\mathcal{L}_{\left(\overrightarrow{X_{1}}, \ldots, \overrightarrow{X_{k}}\right)} F \in C_{k-\text { linear }}^{\infty}(\mathcal{E}) \simeq \Gamma\left(\mathcal{E}_{1}^{*} \otimes \cdots \otimes \mathcal{E}_{k}^{*}\right),
$$

with $X_{i} \in \Gamma_{\text {lin }}\left(A_{\mathcal{E}_{i}}, E_{i}\right)$ a linear section, and since $F$ is multiplicative, taking units we have then that $\left\langle A F,\left(X_{1}, \ldots X_{k}\right)\right\rangle \in C_{k-\text { linear }}^{\infty}(E) \simeq \Gamma\left(E_{1}^{*} \otimes \cdots \otimes E_{k}^{*}\right)$. Hence we define the operator $\mathbf{D}\left(X_{1}, \ldots X_{1}\right)$ as the unique section in $\Gamma\left(E_{1}^{*} \otimes \cdots \otimes E_{k}^{*}\right)$ such that

$$
\begin{equation*}
\ell_{\mathbf{D}\left(X_{1}, \ldots X_{1}\right)}=\left\langle A F,\left(X_{1}, \ldots X_{k}\right)\right\rangle . \tag{2.25}
\end{equation*}
$$

For core sections, if $c_{i} \in \Gamma\left(C_{i}\right)$ then

$$
\mathcal{L}_{\left(0, \ldots, \overrightarrow{S_{c_{i}}}, \ldots, 0\right)} F\left(\eta_{1}, \ldots, \eta_{k}\right)=F\left(\eta_{1}, \ldots, \overrightarrow{c_{i}(\mathbf{t}(g))}, \ldots, \eta_{k}\right)=\iota_{\mathcal{T}\left(c_{i}\right)} F \circ \pi_{i}\left(\eta_{1}, \ldots, \eta_{k}\right)
$$

by multilineartiy of $F$, and by multiplicative condition, taking units we have

$$
\left\langle A F,\left(0, \ldots, S_{c_{i}}, \ldots, 0\right)\right\rangle=: \ell_{\sigma_{i}\left(c_{i}\right)} \circ \gamma^{i}
$$

where $\gamma^{i}: \oplus E_{j} \longrightarrow \oplus_{j \neq i} E_{j}$ are the forgetful projections

$$
\begin{equation*}
\gamma^{i}\left(e_{1}, \ldots, e_{k}\right)=\left(e_{1}, \ldots, \widehat{e_{i}}, \ldots, e_{k}\right) \tag{2.26}
\end{equation*}
$$

i.e., $\gamma^{i}$ forgets its $i$-entry, and $\sigma_{i}: C_{i} \longrightarrow E_{1}^{*} \otimes \cdots \otimes \widehat{E_{i}^{*}} \otimes \cdots \otimes E_{k}^{*}$ are vector bundle maps. Conversely define a map

$$
\begin{align*}
\left\langle\mu,\left(X_{1}, \ldots, X_{k}\right)\right\rangle & =\ell_{\mathbf{D}\left(X_{1}, \ldots, X_{k}\right)}  \tag{2.27}\\
\left\langle\mu, S_{c_{i}}\right\rangle & =\ell_{\sigma_{i}\left(c_{i}\right)} \circ \gamma^{j} \tag{2.28}
\end{align*}
$$

for $X_{i} \in \Gamma_{\text {lin }}\left(A_{\mathcal{E}_{i}}, E_{i}\right)$ and $c_{i} \in \Gamma\left(C_{i}\right), i, j=1, \ldots, k, i \neq j$. By arguments similar to the previous subsection, this is a well-defined map which is a morphism of Lie algebroids and $k$-linear with respect to the linear structure over $A$. And since $\mathcal{G}$ is source connected, and using similar arguments of the previous sections, the function who integrates $\mu$ is $F$.

### 2.4 Infinitesimal bilinear cocycles

Let

be two VB-algebroids over $A$ with core bundles $C_{i}$. Consider the VB-algebroid sum $\mathcal{A}=\mathcal{A}_{1} \oplus \mathcal{A}_{2}$. In this section we study functions defined on $\mathcal{A}$ which are bilinear with respect to the linear structure over $A$, and morphism with respect to the Lie algebroid structure. We give a description of this kind of functions in terms of some infinitesimal data, and then we establish a correspondence with bilinear cocycles.

Definition 2.27. A function $F \in C^{\infty}(\mathcal{A})$ is a bilinear $\mathcal{A}$-cocycle if it is a cocycle on $\mathcal{A}$ and if it is bilinear with respect to the vector bundle structure $\mathcal{A}_{1} \oplus \mathcal{A}_{2} \longrightarrow A$.

Proposition 2.28. Let $f \in C^{\infty}(\mathcal{A})$ be a bilinear $\mathcal{A}$-cocycle. Then there exists a triple $\left(\mathbf{D}, \sigma_{1}, \sigma_{2}\right)$ where

- $\mathbf{D}: \Gamma_{\text {lin }}\left(A_{\mathcal{E}_{1}}, E_{1}\right) \times_{\Gamma(A)} \Gamma_{\text {lin }}\left(A_{\mathcal{E}_{2}}, E_{2}\right) \longrightarrow \Gamma\left(E_{1}^{*} \otimes E_{2}^{*}\right)$ is a $C^{\infty}(M)$-linear,
- $\sigma_{1}: C_{1} \longrightarrow E_{2}^{*}$ and $\sigma_{2}: C_{2} \longrightarrow E_{1}^{*}$ are vector bundle maps covering the identity of $M$,
such that

$$
\begin{equation*}
\mathbf{D}\left(S_{T_{1}}, S_{T_{2}}\right)=\sigma_{1}\left(T_{1}\right) \circ \gamma^{1}+\sigma_{2}\left(T_{2}\right) \circ \gamma^{2} \quad \text { for all } T_{i} \in \Gamma\left(\operatorname{Hom}\left(E_{i}, C_{i}\right)\right) \tag{2.29}
\end{equation*}
$$

and satisfy

$$
\begin{align*}
\mathbf{D}([X, Y]) & =\left(\nabla^{1}\right)_{X}^{*} \mathbf{D}(Y)-\left(\nabla^{1}\right)_{Y}^{*} \mathbf{D}(X)  \tag{2.30}\\
\iota_{\partial_{1}\left(c_{1}\right)} \mathbf{D}(X) & =\left(\nabla^{1}\right)_{X_{2}}^{*} \sigma_{1}\left(c_{1}\right)-\sigma_{1}\left(\nabla_{X_{1}}^{0} c_{1}\right)  \tag{2.31}\\
\iota_{\partial_{2}\left(c_{2}\right)} \mathbf{D}(X) & =\left(\nabla^{1}\right)_{X_{1}}^{*} \sigma_{2}\left(c_{2}\right)-\sigma_{2}\left(\nabla_{X_{2}}^{0} c_{2}\right)  \tag{2.32}\\
\partial_{2}^{*} \circ \sigma_{1} & =\sigma_{2}^{*} \circ \partial_{1}, \tag{2.33}
\end{align*}
$$

where $\partial_{i}: C_{i} \longrightarrow E_{i}$ are the core anchor maps defined in (1.23) Reciprocally, any triple $\left(\mathbf{D}, \sigma_{1}, \sigma_{2}\right)$ satisfying the previous conditions induces a bilinear cocycle on $\mathcal{A}$.
Proof. Let $f \in C^{\infty}(\mathcal{A})$ be a bilinear cocycle. Consider it as a map over sections $f: \Gamma(\mathcal{A}) \longrightarrow C^{\infty}(E)$. Take a linear section defined by $X_{a}=\left(X_{a}^{1}, X_{a}^{2}\right)$. Then

$$
\begin{aligned}
\left\langle f, X_{a}\right\rangle\left(\lambda e_{1}+d_{1}, e_{2}\right) & =f\left(X_{a}^{1}\left(\lambda e_{1}+d_{1}\right), X_{a}^{2}\left(e_{2}\right)\right) \\
& =f\left(\lambda X_{a}^{1}\left(e_{1}\right)+{ }_{A} X_{a}^{1}\left(d_{1}\right), X_{a}^{2}\left(e_{2}\right)\right) \\
& =\lambda f\left(X_{a}^{1}\left(e_{1}\right), X_{a}^{2}\left(e_{2}\right)\right)+f\left(X_{a}^{1}\left(d_{1}\right), X_{a}^{2}\left(e_{2}\right)\right)
\end{aligned}
$$

because $f$ is bilinear over $A$. So $\left\langle f, X_{a}\right\rangle \in C_{\text {bil }}^{\infty}\left(E_{1} \oplus E_{2}\right) \simeq \Gamma\left(E_{1}^{*} \otimes E_{2}^{*}\right)$. We define then

$$
\mathbf{D}: \Gamma_{\operatorname{lin}}\left(\mathcal{A}_{1}, E_{1}\right) \times_{\Gamma(A)} \Gamma_{\operatorname{lin}}\left(\mathcal{A}_{2}, E_{2}\right) \longrightarrow \Gamma\left(E_{1}^{*} \otimes E_{2}^{*}\right) .
$$

by

$$
\mathbf{D}=\left.f\right|_{\Gamma_{\operatorname{lin}\left(\mathcal{A}_{1}, E_{1}\right) x_{\Gamma(A)} \Gamma_{\operatorname{lin}}\left(\mathcal{A}_{2}\right), E_{2}} .} .
$$

Now, let $c_{1} \in \Gamma\left(C_{1}\right)$. Then

$$
\begin{aligned}
\left\langle f,\left(S_{c_{1}}, 0\right)\right\rangle\left(e_{1}, e_{2}\right) & =f\left(0_{e_{1}}+{ }_{A} \overline{c_{1}(p)}, 0_{e_{2}}\right) \\
& =f\left(0_{e_{1}}, 0_{e_{2}}\right)+f\left(\overline{c_{1}(p)}, 0_{e_{2}}\right) \quad \text { by bilinearity } \\
& =f\left(\overline{c_{1}(p)}, 0_{e_{2}}\right)
\end{aligned}
$$

Note that the element $0_{e_{2}}$ projects to $e_{2} \in E_{2}$ and to $0 \in A$ but $0_{e_{2}}$ is not the zero element of the fiber $\left(\mathcal{A}_{2}\right)_{0}$ over $0 \in A$. So this induces a map $\sigma_{1}: \Gamma\left(C_{1}\right) \longrightarrow \Gamma\left(E_{2}^{*}\right)$ by:

$$
\left\langle\sigma_{1}\left(c_{1}\right), e_{2}\right\rangle=f\left(\overline{c_{1}(p)}, 0_{e_{2}}\right)
$$

In the same way, we define $\sigma_{2}: \Gamma\left(C_{2}\right) \longrightarrow \Gamma\left(E_{1}^{*}\right)$ by

$$
\left\langle\sigma_{2}\left(c_{2}\right), e_{1}\right\rangle=f\left(0_{e_{1}}, \overline{c_{2}(p)}\right) .
$$

Note that the maps $\sigma_{1}$ and $\sigma_{2}$ are both $C^{\infty}(M)$-linear, so we have two vector bundle morphisms $\sigma_{1}: C_{1} \longrightarrow E_{2}^{*}$ and $\sigma_{2}: C_{2} \longrightarrow E_{1}^{*}$. To see the compatibility condition, let $T_{i} \in \Gamma\left(\operatorname{Hom}\left(E_{i}, C_{i}\right)\right)$ and consider the associated linear core sections $S_{T_{i}}$. Then

$$
\begin{aligned}
\left\langle\mathbf{D}\left(S_{T_{1}}, S_{T_{2}}\right)\right\rangle\left(e_{1}, e_{2}\right) & =\left\langle f,\left(S_{T_{1}}, S_{T_{2}}\right)\right\rangle\left(e_{1}, e_{2}\right) \\
& =f\left(S_{T_{1}}\left(e_{1}\right), e_{2}\right)+f\left(e_{1}, S_{T_{2}}\left(e_{2}\right)\right) \\
& =\left\langle\sigma_{1}\left(T_{1}\right)\left(e_{1}\right), e_{2}\right\rangle+\left\langle e_{1}, \sigma_{2}\left(T_{2}\right)\left(e_{2}\right)\right\rangle .
\end{aligned}
$$

Now we will check the equations. Since $f$ is a cocycle, it satisfies

$$
\langle f,[Y . Z]\rangle=\mathcal{L}_{\rho_{\mathcal{A}}(Y)}\langle f, Z\rangle-\mathcal{L}_{\rho_{\mathcal{A}}(Z)}\langle f, Y\rangle
$$

for all sections $Y, Z \in \Gamma(\mathcal{A})$. First, take two linear sections $X=\left(X_{1}, X_{2}\right), Y=$ $\left(Y_{1}, Y_{2}\right)$. Their Lie bracket is $[X, Y]=\left(\left[X_{1}, Y_{1}\right],\left[X_{2}, Y_{2}\right]\right)$. By definition of the connection $\left(\nabla^{1}\right)^{*}: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \times \Gamma\left(E^{*}\right) \longrightarrow \Gamma\left(E^{*}\right)$ (see Equation (1.21)), we have that

$$
X \cdot \mathbf{D}(Y)=\left(\nabla^{1}\right)_{X}^{*} \mathbf{D}(Y):=\mathcal{L}_{\rho_{\mathcal{A}}(X)} \mathbf{D}(Y)
$$

Then the first equation holds. Let $\left(S_{c_{1}}, 0\right)$ be a core section. Then

$$
\left[\left(X_{1}, X_{2}\right),\left(S_{c_{1}}, 0\right)\right]=\left(S_{\nabla_{X_{1}}^{0} c_{1}}, 0\right)
$$

So $\left\langle f,\left[\left(X_{1}, X_{2}\right),\left(S_{c_{1}}, 0\right)\right]\right\rangle=\sigma_{1}\left(\nabla_{X_{1}}^{0} c_{1}\right) \circ \gamma_{1}$. On the other hand we have

$$
\mathcal{L}_{\rho_{\mathcal{A}}(X)}\left(\sigma_{1}\left(c_{1}\right) \circ \gamma_{1}\right)=\nabla_{X_{2}}^{0}\left(\sigma_{1}\left(c_{1}\right)\right) \circ \gamma_{1},
$$

and

$$
\mathcal{L}_{\rho_{\mathcal{A}}\left(S_{\left.c_{1}, 0\right)}\right.} \ell_{\mathbf{D}(X)}=\iota_{\partial_{1}\left(c_{1}\right)} \mathbf{D}(X) \circ \gamma_{1} .
$$

Therefore the second equation follows. In the same way we obtain the third equation. For the last one we have that $\left[\left(S_{c_{1}}, 0\right),\left(0, S_{c_{2}}\right)\right]=0$. Also

$$
\mathcal{L}_{\rho_{\mathcal{A}}\left(S_{c_{1}}, 0\right)} \sigma_{2}\left(c_{2}\right)=\left\langle\sigma_{2}\left(c_{2}\right), \partial_{1}\left(c_{1}\right)\right\rangle
$$

and

$$
\mathcal{L}_{\rho_{\mathcal{A}}\left(0, S_{c_{2}}\right)} \sigma_{1}\left(c_{1}\right)=\left\langle\sigma_{1}\left(c_{1}\right), \partial_{2}\left(c_{2}\right)\right\rangle
$$

which imply the last equation. Conversely, given the triple ( $\mathbf{D}, \sigma_{1}, \sigma_{2}$ ) satisfying the equations, we have to construct a bilinear cocycle $f: \mathcal{A} \longrightarrow \mathbb{R}$. We will define it at the level of sections and then we will prove that it is a $C^{\infty}(E)$-linear. Take a linear section covering $a \in \Gamma(A)$ of the form ( $X_{1}, X_{2}$ ), then define

$$
\left\langle f,\left(X_{1}, X_{2}\right)\right\rangle:=\ell_{\mathbf{D}\left(X_{1}, X_{2}\right)} .
$$

For a core section $\left(S_{c_{1}}, 0\right)$ with $c_{1} \in \Gamma\left(C_{1}\right)$, define

$$
\left\langle f,\left(S_{c_{1}}, 0\right)\right\rangle\left(e_{1}, e_{2}\right):=\left\langle\sigma_{1}\left(c_{1}\right), e_{2}\right\rangle
$$

Analogously, for a core section $\left(0, S_{c_{2}}\right)$ with $c_{2} \in \Gamma\left(C_{2}\right)$, define

$$
\left\langle f,\left(0, S_{c_{2}}\right)\right\rangle\left(e_{1}, e_{2}\right):=\left\langle e_{1}, \sigma_{2}\left(c_{2}\right)\right\rangle
$$

The compatibility condition implies that $f$ is well defined in all linear sections. So extending $f$ to all sections by linearity we have a well defined linear map $f$ : $\Gamma(\mathcal{A}, E) \longrightarrow C^{\infty}(E)$. Moreover, by the $C^{\infty}(M)$-linearity of $\mathbf{D}, \sigma_{1}, \sigma_{2}$ we can extend
$f$ by $C^{\infty}(E)$-linearity. Hence we have a linear function $f: \mathcal{A} \longrightarrow \mathbb{R}$ over $E$. The equations satisfied by $\mathbf{D}, \sigma_{1}, \sigma_{2}$ imply that $f$ is a morphism of Lie algebroids. To see the bilinearity over $A$, let $\alpha_{1}, \beta_{1} \in \mathcal{A}_{1}$ and $\alpha_{2} \in \mathcal{A}_{2}$, projectable over $a \in A$ and over $e_{1}, d_{1} \in E_{1}$ and $e_{2} \in E_{2}$, respectively. Let $X \in \Gamma_{\text {lin }}\left(\mathcal{A}_{1}, E_{1}\right)$ such that $X\left(e_{1}\right)=\alpha_{1}$. Then $\beta_{1}=X\left(d_{1}\right)+_{E_{1}} S_{c}\left(d_{1}\right)$ for some section $c \in \Gamma\left(C_{1}\right)$, and let $Y \in \Gamma_{\text {lin }}\left(\mathcal{A}_{1}, E_{1}\right)$ such that $Y\left(e_{2}\right)=\alpha_{2}$. Then

$$
\begin{aligned}
f\left(\alpha_{1}+_{A} \beta_{1}, \alpha_{2}\right) & =f\left(X\left(e_{1}\right){ }_{A}\left(X\left(d_{1}\right)+E_{1} S_{c}\left(d_{1}\right)\right), Y\left(e_{2}\right)\right) \\
& =f\left(\left(X\left(e_{1}\right)+_{A} X\left(d_{1}\right)\right)+_{E_{1}} S_{c}\left(d_{1}\right), Y\left(e_{2}\right)\right) \quad \text { by interchange law } \\
& =f\left(X\left(e_{1}+d_{1}\right)+E_{1} S_{c}\left(d_{1}\right), Y\left(e_{2}\right)\right) \quad \text { by linearity of } X \\
& =f\left(X\left(e_{1}+d_{1}\right), Y\left(e_{2}\right)\right)+f\left(S_{c}\left(d_{1}\right), Y\left(e_{2}\right)\right) \quad \text { by linearity w.r.t } E \\
& =\left\langle\mathbf{D}(X, Y),\left(e_{1}+d_{1}, e_{2}\right)\right\rangle+f\left(S_{c}\left(d_{1}\right), Y\left(e_{2}\right)\right) \\
& =\left\langle\mathbf{D}(X, Y),\left(e_{1}, e_{2}\right)\right\rangle+\left\langle\mathbf{D}(X, Y),\left(d_{1}, e_{2}\right)\right\rangle+f\left(S_{c}\left(d_{1}\right), Y\left(e_{2}\right)\right) \\
& =f\left(X\left(e_{1}\right), Y\left(e_{2}\right)\right)+f\left(X\left(d_{1}\right), Y\left(e_{2}\right)\right)+f\left(S_{c}\left(d_{1}\right), Y\left(e_{2}\right)\right) \\
& =f\left(\alpha_{1}, \alpha_{2}\right)+f\left(X\left(d_{1}\right)+_{E_{1}} S_{c}\left(d_{1}\right), Y\left(e_{2}\right)\right) \\
& =f\left(\alpha_{1}, \alpha_{2}\right)+f\left(\beta_{1}, \alpha_{2}\right) .
\end{aligned}
$$

Definition 2.29. A triple ( $\mathbf{D}, \sigma_{1}, \sigma_{2}$ ) satisfying Equations (2.30), (2.31), (2.32), (2.33), and the compatibility condition (2.29) is called the component of a bilinear $\mathcal{A}$-cocycle over $A$.

Now we enunciate a global-infinitesimal correspondence between bilinear groupoid cocycles and bilinear algebroid cocycles. Let $\mathcal{E}_{i} \rightrightarrows E_{i}, i=1,2$ be two VB-groupoids over $\mathcal{G}$, and let $\mathcal{E}=\mathcal{E}_{1} \oplus \mathcal{E}_{2}$ be the VB-groupoid sum. Denote by $A_{\mathcal{E}}=A_{\mathcal{E}_{1}} \oplus A_{\mathcal{E}_{2}}$ the VB-algebroid of $\mathcal{E}$.

Theorem 2.30. Every bilinear $\mathcal{E}$-cocycle induces a triple $\left(\mathbf{D}, \sigma_{1}, \sigma_{2}\right)$ satisfying the Equations (2.29)-(2.33). Moreover if $\mathcal{G}$ is source connected, there is a one to one correspondence between bilinear $\mathcal{E}$-cocycle and such triples $\left(\mathbf{D}, \sigma_{1}, \sigma_{2}\right)$ given by

$$
\left\{\begin{array}{l}
\mathcal{L}_{\vec{X}} F=\ell_{\mathcal{T}(D(X))} \\
\mathcal{L}_{\overrightarrow{S_{c_{1}, 0}}} F=\ell_{\mathcal{T}\left(\sigma_{1}\left(c_{1}\right)\right)} \circ \pi_{2} \\
\mathcal{L}_{\overrightarrow{S_{0, c_{2}}}} F=\ell_{\mathcal{T}\left(\sigma_{2}\left(c_{2}\right)\right)} \circ \pi_{1}
\end{array}\right.
$$

Proof. If $F \in C^{\infty}(\mathcal{E})$ is a bilinear cocycle then by Theorem 2.21 there exists a triple ( $\mathbf{D}, \sigma_{1}, \sigma_{2}$ ), which defines the components of a bilinear $A_{\mathcal{E}}$-cocycle over $A$ because they are associated to the bilinear cocycle $A F$.

In the case where the VB-algebroids $\mathcal{A}_{i}$ are the same, we can consider bilinear
cocycles $f$ which are symmetric (resp. skew-symmetric). Consider the VB-algebroid


In this situation we have the following description
Proposition 2.31. There is one-to-one correspondence between symmetric (resp. skew-symmetric) bilinear cocycle on $\mathcal{A}^{2}$ and pairs $(\mathbf{D}, \sigma)$ where the operator $\mathbf{D}$ : $\Gamma_{\text {lin }}(\mathcal{A}, E) \longrightarrow \Gamma\left(E^{*} \otimes E^{*}\right)$ is a $C^{\infty}(M)$-linear, $\sigma: C \longrightarrow E^{*}$ is a vector bundle map over the identity of $M$ such that

- $\ell_{\mathbf{D}(X)} \in C^{\infty}\left(E^{2}\right)$ is a symmetric (resp. skew-symmetric) function
- $\mathbf{D}\left(S_{T}\right)=\left\langle\sigma \circ T+(\sigma \circ T)^{*}, i d_{E}\right\rangle$ for every $T \in \Gamma(H o m(E, C))$
and satisfy

$$
\begin{aligned}
\mathbf{D}([X, Y]) & =\left(\nabla^{1}\right)_{X}^{*} \mathbf{D}(Y)-\left(\nabla^{1}\right)_{Y}^{*} \mathbf{D}(X) \\
\iota \partial(c) \mathbf{D}(X) & =\left(\nabla^{1}\right)_{X}^{*} \sigma(c)-\sigma\left(\nabla_{X}^{0} c\right) \\
\partial^{*} \circ \sigma & =\sigma^{*} \circ \partial \quad\left(\text { resp. } \quad \partial^{*} \circ \sigma=-\sigma^{*} \circ \partial\right)
\end{aligned}
$$

Proof. By Proposition 2.28 there is a one-to-one correspondence between bilinear cocycles and component of a infinitesimal bilinear cocycles ( $\widetilde{\mathbf{D}}, \sigma_{1}, \sigma_{2}$ ) over $A$. Since we have two copies of the same VB-algebroid, we can define

$$
\mathbf{D}: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \longrightarrow \Gamma\left(E^{*} \otimes E^{*}\right) \quad \mathbf{D}(X)=\widetilde{\mathbf{D}}(X, X)
$$

and the condition of symmetric (resp. skew-symmetric) of $f$ implies that $\ell_{\mathbf{D}(X)}$ is symmetric (resp. skew-symmetric). The vector bunble maps $\sigma_{1}, \sigma_{2}: C \longrightarrow E^{*}$ are determined by

$$
\left\langle f,\left(S_{c}, 0\right)\right\rangle\left(e_{1}, e_{2}\right):=\left\langle\sigma_{1}(c), e_{2}\right\rangle \quad \text { and } \quad\left\langle f,\left(0, S_{c}\right)\right\rangle\left(e_{1}, e_{2}\right):=\left\langle e_{1}, \sigma_{2}(c)\right\rangle
$$

If $f$ is symmetric then

$$
\begin{aligned}
\left\langle\sigma_{1}(c), e_{2}\right\rangle & =\left\langle f,\left(S_{c}, 0\right)\right\rangle\left(e_{1}, e_{2}\right)=\left\langle f,\left(0, S_{c}\right)\right\rangle\left(e_{2}, e_{1}\right) \\
& =\left\langle\sigma_{2}(c), e_{2}\right\rangle,
\end{aligned}
$$

which implies that $\sigma_{1}=\sigma_{2}$. This last condition implies that

$$
\text { Eq. }(2.31)=\text { Eq. }(2.32)=\text { Eq. }\left(\iota_{\partial(c)} \mathbf{D}(X)=\left(\nabla^{1}\right)_{X}^{*} \sigma(c)-\sigma\left(\nabla_{X}^{0} c\right)\right)
$$

and

$$
\text { Eq. }(2.33) \quad \Longrightarrow \quad \partial^{*} \circ \sigma=\sigma^{*} \circ \partial
$$

In the case when $f$ is skew-symmetric, we have $\sigma_{1}=-\sigma_{2}$, which implies that equations (2.31), (2.32) and $\iota_{\partial(c)} \mathbf{D}(X)=\left(\nabla^{1}\right)_{X}^{*} \sigma(c)-\sigma\left(\nabla_{X}^{0} c\right)$ are all equivalent. Also, the condition $\sigma_{1}=-\sigma_{2}$ implies $\partial^{*} \circ \sigma=-\sigma^{*} \circ \partial$. Conversely, defining a map $\mu: \Gamma\left(A_{\mathcal{E}^{2}}\right) \longrightarrow C^{\infty}\left(E^{2}\right)$ by

$$
\begin{aligned}
\langle\mu,(X, X)\rangle & =\ell_{\mathbf{D}(X)} \\
\left\langle\mu, S_{c, 0}\right\rangle & =\ell_{\sigma(c)} \circ \gamma^{2} \\
\left\langle\mu, S_{0, c}\right\rangle & =\ell_{\sigma(c)} \circ \gamma^{1}
\end{aligned}
$$

follows by similar arguments on the Proposition 2.28 that $\mu$ is well defined. By the properties of $\mathbf{D}$ and $\sigma$ follow that $\mu$ is symmetric. Hence by Proposition 2.11 we get that $F$ symmetric. The skew-symmetric case is analogous.

### 2.4.1 Infinitesimal multilinear cocycles

In this subsection we extend bilinear cocycles on VB-algebroids to the general case, i.e., multilinear cocycles. Take $k$ VB-algebroids over $A$

with core bundles $C_{i}$ and consider the VB-algebroid sum


Definition 2.32. A function $f \in C^{\infty}(\mathcal{A})$ is a $k$-linear cocycle if it is a Lie algebroid morphism and if it is $k$-linear with respect to the vector bundle structure $\oplus_{i=1}^{k} \mathcal{A}_{i} \longrightarrow$ $A$.

Definition 2.33. An infinitesimal $k$-linear structure on $\mathcal{A}$ over $A$ is a $\left(\mathbf{D}, \sigma_{i}\right)$, with $i=1, \ldots, k$, where

$$
\mathbf{D}: \Gamma_{\operatorname{lin}}\left(\mathcal{A}_{1}, E_{1}\right) \times_{\Gamma(A)} \cdots \times_{\Gamma(A)} \Gamma_{\operatorname{lin}}\left(\mathcal{A}_{k}, E_{k}\right) \longrightarrow \Gamma\left(E_{1}^{*} \otimes \cdots \otimes E_{k}^{*}\right)
$$

is a $C^{\infty}(M)$-linear operator, and $\sigma_{i}: C_{i} \longrightarrow \otimes_{j \neq i}^{k} E_{j}^{*}$, for $i=1, \ldots, k$, are vector bundle maps over the identity of $M$, such that

$$
\mathbf{D}\left(S_{T_{1}}, \ldots, S_{T_{k}}\right)=\sum_{i=1}^{k}\left\langle\sigma_{i}\left(T_{i}\right), \operatorname{Id}_{E^{j}}\right\rangle \quad \text { for all } T_{i} \in \Gamma\left(\operatorname{Hom}\left(E_{i}, C_{i}\right)\right)
$$

where $\operatorname{Id}_{E^{i}}: \oplus_{j \neq i} E_{j} \longrightarrow \oplus_{j \neq i} E_{j}$ is the identity in each component and such that

$$
\begin{aligned}
\mathbf{D}([X, Y]) & =X \cdot \mathbf{D}(Y)-Y \cdot \mathbf{D}(X) \\
\iota_{\partial_{i}\left(c_{i}\right)} \mathbf{D}\left(X_{1}, \ldots, X_{k}\right) & =\left(\nabla^{1}\right)_{\left(X_{1}, \ldots, \widehat{X_{i}}, \ldots, X_{k}\right)}^{*} \sigma_{i}\left(c_{i}\right)-\sigma_{i}\left(\nabla_{X_{i}}^{0} c_{i}\right) \text { for } i=1, \ldots k \\
\left\langle\sigma_{i}\left(c_{i}\right), \partial_{j}\left(c_{j}\right)\right\rangle & =\left\langle\sigma_{j}\left(c_{j}\right), \partial_{i}\left(c_{i}\right)\right\rangle \text { for all } i, j=1, \ldots k \text { with } i \neq j
\end{aligned}
$$

Proposition 2.34. Let $\mathcal{A} \longrightarrow E$ be a sum of $k V B$-algebroids over $A$. Then there is one-to-one correspondence between $k$-linear algebroid function $f \in C^{\infty}(\mathcal{A})$ and infinitesimal $k$-linear structure on $\mathcal{A}$ over $A$.

Proof. The proof of this proposition is analogous to the proof of Proposition 2.28.

We enunciate now the global-infinitesimal correspondence between these multilinear objects.

Theorem 2.35. Let $\mathcal{E} \rightrightarrows E$ be sum of $k V B$-groupoids $\mathcal{E}_{i} \rightrightarrows E_{i}$ over a source simply connected Lie groupoid $\mathcal{G}$, and denote by $A_{\mathcal{E}}$ its Lie algebroid, which splits naturally as the sum of the $k V B$-algebroid $A_{\mathcal{E}_{i}}$. Then there is one-to-one correspondence between $k$-linear cocycles on $C^{\infty}(\mathcal{E})$ and infinitesimal $k$-linear structure on $\mathcal{A}$ over $A$.

## Chapter 3

## Applications to multiplicative structures on Lie groupoids

In this chapter we describe multiplicative $(p, q)$-tensors on a Lie groupoid $\mathcal{G}$ with coefficient in a VB-groupoid $\mathcal{E} \rightrightarrows E$ over $\mathcal{G}$. We will see such tensors as cocycles on some VB-groupoid $\mathbb{G}$ over $\mathcal{G}$, and then we will apply all what we did in the Chapter 2. As a consequence, we generalize the description of multiplicative $k$-forms (with trivial coefficients [7] and with values in some representation [14]), the description of multiplicative multivector fields $[24,33]$, with new proofs, and we will consider multiplicative $k$-forms with coefficients in a representation up to homotopy.

Definition 3.1. Let $\pi_{\mathcal{E}}: \mathcal{E} \longrightarrow \mathcal{G}$ be a vector bundle over a Lie groupoid $\mathcal{G} \rightrightarrows M$. A $(p, q)$-tensor field on $\mathcal{G}$ with coefficient in $\mathcal{E}$ is a section $\tau \in \Gamma\left(\bigotimes^{p} T^{*} \mathcal{G} \otimes \bigotimes^{q} T \mathcal{G} \otimes \mathcal{E}\right)$.

Given a $(p, q)$-tensor field $\tau \in \Gamma\left(\bigotimes^{p} T^{*} \mathcal{G} \otimes \bigotimes^{q} T \mathcal{G} \otimes \mathcal{E}\right)$ we associate a componentwise linear function

$$
c_{\tau}:\left(\oplus_{p} T \mathcal{G}\right) \oplus\left(\oplus_{q} T^{*} \mathcal{G}\right) \oplus \mathcal{E}^{*} \longrightarrow \mathbb{R}
$$

defined by

$$
c_{\tau}\left(X_{1}, \ldots, X_{p}, \mu_{1}, \ldots, \nu_{q}, \eta\right)=\left\langle\tau\left(X_{1}, \ldots, X_{p}, \mu_{1}, \ldots, \mu_{q}\right), \eta\right\rangle .
$$

where $\mathcal{E}^{*}$ is the dual of $\mathcal{E}$ over $\mathcal{G}$.
Definition 3.2. Let $\mathcal{E} \rightrightarrows E$ be a VB-groupoid over $\mathcal{G}$ with core bundle $C$. A $(p, q)$ tensor $\tau$ on $\mathcal{G}$ with coefficients in $\mathcal{E}$ is multiplicative if the associated componentwise linear function $c_{\tau} \in C^{\infty}\left(\left(\oplus_{p} T \mathcal{G}\right) \oplus\left(\oplus_{q} T^{*} \mathcal{G}\right) \oplus \mathcal{E}^{*}\right)$ is multiplicative. We call this $\tau$ an $\mathcal{E}$-valued multiplicative $(p, q)$-tensor.
Remark 3.3. Notation. When we have vector bundles $E_{i}$ over some manifold $M$, given a section $\varphi \in \Gamma\left(E_{1}^{*} \otimes \cdots \otimes E_{k}^{*}\right)$ we will denote by $c_{\varphi}: E_{1} \oplus \cdots \oplus E_{k} \longrightarrow \mathbb{R}$ its associated componentwise linear function defined by

$$
c_{\varphi}\left(e_{1}, \ldots, e_{k}\right):=\left\langle\varphi,\left(e_{1}, \ldots, e_{k}\right)\right\rangle
$$

Our goal now is to describe the infinitesimal counterpart of $\tau$ by studying $c_{\tau}$.

### 3.1 Core and linear sections

We fix an $\mathcal{E}$-valued multiplicative $(p, q)$-tensor $\tau$ on $\mathcal{G}$, and let $c_{\tau}$ be its associated componentwise linear function. From now to the end of the chapter we will assume that the $(p, q)$-tensor is skew-symmetric in the first $p$-components and skewsymmetric in the $q$-components of $T^{*} \mathcal{G}$. This is done just to simplify their description but the method applies in general. The case we are interesting have this property.

Before consider the action of $c_{\tau}$ on linear and core sections, for an $\mathcal{E}$-valued multiplicative $(p, q)$-tensor, we need a proposition, which is the same as Proposition 2.7 , but we do it explicitly in this context. We denote

- $\mathbb{G}_{\mathcal{E}}^{(p, q)}=\left(\oplus_{p} T \mathcal{G}\right) \oplus\left(\oplus_{q} T^{*} \mathcal{G}\right) \oplus \mathcal{E}^{*}$,
- $\mathbb{M}_{\mathcal{E}}^{(p, q)}=\left(\oplus_{p} T M\right) \oplus\left(\oplus_{q} A^{*}\right) \oplus C^{*}$.

And when we consider on the Whitney sum of the tangent and cotangent groupoid we will omit the subindice $\mathcal{E}$. Recall the notation for the target maps: $T \mathrm{t}: T \mathcal{G} \longrightarrow T M$, $\widetilde{t}: T^{*} \mathcal{G} \longrightarrow A^{*}, \bar{t}: \mathcal{E} \longrightarrow E$ and $\bar{t}^{*}: \mathcal{E}^{*} \longrightarrow C^{*}$.

Proposition 3.4. The pullback map

$$
\left(\mathbb{T}_{\mathcal{E}}^{(p, q)}\right)^{*}:=\left((T \mathbf{t})^{p},(\widetilde{t})^{q}, \bar{t}^{*}\right)^{*}: C^{\infty}\left(\mathbb{M}_{\mathcal{E}}^{(p, q)}\right) \longrightarrow C^{\infty}\left(\mathbb{G}_{\mathcal{E}}^{(p, q)}\right)
$$

preserves componentwise linear functions. Moreover the pullback function satisfies

$$
\left(\mathbb{T}_{\mathcal{E}}^{(p, q)}\right)^{*}\left(c_{\varphi}\right)=c_{\mathcal{T}(\varphi)}
$$

for every $\varphi \in \Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q} A^{*} \otimes C\right)$, where

$$
\begin{aligned}
\mathcal{T}: \Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q} A^{*} \otimes C\right) & \longrightarrow \Gamma\left(\wedge^{p} T^{*} \mathcal{G} \otimes \wedge^{q} T \mathcal{G} \otimes \mathcal{E}\right) \\
\alpha \otimes a \otimes c & \longrightarrow \mathcal{T}(\alpha \otimes a \otimes c)=\mathbf{t}^{*} \alpha \otimes \vec{a} \otimes c^{\mathcal{E}}(g)
\end{aligned}
$$

and where $c^{\mathcal{E}}(g):=c(\boldsymbol{t}(g)) \cdot 0_{g}$ is the core section of $\mathcal{E} \longrightarrow \mathcal{G}$ associated to $c \in \Gamma(C)$ (see equation (2.2)).

Proof. The first part of the Lemma follows from the fact that each one of the maps $T \mathbf{t}, \tilde{t}$ and $\bar{t}^{*}$ is a morphism of vector bundles. The second part follows by Proposition 2.7. Nevertheless, we give here another proof using the explicit Lie groupoid structure of the tangent groupoid $T \mathcal{G}$ and of the cotangent groupoid $T^{*} \mathcal{G}$. Let $\Phi=\alpha \otimes a \otimes c \in$ $\Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q} A^{*} \otimes C\right)$ and $V_{1}, \ldots, V_{p} \in T_{g} \mathcal{G}, \mu_{1}, \ldots, \mu_{q} \in T_{g}^{*} \mathcal{G}$ and $\eta \in \mathcal{E}_{g}^{*}$. On the one hand we have

$$
c_{\mathcal{T}(\Phi)}\left(V^{p}, \mu^{q}, \eta\right)=\alpha\left(T \mathbf{t}\left(V_{1}\right), \ldots, T \mathbf{t}\left(V_{p}\right)\right) \vec{a}\left(\mu_{1}, \ldots, \mu_{q}\right) c^{\mathcal{E}}(\eta) .
$$

On the other hand

$$
\left.\left(\mathbb{T}_{\mathcal{E}}^{(p, q)}\right)^{*}\left(c_{\Phi}\right)\left(V^{p}, \mu^{q}, \eta\right)=\alpha\left(T \mathbf{t}\left(V_{1}\right), \ldots, T \mathbf{t}\left(V_{p}\right)\right) a \widetilde{t}\left(\mu_{1}\right), \ldots, \widetilde{t}\left(\mu_{q}\right)\right) c\left(\bar{t}^{*}(\eta)\right)
$$

We have to prove that $\vec{a}\left(\mu_{1}, \ldots, \mu_{q}\right)=a\left(\widetilde{t}\left(\mu_{1}\right), \ldots, \widetilde{t}\left(\mu_{q}\right)\right)$ and that $c^{\mathcal{E}}(\eta)=c\left(\widetilde{t}^{*}(\eta)\right)$. For the first equation we proceed by induction on $q$. The case $q=1$ follows by Remark 1.17

$$
\langle\widetilde{t}(\mu), a(\mathbf{t}(g))\rangle:=\left\langle\mu, a(\mathbf{t}(g)) \cdot 0_{g}\right\rangle=\langle\mu, \vec{a}(\mu)\rangle .
$$

Now assume that the result is true for $q-1$. Without loss of generality, we can assume that $a=a_{1} \wedge a_{2}$ for $a_{1} \in \Gamma(A)$ and $a_{2} \in \Gamma\left(\wedge^{q-1} A\right)$. Then

$$
\begin{aligned}
\overrightarrow{a_{1} \wedge a_{2}}\left(\mu_{1}, \ldots, \mu_{q}\right) & =\sum_{j=1}^{q}(-1)^{j}\left\langle\mu_{j}, \overrightarrow{a_{1}}(g)\right\rangle \overrightarrow{a_{2}}\left(\mu_{1}, \ldots, \widehat{\mu_{j}}, \ldots, \mu_{q}\right) \\
& \left.=\sum_{j=1}^{q}(-1)^{j} \widetilde{t}(\mu), a_{1}(\mathbf{t}(g))\right\rangle a_{2} \widetilde{t}\left(\mu_{1}\right), \ldots, \widehat{t}\left(\mu_{j}\right) \\
& \left.\ldots, \widetilde{t}\left(\mu_{q}\right)\right) \\
& =a_{1} \wedge a_{2}\left(\widetilde{t}\left(\mu_{1}\right), \ldots, \widetilde{t}\left(\mu_{q}\right)\right)
\end{aligned}
$$

This is what we wanted to prove. For the second equation we have that

$$
\ell_{c}\left(\bar{t}^{*}(\eta)\right)=\left\langle c, \bar{t}^{*}(\eta)\right\rangle:=\left\langle c(\mathbf{t}(g)) \cdot 0_{g}, \eta\right\rangle=\left\langle c^{\mathcal{E}}(g), \eta\right\rangle .
$$

From the definition it follows that

$$
\begin{equation*}
\mathcal{T}(f \varphi)=\left(\mathrm{t}^{*} f\right) \mathcal{T}(\varphi), \quad \forall \varphi \in \Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q} A^{*} \otimes C\right), f \in C^{\infty}(M) \tag{3.1}
\end{equation*}
$$

Remark 3.5. We write $\mathbb{T}^{(p, q)}$ for the target map $\left((T \mathbf{t})^{p},(\widetilde{t})^{q}\right): C^{\infty}\left(\mathbb{M}^{(p, q)}\right) \longrightarrow$ $C^{\infty}\left(\mathbb{G}^{(p, q)}\right)$. When is not risk to confusion we drop the superindices in both $\mathbb{T}_{\mathcal{E}}^{(p, q)}$ and $\mathbb{T}^{(p, q)}$.

The main result of this section is the following proposition, whose proof will be done in the last part of Subsection 3.1.2:

Proposition 3.6. Let $\mathcal{G} \rightrightarrows M$ be a source connected Lie groupoid and let $\mathcal{E} \rightrightarrows E_{1}$ be a VB-groupoid over $\mathcal{G}$ with core bundle $C$. Then an $\mathcal{E}$-valued multiplicative $(p, q)$ tensor field $\tau$ on $\mathcal{G}$ is multiplicative if and only if

$$
\left.c_{\tau}\right|_{\mathbb{M}_{\varepsilon}^{(p, q)}}=0
$$

and there exist

- D : $\Gamma_{\text {lin }}\left(A_{\mathcal{E}^{*}}, C^{*}\right) \longrightarrow \Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q} A \otimes C\right)$
- $l: A \longrightarrow \wedge^{p-1} T^{*} M \otimes \wedge^{q} A \otimes C$
- $r: T^{*} M \longrightarrow \wedge^{p} T^{*} M \otimes \wedge^{q-1} A^{*} \otimes C$
- $F: \wedge^{p} T M \otimes \wedge^{q} A^{*} \longrightarrow E$
such that $\mathbf{D}$ satisfies the Leibniz rule (3.17) and

$$
\left\{\begin{array}{l}
\mathcal{L}_{\vec{X}} \tau=\mathcal{T}(\mathbf{D}(X))  \tag{3.2}\\
i_{\vec{a}} \tau=\mathcal{T}(l(a)) \\
i_{t^{*} \alpha} \tau=\mathcal{T}(r(\alpha)) \\
i_{S_{\zeta}} \tau=\mathcal{T}\left(F^{*}(\zeta)\right)
\end{array}\right.
$$

### 3.1.1 Core sections

The componentwise linear function $c_{\tau}$ associated to an $\mathcal{E}$-valued multiplicative $(p, q)$ tensor is defined on the VB-groupoid

$$
\left(\bigoplus_{p} T \mathcal{G}\right) \oplus\left(\bigoplus_{q} T^{*} \mathcal{G}\right) \oplus \mathcal{E}^{*}=\mathbb{G}_{\mathcal{E}}^{(p, q)}
$$

Its VB-algebroid, which we denote by $\mathbb{A}_{\mathcal{E}}^{(p, q)}$, splits naturally as the $\operatorname{sum}\left(\bigoplus_{p} T A\right) \oplus$ $\left(\bigoplus_{q} T^{*} A\right) \oplus A_{\mathcal{E}^{*}}$. Hence there are three different kinds of core sections: one coming from the core $A$, one coming from the core $T^{*} M$ and one coming from the core $E^{*}$. We study now the action of the function $c_{\tau}$ on these three kinds of sections. When there is no risk of confusion we will not write the superindices $(p, q)$.

Let $a \in \Gamma(A)$. We denote by $S_{a}$ the core section of the tangent algebroid $T A$ generated by $a$ and let $\overrightarrow{S_{a}}$ be its corresponding right invariant vector field on $T \mathcal{G}$. The local flow of this vector field is given by $\varphi_{S_{a}}^{t}(V)=V+t \vec{a}(g)$ for $V \in T_{g} \mathcal{G}$. Consider the core section $S_{a}^{i}$ of $\mathbb{A}_{\mathcal{E}}$ defined by:

$$
S_{a}^{i}=(\underbrace{0, \ldots, \overbrace{S_{a}}^{i}, \ldots, 0}_{p}, \underbrace{0, \ldots, 0}_{q}, 0): \mathbb{M}_{\mathcal{E}} \longrightarrow \mathbb{A}_{\mathcal{E}}
$$

and let $\overrightarrow{S_{a}^{i}} \in \mathfrak{X}\left(\mathbb{G}_{\mathcal{E}}^{(p, q)}\right)$ be the associated right invariant vector field. Since $\tau$ is an $\mathcal{E}$-valued multiplicative $(p, q)$-tensor then

$$
\begin{aligned}
\left(\mathbb{T}_{\mathcal{E}}^{(p, q)}\right)^{*}\left\langle A c_{\tau}, S_{a}^{i}\right\rangle\left(V^{p}, \mu^{q}, \eta\right) & =\left(\mathcal{L}_{\overrightarrow{S a^{i}}} c_{\tau}\right)\left(V^{p}, \mu^{q}, \eta\right) \\
& =\left.\frac{d}{d t}\right|_{t=0}\left\langle\tau\left(V_{1}, \ldots, V_{i}+t \vec{a}, \ldots, V_{k}, \mu^{q}\right), \eta\right\rangle \\
& =\left\langle\tau\left(V_{1}, \ldots, V_{i-1}, \vec{a}, V_{i+1}, \ldots, V_{p}, \mu^{q}\right), \eta\right\rangle \\
& =(-1)^{i-1} c_{i_{\vec{a}} \tau} \circ \pi_{(i)}\left(V^{p}, \mu^{q}, \eta\right)
\end{aligned}
$$

for $V_{i} \in T \mathcal{G}, \mu_{j} \in T^{*} \mathcal{G}$ and $\eta \in \mathcal{E}^{*}$, where $V^{p}=\left(V_{1}, \ldots, V_{p}\right), \mu^{q}=\left(\mu_{1}, \ldots, \mu_{q}\right)$, and $\pi_{(i)}: \mathbb{G}_{\mathcal{E}}^{(p, q)} \longrightarrow \mathbb{G}_{\mathcal{E}}^{(p-1, q)}$ is the forgetful map with respect to the $i$-entry of $\bigoplus_{p} T \mathcal{G}$ (see (2.26)). Taking now units $\left(v^{p}, \nu^{q}, \xi\right) \in \mathbb{M}_{\mathcal{E}}$ we have

$$
\begin{aligned}
\left\langle A c_{\tau}, S_{a}^{i}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) & =\left(\mathcal{L}_{\overrightarrow{S_{a}^{c}}} c_{\tau}\right)\left(v^{p}, \nu^{q}, \xi\right) \\
& =\left\langle\tau\left(v_{1}, \ldots, v_{i-1}, \vec{a}, v_{i+1}, \ldots, v_{p}, \nu^{q}\right), \xi\right\rangle \\
& =(-1)^{i-1}\left\langle\tau\left(\vec{a}, v_{1}, \ldots, v_{i-1}, v_{i+1}, \ldots, v_{p}, \nu^{q}\right), \xi\right\rangle
\end{aligned}
$$

This implies that $\left\langle A c_{\tau}, S_{a}^{i}\right\rangle$ is a componentwise linear function of $\gamma_{(i)}\left(v^{p}, \nu^{q}, \xi\right) \in$ $\mathbb{M}_{\mathcal{E}}^{(p-1, q)}$, where

$$
\gamma_{(i)}^{(p, q)}: \mathbb{M}_{\mathcal{E}}^{(p, q)} \longrightarrow \mathbb{M}_{\mathcal{E}}^{(p-1, q)}
$$

if the forgetful map with respect to the $i$-entry of $\bigoplus_{q} T M$. Thus there is a $l(a) \in$ $\Gamma\left(\wedge^{p-1} T^{*} M \otimes \wedge^{q} A \otimes C\right)$ such that

$$
\begin{equation*}
\left\langle A c_{\tau}, S_{a}^{i}\right\rangle=(-1)^{i-1} c_{l(a)} \circ \gamma_{(i)} . \tag{3.3}
\end{equation*}
$$

Now note that

$$
\begin{aligned}
\mathcal{L}_{\vec{S}_{a}^{2}} c_{\tau} & =\left(\mathbb{T}_{\mathcal{E}}^{(p, q)}\right)^{*}\left\langle A c_{\tau}, S_{a}^{i}\right\rangle \\
& =\left(\mathbb{T}_{\mathcal{E}}^{(p, q)}\right)^{*}(-1)^{i-1} c_{l(a)} \circ \gamma_{(i)} \\
& =(-1)^{i-1} c_{\mathcal{T}(l(a))} \circ \pi_{(i)},
\end{aligned}
$$

We summarize these facts in the following proposition:
Proposition 3.7. For any multiplicative $\mathcal{E}$-valued $(p, q)$-tensor $\tau$ on $\mathcal{G}$ we have that

$$
\begin{equation*}
\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A c_{\tau}, S_{a}^{i}\right\rangle=(-1)^{i-1} c_{i_{\vec{\alpha}} \tau} \circ \pi_{(i)} \tag{3.4}
\end{equation*}
$$

In particular there exists vector bundle morphism l: $A \longrightarrow \wedge^{p-1} T^{*} M \otimes \wedge^{q} A \otimes C$ such that

$$
\begin{equation*}
\left\langle A c_{\tau}, S_{a}^{i}\right\rangle=(-1)^{i-1} c_{l(a)} \circ \gamma_{(i)} . \tag{3.5}
\end{equation*}
$$

Proof. The previous discussion implies Equation (3.5). Observe that for each $a \in$ $\Gamma(A)$

$$
c_{i_{\vec{a} \tau}}=\langle\tau(\vec{a}, \cdot, \ldots, \cdot), \cdot\rangle=\left(\mathcal{L}_{\vec{S}_{a}^{1}} c_{\tau}\right)=c_{\mathcal{T}(l(a))} \in C^{\infty}\left(\mathbb{G}_{\mathcal{E}}^{(p-1, q)}\right),
$$

then

$$
\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A c_{\tau}, S_{a}^{i}\right\rangle=\mathcal{L}_{\vec{S}_{a}^{i}} c_{\tau}=(-1)^{i-1} c_{\mathcal{T}(l(a))} \circ \pi_{(i)}=(-1)^{i-1} c_{l(a)} \circ \gamma_{(i)} .
$$

Hence Equation (3.4) holds. Finally we prove that the map $l$ is $C^{\infty}(M)$-linear. For $h \in C^{\infty}(M)$ we have

$$
\mathcal{T}(l(h a))=i_{\overrightarrow{h a}} \tau=\left(\mathrm{t}^{*} h\right) i_{\vec{a}} \tau=\left(\mathrm{t}^{*} h\right) \mathcal{T}(l(a))=\mathcal{T}(h l(a))
$$

where the last equality follows by (3.1). Since $\mathcal{T}$ is injective follows that $l(h a)=$ $h l(a)$.

Consider now a 1-form $\alpha \in \Omega^{1}(M)$ and let $S_{\alpha}$ be the corresponding core section of the cotangent algebroid $T^{*} A$. The local flow of the right invariant vector field $\overrightarrow{S_{\alpha}} \in \mathfrak{X}\left(T^{*} \mathcal{G}\right)$ associated to $S_{\alpha}$ is given by $\varphi_{S_{\alpha}}^{t}(\mu)=\mu+t\left(\mathbf{t}^{*} \alpha\right)$ for $\mu \in T_{g}^{*} \mathcal{G}$. Define a core section of $\mathbb{A}_{\mathcal{E}}$ by

$$
S_{\alpha}^{j}=(\underbrace{0, \ldots, 0}_{p}, \underbrace{0, \ldots, \overbrace{S_{\alpha}}^{j}, \ldots 0}_{q}, 0): \mathbb{M}_{\mathcal{E}} \longrightarrow \mathbb{A}_{\mathcal{E}}
$$

Then for a $\mathcal{E}$-valued multiplicative $(p, q)$-tensor $\tau$,

$$
\begin{aligned}
\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A c_{\tau}, S_{\alpha}^{j}\right\rangle\left(V^{p}, \mu^{q}, \eta\right) & =\left(\mathcal{L}_{\vec{S}_{\alpha}^{j}} c_{\tau}\right)\left(V^{p}, \mu^{q}, \eta\right) \\
& =\left.\frac{d}{d t}\right|_{t=0}\left\langle\tau\left(V^{p}, \mu_{1}, \ldots, \mu_{j}+t\left(\mathbf{t}^{*} \alpha\right), \mu_{j+1}, \ldots, \mu_{q}\right), \eta\right\rangle \\
& =\left\langle\tau\left(V^{p}, \mu_{1}, \ldots, \mu_{j-1},\left(\mathbf{t}^{*} \alpha\right), \mu_{j+1}, \ldots, \mu_{q}\right), \eta\right\rangle \\
& =(-1)^{j-1} c_{i_{\mathbf{t}^{*} \alpha}} \tau \circ \pi_{(j)}^{*}\left(V^{p}, \mu^{q}, \eta\right),
\end{aligned}
$$

where $i_{t^{*} \alpha} \tau:=\tau(\underbrace{}_{p}, \ldots, \cdot, \mathbf{t}^{*} \alpha, \cdot, \ldots, \cdot)$ and where $\pi_{(j) *}^{(p, q)}: \mathbb{G}_{\mathcal{E}}^{(p, q)} \longrightarrow \mathbb{G}_{\mathcal{E}}^{(p, q-1)}$ is the forgetful map with respect to the $j$-entry of $\bigoplus_{q} T^{*} \mathcal{G}$. Taking now units $\left(v^{p}, \nu^{q}, \xi\right) \in$ $\mathbb{M}_{\mathcal{E}}$ then

$$
\begin{aligned}
\left\langle A c_{\tau}, S_{\alpha}^{j}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) & =\left(\mathcal{L}_{\overrightarrow{S_{\alpha}^{\alpha}}} c_{\tau}\right)\left(v^{p}, \nu^{q}, \xi\right) \\
& =\left\langle\tau\left(v^{p}, \nu_{1}, \ldots, \nu_{j-1},\left(\mathbf{t}^{*} \alpha\right), \nu_{j+1}, \ldots, \nu_{q}\right), \xi\right\rangle \\
& =(-1)^{j-1}\left\langle\tau\left(v^{p},\left(\mathbf{t}^{*} \alpha\right), \nu_{1}, \ldots, \nu_{j-1}, \nu_{j+1}, \ldots, \nu_{q}\right), \xi\right\rangle
\end{aligned}
$$

This last equation implies that $\left\langle A c_{\tau}, S_{\alpha}^{j}\right\rangle$ is a componentwise linear function of $\gamma_{(j)}^{*}\left(v^{p}, \nu, \xi\right) \in \mathbb{M}_{\mathcal{E}}^{(p, q-1)}$, where

$$
\gamma_{(j) *}^{(p, q)}: \mathbb{M}_{\mathcal{E}}^{(p, q)} \longrightarrow \mathbb{M}_{\mathcal{E}}^{(p, q-1)}
$$

is the forgetful map with respect to the $j$-entry of $\bigoplus_{q} T^{*} A$. Thus there is a $r(\alpha) \in$ $\Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q-1} A \otimes C\right)$ such that

$$
\begin{equation*}
\left\langle A c_{\tau}, S_{\alpha}^{j}\right\rangle=(-1)^{j-1} c_{r(\alpha)} \circ \gamma_{(j)}^{*} . \tag{3.6}
\end{equation*}
$$

Proposition 3.8. For any multiplicative $\mathcal{E}$-valued $(p, q)$-tensor $\tau$ on $\mathcal{G}$ we have that

$$
\begin{equation*}
\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A c_{\tau}, S_{\alpha}^{j}\right\rangle=(-1)^{j-1} c_{i_{\mathfrak{t}^{*} \alpha} \tau} \circ \pi_{(j)}^{*}, \tag{3.7}
\end{equation*}
$$

In particular there exists vector bundle morphism $r: T^{*} M \longrightarrow \wedge^{p} T^{*} M \otimes \wedge^{q-1} A \otimes C$ such that

$$
\begin{equation*}
\left\langle A c_{\tau}, S_{\alpha}^{j}\right\rangle=(-1)^{j-1} c_{r(\alpha)} \circ \gamma_{(j)}^{*} . \tag{3.8}
\end{equation*}
$$

Proof. The proof is analogous to the Proposition 3.7. Note that the following equation holds

$$
\begin{equation*}
i_{t^{*} \alpha} \tau=\mathcal{T}(r(\alpha)) \tag{3.9}
\end{equation*}
$$

Finally, let $\zeta: M \longrightarrow E^{*}$ be a section of the core bundle $E^{*}$ and let $S_{\zeta}: C^{*} \longrightarrow$ $A_{\mathcal{E}^{*}}$ be the core section of $A_{\mathcal{E}^{*}}$ over $C^{*}$ associated to $\zeta$. Since $\tau$ is an $\mathcal{E}$-valued multiplicative $(p, q)$-tensor, we have

$$
\begin{aligned}
\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A c_{\tau}, S_{\zeta}\right\rangle\left(V^{p}, \mu^{q}, \eta\right) & =\mathcal{L}_{\vec{S}_{\zeta}} c_{\tau}\left(V^{p}, \mu^{q}, \eta\right) \\
& =\left.\frac{d}{d t}\right|_{t=0}\left\langle\tau\left(V^{p}, \mu^{q}\right), \eta+t \zeta^{\mathcal{E}}(g)\right\rangle \\
& =\left\langle\tau\left(V^{p}, \mu^{q}\right), \zeta^{\mathcal{E}}\right\rangle \\
\text { by property of units } & =\left\langle\bar{t}\left(\tau\left(V^{p}, \mu^{q}\right)\right) \cdot \tau\left(V^{p}, \mu^{q}\right), \zeta(\mathbf{t}(g)) \cdot 0_{g}\right\rangle \\
\text { by multiplication in the dual } & \left.=\left\langle\bar{t}\left(\tau\left(V^{p}, \mu^{q}\right)\right), \zeta(\mathbf{t}(g))\right\rangle+\left\langle\tau\left(V^{p}, \mu^{q}\right)\right), 0_{g}\right\rangle \\
& =\left\langle\bar{t}\left(\tau\left(V^{p}, \mu^{q}\right)\right), \zeta(\mathbf{t}(g))\right\rangle \\
& =c_{F}\left(\mathbb{T}\left(V^{p}, \mu^{q}\right), \zeta(\mathbf{t}(g))\right)
\end{aligned}
$$

where $c_{F}: \mathbb{M}_{\mathcal{E}}^{(p, q)} \longrightarrow \mathbb{R}$ is the componentwise linear function defined on the units of $\mathbb{G}_{\mathcal{E}}^{(p, q)}$ covered by $c_{\tau}$. Hence $c_{F}$ has associated a multilinear map $F: \bigotimes_{p} T M \otimes$ $\otimes_{q} A^{*} \longrightarrow E$. Then taking units $\left(v^{p}, \nu^{q}, \xi\right) \in \mathbb{M}_{\mathcal{E}}$ we have

$$
\left\langle A c_{\tau}, S_{\zeta}\right\rangle\left(v^{p}, \nu^{q}, \xi\right)=\left\langle F\left(v^{p}, \nu^{q}\right), \zeta\right\rangle=\left\langle\left(v^{p}, \nu^{q}\right), F^{*}(\zeta)\right\rangle .
$$

The previous discussion is the proof of the following proposition
Proposition 3.9. For any multiplicative $\mathcal{E}$-valued $(p, q)$-tensor $\tau$ on $\mathcal{G}$ we have that

$$
\begin{equation*}
\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A \ell_{\tau}, S_{\zeta}\right\rangle=\langle F \circ \mathbb{T}, \zeta\rangle \circ \gamma=\left\langle\mathbb{T}, F^{*}(\zeta)\right\rangle \circ \gamma, \tag{3.10}
\end{equation*}
$$

where $\gamma: \mathbb{G}_{\mathcal{E}}^{(p, q)} \longrightarrow \mathbb{G}^{(p, q)}$ forgets the last component. Moreover there exist a section $\sigma(\zeta)=F^{*}(\zeta) \in \Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q} A\right)$ such that

$$
\begin{equation*}
c_{\mathcal{T}(\sigma(\zeta))}=\langle F \circ \mathbb{T}, \zeta\rangle=\left\langle\mathbb{T}, F^{*}(\zeta)\right\rangle \tag{3.11}
\end{equation*}
$$

Equivalently to Equation (3.11) we have

$$
i_{\zeta} \varepsilon \tau=\mathcal{T}\left(F^{*}(\zeta)\right),
$$

where $i_{\zeta} \varepsilon \tau \in \Gamma\left(\wedge^{p} T \mathcal{G} \otimes \wedge^{q} T^{*} \mathcal{G}\right)$ means

$$
c_{i_{\varsigma} \mathcal{E} \tau}\left(V^{p}, \mu^{q}\right)=\left\langle\tau\left(V^{p}, \mu^{q}\right), \zeta^{\mathcal{E}}(g)\right\rangle .
$$

### 3.1.2 Linear sections

We keep with a fix $\mathcal{E}$-valued multiplicative $(p, q)$-tensor $\tau$. Let $X_{a}$ be a linear section of $A_{\mathcal{E}^{*}}$ over $C^{*}$ covering a section $a \in \Gamma(A)$. We define a linear section of $\mathbb{A}_{\mathcal{E}}^{(p, q)}$ over $\mathbb{M}_{\mathcal{E}}^{(p, q)}$, which covers $a$, by

$$
\chi_{a}=(\underbrace{T a, \ldots, T a}_{p-\text { times }}, \underbrace{R_{a}, \ldots, R_{a}}_{q-\text { times }}, X_{a})=\left((T a)^{p},\left(R_{a}\right)^{q}, X_{a}\right) .
$$

The right invariant vector field associated to it is

$$
\overrightarrow{\chi_{a}}=\left((\overrightarrow{T a})^{p},\left((\vec{a})^{T^{*}}\right)^{q}, \overrightarrow{X_{a}}\right),
$$

and since this vector field is linear there exists a derivation $D_{\chi_{a}} \in \operatorname{Der}\left(\mathbb{G}_{\mathcal{E}}^{(p, q)^{*}}\right)$ such that

$$
\begin{equation*}
\mathcal{L}_{\overrightarrow{\chi_{a}}} c_{\tau}=\overrightarrow{\chi_{a}}\left(c_{\tau}\right)=c_{D_{\chi a}(\tau)} . \tag{3.12}
\end{equation*}
$$

Since $\tau$ is an $\mathcal{E}$-valued multiplicative $(p, q)$-tensor, we have

$$
\begin{equation*}
\mathcal{L}_{\overrightarrow{\chi_{a}}} c_{\tau}=\overrightarrow{\chi_{a}}\left(c_{\tau}\right)=c_{D_{X_{a}}(\tau)}=\left(\mathbb{T}_{\mathcal{E}}^{(p, q)}\right)^{*}\left\langle A c_{\tau}, \chi_{a}\right\rangle \tag{3.13}
\end{equation*}
$$

Remark 3.10. When we do not need to remark the section of $A$ which is covered by a linear section of $\mathbb{A}_{\mathcal{E}}$, we just write $X$ for the linear section of $\mathbb{A}_{\mathcal{E}}$, and $\chi$ for the linear section of $\mathbb{A}_{\mathcal{E}}^{(p, q)}$ built from $X$.

Proposition 3.11. Let $\mathcal{E} \rightrightarrows E$ be a VB-groupoid over $\mathcal{G}$. For any multiplicative $\mathcal{E}$-valued $(p, q)$-tensor $\tau$ on $\mathcal{G}$ one has that

$$
\begin{equation*}
\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A c_{\tau}, \chi\right\rangle=c_{D_{\chi}(\tau)} \tag{3.14}
\end{equation*}
$$

In particular there exists an operator $\mathbf{D}: \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}^{*}}\right) \longrightarrow \Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q} A \otimes C\right)$ such that

$$
\begin{equation*}
\left\langle A c_{\tau}, \chi\right\rangle=c_{\mathbf{D}(X)}, \tag{3.15}
\end{equation*}
$$

or equivalently

$$
\begin{equation*}
\mathcal{L}_{\vec{\chi}} c_{\tau}=c_{\mathcal{T}(\mathbf{D}(X))}, \tag{3.16}
\end{equation*}
$$

and satisfying the following Leibniz rule for $f \in C^{\infty}(M)$

$$
\begin{equation*}
\mathbf{D}\left(f X_{a}\right)=f \mathbf{D}\left(X_{a}\right)+d f \wedge l(a)-a \wedge r(d f) \tag{3.17}
\end{equation*}
$$

Remark 3.12. An explanation about the notation. Let $f \in C^{\infty}(M)$. The expressions $\mathrm{d} f \wedge l(a), a \wedge r(\mathrm{~d} f) \in \Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q} A \otimes C\right)$ mean:

$$
\begin{aligned}
& \left\langle\mathrm{d} f \wedge l(a),\left(v^{p}, \nu^{q}, \xi\right)\right\rangle=\sum_{i=1}^{p}(-1)^{i-1} \mathrm{~d} f\left(v_{i}\right)\left\langle l(a),\left(v_{1}, \ldots, \widehat{v_{i}}, \ldots v_{p}, \nu^{q}, \xi\right)\right\rangle \\
& \left\langle a \wedge r(\mathrm{~d} f),\left(v^{p}, \nu^{q}, \xi\right)\right\rangle=\sum_{i=1}^{q}(-1)^{i-1}\left\langle a, \nu_{i}\right\rangle\left\langle r(\mathrm{~d} f),\left(v^{p}, \nu_{1}, \ldots, \widehat{\nu_{i}}, \ldots, \xi\right)\right\rangle .
\end{aligned}
$$

Proof. Since $\tau$ is multiplicative the Equation (3.13) holds for any linear section $\chi \in$ $\Gamma\left(\mathbb{A}_{\mathcal{E}}, \mathbb{M}_{\mathcal{E}}^{(p, q)}\right)$. And combining with (3.12), then the Equation (3.14) follows. Also Equation (3.13) implies, taking units, that the function $\left\langle A c_{\tau}, \chi\right\rangle$ is multilinear in $C^{\infty}\left(\left(\oplus^{p} T M\right) \oplus\left(\oplus^{q} A^{*}\right) \oplus C^{*}\right)$. Then there exists a section $\mathbf{D}(\chi) \in \Gamma\left(\wedge^{p} T^{*} M \otimes\right.$ $\left.\wedge^{q} A \otimes C\right)$ such that the Equation (3.15) holds. Using now the Proposition 3.4, we get the Equation (3.16). Finally we prove the Leibniz rule. For $f \in C^{\infty}(M)$ and $X_{a} \in \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}^{*}}, C^{*}\right)$ we have

$$
\begin{aligned}
c_{\mathbf{D}\left(f X_{a}\right)}(v, \nu, c)= & \left\langle A c_{\tau},\left((T(f a))^{p},\left(R_{f a}\right)^{q}, f X_{a}\right)\right\rangle\left(v^{p}, \nu^{q}, \xi\right) \\
= & \left\langle A c_{\tau},\left(\left(f T a+\ell_{\mathrm{d} f} S_{a}\right)^{p},\left(f R_{a}+\ell_{-a} S_{\mathrm{d} f}\right)^{q}, f X_{a}\right)\right\rangle\left(v^{p}, \nu^{q}, \xi\right) \\
= & \left\langle A c_{\tau},\left((f T a)^{p},\left(f R_{a}\right)^{q}, f X_{a}\right)+\left(\left(\ell_{\mathrm{d} f} S_{a}\right)^{p},\left(\ell_{-a} S_{\mathrm{d} f}\right)^{q}, 0\right)\right\rangle\left(v^{p}, \nu^{q}, \xi\right) \\
= & \left\langle A c_{\tau},\left((f T a)^{p},\left(f R_{a}\right)^{q}, f X_{a}\right)\right\rangle\left(v^{p}, \nu^{q}, \xi\right) \\
& +\left\langle A c_{\tau},\left(\left(\ell_{\mathrm{d} f} S_{a}\right)^{p},\left(\ell_{-a} S_{\mathrm{d} f}\right)^{q}, 0\right)\right\rangle\left(v^{p}, \nu^{q}, \xi\right) \\
= & f\left\langle A c_{\tau},\left((T a)^{p},\left(R_{a}\right)^{q}, X_{a}\right)\right\rangle\left(v^{p}, \nu^{q}, \xi\right)+\left\langle A c_{\tau},\left(\ell_{\mathrm{d} f} S_{a}\right)^{p}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) \\
& +\left\langle A c_{\tau},\left(\ell_{-a} S_{\left.\mathrm{d} f)^{q}\right\rangle\left(v^{p}, \nu^{q}, \xi\right)}^{=}\right.\right. \\
= & f c_{\mathbf{D}\left(X_{a}\right)}\left(v^{p}, \nu^{q}, \xi\right)+\sum_{i=1}^{p}\left\langle A c_{\tau}, \ell_{\mathrm{d} f} S_{a}^{i}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) \\
& +\sum_{i=1}^{q}\left\langle A c_{\tau}, \ell_{-a} S_{\mathrm{d} f}^{i}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) \\
= & f c_{\mathbf{D}\left(X_{a}\right)}\left(v^{p}, \nu^{q}, \xi\right) \\
& +\sum_{i=1}^{p}(-1)^{i-1} \mathrm{~d} f\left(v_{i}\right)\left\langle l(a),\left(v_{1}, \ldots, \widehat{v_{i}}, \ldots v_{p}, \nu^{q}, \xi\right)\right\rangle \\
& -\sum_{i=1}^{q}(-1)^{i-1}\left\langle a, \nu_{i}\right\rangle\left\langle r(\mathrm{~d} f),\left(v^{p}, \nu_{1}, \ldots, \widehat{\nu_{i}}, \ldots, \xi\right)\right\rangle \\
= & \left(f c_{\mathbf{D}\left(X_{a}\right)}+c_{\mathrm{d} f \wedge l(a)}-c_{a \wedge r(\mathrm{~d} f)}\right)\left(v^{p}, \nu^{q}, \xi\right)
\end{aligned}
$$

where we used that

$$
\begin{aligned}
\left\langle A c_{\tau}, \ell_{\mathrm{d} f} S_{a}^{i}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) & =(-1)^{i-1} \mathrm{~d} f\left(v_{i}\right) c_{l(a)} \circ \gamma_{(i)}\left(v^{p}, \nu^{q}, \xi\right) \\
\left\langle A c_{\tau}, \ell_{-a} S_{\mathrm{d} f}^{i}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) & =(-1)^{i-i}\left\langle-a, \nu_{i}\right\rangle c_{r(\mathrm{~d} f)} \circ \gamma_{(j)}^{*}\left(v^{p}, \nu^{q}, \xi\right)
\end{aligned}
$$

Therefore the Leibniz rule holds.

Now we proof the main theorem
Proof. Proposition 3.6. If $\tau$ is an $\mathcal{E}$-valued multiplicative $(p, q)$-tensor on $\mathcal{G}$, then Propositions 3.11, 3.7, 3.8 and 3.9 show the existence of $(\mathbf{D}, l, r, F)$ satisfying the Equations (3.2). Conversely, let ( $\mathbf{D}, l, r, F)$ satisfying those conditions. We will define a function $\lambda \in C^{\infty}\left(\mathbb{A}_{\mathcal{E}}^{(p, q)}\right)$ which is a cocycle. Recall that we have an injective map

$$
\begin{aligned}
\Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}^{*}}, C^{*}\right) & \longrightarrow \Gamma_{\operatorname{lin}}\left(\mathbb{A}_{\mathcal{E}}^{(p, q)}, \mathbb{M}_{\mathcal{E}}^{(p, q)}\right) \\
X_{a} & \longrightarrow \chi_{a}:=\left((T a)^{p},\left(R_{a}\right)^{q}, X_{a}\right) .
\end{aligned}
$$

The function $\lambda$ is determined by

$$
\begin{aligned}
\langle\lambda, \chi\rangle & =c_{\mathbf{D}(X)} \\
\left\langle\lambda, S_{a}^{i}\right\rangle & =(-1)^{i-1} c_{l(a)} \circ \gamma_{(i)} \\
\left\langle\lambda, S_{\alpha}^{j}\right\rangle & =(-1)^{j-1} c_{r(\alpha)} \circ \gamma_{(j)}^{*} \\
\left\langle\lambda, S_{\zeta}\right\rangle & =c_{F^{*}(\zeta)} \circ \gamma
\end{aligned}
$$

where $\alpha \in \Omega^{1}(M)$ and $\zeta \in \Gamma\left(E^{*}\right)$. In the case of linear sections, it is enough to define $\lambda$ only in sections $\chi_{a}$ coming from $X_{a} \in \Gamma_{\operatorname{lin}}\left(A_{\mathcal{E}^{*}}, C^{*}\right)$. Since $\left(f \circ q_{C}^{*}\right) X_{a}$ is also a linear section of $A_{\mathcal{E}^{*}}$ over $C^{*}$, the action of $\lambda$ on the section $\chi$ associated to $\left(f \circ q_{C}^{*}\right) X_{a}$ is given by the Leibniz rule satisfied by $\mathbf{D}$. Hence $\lambda$ is well defined and it can be extended to all section of $\mathbb{A}_{\mathcal{E}}^{(p, q)}$ by $C^{\infty}\left(\mathbb{M}_{\mathcal{E}}^{(p, q)}\right)$-linearity. Moreover

$$
\mathcal{L}_{\overrightarrow{\chi_{a}}} c_{\tau}=c_{D\left(X_{a}\right)(\tau)}=c_{\mathcal{T}\left(D\left(X_{a}\right)\right)}=\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left(c_{D\left(X_{a}\right)}\right)=\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A c_{\tau}, \chi_{a}\right\rangle
$$

A similar argument shows that $\mathcal{L}_{\vec{S}_{b}^{i}} c_{\tau}=\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A c_{\tau}, S_{b}^{i}\right\rangle, \mathcal{L}_{\vec{S}_{\alpha}^{j}} c_{\tau}=\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A c_{\tau}, S_{\alpha}^{j}\right\rangle$ and $\mathcal{L}_{\vec{S}_{\zeta}} c \ell_{\tau}=\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A c_{\tau}, S_{\zeta}\right\rangle$. Then by linearity, we have that

$$
\mathcal{L}_{\vec{\chi}} c_{\tau}=\left(\mathbb{T}_{\mathcal{E}}\right)^{*}\left\langle A c_{\tau}, \chi\right\rangle
$$

for all section $\chi \in \Gamma\left(\mathbb{A}_{\mathcal{E}}^{(p, q)}\right)$. Since $\mathbb{G}_{\mathcal{E}}^{(p, q)}$ is source connected, the result follows by Proposition (1.11).

### 3.2 IM equations

Let $(A, \rho,[\cdot, \cdot])$ be a Lie algebroid over $M$, and let $\mathcal{A} \longrightarrow E$ be a VB-algebroid over $A \longrightarrow M$ with core bundle $C \longrightarrow M$. In this section we study tensor fields on $A$ with coefficient in $\mathcal{A}$ which are compatible with the Lie algebroid structure of $A$. We give a description of these tensors in terms of an infinitesimal data, and then we establish a correspondence with multiplicative tensor fields.

A $(p, q)$-tensor on $A$ with coefficients in a vector bundle $\mathcal{A}$ is a section $\phi \in$ $\Gamma\left(\wedge^{p} T^{*} A \otimes \wedge^{q} T A \otimes \mathcal{A}\right)$. As in the previous section, we associate to $\phi$ a componentwise linear function $c_{\phi}: \mathbb{A}_{\mathcal{A}}^{(p, q)}:=\left(\bigoplus_{p} T A\right) \oplus\left(\bigoplus_{q} T^{*} A\right) \oplus \mathcal{A}^{*} \longrightarrow \mathbb{R}$ defined by

$$
c_{\phi}\left(Y^{p}, \mu^{q}, \zeta\right)=\left\langle\phi\left(Y^{p}, \mu^{q}\right), \zeta\right\rangle .
$$

In the case when $\mathcal{A}$ is a VB-algebroid, the space $\mathbb{A}_{\mathcal{A}}^{(p, q)}$ is also a VB-algebroid over $A$.
Definition 3.13. A $(p, q)$-tensor $\phi$ on $A$ with coefficients in a VB-algebroid $\mathcal{A}$ is called Lie algebroid tensor if its associated componentwise linear function $c_{\phi}$ is a Lie algebroid cocycle on $\mathbb{A}_{\mathcal{A}}^{(p, q)}$.

The function $c_{\phi} \in C^{\infty}\left(\mathbb{A}_{\mathcal{A}}^{(p, q)}\right)$ is a Lie algebroid cocycle if and only if $d_{\mathbb{A}} c_{\phi}=0$, where $d_{\mathbb{A}}$ is the Lie algebroid differential of $\mathbb{A}_{\mathcal{A}}^{(p, q)}$. This is equivalent to

$$
\begin{equation*}
\left\langle c_{\phi},[U, V]\right\rangle=\mathcal{L}_{\rho_{\mathrm{A}}(U)}\left\langle c_{\phi}, V\right\rangle-\mathcal{L}_{\rho_{\mathrm{A}}(V)}\left\langle c_{\phi}, U\right\rangle . \tag{3.18}
\end{equation*}
$$

where $\rho_{\mathbb{A}}$ is the anchor map of the Lie algebroid $\mathbb{A}_{\mathcal{A}}^{(p, q)}$. Since $\mathbb{A}_{\mathcal{A}}^{(p, q)}$ is also a VBalgebroid over $A$ it is enough to check Equation (3.18) for core and linear sections. Because of that we define first an infinitesimal tensor in terms of these kinds of sections, and then we give the correspondence with Lie algebroid tensors.

Recall that given the VB-algebroid $\mathcal{A}^{*} \longrightarrow C^{*}$, dual of the VB-algebroid $\mathcal{A} \longrightarrow$ $E$, it has canonical operators (see (1.23) and (1.22)) which we denote by

- $\partial^{*}: E^{*} \longrightarrow C^{*}$
- $\left(\widetilde{\nabla}^{0}\right): \Gamma_{\operatorname{lin}}\left(\mathcal{A}^{*}, C^{*}\right) \times \Gamma\left(E^{*}\right) \longrightarrow \Gamma\left(E^{*}\right)$.

Also we have an injective map $\Gamma_{\operatorname{lin}}\left(\mathcal{A}^{*}, C^{*}\right) \longrightarrow \Gamma_{\operatorname{lin}}\left(\mathbb{A}_{\mathcal{A}}^{(p, q)}, \mathbb{M}_{\mathcal{E}}^{(p, q)}\right)$ given by

$$
X_{a} \longrightarrow \chi_{a}:=\left((T a)^{p},\left(R_{a}\right)^{p}, X_{a}\right) .
$$

Definition 3.14. An $\mathcal{A}$-valued $(p, q)$-tensor on $A$ is a quadruple $(\mathbf{D}, l, r, \sigma)$ where

- $\mathbf{D}: \Gamma_{\operatorname{lin}}\left(\mathcal{A}^{*}, C^{*}\right) \longrightarrow \Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q} A \otimes C\right)$
- $l: A \longrightarrow \wedge^{p-1} T^{*} M \otimes \wedge^{q} A \otimes C$
- $r: T^{*} M \longrightarrow \wedge^{p} T^{*} M \otimes \wedge^{q-1} A \otimes C$
- $\sigma: E^{*} \longrightarrow \wedge^{p} T^{*} M \otimes \wedge^{q} A$
satisfying the Leibniz rule

$$
\begin{equation*}
\mathbf{D}\left(f X_{a}\right)=f \mathbf{D}\left(X_{a}\right)+\mathrm{d} f \wedge l(a)-a \wedge r(\mathrm{~d} f), \tag{3.19}
\end{equation*}
$$

the compatibility condition

$$
\begin{equation*}
\mathbf{D}\left(S_{T}\right)=\sigma \circ T \quad \text { for } T \in \Gamma\left(\operatorname{Hom}\left(C^{*}, E^{*}\right)\right) \tag{3.20}
\end{equation*}
$$

and the following equations

$$
\begin{align*}
\mathbf{D}\left(\left[X_{a}, X_{b}\right]\right) & =X_{a} \cdot \mathbf{D}\left(X_{b}\right)-X_{b} \cdot \mathbf{D}\left(X_{a}\right)  \tag{3.21}\\
i_{\rho(b)} \mathbf{D}\left(X_{a}\right) & =X_{a} \cdot l(b)-l([a, b])  \tag{3.22}\\
i_{\rho^{*}(\beta)} \mathbf{D}\left(X_{a}\right) & =X_{a} \cdot r(\beta)-r\left(\mathcal{L}_{\rho(a)} \beta\right)  \tag{3.23}\\
i_{\partial^{*}(\gamma)} \mathbf{D}\left(X_{a}\right) & =X_{a} \cdot \sigma(\gamma)-\sigma\left(\left(\nabla^{1}\right)_{X_{a}}^{*} \gamma\right)  \tag{3.24}\\
i_{\rho(a)} l(b) & =-i_{\rho(b)} l(a)  \tag{3.25}\\
i_{\rho^{*}(\alpha) r} r(\beta) & =-i_{\rho^{*}(\beta)} r(\alpha)  \tag{3.26}\\
i_{\rho(a)} r(\beta) & =i_{\rho^{*}(\beta)} l(a)  \tag{3.27}\\
i_{\partial^{*}(\gamma)} l(a) & =i_{\rho(a)} \sigma(\gamma)  \tag{3.28}\\
i_{\rho^{*}(\alpha)} \sigma(\gamma) & =i_{\partial^{*}(\gamma)} r(\alpha) . \tag{3.29}
\end{align*}
$$

for $X_{a}, X_{b} \in \Gamma_{\text {lin }}\left(\mathcal{A}^{*}, C^{*}\right) ; a, b \in \Gamma(A) ; \alpha, \beta \in \Omega^{1}(M)$ and $\zeta \in \Gamma\left(E^{*}\right)$.
Remark 3.15. The notation $X_{a} \cdot \mathbf{D}\left(X_{b}\right)$ if for a module structure on $\Gamma\left(\left(\otimes^{p} T^{*} M\right) \otimes\right.$ $\left.\left(\otimes^{q} A\right) \otimes C\right)$ over $\Gamma_{\text {lin }}\left(\mathcal{A}^{*}, C^{*}\right)$. Its definition together with its properties, which we will use in the next proposition, are in the Appendix.

Proposition 3.16. There is a one-to-one correspondence between Lie algebroid $(p, q)$-tensor on $A$ with coefficients in $\mathcal{A}$ and $\mathcal{A}$-valued $(p, q)$-tensor on $A$.

Proof. Let $\phi$ be a Lie algebroid $(p, q)$-tensor on $A$ with coefficients in $\mathcal{A}$ and consider its associated componentwise linear function $c_{\phi}$. We define $\mathbf{D}: \Gamma_{\operatorname{lin}}\left(\mathcal{A}^{*}, C^{*}\right) \longrightarrow$ $\Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q} A \otimes C\right)$ by

$$
c_{\mathbf{D}\left(X_{a}\right)}:=c_{\phi}\left(\chi_{a}\right),
$$

where $a \in \Gamma(A)$. Consider the core section $S_{a}^{1}$. Then the function $\left\langle\phi, S_{a}^{1}\right\rangle$ is multilinear on $\mathbb{M}_{\mathcal{A}}^{(p-1, q)}$, so there exists a section $l(a) \in \Gamma\left(\wedge^{p-1} T^{*} M \otimes \wedge^{q} A \otimes C\right)$ such that

$$
\left\langle\phi, S_{a}^{1}\right\rangle=c_{l(a)} \circ \gamma_{(1)} .
$$

Hence we have that $\left\langle\phi, S_{a}^{i}\right\rangle=(-1)^{i-1} c_{l(a)} \circ \gamma_{(i)}$. Note that

$$
\left\langle\phi, S_{h a}^{1}\right\rangle=\left\langle\phi,(h \circ \widetilde{q}) S_{a}^{1}\right\rangle=(h \circ \widetilde{q})\left\langle\phi, S_{a}^{1}\right\rangle,
$$

where $\widetilde{q}: \mathbb{M}_{\mathcal{E}}^{(p, q)} \longrightarrow M$ is the projection, which implies that $l(f a)=f l(a)$. Taking now core sections of the form $S_{\alpha}^{i}$ and $S_{\zeta}$, with $\alpha \in \Omega^{1}(M)$ and $\zeta \in \Gamma\left(E^{*}\right)$, we get the
maps $r$ and $\sigma$, respectively. Now we check the equations. First we start with linear sections. For $\chi_{a}$ and $\chi_{b}$ we have

$$
\left[\chi_{a}, \chi_{b}\right]=\left[\left((T a)^{p},\left(R_{a}\right)^{q}, X_{a}\right),\left((T b)^{p},\left(R_{b}\right)^{q}, X_{b}\right)\right]=\left((T[a, b])^{p},\left(R_{[a, b]}\right)^{q},\left[X_{a}, X_{b}\right]\right)
$$

then

$$
\begin{aligned}
c_{\mathbf{D}\left(\left[X_{a}, X_{b}\right]\right)} & =\mathcal{L}_{\rho_{\mathrm{A}}\left(X_{a}\right)} c_{\mathbf{D}\left(X_{b}\right)}-\mathcal{L}_{\rho_{\mathrm{A}}\left(X_{b}\right)} c \ell_{\mathbf{D}\left(X_{a}\right)} \\
& =c_{X_{a} \cdot \mathbf{D}\left(X_{b}\right)}-c_{X_{b}} \cdot \mathbf{D}\left(X_{a}\right) .
\end{aligned}
$$

Then the Equation (IM1) holds. For Equation (IM2) we consider a linear section $\chi_{a}$ and a core section $S_{b}^{1}$. The two terms of right side of (3.18) are

$$
\begin{aligned}
\mathcal{L}_{\rho_{\mathbb{A}}\left(\chi_{a}\right)}\left\langle c_{\phi}, S_{b}^{1}\right\rangle & =\mathcal{L}_{\left(\left(\rho(a)^{T}\right)^{p},\left(H_{a}\right)^{q}, \rho_{\mathcal{A}^{*}}\left(X_{a}\right)\right)}\left(c_{l(b)} \circ \gamma_{(1)}\right) \\
& =\left(\mathcal{L}_{\left(0,\left(\rho(a)^{T}\right)^{p-1},\left(H_{a}\right)^{q}, \rho_{\mathcal{A}^{*}}\left(X_{a}\right)\right)} c_{l(b)}\right) \circ \gamma_{(1)} \\
& =c_{X_{a} \cdot l(b)} \circ \gamma_{(1)} . \\
\mathcal{L}_{\left.(\rho(b))^{\uparrow}, 0,0\right)}\left\langle c_{\phi}, \chi_{a}\right\rangle & =\mathcal{L}_{\left.\left(\rho(b)^{\uparrow}, 0,0\right)\right)^{c}} c_{\mathbf{D}\left(X_{a}\right)} \\
& =\left\langle\mathbf{D}\left(X_{a}\right), \rho_{A}(b)\right\rangle \circ \gamma_{(1)} \\
& =c_{i_{\rho(b)} \mathbf{D}\left(X_{a}\right)} \circ \gamma_{(1)} .
\end{aligned}
$$

while in the left-han side is

$$
\left\langle c_{\phi},\left[\chi_{a}, S_{b}^{1}\right]\right\rangle=\left\langle c_{\phi}, S_{([a, b]}^{1}\right\rangle=c_{l([a, b])} \circ \gamma_{(1)}
$$

which proves the Equation (IM2). Now take a linear section $\chi_{a}$ and a core section $S_{\beta}^{1}$. Then the right side of (3.18) has terms

$$
\begin{aligned}
\mathcal{L}_{\rho_{A}\left(\chi_{a}\right)}\left\langle c_{\phi}, S_{\beta}^{1}\right\rangle & =\mathcal{L}_{\left(\left(\rho(a)^{T}\right)^{p},\left(H_{a}\right)^{q}, \rho_{\mathcal{A}^{*}}\left(X_{a}\right)\right)}\left(c_{r(\beta)} \circ \gamma_{(1)}^{*}\right) \\
& =\left(\mathcal{L}_{\left(\left(\rho(a)^{T}\right)^{p}, 0,\left(H_{a}\right)^{q-1}, \rho_{\mathcal{A}^{*}}\left(X_{a}\right)\right)} c_{r(\beta)}\right) \circ \gamma_{(1)}^{*} \\
& =c_{X_{X} \cdot r(\beta)} \circ \gamma_{(1)}^{*} . \\
\mathcal{L}_{\left(0, \rho^{*}(\beta)^{\uparrow}, 0\right)}\left\langle c_{\phi}, \chi_{a}\right\rangle & =\mathcal{L}_{\left(0, \rho^{*}(\beta)^{\uparrow}, 0\right)}\left(c_{\mathbf{D}\left(X_{a}\right)} \circ \gamma_{(1)}^{*}\right) \\
& =\left\langle\mathbf{D}\left(X_{a}\right), \rho^{*}(\beta)\right\rangle \circ \gamma_{(1)}^{*} \\
& =c_{i_{\rho^{*}(\beta)}} \mathbf{D}\left(X_{a}\right) \circ \gamma_{(1)}^{*} .
\end{aligned}
$$

The left-hand side is

$$
\left\langle c_{\phi},\left[\chi_{a}, S_{\beta}^{1}\right]\right\rangle=\left\langle c_{\phi},\left[R_{a}, \beta\right]\right\rangle=\left\langle c_{\phi}, S_{\left(\mathcal{L}_{\rho(a)} \beta\right)}\right\rangle=c_{r\left(\mathcal{L}_{\rho(a)} \beta\right)} \circ \gamma_{(1)}^{*} .
$$

Then Equation (IM3) holds. Taking now a linear section $\chi_{a}$ and a core section $S_{\zeta}$ we have

$$
\begin{aligned}
\mathcal{L}_{\rho_{\mathbb{A}}\left(\chi_{a}\right)}\left\langle c_{\phi}, S_{\zeta}\right\rangle & =\mathcal{L}_{\left(\left(\rho(a)^{T}\right)^{p},\left(H_{a}\right)^{q}, \rho_{\left.\mathcal{A}^{*}(X a)\right)}\right.}\left(c_{\sigma(\zeta)} \circ \gamma\right) \\
& =\left(\mathcal{L}_{\left(\left(\rho(a)^{T}\right)^{p},\left(H_{a}\right)^{q}, 0\right)} c_{\sigma(\zeta)}\right) \circ \gamma \\
& =c_{X_{a} \cdot \sigma(\zeta)} \circ \gamma \\
\mathcal{L}_{\left(0,0, \partial^{*}(\zeta)^{\uparrow}\right)}\left\langle c_{\phi}, \chi_{a}\right\rangle & =\left\langle\mathbf{D}\left(X_{a}\right), \partial^{*}(\zeta)\right\rangle \circ \gamma \\
& =c_{i_{\partial^{*}(\zeta)} \mathbf{D}\left(X_{a}\right)} \circ \gamma .
\end{aligned}
$$

and on the other side

$$
\left\langle c_{\phi},\left[\chi_{a}, S_{\zeta}\right]\right\rangle=\left\langle c_{\phi},\left[X_{a}, S_{\zeta}\right]\right\rangle=\left\langle c_{\phi}, S_{\left(\tilde{\nabla}^{0}\right)_{X_{a}} \zeta}\right\rangle=c_{\sigma\left(\left(\tilde{\nabla}^{0}\right)_{X_{a}} \zeta\right)} \circ \gamma .
$$

Therefore IM4 holds.
Now we will take only core sections. Since their brackets are zero, the left side of (3.18) will be always equal to zero. For sections $S_{a}^{1}$ and $S_{b}^{1}$ we have

$$
\begin{aligned}
\mathcal{L}_{\left(\rho(a)^{\uparrow}, 0,0\right)}\left\langle c_{\phi}, S_{b}^{2}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) & =\left.\frac{d}{d t}\right|_{t=0} c_{l(b)} \circ \gamma_{(2)}\left(v_{1}+t \rho(a), v_{2}, \ldots, v_{p}, \nu^{q}, \xi\right) \\
& =\left\langle l(b)\left(\rho(a), v_{2}, \ldots, v_{p}, \nu^{q}\right), \xi\right\rangle .
\end{aligned}
$$

Doing the same, interchanging $b$ with $a$, Equation (IM5) follows. In a similar way, taking now core sections of the form $S_{\alpha}^{1}$ and $S_{\beta}^{1}$, Equation (IM6) follows. If we take the core sections $S_{a}^{1}$ and $S_{\alpha}^{1}$ then

$$
\begin{aligned}
\mathcal{L}_{\left(\rho(a)^{\uparrow}, 0,0\right)}\left\langle c_{\phi}, S_{\alpha}^{1}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) & =\left.\frac{d}{d t}\right|_{t=0} c_{r(\alpha)} \circ \gamma_{(1)}^{*}\left(v_{1}+t \rho(a), v_{2}, \ldots, v_{p}, \nu^{q}, \xi\right) \\
& =\left\langle r(\alpha)\left(\rho(a), v_{2}, \ldots, v_{p}, \nu_{2}, \ldots, \nu_{q}\right), \xi\right\rangle . \\
\mathcal{L}_{\left(0, \rho^{*}(\alpha), 0\right)}\left\langle c_{\phi}, S_{a}^{1}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) & =\left.\frac{d}{d t}\right|_{t=0} c_{l(a)} \circ \gamma_{(1)}\left(v^{p}, \nu_{1}+t \rho^{*}(\alpha), \nu_{2}, \ldots, \nu_{q}, \xi\right) \\
& =\left\langle l(a)\left(v_{2}, \ldots, v_{p}, \rho^{*}(\alpha), \nu_{2}, \ldots, \nu_{q}\right), \xi\right\rangle .
\end{aligned}
$$

which proves Equation (IM7). For $S_{a}^{1}$ and $S_{\zeta}$

$$
\begin{aligned}
\mathcal{L}_{\rho_{\mathrm{A}}\left(S_{a}^{1}\right)}\left\langle c_{\phi}, S_{\zeta}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) & =\mathcal{L}_{\left((\rho(a))^{\uparrow}, 0,0\right)}\left\langle c_{\phi}, S_{\zeta}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) \\
& =\left.\frac{d}{d t}\right|_{t=0}\left\langle\left(v^{1}+t \rho(a), v^{2}, \ldots, v^{p}, \nu^{q}\right), \sigma(\zeta)\right\rangle \\
& =\left\langle\left(\rho(a), v^{2}, \ldots, v^{p}, \nu^{q}\right), \sigma(\zeta)\right\rangle \\
\mathcal{L}_{\rho_{\mathrm{A}}\left(S_{\zeta}\right)}\left\langle c_{\phi}, S_{a}^{1}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) & =\mathcal{L}_{\left(0,0, \partial^{*}(\zeta)^{\uparrow}\right)}\left(c_{l(a)} \circ \gamma_{(1)}\right)\left(v^{p}, \nu^{q}, \xi\right) \\
& =\left.\frac{d}{d t}\right|_{t=0}\left(c_{-} l(a) \circ \gamma_{(1)}\right)\left(v^{p}, \nu^{q}, \xi+t \partial^{*}(\zeta)\right) \\
& =\left(c_{l(a)} \circ \gamma_{(1)}\right)\left(v^{p}, \nu^{q}, \partial^{*}(\zeta)\right) \\
& =\left\langle l(a)\left(v^{2}, \ldots, v^{p}, \nu^{q}\right), \partial^{*}(\zeta)\right\rangle
\end{aligned}
$$

Therefore Equation (IM8) follows. Finally, consider $S_{\alpha}^{1}$ and $S_{\zeta}$. Then

$$
\begin{aligned}
\mathcal{L}_{\left(0,0, \partial^{*}(\zeta)^{\uparrow}\right)}\left\langle c_{\phi}, S_{\alpha}^{1}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) & =\left.\frac{d}{d t}\right|_{t=0} c_{r(\alpha)} \circ \gamma_{(1)}^{*}\left(v^{p}, \nu^{q}, \xi+t \partial^{*}(\zeta)\right) \\
& =\left\langle r(\alpha)\left(v^{p}, \nu_{2}, \ldots, \nu_{q}\right), \partial^{*}(\zeta)\right\rangle \\
\mathcal{L}_{\left(0, \rho^{*}(\alpha)^{\uparrow}, 0\right)}\left\langle c_{\phi}, S_{\zeta}\right\rangle\left(v^{p}, \nu^{q}, \xi\right) & =\left.\frac{d}{d t}\right|_{t=0}\left\langle\left(v^{p}, \nu_{1}+t \rho^{*}(\alpha), \nu_{2}, \ldots, \nu_{q}\right), \sigma(\zeta)\right\rangle \\
& =\left\langle\sigma^{*}\left(v^{p}, \rho_{A}^{*}(\alpha), \nu_{2}, \ldots, \nu_{q}\right), \zeta\right\rangle .
\end{aligned}
$$

So Equation (IM9) holds. Finally, the Leibniz rule follows by the same arguments in the proof of Proposition 3.11. Conversely given a $(\mathbf{D}, l, r, \sigma)$ define the map $\mu$ : $\Gamma\left(\mathbb{A}_{\mathcal{A}}^{(p, q)}, \mathbb{M}_{\mathcal{E}}^{(p, q)}\right) \longrightarrow C^{\infty}\left(\mathbb{M}_{\mathcal{E}}^{(p, q)}\right)$ by

$$
\begin{aligned}
\left\langle\mu, \chi_{a}\right\rangle & =c_{\mathbf{D}\left(X_{a}\right)} \\
\left\langle\mu, S_{a}^{i}\right\rangle & =(-1)^{i-1} c_{l(a)} \circ \gamma_{(i)} \\
\left\langle\mu, S_{\alpha}^{j}\right\rangle & =(-1)^{j-1} c_{r(\alpha)} \circ \gamma_{(j)}^{*} \\
\left\langle\mu, S_{\zeta}\right\rangle & =c_{\sigma(\zeta)} \circ \gamma .
\end{aligned}
$$

By the proof of Theorem 3.6 it follows that $\mu$ is a well defined linear map with respect to the structure $\mathbb{A}_{\mathcal{A}}^{(p, q)} \longrightarrow \mathbb{M}_{\mathcal{E}}^{(p, q)}$ and componentwise linear function with respect to $\mathbb{A}_{\mathcal{A}}^{(p, q)} \longrightarrow A$. Hence we can see $\mu=c_{\phi}$ where $\phi$ is a $(p, q)$ tensor on $A$ with coefficients in $\mathcal{A}$. Also the IM equations satisfied by ( $\mathbf{D}, l, r, \sigma$ ) imply that $c_{\phi}$ is a cocycle, which means that $\phi$ is a Lie algebroid tensor.

We state now the infinitesimal-global correspondence
Theorem 3.17. Given a multiplicative $\mathcal{E}$-valued $(p, q)$-tensor on $\mathcal{G}$, the associated quadruple $(\mathbf{D}, l, r, \sigma)$ is an $A_{\mathcal{E}}$-valued $(p, q)$-tensor on $A$. Moreover, if $\mathcal{G}$ is source simply connected the correspondence is one-to-one, given by

$$
\left\{\begin{array}{l}
\mathcal{L}_{\vec{X}} \tau=\mathcal{T}(\mathbf{D}(X))  \tag{3.30}\\
i \vec{a} \tau=\mathcal{T}(l(a)) \\
i_{*^{*} \alpha} \tau=\mathcal{T}(r(\alpha)) \\
i_{S_{\zeta}} \tau=\mathcal{T}(\sigma(\zeta))
\end{array}\right.
$$

Proof. If $\tau$ is a multiplicative $\mathcal{E}$-valued $(p, q)$-tensor on $\mathcal{G}$ then the infinitesimal counterpart $A c_{\tau}$ of its associated componentwise linear function $c_{\tau}$ is a Lie algebroid cocycle. And by definition of ( $\mathbf{D}, l, r, \sigma$ ) associated to $\tau$ follows that this quadruple is the corresponding one with the cocycle $A c_{\tau}$. Hence $(\mathbf{D}, l, r, \sigma)$ is an $A_{\mathcal{E}}$-valued ( $p, q$ )-tensor on $A$.
Remark 3.18. If $\mathcal{E}$ is trivial VB-groupoid $\mathbb{R}$, we are in the case of usual tensor fields on a Lie groupoid $\mathcal{G}$. In this situation our result recovers the description of multiplicative $(p, q)$-tensors given in [7].

We will now see how to recover various results in the literature from this theorem, and get new ones.

### 3.3 Multiplicative $k$-forms with coefficients in a representation up to homotopy

In this section we apply the theory of multiplicative tensors with coefficients to the case of $k$-forms with coefficients in a representation up to homotopy. We will characterize such forms and we will describe them infinitesimally.

Also we show that the known cases of multiplicative forms and multiplicative forms with coefficients in a representation are particular cases of this more general approach.

Let $\left(\Delta^{0}, \Delta^{1}, \partial, \Omega\right)$ be a representation up to homotopy of $\mathcal{G}$ on $C_{[0]} \oplus E_{[1]}$, and let $\mathcal{E}:=\mathbf{s}^{*}(E) \oplus \mathbf{t}^{*}(C)$ be the associated VB-groupoid (see Subsection 1.3.3). A multiplicative $k$-form on $\mathcal{G}$ with coefficient in a representation up to homotopy is a multiplicative $(k, 0)$-tensor on $\mathcal{G}$ with coefficients in $\mathcal{E}$. We may think of a $k$-form $\omega$ on $\mathcal{G}$ with coefficient in $\mathcal{E}$ as a pair $\omega=\left(\omega^{0}, \omega^{1}\right)$ where $\omega^{0} \in \Omega^{k}\left(\mathcal{G}, \mathbf{t}^{*}(C)\right)$ and $\omega^{1} \in \Omega^{k}\left(\mathcal{G}, \mathbf{s}^{*}(E)\right)$. With this expression for $\omega$, we can write the multiplicativity condition in terms of $\omega^{0}$ and $\omega^{1}$.

Proposition 3.19. $A k$-form $\omega=\left(\omega^{0}, \omega^{1}\right) \in \Omega^{k}(\mathcal{G} ; \mathcal{E})$ is multiplicative if and only if the following equations hold

$$
\begin{align*}
\omega^{1} & =s^{*}(\theta)  \tag{3.31}\\
\partial \circ \omega^{0}+g \cdot \omega^{1} & =t^{*}(\theta) \quad \text { for some } \theta \in \Omega^{k}(M, E)  \tag{3.32}\\
\left(m^{*} \omega^{0}\right)_{(g, h)} & =\left(P_{1}^{*} \omega^{0}\right)_{(g, h)}+g \cdot\left(P_{2}^{*} \omega^{0}\right)_{(g, h)}-\Omega_{g, h}\left(P_{2}^{*} \omega^{1}\right)_{(g, h)} \tag{3.33}
\end{align*}
$$

where $P_{1}, P_{2}: \mathcal{G}^{(2)} \longrightarrow \mathcal{G}$ are the projections on the first and second component, respectively.

Proof. Let $\omega=\left(\omega^{0}, \omega^{1}\right) \in \Omega^{k}(T \mathcal{G} \otimes \mathcal{E})$ be a $k$-form with coefficients in $\mathcal{E}$. By definition $\omega$ is multiplicative if its associated componentwise linear function $c_{\omega}$ : $\left(\bigoplus_{k} T \mathcal{G}\right) \oplus \mathcal{E}^{*} \longrightarrow \mathbb{R}$ is multiplicative. Note that this is equivalent to the map $\omega: \bigoplus_{k} T \mathcal{G} \longrightarrow \mathcal{E}$ being a morphism of Lie groupoids. In particular there exists a $k$-form $\theta \in \Omega^{k}(M, E)$ such that $\bar{s} \circ \omega=\theta \circ(T \mathbf{s})^{k}$ and $\bar{t} \circ \omega=\theta \circ(T \mathbf{t})^{k}$, where $(T \mathbf{s})^{k}$ and $T \mathbf{t})^{k}$ are the source and target maps of $\bigoplus_{k} T \mathcal{G} \longrightarrow \bigoplus_{k} T M$, respectively. This implies that

$$
\begin{aligned}
\theta \circ(T \mathbf{s})^{k} & =\omega^{1} \\
\theta \circ(T \mathbf{t})^{k} & =\partial \circ \omega^{0}+g \cdot \omega^{1}
\end{aligned}
$$

Hence the compatibility of $\omega$ with the source and the target maps is equivalent to (3.31) and (3.32). Let now $X_{g}^{k}=\left(g, X_{1}, \ldots, X_{k}\right)$ and $Y_{h}^{k}=\left(h, Y_{1}, \ldots, Y_{k}\right)$ in $\oplus^{k} T \mathcal{G}$ be two composable elements. Since $\omega$ is a morphism of Lie groupoids, it follows that $\omega\left(X_{g}^{k}\right)$ and $\omega\left(Y_{h}^{k}\right)$ are composable in $\mathcal{E}$. Since

$$
\begin{aligned}
\bar{s}\left(\omega\left(X_{g}^{k}\right)\right) & =\omega^{1}\left(X_{g}^{k}\right) \\
\bar{t}\left(\omega\left(Y_{h}^{k}\right)\right) & =\partial \circ \omega^{0}\left(Y_{h}^{k}\right)+h \cdot \omega^{1}\left(Y_{h}^{k}\right)
\end{aligned}
$$

then $\omega\left(X_{g}^{k}\right)$ and $\omega\left(Y_{h}^{k}\right)$ are composable if and only if

$$
\left(P_{1}^{*} \omega^{1}\right)_{(g, h)}=\partial \circ\left(P_{2}^{*} \omega^{0}\right)_{(g, h)}+h \cdot\left(P_{2}^{*} \omega^{1}\right)_{(g, h)} .
$$

Now with respect to the multiplication we have

$$
\omega\left(X_{g}^{k} \cdot Y_{h}^{k}\right)=\left(\omega^{0}\left(X_{g}^{k} \cdot Y_{h}^{k}\right), \omega^{1}\left(X_{g}^{k} \cdot Y_{h}^{k}\right)\right) .
$$

On the other hand

$$
\begin{aligned}
\omega\left(X_{g}^{k}\right) \cdot \omega\left(Y_{h}^{k}\right) & =\left(\omega^{0}\left(X_{g}^{k}\right) \cdot \omega^{0}\left(Y_{h}^{k}\right), \omega^{1}\left(X_{g}^{k}\right) \cdot \omega^{1}\left(Y_{h}^{k}\right)\right) \\
& =\left(g h, \omega^{0}\left(X_{g}^{k}\right)+g \cdot \omega^{0}\left(Y_{h}^{k}\right)-\Omega_{g, h} \omega^{1}\left(Y_{h}^{k}\right), \omega^{1}\left(Y_{h}^{k}\right)\right.
\end{aligned}
$$

Therefore $\omega$ respects the multiplication if and only if

$$
\begin{aligned}
\left(m^{*} \omega^{0}\right)_{(g, h)} & =\left(P_{1}^{*} \omega^{0}\right)_{(g, h)}+g \cdot\left(P_{2}^{*} \omega^{0}\right)_{(g, h)}-\Omega_{g, h}\left(P_{2}^{*} \omega^{1}\right)_{(g, h)} \\
\left(m^{*} \omega^{1}\right)_{(g, h)} & =\left(P_{2}^{*} \omega^{1}\right)_{(g, h)}
\end{aligned}
$$

Note that by Equation (3.31) and by properties of the multiplication, we have

$$
\begin{aligned}
\left(m^{*} \omega^{1}\right)\left(X_{g}^{k}, Y_{h}^{k}\right) & =m^{*}\left(\mathbf{s}^{*} \theta\right)\left(X_{g}^{k}, Y_{h}^{k}\right)=\theta\left((\mathrm{d} \mathbf{s})^{k}\left(X_{g}^{k} \cdot Y_{h}^{k}\right)=\theta\left((\mathrm{d} \mathbf{s})^{k}\left(Y_{h}^{k}\right)\right)\right. \\
\left(P_{2}^{*} \omega^{1}\right)\left(X_{g}^{k}, Y_{h}^{k}\right) & =\left(\mathbf{s} \circ P_{2}\right)^{*} \theta\left(X_{g}^{k}, Y_{h}^{k}\right)=\theta\left((\mathrm{ds})^{k} Y_{h}^{k}\right) .
\end{aligned}
$$

Example 3.20. In the case with trivial coefficient, $\mathcal{E}=\mathbb{R} \simeq C$ with the action given by the identity map, $E=\{*\}$ is a point, and the maps $\partial=0$ and $\Omega=0$. Therefore we have a usual $k$-form $\omega \in \Omega^{k}(\mathcal{G})$, and it is multiplicative if and only if

$$
\left(m^{*} \omega\right)_{(g, h)}=\left(P_{1}^{*} \omega\right)_{(g, h)}+\left(P_{2}^{*} \omega\right)_{(g, h)},
$$

which is precisely the case treated in [7].
Example 3.21. If $C \longrightarrow M$ is a representation of $\mathcal{G}$, then the VB-groupoid associated is $\mathcal{E}=C \rtimes \mathcal{G}$, with trivial side bundle $E$. Then $\partial=0$ and $\Omega=0$. Therefore, a $k$-form $\omega$ on $\mathcal{G}$ with coefficient in $\mathcal{E}$ is multiplicative if and only if

$$
\left(m^{*} \omega\right)_{(g, h)}=\left(P_{1}^{*} \omega\right)_{(g, h)}+g \cdot\left(P_{2}^{*} \omega\right)_{(g, h)},
$$

which is the definition given in [14].
Let $\omega \in \Omega^{k}(\mathcal{G}, \mathcal{E})$ be a multiplicative $k$-form, where $\mathcal{E}=\mathbf{s}^{*} E \oplus \mathbf{t}^{*} C$ is the VBgroupoid associated to a representation up to homotopy $\left(\Delta^{0}, \Delta^{1}, \partial, \Omega\right)$ of $\mathcal{G}$. We will describe in detail the $A_{\mathcal{E}}$-valued ( $k, 0$ )-tensor on $A$ associated to the multiplicative ( $k, 0$ )-tensor $\omega$. To do this, first we need a little work.

A representation up to homotopy $\left(\Delta^{0}, \Delta^{1}, \partial, \Omega\right)$ induces a representation up to homotopy of $\mathcal{G}$ on the graded vector bundle $E_{[0]}^{*} \oplus C_{[1]}^{*}$ as follows:

- The quasi action $\left(\Delta^{T}\right)_{g}^{0}: E_{\mathbf{s}(g)}^{*} \longrightarrow E_{\mathbf{t}(g)}^{*}$ given by:

$$
\left(\Delta^{T}\right)_{g}^{0}(\eta):=\left(\Delta_{g^{-1}}^{1}\right)^{*} \eta, \quad \text { for } \eta \in E_{\mathbf{s}(g)}^{*}
$$

- The quasi actions $\left(\Delta^{T}\right)_{g}^{1}: C_{\mathbf{s}(g)}^{*} \longrightarrow C_{\mathbf{t}(g)}^{*}$ given by:

$$
\left(\Delta^{T}\right)_{g}^{1}(\xi):=\left(\Delta_{g^{-1}}^{0}\right)^{*} \xi, \quad \text { for } \xi \in C_{\mathbf{s}(g)}^{*}
$$

- The vector bundle map $\partial^{T}: E^{*} \longrightarrow C^{*}$ is the dual map $\partial^{*}$.
- The operator $\Omega^{T}$ is given by: $\xi \in C_{\mathbf{s}(g)}^{*}$ we have

$$
\Omega_{(g, h)}^{T}: C_{\mathbf{s}(h)}^{*} \longrightarrow E_{\mathbf{t}(g)}^{*} \quad \Omega_{(g, h)}^{T}(\xi):=\left(\Omega_{\left(h^{-1}, g^{-1}\right)}\right)^{*} \xi
$$

for $(g, h) \in \mathcal{G}^{(2)}$.
We check now the equations that the quadruple $\left.\left(\Delta^{0}\right)^{T},\left(\Delta^{1}\right)^{T}, \partial^{T}, \Omega^{T}\right)$ has to satisfy (see Subsection 1.3.2). The compatibility of the quasi actions with the vector bundle map $\partial^{T}$ :

$$
\left(\Delta^{1}\right)^{T} \circ \partial^{T}-\partial^{T} \circ\left(\Delta^{0}\right)^{T}=\left(\partial \circ \Delta^{0}\right)^{*}-\left(\Delta^{1} \circ \partial\right)^{*}=-\left(\Delta^{1} \circ \partial-\partial \circ \Delta^{0}\right)^{*}=0
$$

For the second equation we have

$$
\begin{aligned}
\left(\Delta^{0}\right)_{g_{1}}^{T}\left(\Delta^{0}\right)_{g_{2}}^{T}-\left(\Delta^{0}\right)_{g_{1} g_{2}}^{T}+\Omega_{\left(g_{1}, g_{2}\right)}^{T} \circ \partial^{T}= & \left(\Delta_{g_{1}^{-1}}^{1}\right)^{*}\left(\Delta_{g_{2}^{-1}}^{1}\right)^{*}-\left(\Delta_{g_{2}^{-1}}^{1} g_{1}^{-1}\right)^{*} \\
& +\left(\partial \circ \Omega_{\left(g_{2}^{-1}, g_{1}^{-1}\right)}^{T}\right)^{*} \\
= & \left(\Delta_{g_{2}^{-1}}^{1} \Delta_{g_{1}^{-1}}^{1}-\Delta_{g_{2}^{-1}}^{1} g_{1}^{-1}+\partial \circ \Omega_{\left(g_{2}^{-1}, g_{1}^{-1}\right)}^{T}\right)^{*} \\
= & 0 .
\end{aligned}
$$

In a similar way we get the third and fourth equation. Hence $\left(\left(\Delta^{0}\right)^{T},\left(\Delta^{1}\right)^{T}, \partial^{T}, \Omega^{T}\right)$ is a representation up to homotopy of $\mathcal{G}$ on $E_{[0]}^{*} \oplus C_{[1]}^{*}$, called dual representation.

On the other hand the dual VB-groupoid of $\mathcal{E}=\mathbf{s}^{*} E \oplus \mathbf{t}^{*} C$ is the VB-groupoid with structure maps given by:

- The source and target maps $\widehat{s}, \widehat{t}: \mathcal{E}^{*}=\mathbf{s}^{*}\left(E^{*}\right) \oplus \mathbf{t}^{*}\left(C^{*}\right) \longrightarrow C^{*}$ are

$$
\begin{aligned}
\widehat{s}(g, \eta, \xi) & =\partial^{*}(\eta)+\left(\Delta_{g}^{0}\right)^{*} \xi \\
\widehat{t}(g, \eta, \xi) & =\xi
\end{aligned}
$$

where $\eta \in E_{\mathbf{s}(g)}^{*}$ and $\xi \in C_{\mathbf{t}(g)}^{*}$. The multiplication is

$$
\left(g_{1}, \eta_{1}, \xi_{1}\right) \cdot\left(g_{2}, \eta_{2}, \xi_{2}\right)=\left(g_{1} g_{2}, \eta_{2}+\left(\Delta_{g_{2}}^{1}\right)^{*} \eta_{1}-\Omega_{g_{1}, g_{2}}^{*} \xi_{1}, \xi_{1}\right),
$$

under the compatibility condition $\xi_{2}=\partial^{*}\left(\eta_{1}\right)+\left(\Delta_{g}^{0}\right)^{*} \xi_{1}$.
Lemma 3.22. There is an isomorphism of Lie groupoids between the Lie groupoid $s^{*}\left(C^{*}\right) \oplus \boldsymbol{t}^{*}\left(E^{*}\right)$ obtained by the dual representation $\left(\left(\Delta^{0}\right)^{T},\left(\Delta^{1}\right)^{T}, \partial^{T}, \Omega^{T}\right)$, and the Lie groupoid $s^{*}\left(E^{*}\right) \oplus \boldsymbol{t}^{*}\left(C^{*}\right)$ which is obtained by dualization of the VB-groupoid $\mathcal{E}=s^{*} E \oplus \boldsymbol{t}^{*} C$. Moreover this is an isomorphism of VB-groupoids.

Proof. Let $(g, \xi, \eta) \in \mathbf{s}^{*}\left(C^{*}\right) \oplus \mathbf{t}^{*}\left(E^{*}\right)$. The inverse of this element is (see [19]):

$$
(g, \xi, \eta)^{-1}=\left(g^{-1},-\left(\Delta^{0}\right)_{g^{-1}}^{T} \eta+\Omega_{g^{-1}, g}^{T} \xi, \partial^{T} \eta+\left(\Delta^{1}\right)_{g}^{T} \xi\right)
$$

Define the map $\varphi: \mathbf{s}^{*}\left(C^{*}\right) \oplus \mathbf{t}^{*}\left(E^{*}\right) \longrightarrow \mathbf{s}^{*}\left(E^{*}\right) \oplus \mathbf{t}^{*}\left(C^{*}\right)$ by

$$
\varphi(g, \xi, \eta)=\left(g,-\left(\Delta^{0}\right)_{g^{-1}}^{T} \eta+\Omega_{g^{-1}, g}^{T} \xi, \partial^{T} \eta+\left(\Delta^{1}\right)_{g}^{T} \xi\right) .
$$

We show now the compatibility of $\varphi$ with the source, target and multiplication. Recall that the source and target maps of $\mathbf{s}^{*}\left(C^{*}\right) \oplus \mathbf{t}^{*}\left(E^{*}\right)$, denoted by $\widetilde{s}, \widetilde{t}$, are defined by (see Subsection 1.3.3):

- $\widetilde{s}(g, \xi, \eta)=\xi$
- $\tilde{t}(g, \xi, \eta)=\partial^{T} \eta+\left(\Delta^{1}\right)_{g}^{T} \xi$
for $\xi \in C_{\mathbf{s}(g)}^{*}$ and $\eta \in E_{\mathbf{t}(g)}^{*}$. Then

$$
\begin{aligned}
\widehat{s}(\varphi(g, \xi, \eta)) & =\widehat{s}\left(g,-\left(\Delta^{0}\right)_{g^{-1}}^{T} \eta+\Omega_{g^{-1}, g}^{T} \xi, \partial^{T} \eta+\left(\Delta^{1}\right)_{g}^{T} \xi\right) \\
& =\partial^{*}\left(-\left(\Delta_{g}^{1}\right)^{*} \eta+\Omega_{g^{-1}, g}^{*} \xi\right)+\left(\Delta_{g}^{0}\right)^{*}\left(\partial^{*}(\eta)+\left(\Delta_{g^{-1}}^{0}\right)^{*} \xi\right) \\
& =-\left(\Delta_{g}^{1} \circ \partial\right)^{*} \eta+\left(\Omega_{g^{-1}, g} \circ \partial\right)^{*} \xi+\left(\partial \circ \Delta_{g}^{0}\right)^{*}(\eta)+\left(\Delta_{g^{-1}}^{0} \Delta_{g}^{0}\right)^{*} \xi \\
& =\left(\Delta_{g^{-1} g}^{0}\right)^{*} \xi=\xi \\
& =\widetilde{s}(g, \xi, \eta)
\end{aligned}
$$

With respect to the target map

$$
\begin{aligned}
\widehat{t}(\varphi(g, \xi, \eta)) & =\widehat{t}\left(g,-\left(\Delta^{0}\right)_{g^{-1}}^{T} \eta+\Omega_{g^{-1}, g}^{T} \xi, \partial^{T} \eta+\left(\Delta^{1}\right)_{g}^{T} \xi\right) \\
& =\partial^{T} \eta+\left(\Delta^{1}\right)_{g}^{T} \xi \\
& =\widetilde{t}(g, \xi, \eta)
\end{aligned}
$$

The compatibility with respect to the multiplication is a long computation and it is presented in the Appendix.

The representation up to homotopy $\left(\Delta^{0}, \Delta^{1}, \partial, \Omega\right)$ of $\mathcal{G}$ on $C_{[0]} \oplus E_{[1]}$ also induces a representation up to homotopy $\left(\nabla^{0}, \nabla^{1}, \partial, \widetilde{\Omega}\right)$ of $A$ on $C_{[0]} \oplus E_{[1]}$ in the following way (see [3] for details) :

- the connection $\nabla^{0}: \Gamma(A) \times \Gamma(C) \longrightarrow \Gamma(C)$ is given by

$$
\left(\nabla_{a}^{0} c\right)(p)=\left.\frac{d}{d t}\right|_{t=0}\left(\Delta_{g(t)}^{0} c(p)\right)
$$

where $g(t)$ is a curve in $\mathbf{s}^{-1}(p)$ with $g^{\prime}(0)=a(p)$. In a similar way define the connection $\nabla^{1}: \Gamma(A) \times \Gamma(E) \longrightarrow \Gamma(E)$.

- The operator $\Omega$ can also be differentiated to an operator $\widetilde{\Omega} \in \Gamma\left(\wedge^{2} A^{*} \otimes\right.$ $\operatorname{Hom}(E, C))$ (see Definition 3.9 in [3]).
- The vector bundle map from $C$ to $E$ is the map $\partial$

Consider the dual representation (see e.g. [17]) $\left(\nabla^{T_{0}}, \nabla^{T_{1}}, \partial^{T}, \widetilde{\Omega}^{T}\right)$ of $A$ on $E_{[0]}^{*} \oplus C_{[1]}^{*}$, where

$$
\nabla^{T_{0}}=\left(\nabla^{1}\right)^{*} \quad \nabla^{T_{1}}=\left(\nabla^{0}\right)^{*} \quad \partial^{T}=\partial^{*} \quad{\widetilde{\Omega^{T}}}_{a, b}=-\widetilde{\Omega}_{a, b}^{*} .
$$

Note that by definition of the quadruple $\left(\nabla^{T_{0}}, \nabla^{T_{1}}, \partial^{T}, \widetilde{\Omega}^{T}\right)$, it follows that this representation is induced by the dual representation $\left(\left(\Delta^{0}\right)^{T},\left(\Delta^{1}\right)^{T}, \partial^{T}, \Omega^{T}\right)$. Also this dual representation induces a VB-algebroid structure on $\mathbb{A}:=A \oplus E^{*} \oplus C^{*}$

with core bundle $E^{*} \longrightarrow M$.
Corollary 3.23. There is a Lie algebroid isomorphism between the Lie algebroid $\mathbb{A}:=A \oplus E^{*} \oplus C^{*}$ induced by the dual representation and the Lie algebroid $A_{\mathcal{E}^{*}}$. Moreover this is an isomorphism of VB-algebroids.

In what follows we will use the VB-algebroid ( $\left.\mathbb{A}, C^{*} ; A, M\right)$ instead of $\left(A_{\mathcal{E}^{*}}, C^{*} ; A, M\right)$ because the calculus are easier and more explicit. Denote by $h: \Gamma(A) \longrightarrow \Gamma_{\operatorname{lin}}\left(\mathbb{A}, C^{*}\right)$ the canonical horizontal lift: $h(a)(\xi)=(a, 0, \xi)$. This horizontal lift is $C^{\infty}(M)$-linear and satisfies

$$
[h(a), h(b)]=h([a, b])+S_{\widetilde{\Omega}^{T}(a, b)}
$$

Now with respect to the sections of the tangent algebroid, there is also a natural inclusion $\Gamma(A) \hookrightarrow \Gamma_{\operatorname{lin}}(T A, T M), \quad a \mapsto T a$. However, unlike the previous horizontal lift, this inclusion is not $C^{\infty}(M)$-linear:

$$
T(f a)=f T a+\ell_{\mathrm{d} f} S_{a} .
$$

Remember that the $A_{\mathcal{E}}$-valued ( $k, 0$ )-tensor on $A$ associated to the $\mathcal{E}$-valued multiplicative $(k, 0)$-tensor $\omega$ on $\mathcal{G}$ is a triple $(\mathbf{D}, l, \sigma)$ where

- $\mathbf{D}: \Gamma_{\operatorname{lin}}\left(\mathcal{A}^{*}, C^{*}\right) \longrightarrow \Gamma\left(\wedge^{p} T^{*} M \otimes C\right)=\Omega^{k}(M, C)$
- $l: A \longrightarrow \wedge^{p-1} T^{*} M \otimes \wedge^{q} A \otimes C$
- $\sigma: E^{*} \longrightarrow \wedge^{p} T^{*} M$ which we view as an element $\theta \in \Omega^{k}(M, E)$
satisfying some equations. Note that there is not a map $r: T^{*} M \longrightarrow \wedge^{p} T^{*} M \otimes$ $\wedge^{q-1} A^{*} \otimes C$ because there is not a cotangent algebroid. Since we have a natural inclusion of $\Gamma(A)$ in $\Gamma_{\operatorname{lin}}\left(\mathcal{A}^{*}, C^{*}\right)$, we can define a new operator

$$
\mathbb{D}: \Gamma(A) \longrightarrow \Omega^{k}(M, C) \quad \text { by } \quad \mathbb{D}(a)=\mathbf{D}(h(a))
$$

Note that by Proposition 3.11, and using that $h: \Gamma(A) \longrightarrow \Gamma_{\operatorname{lin}}\left(\mathcal{A}^{*}, C^{*}\right)$ is $C^{\infty}(M)$ linear we have

$$
\begin{aligned}
\mathbb{D}(f a) & =\mathbf{D}(h(f a))=\mathbf{D}(f h(a)) \\
& =f \mathbf{D}(h(a))+\mathrm{d} f \wedge l(a) \\
& =f \mathbb{D}(a)+\mathrm{d} f \wedge l(a)
\end{aligned}
$$

This motivates the following definition
Definition 3.24. An $A_{\mathcal{E}}$-valued $(k, 0)$-tensor on $A$ is

- $\mathbb{D}: \Gamma(A) \longrightarrow \Omega^{k}(M, C)$
- $l: A \longrightarrow \wedge^{k-1} T^{*} M \otimes C$
- $\theta \in \Omega^{k}(M, E)$
such that the following equations hold

$$
\begin{align*}
\mathbb{D}(f a) & =f \mathbb{D}(a)+\mathrm{d} f \wedge l(a)  \tag{3.34}\\
\mathbb{D}([a, b]) & =a \cdot \mathbb{D}(b)-b \cdot \mathbb{D}(a)+\widetilde{\Omega}_{a, b} \circ \theta  \tag{3.35}\\
\iota_{\rho(b)} \mathbb{D}(a) & =a \cdot l(b)-l([a, b])  \tag{3.36}\\
\iota_{\partial^{*}(\eta)} \mathbb{D}(a) & =a \cdot \theta^{*}(\eta)-\theta^{*}\left(\left(\nabla^{1}\right)_{a}^{*} \eta\right)  \tag{3.37}\\
\iota_{\rho(a)} l(b) & =-\iota_{\rho(b)} l(a)  \tag{3.38}\\
\iota_{\partial^{*}(\eta)} l(a) & =\iota_{\rho(a)} \theta^{*}(\eta) \tag{3.39}
\end{align*}
$$

We only need to check the Equation (3.35). Let $a, b \in \Gamma(A)$, then

$$
\begin{aligned}
\mathbb{D}([a, b]) & =\mathbf{D}(h([a, b])) \\
& =\mathbf{D}\left([h(a), h(b)]-S_{\widetilde{\Omega}_{a, b}^{T}}\right) \\
& =\mathbf{D}([h(a), h(b)])-\mathbf{D}\left(0, S_{\widetilde{\Omega}_{a, b}^{T}}\right) \\
& =h(a) \cdot \mathbf{D}(h(b))-h(b) \cdot \mathbf{D}(h(a))-\theta^{*}\left(\widetilde{\Omega}_{a, b}^{T}\right) \\
& =a \cdot \mathbb{D}(b)-b \cdot \mathbb{D}(a)+\widetilde{\Omega}_{a, b} \circ \theta .
\end{aligned}
$$

Therefore applying Theorem 3.17 to this case we obtain a global-infinitesimal correspondence between multiplicative $k$-form $\omega \in \Omega^{k}(\mathcal{G}, \mathcal{E})$ with coefficients in a representation up to homotopy and $A_{\mathcal{E}}$-valued $(k, 0)$-tensor $(\mathbb{D}, l, \theta)$ on $A$.

Theorem 3.25. Let $\mathcal{G}$ be a source simply connected Lie groupoid. There is one-toone correspondence between multiplicative $k$-forms $\omega \in \Omega^{k}(\mathcal{G}, \mathcal{E})$ with coefficients in a representation up to homotopy and $A_{\mathcal{E}}$-valued $(k, 0)$-tensor $(\mathbb{D}, l, \theta)$ on $A$.

Now we will give an explicit expression for the operator $\mathbb{D}: \Gamma(A) \longrightarrow \Omega^{k}(M, C)$. The anchor map of the Lie algebroid $\mathbb{A} \longrightarrow C^{*}$ on linear sections is

$$
\rho_{\mathbb{A}}(h(a))\left(\xi_{p}\right)=\left.\frac{d}{d t}\right|_{t=0}\left(\left(\varphi_{t}^{a}(p)\right)\right)^{*} \cdot \xi_{p} \quad \in T C^{*}
$$

where $\varphi_{t}^{a}$ is the flow of the right invariant vector field $\vec{a} \in \mathfrak{X}(\mathcal{G})$. It follows then that the flow of the right invariant vector field $\overrightarrow{h(a)}$, restricted to units, is

$$
\Phi_{t}^{h(a)}\left(p, \xi_{p}, 0\right)=\left(\varphi_{t}^{a}(p),\left(\left(\varphi_{t}^{a}(p)\right)\right)^{*} \cdot \xi_{p}, 0_{p}\right)
$$

This flow $\Phi_{t}^{h(a)}$ is a linear map over $\varphi_{t}^{a}$ :

which can be restricts to


Taking dual we get

given by

$$
\left(\Phi_{t}^{h(a)}\right)_{p}^{-1}(c)=\varphi_{t}^{a}(p)^{-1} \cdot c
$$

for $c \in C_{\mathbf{t}\left(\varphi_{t}^{a}(p)\right)}$.
Proposition 3.26. Let $\omega=\left(\omega^{0}, \omega^{1}\right) \in \Omega^{k}(\mathcal{G}, \mathcal{E})$ be a multiplicative $k$-form with coefficients in a representation up to homotopy. Then the associated operator $\mathbb{D}$ : $\Gamma(A) \longrightarrow \Omega^{k}(M, C)$ is given by

$$
\begin{equation*}
\mathbb{D}(a)\left(v_{1}, \ldots, v_{k}\right)=\left.\frac{d}{d t}\right|_{t=0} \varphi_{t}^{a}(p)^{-1} \cdot \omega^{0}\left(d \varphi_{t}^{a}\left(v_{1}\right), \ldots, d \varphi_{t}^{a}\left(v_{k}\right)\right) \tag{3.40}
\end{equation*}
$$

Proof. For $v_{i} \in T M$ and $\xi \in C^{*}$ we have

$$
\begin{aligned}
\left\langle\mathbb{D}(a),\left(v_{1}, \ldots, v_{k}, \xi\right)\right\rangle & =\left\langle A c_{\omega},\left(v_{1}, \ldots, v_{k}, \xi\right)\right\rangle \\
& =\left.\frac{d}{d t}\right|_{t=0}\left\langle\omega\left(\mathrm{~d} \varphi_{t}^{a}\left(v_{1}\right), \ldots, \mathrm{d} \varphi_{t}^{a}\left(v_{k}\right)\right),\left(\Phi_{t}^{h(a)}\right)(\xi)\right\rangle \\
& =\left.\frac{d}{d t}\right|_{t=0}\left\langle\varphi_{t}^{a}(p)^{-1} \cdot \omega\left(\mathrm{~d} \varphi_{t}^{a}\left(v_{1}\right), \ldots, \mathrm{d} \varphi_{t}^{a}\left(v_{k}\right)\right), \xi\right\rangle \\
& =\left.\frac{d}{d t}\right|_{t=0}\left\langle\varphi_{t}^{a}(p)^{-1} \cdot \omega^{0}\left(\mathrm{~d} \varphi_{t}^{a}\left(v_{1}\right), \ldots, \mathrm{d} \varphi_{t}^{a}\left(v_{k}\right)\right), \xi\right\rangle .
\end{aligned}
$$

Example 3.27. Multiplicative $k$-forms. Consider a multiplicative linear $k$-form $\omega$ on $\mathcal{G}$. In our context this means that $\omega$ is a multiplicative $(k, 0)$-tensor on $\mathcal{G}$ with trivial coefficients, which means that $C=\mathbb{R}$ and $E=0$. Then its associated $I M-(k, 0)$ tensor on $A$ is the pair $(\mathbb{D}, l)$ where

- $\mathbb{D}: \Gamma(A) \longrightarrow \Omega^{k}(M)$ given by

$$
\mathbb{D}(a)\left(v_{1}, \ldots, v_{k}\right)=\left.\frac{d}{d t}\right|_{t=0} \omega\left(d \phi_{\alpha}^{t}\left(v_{1}\right), \ldots, d \phi_{\alpha}^{t}\left(v_{k}\right)\right)
$$

- $l: A \longrightarrow \wedge^{k-1} T^{*} M$ determined by

$$
l(a)=\epsilon^{*}\left(i_{\vec{a}} \omega\right)
$$

where $\epsilon: M \longrightarrow \mathcal{G}$ is the unit map, and such that the following Leibniz rule holds

$$
\mathbb{D}(f a)=f \mathbb{D}(a)+d f \wedge l(a)
$$

(See Theorem 1 in [14], in the case of the trivial representation). The pair ( $\mathbb{D}, l$ ) satisfies then the following conditions

$$
\begin{align*}
\mathbb{D}(f a) & =f \mathbb{D}(a)+\mathrm{d} f \wedge l(a)  \tag{3.41}\\
\mathbb{D}([a, b]) & =a \cdot \mathbb{D}(b)-b \cdot \mathbb{D}(a)  \tag{3.42}\\
\iota_{\rho(b)} \mathbb{D}(a) & =a \cdot l(b)-l([a, b])  \tag{3.43}\\
\iota_{\rho(a)} l(b) & =-\iota_{\rho(b)} l(a) \tag{3.44}
\end{align*}
$$

which is what in [14] is called $k$-Spencer Operator with trivial coefficients.
On the other hand, take $a \in \Gamma(A)$, then $\sigma(a) \in \Omega^{k-1}(M)$. Define $\nu(a)=\mathbb{D}(a)-$ $d(\sigma(a)) \in \Omega^{k}(M)$. Let $h \in C^{\infty}(M)$. Then

$$
\begin{aligned}
\nu(h a) & =\mathbb{D}(h a)-d(\sigma(h a)) \\
& =h \mathbb{D}(a)-d h \wedge \sigma(a)-d(h \sigma(a)) \\
& =h \mathbb{D}(a)-d h \wedge \sigma(a)-(h d(\sigma(a))-d h \wedge \sigma(a)) \\
& =h(\mathbb{D}(a)-d(\sigma(a))) \\
& =h \nu(a) .
\end{aligned}
$$

Therefore $\nu: A \longrightarrow \wedge^{k} T^{*} M$ is a vector bundle morphism over $M$. The next corollary recovers the results in [7].
Corollary 3.28. Given a multiplicative $k$-form $\omega \in \Omega^{2}(\mathcal{G})$ there exists vector bundle maps $\nu: A \longrightarrow \wedge^{2} T^{*} M, \mu: A \longrightarrow T^{*} M$ such that $\mathbb{D}(a)=\nu(a)+d(\mu(a))$. Moreover the pair $(l, \nu)$ is $I M-k$ form on $A$.

Example 3.29. Multiplicative $k$-form with coefficient in a representation. Consider a representation of $\mathcal{G}$ on a vector bundle $C$, and let $\omega \in \Omega^{k}\left(\mathcal{G}, \mathbf{t}^{*} C\right)$ be a $k$-form on $\mathcal{G}$ with coefficient in the representation. Its associated $(k, 0)$ tensor on $A$ with coefficients in $C$ is the pair $(\mathbb{D}, l)$ where

- $\mathbb{D}: \Gamma(A) \longrightarrow \Omega^{k}(M, C)$ given by

$$
\mathbb{D}(a)\left(v_{1}, \ldots, v_{k}\right)=\left.\frac{d}{d t}\right|_{t=0} \varphi_{t}^{a}(p)^{-1} \cdot \omega\left(d \phi_{\alpha}^{t}\left(v_{1}\right), \ldots, d \phi_{\alpha}^{t}\left(v_{k}\right)\right)
$$

- $l: A \longrightarrow \wedge^{k-1} T^{*} M \otimes C$ determined by

$$
l(a)=\epsilon^{*}\left(i_{\vec{a}} \omega\right)
$$

and such that the following Leibniz rule holds

$$
\mathbb{D}(f a)=f \mathbb{D}(a)+d f \wedge l(a)
$$

(See Theorem 1 in [14]). Moreover, in this case, the operators $\Omega=0, \theta=0$ and the equations for $(\mathbb{D}, l)$ are

$$
\begin{align*}
\mathbb{D}(f a) & =f \mathbb{D}(a)+\mathrm{d} f \wedge l(a)  \tag{3.45}\\
\mathbb{D}([a, b]) & =a \cdot \mathbb{D}(b)-b \cdot \mathbb{D}(a)  \tag{3.46}\\
\iota_{\rho(b)} \mathbb{D}(a) & =a \cdot l(b)-l([a, b])  \tag{3.47}\\
\iota_{\rho(a)} l(b) & =-\iota_{\rho(b)} l(a) \tag{3.48}
\end{align*}
$$

which is precisely the definition of a $C$-valued $k$-Spencer operator over $A$ given in [14].
Remark 3.30. The module structure on $\Omega^{k}(M, C)$ over $\Gamma(A)$ in this context coincides with Lie derivative operator $\mathcal{L}_{a}$ acting on $\Omega^{k}(M, C)$ defined on [14] (see Appendix).

## Chapter 4

## Applications to VB-subalgebroids

Let $\mathcal{A} \longrightarrow E$ be a VB-algebroid over a Lie algebroid $A \longrightarrow M$. In this chapter we study IM-subbundles, that is, double vector subbundles $\Delta \longrightarrow \Delta_{M}$ which are Lie subalgebroids of $\mathcal{A} \longrightarrow E$. The linear quotient $\mathcal{A} / \Delta$ is, indeed, a Lie algebroid. Then the idea is to consider an IM-subbundle as the kernel of a morphism of Lie algebroids $\Phi: \mathcal{A} \longrightarrow \mathcal{A} / \Delta$. Moreover, since $\mathcal{A} / \Delta$ is also a VB-algebroid over $A$ we can dualize and then we get a function $F_{\Phi}: \mathcal{A} \oplus \Delta^{\circ} \longrightarrow \mathbb{R}$, where $\Delta^{\circ}$ denote the annihilator of $\Delta$ in $\mathcal{A}^{*}$, which we identify with the dual over $A$ of $\mathcal{A} / \Delta$. This function $F_{\Phi}$ is an infinitesimal bilinear cocycle, hence we can use what we did in the previous chapters.

As particular cases, we consider IM-distributions, IM-subbundles of $T A \oplus T^{*} A$, and finally IM-Dirac structures, offering a new viewpoint and giving new proofs to results in $[17,26,27]$. We remark, however, that our approach is more general and allows to consider IM-subbundles not only of $T A$ or $T A \oplus T^{*} A$.

The objective of this chapter is the description in terms of some infinitesimal data of the IM-subbundles. We will mention, however, the global objects, i.e., the multiplicative geometric structures defined on Lie groupoids, whose infinitesimal counterparts are examples of IM-subbundles. We will also say something about the integration of IM-subbundles.

### 4.1 Double vector subbundles

First we study double vector subbundles, without any Lie algebroid conditions. We look at them as the kernel of double vector bundles, which are also surjective submersions.

Let

be two double vector bundles over $A$ with core bundles $C_{i}$. Let $F: \mathcal{A}_{1} \longrightarrow \mathcal{A}_{2}$ be a surjective submersion morphism of double vector bundles covering $F_{1}: E_{1} \longrightarrow E_{2}$, $F_{0}: C_{1} \longrightarrow C_{2}$ and the identity on $A$. In particular, the maps $F_{0}$ and $F_{1}$ are surjective submersions. Consider the double vector bundle dual of $\mathcal{A}_{2}$ with respect to $A$

with core bundle $E_{2}^{*}$ and define the map

$$
\bar{F}: \mathcal{A}_{1} \times_{A} \mathcal{A}_{2}^{*} \longrightarrow \mathbb{R} \quad \text { by } \quad \bar{F}(X, \alpha)=\langle F(X), \alpha\rangle
$$

where the pairing is canonical one over $A$.
Lemma 4.1. $F: \mathcal{A}_{1} \longrightarrow \mathcal{A}_{2}$ is a double vector bundle morphism if and only if $\bar{F}: \mathcal{A}_{1} \times{ }_{A} \mathcal{A}_{2}^{*} \longrightarrow \mathbb{R}$ is linear with respect to $E_{1} \times{ }_{M} C_{2}^{*}$ and bilinear with respect to $A$.

Proof. From the definition of the pairing it follows that $\bar{F}$ is linear with respect to the second entry. The linearity of $\bar{F}$ with respect to the first entry is equivalent to the linearity of $F$ with respect to the linear structure over $A$. Let $(X, \alpha),(Y, \beta) \in$ $\left(\mathcal{A}_{1} \times{ }_{A} \mathcal{A}_{2}^{*}\right)_{(e, \xi)}$. On the one hand we have

$$
\begin{equation*}
\bar{F}((X, \alpha)+(Y, \beta))=\bar{F}\left(X+_{E_{1}} Y, \alpha+\beta\right)=\left\langle F\left(X+_{E_{1}} Y\right), \alpha+\beta\right\rangle . \tag{4.1}
\end{equation*}
$$

On the other hand

$$
\begin{equation*}
\bar{F}(X, \alpha)+\bar{F}(Y, \beta)=\langle F(X), \alpha\rangle+\langle F(Y), \beta\rangle=\left\langle F(X)+_{E_{2}} F(Y), \alpha+\beta\right\rangle . \tag{4.2}
\end{equation*}
$$

Then (4.1) $=(4.2)$ if and only if $F$ is linear with respect to the vertical linear structure.

Define the map

$$
\mathbf{D}: \Gamma_{l i n}\left(\mathcal{A}_{1}, E_{1}\right) \times{ }_{A} \Gamma_{l i n}\left(\mathcal{A}_{2}^{*}, C_{2}^{*}\right) \longrightarrow \Gamma\left(E_{1}^{*} \otimes C_{2}\right)
$$

by

$$
\mathbf{D}\left(\chi_{a}, \phi_{a}\right)(e, \xi)=\left\langle F\left(\chi_{a}(e)\right), \phi_{a}(\xi)\right\rangle_{A}=\bar{F}\left(\chi_{a}(e), \phi_{a}(\xi)\right) .
$$

for $e \in E_{1}$ and $\xi \in C_{2}^{*}$.
Remark 4.2. The function $\bar{F}$ is actually a bilinear cocycle on $\mathcal{A}_{1} \oplus \mathcal{A}_{2}$, thinking the double vector bundles of as VB-groupoids, where the Lie groupoids are vector bundles. Hence the operator $\mathbf{D}$ is the same as in Proposition 2.21.

Lemma 4.3. There is a well defined operator $\mathcal{D}: \Gamma_{\text {lin }}\left(\mathcal{A}_{1}, E_{1}\right) \longrightarrow \Gamma\left(\left(\operatorname{Ker} F_{1}\right)^{*} \otimes C_{2}\right)$ given by

$$
\mathcal{D}\left(\chi_{a}\right)(e, \xi)=\mathbf{D}\left(\chi_{a}, \phi_{a}\right)(e, \xi)
$$

where $\phi_{a} \in \Gamma_{\text {lin }}\left(\mathcal{A}_{2}^{*}, C_{2}^{*}\right)$ is any linear section covering $a \in \Gamma(A)$.
Proof. Remember the short exact sequence (1.20) for the double vector bundle $\left(\mathcal{A}_{2}^{*}, C_{2}^{*} ; A, M\right)$ :

$$
0 \longrightarrow \Gamma\left(\operatorname{Hom}\left(C_{2}^{*}, E_{2}^{*}\right)\right) \longrightarrow \Gamma_{\text {lin }}\left(\mathcal{A}_{2}^{*}, C_{2}^{*}\right) \longrightarrow \Gamma(A) \longrightarrow 0
$$

Let $\varphi \in \Gamma\left(\operatorname{Hom}\left(C_{2}^{*}, E_{2}^{*}\right)\right)$ and let $\phi_{\varphi}(\xi)=0_{\xi}+_{A} \overline{\varphi(\xi)}$ the linear section associated to $\varphi$. Since $F$ is a morphism of double vector bundles we have that $F\left(0_{e}\right)=0_{F_{1}(e)}$ for every $e \in E_{1}$. Then

$$
\begin{aligned}
\mathbf{D}\left(0, \phi_{\varphi}\right)(e, \xi) & =\left\langle F\left(0_{e}\right), \phi_{\varphi}(\xi)\right\rangle \\
& =\left\langle 0_{F_{1}(e)}, 0_{\xi}+_{A} \overline{\varphi(\xi)}\right\rangle \\
& =\left\langle F_{1}(e), \varphi(\xi)\right\rangle
\end{aligned}
$$

Hence, if $e \in \operatorname{Ker}\left(F_{1}\right)$ we have $\mathbf{D}\left(0, \phi_{\varphi}\right)(e, \xi)=0$ for every $\varphi \in \Gamma\left(\operatorname{Hom}\left(C_{2}^{*}, E_{2}^{*}\right)\right)$. So if $\phi_{a}, \psi_{a} \in \Gamma_{\text {lin }}\left(\mathcal{A}_{2}^{*}, C_{2}^{*}\right)$ and $\chi_{a} \in \Gamma_{\text {lin }}\left(\mathcal{A}_{1}, E_{1}\right)$, then

$$
\left(\mathbf{D}\left(\chi_{a}, \phi_{a}\right)-\mathbf{D}\left(\chi_{a}, \psi_{a}\right)\right)(e, \xi)=\mathbf{D}\left(0, \phi_{a}-\psi_{a}\right)(e, \xi)=\mathbf{D}\left(0, \phi_{\varphi}\right)(e, \xi)=0
$$

for every $e \in \operatorname{Ker}\left(F_{1}\right)$.
Let $\alpha \in \mathcal{A}_{1}$ be any element which projects to $e_{p} \in E_{1}$ and to $a_{p} \in A$, with $p \in M$. Denote by $a \in \Gamma(A)$ any section such that $a(p)=a_{p}$, and let $\chi_{a}: E_{1} \longrightarrow \mathcal{A}_{1}$ be any linear section covering $a$. Then there exists a unique element $\delta \in \mathcal{A}_{1}$ such that $\alpha=\chi_{a}(e)+_{E_{1}} \delta:$


Moreover, $\delta$ can be written $\delta=0_{e}+{ }_{A} \overline{c_{p}}=S_{c}(e)$ where $c \in \Gamma\left(C_{1}\right)$ such that $c(p)=c_{p}$.
Proposition 4.4. Let $\alpha \in \mathcal{A}_{1}$, and write it as $\alpha=\chi_{a}(e)+_{E_{1}}\left(0_{e}+_{A} \bar{c}\right)$ for some linear sections $\chi_{a}$ covering $a$. Then

$$
\alpha \in \operatorname{Ker}(F) \Leftrightarrow\left\{\begin{array}{l}
e \in \operatorname{Ker}\left(F_{1}\right) \\
\mathcal{D}\left(\chi_{a}\right)(e, \cdot)=-F_{0}(c)
\end{array}\right.
$$

Proof. We have to show that $\langle F(\alpha), \nu\rangle=0$ for all element $\nu \in \mathcal{A}_{2}^{*}$, where the dual and the pairing is over $A$. The fiber $\mathcal{A}_{2}^{*} \longrightarrow A$ over $a_{p}$ is generated by $0_{a}+C_{2}^{*} \eta$ and $\phi(\xi)$ for a fixed $\phi \in \Gamma_{\text {lin }}\left(\mathcal{A}_{2}^{*}, C_{2}^{*}\right)$ covering $a$, and $\xi \in\left(C_{2}^{*}\right)_{p}, \eta \in\left(E_{2}^{*}\right)_{p}$ varying . Hence

$$
F(\alpha)=0 \Leftrightarrow\left\{\begin{array}{l}
\left\langle F(\alpha), 0_{a}+C_{2}^{*} \eta\right\rangle=0 \\
\langle F(\alpha), \phi(\xi)\rangle=0
\end{array}\right.
$$

Since $F(\alpha)=F(\alpha)+E_{E_{2}} 0_{F_{1}(e)}$, the first equations becomes

$$
\begin{aligned}
0=\left\langle F(\alpha)+E_{2} 0_{F_{1}(e)}, 0_{a}+C_{2}^{*} \eta\right\rangle & =\left\langle F(\alpha), 0_{a}\right\rangle+\left\langle 0_{F_{1}(e)}, \bar{\eta}\right\rangle \\
& =0+\left\langle F_{1}(e), \eta\right\rangle .
\end{aligned}
$$

As $\eta$ is arbitrary, the first equation holds if and only if $e \in \operatorname{Ker}\left(F_{1}\right)$. Since $F$ is a double vector bundle morphism we have that $F(\alpha)=F\left(\chi_{a}(e)\right)+_{E_{2}}\left(0_{F_{1}(e)}+C_{2} \overline{F_{0}(c)}\right)$. Then the second equation is

$$
\begin{aligned}
0 & =\left\langle F\left(\chi_{a}(e)\right)+E_{E_{2}}\left(0_{F_{1}(e)}+C_{2} \overline{F_{0}(c)}\right), \phi(\xi)+C_{2}^{*} 0_{\xi}\right\rangle \\
& =\left\langle F\left(\chi_{a}(e)\right), \phi(\xi)\right\rangle+\left\langle\left(0_{F_{1}(e)}+C_{2} \overline{F_{0}(c)}, 0_{\xi}\right\rangle\right. \\
& =\mathcal{D}\left(\chi_{a}, \phi\right)(e, \xi)+\left\langle\xi, F_{0}(c)\right\rangle .
\end{aligned}
$$

Since $\xi$ is arbitrary, the second equation holds if and only if $\mathcal{D}\left(\chi_{a}\right)(e, \cdot)=-F_{0}(c)$.
The next theorem characterizes double vector subbundles in terms of the operator $\mathcal{D}$

Theorem 4.5. Let $(\mathcal{A}, E, A, M)$ be a DVB with core bundle $C$. Let $\Delta_{M} \subseteq E$ and $K \subseteq C$ be vector subbundles. Then there is a one to one correspondence between double vector subbundles $\left(\Delta, \Delta_{M} ; A, M\right)$ with core bundle $K$ and linear operators $\mathcal{D}: \Gamma_{\text {lin }}(\mathcal{A}, E) \longrightarrow \Gamma\left(\Delta_{M}^{*} \otimes C / K\right)$.

Proof. The first part of the proposition is Lemma 4.3, taking as double vector bundles $(\mathcal{A}, E ; A, M)$ and $\left(\mathcal{A} / \Delta, E / \Delta_{M} ; A, M\right)$, and as maps the respective projections. For the second part, write an element $\alpha \in \mathcal{A}$ as $\alpha=\chi_{a}(e)+_{E}\left(0_{e}+_{A} \bar{c}\right)$. Define

$$
\Delta=\left\{\begin{array}{l}
\alpha \in \mathcal{A}: \alpha=\chi_{a}(e)+_{E}\left(0_{e}+_{A} \bar{c}\right) \text { for } \chi_{a} \in \Gamma_{\text {lin }}(\mathcal{A}, E), \\
e \in \Delta_{M}, c \in C \text { s.t. } \mathcal{D}\left(\chi_{a}\right)(e)=-\pi(c)
\end{array}\right\}
$$

where $\pi: C \longrightarrow C / K$ is the projection. Note that $\Delta$ is well defined. We will prove now that $\Delta$ is linear with respect to the two linear structures on $\mathcal{A}$. Let $\alpha_{1}, \alpha_{2} \in \mathcal{A}_{e}$ with $e \in \Delta_{M}$, and write them as $\alpha_{i}=\chi_{a_{i}}(e)+_{E}\left(0_{e}+_{A} \bar{c}_{i}\right)$. Then

$$
\begin{aligned}
\alpha_{1}+_{E} \alpha_{2} & =\left(\chi_{a_{1}}(e)+_{E}\left(0_{e}+A \bar{c}_{1}\right)\right)+_{E}\left(\chi_{a_{2}}(e)+_{E}\left(0_{e}+_{A} \bar{c}_{2}\right)\right) \\
& =\left(\chi_{a_{1}}(e)+_{E} \chi_{a_{2}}(e)\right)+_{E}\left(0_{e}+_{A} \overline{c_{1}+c_{2}}\right)
\end{aligned}
$$

Since $\alpha_{1}, \alpha_{2} \in \Delta$ we have that $\mathcal{D}\left(\alpha_{i}\right)(e)=-\pi\left(c_{i}\right)$. The section $\chi_{a_{1}}+\chi_{a_{2}}$ is a linear section covering $a_{1}+a_{2}$, and by the linearity of $\mathcal{D}$ and of $\pi: C \longrightarrow C / K$ follow that
$\mathcal{D}\left(\chi_{a_{1}}+\chi_{a_{2}}\right)(e, \cdot)=-\pi\left(c_{1}+c_{2}\right)$. Hence $\alpha_{1}+\alpha_{2} \in \Delta$ over $e \in \Delta_{M}$. Suppose now that $\alpha_{1}, \alpha_{2} \in \mathcal{A}_{a}$ and write them as $\alpha_{1}=\chi_{a}\left(e_{1}\right)$ and $\alpha_{2}=\chi_{a}\left(e_{2}\right)+_{E}\left(0_{e_{2}}+{ }_{A} \bar{c}\right)$. Then

$$
\begin{aligned}
\alpha_{1}+_{A} \alpha_{2} & =\left(\chi_{a}\left(e_{1}\right)\right)+_{A}\left(\chi_{a}\left(e_{2}\right)+_{E}\left(0_{e_{2}}+_{A} \bar{c}\right)\right) \\
& =\left(\chi_{a}\left(e_{1}\right)+_{A} \chi_{a}\left(e_{2}\right)\right)+_{E} \bar{c} \\
& =\chi_{a}\left(e_{1}+e_{2}\right)+_{E} \bar{c}
\end{aligned}
$$

where we have used the interchange law and the linearity of the section. Then $\alpha_{1}+_{A} \alpha_{2} \in \Delta$ over $a \in A$. Therefore $\Delta$ is linear with respect to both structures of $\mathcal{A}$.

As consequence we can characterize the linear sections of $\mathcal{A} \longrightarrow E$ which restrict to $\Delta \longrightarrow \Delta_{M}$. For $X \in \Gamma_{\operatorname{lin}}(\mathcal{A}, E)$ we have

$$
\begin{equation*}
\left.X\right|_{\Delta_{M}} \in \Gamma_{\operatorname{lin}}\left(\Delta, \Delta_{M}\right) \Leftrightarrow \mathcal{D}(X)(e)=0 \tag{4.3}
\end{equation*}
$$

for all $e \in \Delta_{M}$.
Although we can say when a linear section of $\mathcal{A} \longrightarrow E$ restricts to $\Delta \longrightarrow \Delta_{M}$, the operator $\mathcal{D}$ is defined at the level of elements and not of sections. But we will need to use the sections of the vector bundle $\Delta \longrightarrow \Delta_{M}$, for example when we consider it as a Lie subalgebroid of $\mathcal{A} \longrightarrow E$.

Definition 4.6. [17] Given a double vector bundle $(\mathcal{A} \longrightarrow E ; A \longrightarrow M)$ with a double vector subbundle $\Delta \subseteq \mathcal{A}$, a horizontal lift $h: \Gamma(A) \longrightarrow \Gamma_{\operatorname{lin}}(\mathcal{A}, E)$ is called adapted to $\Delta$ if for every section $a \in \Gamma(A)$, the section $\left.h(a)\right|_{\Delta_{M}} \in \Gamma_{\text {lin }}\left(\Delta, \Delta_{M}\right)$.

Proposition 4.7. Let $\Delta$ be a double vector subbundle of $\mathcal{A}$ with side bundle $\Delta_{M}$ and core bundle $K$. Then there exists an operator

$$
\nabla: \Gamma_{l i n}(\mathcal{A}, E) \longrightarrow \Gamma\left(E^{*} \otimes C\right)
$$

such that

$$
\begin{equation*}
\mathcal{D}(X)(u)=\pi\left(\nabla_{u}(X)\right) \quad u \in \Gamma\left(\Delta_{M}\right) \tag{4.4}
\end{equation*}
$$

where $\pi: C \longrightarrow C / K$ is the projection map. Moreover if we have two operators $\nabla_{1}, \nabla_{2}: \Gamma_{\text {lin }}(\mathcal{A}, E) \longrightarrow \Gamma\left(E^{*} \otimes C\right)$ satisfying Equation (4.4) then

$$
\left(\nabla_{1}-\nabla_{2}\right) X \in \Gamma\left(\Delta_{M}^{*} \otimes K\right)
$$

Proof. Let $h: \Gamma(A) \longrightarrow \Gamma_{\text {lin }}(\mathcal{A}, E)$ be an adapted horizontal lift (for existence, see [17]). Let $X_{a} \in \Gamma_{\text {lin }}(\mathcal{A}, E)$. Then the section $h(a)-_{E} X_{a}$ is a core linear section covering $0 \in \Gamma(A)$. This means that there exists $T\left(X_{a}\right) \in \Gamma(H o m(E, C))$ such that

$$
h(a)-_{E} X_{a}=-S_{T\left(X_{a}\right)} .
$$

We define the operator $\nabla: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \longrightarrow \Gamma\left(E^{*} \otimes C\right)$ characterized by

$$
-S_{\nabla\left(X_{a}\right)}=h(a)-_{E} X_{a} .
$$

Since $h$ is adapted to the subbundle, we have that

$$
h(a)=X_{a}-{ }_{E} S_{\nabla\left(X_{a}\right)} \in \Gamma\left(\Delta, \Delta_{M}\right) .
$$

Then $\mathcal{D}\left(X_{a}\right)(u)=\pi\left(\nabla_{u}\left(X_{a}\right)\right)$ for all $u \in \Gamma\left(\Delta_{M}\right)$. Now, suppose we have two adapted horizontal lifts $h_{1}$ and $h_{2}$ and let $\nabla_{1}$ and $\nabla_{2}$ be the correspondent associated operator. Then

$$
h_{i}(a)(u)=X_{a}(u)-_{E} S_{\left(\nabla_{i}\right)_{u}\left(X_{a}\right)}(u) \quad \text { for } u \in \Gamma\left(\Delta_{M}\right) .
$$

Then

$$
\Delta_{u} \ni\left(h_{1}(a)-{ }_{A} h_{2}(a)\right)(u)=-S_{\left(\nabla_{1}-\nabla_{2}\right)_{u}\left(X_{a}\right)}(u)
$$

which means that $\left(\nabla_{1}-\nabla_{2}\right)_{u}\left(X_{a}\right) \in \Gamma(K)$.
Remark 4.8. Let $\nabla: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \longrightarrow \Gamma\left(E^{*} \otimes C\right)$ be a connection associated to $\Delta$, and let $f \in C^{\infty}(M)$. Then

$$
\nabla_{f e}(X)=f \nabla_{e}(X)
$$

Hence, we will write the connection as $\nabla: \Gamma(E) \times \Gamma_{\text {lin }}(\mathcal{A}, E) \longrightarrow \Gamma(C)$ when we want to emphasize the $C^{\infty}(M)$-linearity with respect to $\Gamma(E)$.

### 4.1.1 Linear distributions

Let $A \longrightarrow M$ be a vector bundle and consider the prolonged tangent bundle

with core bundle $A \longrightarrow M$.
Definition 4.9. A linear distribution $\Delta$ of $A$ is a double vector subbundle of the prolonged tangent bundle $T A$. In particular, there exist vector subbundles $\Delta_{M} \subseteq$ $T M$ and $C \subseteq A$ such that

is a double vector bundle with core bundle $C \longrightarrow M$.
We will apply what we did for double vector subbundles of this particular case.

Proposition 4.10. Let $A \longrightarrow M$ be a vector bundle and let $\Delta_{M} \subseteq T M$ and $C \subseteq A$ be vector subbundles. Then there is a one to one correspondence between
$\left\{\begin{array}{l}\Delta \subseteq T A \text { double vector subbundle with } \\ \text { side bundle } \Delta_{M} \text { and core bundle } C\end{array}\right\} \longleftrightarrow\left\{\begin{array}{l}\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(\left(\Delta_{M}\right)^{*} \otimes A / C\right) \text { s.t. } \\ \mathbb{D}_{u}(f a)=f \mathbb{D}_{u}(a)+\left(\mathcal{L}_{u} f\right) \pi(a)\end{array}\right\}$ where $u \in \Gamma\left(\Delta_{M}\right)$.

Proof. Let $\mathcal{D}: \Gamma_{\operatorname{lin}}(T A, T M) \longrightarrow \Gamma\left(\Delta_{M}^{*} \otimes A / C\right)$ be the operator associated to a linear distribution $\Delta$. Recall that the natural inclusion $\Gamma(A) \ni a \hookrightarrow T a \in \Gamma_{\operatorname{lin}}(T A, T M)$, satisfies the property (see [32])

$$
\begin{equation*}
T(f a)=(f \circ q) T a+\ell_{\mathrm{d} f} S_{a} \tag{4.5}
\end{equation*}
$$

Then define the map

$$
\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(\Delta_{M}^{*} \otimes A / C\right) \quad \mathbb{D}(a)=\mathcal{D}(T a)
$$

It follows that

$$
\begin{aligned}
\mathbb{D}(f a) & =\mathcal{D}(T(f a)) \\
& =\mathcal{D}\left((f \circ q) T a+\ell_{\mathrm{d} f} S_{a}\right) \\
& =f \mathcal{D}(T a)+\ell_{\mathrm{d} f} \pi_{T A}\left(S_{a}\right) \\
& =f \mathbb{D}(a)+\ell_{\mathrm{d} f} \pi(a) .
\end{aligned}
$$

Conversely, giving an operator $\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(\Delta_{M}^{*} \otimes A / C\right)$, let $\mathcal{D}(T a):=\mathbb{D}(a)$. The Leibniz rule implies that we can extend the map $\mathcal{D}$ to all linear sections of $T A$ over TM.

Remark 4.11. Proposition 4.10 can be obtained from [17], combining Proposition 5.5 and Lemma 5.6 therein. However, here the proof is different.

In [17] there is an operator

$$
\mathbb{D}^{\Delta}: \Gamma(A) \longrightarrow \Gamma\left(\Delta_{M}^{*} \otimes A / C\right)
$$

associated to a double vector subbundle $\Delta$ of $T A$, defined as follows:

$$
\mathbb{D}^{\Delta}(a)(x, \cdot)=\pi\left(L_{\chi}(a)\right)
$$

where $\chi: A \longrightarrow \Delta$ is any linear vector field taking values on the distribution $\Delta$, covering $x \in \Gamma\left(\Delta_{M}\right)$ and $L_{\chi}: \Gamma(A) \longrightarrow \Gamma(A)$ is the associated derivation to $\chi$. We have another operator $\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(\Delta_{M}^{*} \otimes A / C\right)$ associated to $\Delta$ which is obtained from the Proposition 4.10.

Proposition 4.12. We have that $\mathbb{D}=\mathbb{D}^{\Delta}$, where $\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(\Delta_{M}^{*} \otimes A / C\right)$ is the associated operator to $\Delta$, obtained from the Proposition 4.10.

Proof. For any choice of a linear section $\chi: A \longrightarrow \Delta$ we have

$$
\pi_{T A}(\chi(a))=0
$$

where $\pi_{T A}: T A \longrightarrow T A / \Delta$ is the natural projection. Combining Propositions 4.4 and 4.10 we have $\mathbb{D}_{u}(a)=-\pi\left(c_{p}\right)$, where $c_{p} \in A_{p}$ is the core element such that

$$
\chi(a)=T a(u)+_{T M}(u, c) .
$$

Now we will prove that $c=L_{\chi}(a)$. For this we shall see that $\chi\left(a_{p}\right)$ and $T a(u)+_{T M} \xi$, where $\xi=\left(u,-L_{\chi}(a)_{p}\right)$, are equal by checking that they act equally on functions locally defined at $a_{p}$. As usual, it suffices to consider pull-back functions $f \circ q$ for $f \in C_{\mathrm{loc}}^{\infty}(M)$ and fiberwise linear functions $\ell_{\varphi}$, for $\varphi \in \Gamma_{\mathrm{loc}}\left(A^{*}\right)$. For the first type, as

$$
T q\left(\chi\left(a_{p}\right)\right)=T q\left(T a(u)+_{T M} \xi\right)=u
$$

it follows that they act equally on pull-back functions. For the second type, on one hand, we have by definition,

$$
\left\langle\mathrm{d} \ell_{\varphi}\left(a_{p}\right), \chi\left(a_{p}\right)\right\rangle=\mathcal{L}_{u}\langle\varphi, a\rangle(p)-\left\langle\varphi(p), L_{\chi}(a)_{p}\right\rangle .
$$

On the other hand, using that $\mathrm{d} \ell_{\varphi}: A \longrightarrow T^{*} A$ is a vector bundle morphism from $A \longrightarrow M$ to the tangent prolongation $T^{*} A \longrightarrow A^{*}$ covering $\varphi: M \longrightarrow A^{*}$, it follows that

$$
\begin{aligned}
\left\langle\mathrm{d} \ell_{\varphi}\left(a_{p}\right), T a(u)+_{T M} \xi\right\rangle & =\left\langle\mathrm{d} \ell_{\varphi}\left(a_{p}\right)+_{A^{*}} \mathrm{~d} \ell_{\varphi}\left(0_{p}\right), T a(u)+_{T M} \xi\right\rangle \\
& =\left\langle\mathrm{d} \ell_{\varphi}\left(a_{p}\right), T a(u)\right\rangle+\left\langle\mathrm{d} \ell_{\varphi}\left(0_{p}\right), \xi\right\rangle \\
& =\mathcal{L}_{u}\langle\varphi, a\rangle(p)+\left\langle\mathrm{d} \ell_{\varphi}\left(0_{p}\right), \xi\right\rangle .
\end{aligned}
$$

The result follows now from the identity

$$
\left\langle\mathrm{d} \ell_{\varphi}\left(0_{p}\right),(u, c)\right\rangle=\left\langle\varphi(p), c_{p}\right\rangle,
$$

as the identification $T_{0_{p}} A=T_{p} M \oplus A_{p}$ sees $T_{p} M$ as the tangent space to the zero section and $A_{p}$ as the tangent space to the fiber $q^{-1}(p)$.

Let $h: \Gamma(A) \longrightarrow \Gamma_{\operatorname{lin}}(T A, T M)$ be an adapted horizontal lift to $\Delta$, and let

$$
\nabla^{h}: \Gamma_{l i n}(T A, T M) \longrightarrow \Gamma\left(T^{*} M \otimes A\right)
$$

be the associated connection operator to $\Delta$ satisfying $\left.\pi \circ \nabla^{h}\right|_{\Delta_{M}}=\mathcal{D}$. Since we have a natural inclusion $\Gamma(A) \hookrightarrow \Gamma_{\text {lin }}(T A, T M)$, we define a new operator by

$$
\widetilde{\nabla}: \Gamma(T M) \times \Gamma(A) \longrightarrow \Gamma(A) \quad \widetilde{\nabla}_{u}(a):=\nabla_{u}^{h}(T a)
$$

Note that since the inclusion $\Gamma(A) \hookrightarrow \Gamma_{\text {lin }}(T A, T M)$ is not $C^{\infty}(M)$-linear we have

$$
\widetilde{\nabla}_{u}(f a)=f \widetilde{\nabla}_{u} a+\left(\mathcal{L}_{u} f\right) a,
$$

which means that $\widetilde{\nabla}$ is actually a usual connection. By Proposition 4.12 we have

$$
\left.\pi \circ \widetilde{\nabla}\right|_{\Delta_{M}}=\mathbb{D}=\mathbb{D}^{\Delta}
$$

Hence by Theorem 5.7 in [17], it follows that $\widetilde{\nabla}$ is adapted to the distribution, that is, that for every $u \in \Gamma\left(\Delta_{M}\right)$ the linear vector field $X_{\widetilde{\nabla}_{u}}: A \longrightarrow T A$ corresponding to the derivation $\widetilde{\nabla}_{u}: \Gamma(A) \longrightarrow \Gamma(A)$ is a section of the distribution $\Delta$ (see [17]).

Example 4.13. Involutive Distributions. Consider now a linear distribution $\Delta \subseteq T A$ which is also involutive. In particular this means that $\Delta \longrightarrow A$ is a VB-algebroid over $\Delta_{M} \longrightarrow M$, which implies that $\Delta_{M} \longrightarrow M$ has a Lie algebroid structure, which in this case means that $\Delta_{M}$ is an involutive distribution over $M$. Let $\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(\left(\Delta_{M}\right)^{*} \otimes A / K\right)$ and let $a \in \Gamma(K)$. Since $K$ is the core bundle of $\left(\Delta, A ; \Delta_{M}, M\right)$ it follows that $a^{\uparrow} \in \Gamma_{A}(\Delta)$. By the involutive condition we have $\left[a^{\uparrow}, \Gamma_{A}(\Delta)\right] \subseteq \Gamma_{A}(\Delta)$. Using Lemma 4.2 in [27], we get that

$$
\left.T a\right|_{\Delta_{M}} \in \Gamma_{\operatorname{lin}}\left(\Delta, \Delta_{M}\right)
$$

Then $h(a)=T a-S_{\tilde{\nabla}(a)} \in \Gamma_{\operatorname{lin}}\left(\Delta, \Delta_{M}\right)$, so $\widetilde{\nabla}_{u} a \in \Gamma(K)$ for all $u \in \Gamma(\Delta)$. Hence $\pi\left(\widetilde{\nabla}_{u} a\right)=0$, and therefore $\left.\mathbb{D}\right|_{\Gamma(K)}=0$. This allows us to define a map $\mathbb{D}: \Gamma\left(\Delta_{M}\right) \times$ $\Gamma(A / K) \longrightarrow \Gamma(A / K)$. Let $s: \Gamma(T M) \longrightarrow \mathfrak{X}_{\operatorname{lin}}(A)$ be the horizontal lift given by

$$
s(u)\left(a_{p}\right)=h(a)\left(u_{p}\right) \in T_{p} A
$$

Consider the following linear vector fields on $A: s(u)+\left(\widetilde{\nabla}_{u}(a)\right)^{\uparrow}, s(v)+\left(\widetilde{\nabla}_{v}(a)\right)^{\uparrow}$ and $s([u, v])+\left(\widetilde{\nabla}_{[u, v]}(a)\right)^{\uparrow}$, for $u, v \in \Gamma\left(\Delta_{M}\right)$. Then
(4.6) $\left[s(u)+\left(\widetilde{\nabla}_{u}(a)\right)^{\uparrow}, s(v)+\left(\widetilde{\nabla}_{v}(a)\right)^{\uparrow}\right]=[s(u), s(v)]+\left(\mathbb{D}_{s(u)}\left(\widetilde{\nabla}_{v} a\right)-\mathbb{D}_{s(v)}\left(\widetilde{\nabla}_{u} a\right)\right)^{\uparrow}$

The linear vector fields $s([u, v])+\left(\widetilde{\nabla}_{[u, v]}(a)\right)^{\uparrow}$ and (4.6) cover the same section $[u, v]$, so their difference is a linear core section $k^{\uparrow}$. But since the horizontal lift $s$ is adapted and $[u, v] \in \Gamma\left(\Delta_{M}\right)$, then $k \in \Gamma(K)$. So

$$
k+\widetilde{\nabla}_{[u, v]} a=\mathbb{D}_{s(u)}\left(\widetilde{\nabla}_{v} a\right)-\mathbb{D}_{s(v)}\left(\widetilde{\nabla}_{u} a\right)
$$

Then applying $\pi$ to both sides, we get that the induced map $\mathbb{D}: \Gamma\left(\Delta_{M}\right) \times \Gamma(A / K) \longrightarrow$ $\Gamma(A / K)$ is a flat $\Delta_{M}$-connection. Then we recover the next result.

Proposition 4.14. $[17,27] \operatorname{Let}\left(\Delta, A ; \Delta_{M}, M\right)$ be a linear distribution on $A$ with core bundle $K$. Then $\Delta$ is involutive if and only if $\Delta_{M}$ is involutive and the associated map $\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(\Delta_{M}^{*} \otimes A / K\right)$ satisfies

1. $\left.\mathbb{D}\right|_{\Gamma(K)}=0$
2. The induced connection $\mathbb{D}: \Gamma\left(\Delta_{M}\right) \times \Gamma(A / K) \longrightarrow \Gamma(A / K)$ is a flat $\Delta_{M^{-}}$ connection.

### 4.1.2 Double vector subbundles of $T A \oplus T^{*} A$

Let $(\mathfrak{L}, U ; A, M)$ be a double vector subbundle of $\left(T A \oplus T^{*} A, T M \oplus A^{*} ; A, M\right)$ with core bundle $K \subseteq A \oplus T^{*} M$, and let

$$
\mathcal{D}: \Gamma_{l i n}\left(T A \oplus T^{*} A, T M \oplus A^{*}\right) \longrightarrow \Gamma\left(U^{*} \otimes \frac{A \oplus T^{*} M}{K}\right)
$$

be the associated canonical operator. We characterize this double vector subbundles.
Proposition 4.15. Let $A \longrightarrow M$ be a vector bundle and let $U \subseteq T M \oplus A^{*}$ and $K \subseteq A \oplus T^{*} M$ be vector subbundles. Then there is a one to one correspondence between double vector subbundles $\mathfrak{L} \subseteq T A \oplus T^{*} A$ with side bundle $U$ and core bundle $K$ and operators

$$
\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(U^{*} \otimes \frac{A \oplus T^{*} M}{K}\right)
$$

satisfying the following Leibniz rule

$$
\mathbb{D}_{u}(f a)=f \mathbb{D}_{u}(a)+\left(\ell_{d f} a, \ell_{-a} d f\right)
$$

Proof. Define the operator $\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(U^{*} \otimes \frac{A \oplus T^{*} M}{K}\right)$ by

$$
\mathbb{D}(a):=\mathcal{D}\left(T a, R_{a}\right),
$$

where $T a: T M \longrightarrow T A$ is the linear section associated to $a: M \longrightarrow A$, and $R_{a}: A^{*} \longrightarrow T^{*} A$ is given by Equation (1.24). We only need to check the Leibniz rule

$$
\begin{aligned}
\mathbb{D}(f a) & =\mathcal{D}\left(T(f a), R_{(f a)}\right) \\
& =\mathcal{D}\left(f T a+\ell_{\mathrm{d} f} S_{a}, f R_{a}+\ell_{-a} S_{\mathrm{d} f}\right) \\
& =\mathcal{D}\left(f T a, f R_{a}\right)+\mathcal{D}\left(\ell_{\mathrm{d} f} S_{a}, \ell_{-a} S_{\mathrm{d} f}\right) \\
& =f \mathcal{D}\left(T a, R_{a}\right)+\pi_{T A \oplus T^{*} A}\left(\ell_{\mathrm{d} f} S_{a}, \ell_{-a} S_{\mathrm{d} f}\right) \\
& =f \mathbb{D}(a)+\left(\ell_{\mathrm{d} f} a, \ell_{-a} \mathrm{~d} f\right) .
\end{aligned}
$$

Let $h: \Gamma(A) \longrightarrow \Gamma_{\text {lin }}\left(T A \oplus T^{*} A, T M \oplus A^{*}\right)$ be an adapted horizontal lift and let

$$
\nabla^{h}: \Gamma_{\operatorname{lin}}\left(T A \oplus T^{*} A, T M \oplus A^{*}\right) \longrightarrow \Gamma\left(\left(T M \oplus A^{*}\right)^{*} \otimes\left(A \oplus T^{*} M\right)\right.
$$

be the associated connection operator with the property $\left.\pi \circ \nabla^{h}\right|_{U}=\mathcal{D}$. Define now the operator

$$
\widetilde{\nabla}: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma(A) \longrightarrow \Gamma\left(A \oplus T^{*} M\right) \quad \widetilde{\nabla}_{u} a:=\nabla_{u}^{h}\left(T a, R_{a}\right) .
$$

Note that $\left.\pi \circ \widetilde{\nabla}\right|_{U}=\mathbb{D}$.

Proposition 4.16. The map $\nabla^{h}: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma(A) \longrightarrow \Gamma\left(A \oplus T^{*} M\right)$ is $C^{\infty}(M)$ linear in the first coordinate and satisfies the following Leibniz rule with respect to the second coordinate

$$
\nabla^{h}(f a)=f \nabla^{h}(a)+\left(\ell_{d f} a, \ell_{-a} d f\right)
$$

Proof. Assume that the horizontal lift $h$ is $C^{\infty}(M)$-linear. Then

$$
\begin{aligned}
h(f a)=f h(a) & =f\left(T a, R_{a}\right)-f S_{\nabla^{h}(a)} \\
h(f a) & =\left(T(f a), R_{f a}\right)-S_{\nabla^{h}(f a)}
\end{aligned}
$$

We know that

$$
\begin{aligned}
T(f a) & =f T a+_{T M} \ell_{\mathrm{d} f} S_{a} \\
R_{f a} & =f R_{a}+_{A^{*}} \ell_{-a} S_{\mathrm{d} f}
\end{aligned}
$$

Then $\left(T(f a), R_{f a}\right)=f\left(T a, R_{a}\right)+\left(\ell_{\mathrm{d} f} S_{a}, \ell_{-a} S_{\mathrm{d} f}\right)$, which implies that

$$
S_{\nabla^{h}(f a)}=f S_{\nabla^{h}(a)}+\left(\ell_{\mathrm{d} f} S_{a}, \ell_{-a} S_{\mathrm{d} f}\right)
$$

Hence

$$
\nabla^{h}(f a)=f \nabla^{h}(a)+\left(\ell_{\mathrm{d} f} a, \ell_{-a} \mathrm{~d} f\right) .
$$

With respect to the first coordinate, for $\tau \in \Gamma\left(T M \oplus A^{*}\right)$,

$$
-S_{\nabla_{f \tau}^{h} a}(\tau)=h(a)(f \tau)-\left(T a, R_{a}\right)(f \tau)=f h(a)(\tau)-f\left(T a, R_{a}\right)(\tau)=f S_{\nabla_{\tau} a}
$$

Therefore $\nabla^{h}$ is $C^{\infty}(M)$-linear in the first argument.
The following proposition connects this work with [26]. See Appendix for definition of Dorfman connections and for the proof of this proposition.

Proposition 4.17. There is one-to-one correspondence between horizontal lifts $h$ : $\Gamma(A) \longrightarrow \Gamma\left(T A \oplus T^{*} A\right)$ and $\left(T M \oplus A^{*}\right)$-Dorfman connection on $A \oplus T^{*} M$

$$
\Lambda: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma\left(A \oplus T^{*} M\right) \longrightarrow \Gamma\left(A \oplus T^{*} M\right)
$$

via the relation

$$
\begin{equation*}
\Lambda_{(u, \xi)}(a, \theta)=\nabla_{(u, \xi)}^{h} a+\left(0, d\langle\xi, a\rangle+\mathcal{L}_{u} \theta\right) \tag{4.7}
\end{equation*}
$$

Moreover, if $(\mathfrak{L}, U ; A, M)$ be a double vector subbundle of $\left(T A \oplus T^{*} A, T M \oplus A^{*} ; A, M\right)$ with core bundle $K \subseteq A \oplus T^{*} M$, then $h$ is adapted to $\mathfrak{L}$ if and only if $\Lambda$ is adapted to $\mathfrak{L}$.

### 4.2 Double vector subalgebroids

In this section we endow on a double vector subbundle a Lie algebroid structure, and then we describe it in terms on an infinitesimal data. As before, we consider the particular cases of subbundles of $T A$ and of $T A \oplus T^{*} A$.

Definition 4.18. [17]. Let $(\mathcal{A}, E ; A, M)$ be a VB-algebroid. A double vector subbundle $\left(\Delta, \Delta_{M} ; A, M\right)$ is a $V B$-subalgebroid of $\mathcal{A}$ if $\Delta \longrightarrow \Delta_{M}$ is a Lie subalgebroid of $\mathcal{A} \longrightarrow E$.

Let $(\mathcal{A}, E ; A, M)$ be a VB-algebroid with core bundle $C$ and let $\left(\Delta, \Delta_{M} ; A, M\right)$ be a VB-subalgebroid of $\mathcal{A}$, with core bundle $K$. Since we are working with quotients, we will show that the (linear) quotient $\mathcal{A} / \Delta$ over $A$ has a Lie algebroid structure over $E / \Delta_{M}$ such that $\left(\mathcal{A} / \Delta, E / \Delta_{M} ; A, M\right)$ is a VB-algebroid with core bundle $C / K$. The compatibility of the double linear structure on

follows by the definition of double vector subbundle. Let $h: \Gamma(A) \longrightarrow \Gamma_{\operatorname{lin}}(\mathcal{A}, E)$ be an adapted horizontal lift. Define the horizontal lift

$$
\bar{h}: \Gamma(A) \longrightarrow \Gamma_{\operatorname{lin}}\left(\mathcal{A} / \Delta, E / \Delta_{M}\right) \quad \text { by } \quad \bar{h}(a):=\overline{h(a)}
$$

Since $h$ is adapted, $\bar{h}$ is well defined. With respect to core sections, for $\bar{c} \in \Gamma(C / K)$, the section $S_{\bar{c}}$ is defined by

$$
S_{\bar{c}}: E / \Delta_{M} \longrightarrow \mathcal{A} / \Delta \quad S_{\bar{c}}(\bar{e})=\overline{S_{c}(e)}
$$

Let us see that this is well defined. Let $c_{1} \in \bar{c}$ and $e_{1} \in \bar{e}$. That means there exist $k \in K$ and $\delta \in \Delta_{M}$ such that $c_{1}=c+k$ and $e_{1}=e+\delta$. Then

$$
\begin{aligned}
S_{c_{1}}\left(e_{1}\right) & =S_{c+k}(e+\delta) \\
& =0_{e+\delta}+(\overline{c+\delta}) \\
& =\left(0_{e}+\bar{C}\right)+\left(0_{\delta}+\bar{k}\right) \\
& =S_{c}(e)+S_{k}(\delta) .
\end{aligned}
$$

Since $S_{k}(\delta) \in \mathcal{A} / \Delta$ follows that $\overline{S_{c_{1}}\left(e_{1}\right)}=\overline{S_{c}(e)}$, which implies that the core section is well defined. With respect to the bracket, we define

- $[\bar{h}(a), \bar{h}(b)]=\overline{h[a, b]}$
- $\left[\bar{h}(a), S_{\bar{c}}\right]=S_{\overline{\nabla_{h(a)}^{0}}}$
- $\left[S_{\bar{c}_{1}}, S_{\overline{c_{2}}}\right]=0$.

The anchor map $\bar{\rho}: \mathcal{E} / \Delta \longrightarrow T E / T \Delta_{M}$ is determined by

- $\bar{\rho}(\bar{h}(a))=\overline{\rho(h(a))}$,
- $\bar{\rho}\left(S_{\bar{c}}\right)=\overline{\partial(c)}^{\uparrow}$
which is well defined because $\Delta$ is a subalgebriod, $h$ is adapted to $\Delta$, and the map $\partial: E \longrightarrow C$ restrics to $\Delta_{M} \longrightarrow K$. Therefore $\mathcal{E} / \Delta \longrightarrow E / \Delta$ has a Lie algebroid structure, and hence it is a VB-algebroid over $A$. The projection map $F: \mathcal{A} \longrightarrow \mathcal{A} / \Delta$ is now a morphism of Lie algebroids. Indeed, the compatibility with the anchor follows by definition of $\bar{\rho}$. The core and linear sections of $\Gamma\left(\mathcal{A} / \Delta, E / \Delta_{M}\right)$ are induced by core and linear sections of $\Gamma(\mathcal{A}, E)$, so the compatibility of the bracket follows by
- $\overline{[h(a), h(b)]}=\overline{h([a, b])+\Omega_{a, b}}=\overline{h([a, b])}+\overline{S_{\Omega_{a, b}}}$, and since $h$ is adapted the section $\Omega_{a, b} \in \Gamma\left(\operatorname{Hom}\left(\Delta_{M}, K\right)\right)$
- $\overline{\left[h(a), S_{c}\right]}=\overline{\left[S_{\nabla_{h(a)}^{0} c}\right]}=S_{\overline{\nabla_{h(a)}^{0}}}$.

Hence the map $F: \mathcal{A} \longrightarrow \mathcal{A} / \Delta$ is a morphism of Lie algebroids.
Now dualizing $\mathcal{A} / \Delta$ over $A$ we obtain the VB-algebroid

with core bundle $\Delta_{M}^{\circ}$, where we have identified $(\mathcal{A} / \Delta)^{*} \simeq \Delta^{\circ}$, the annihilator of $\Delta$ in $\mathcal{A}^{*} ;\left(E / \Delta_{M}\right)^{*} \simeq \Delta_{M}^{\circ}$, the annihilator of $\Delta_{M}$ in $E^{*} ;$ and $(C / K)^{*} \simeq K^{\circ}$, the annihilator of $K$ in $C^{*}$. Denote by $F: \mathcal{A} \longrightarrow \mathcal{A} / \Delta$ be the projection map and by

$$
\bar{F}: \mathcal{A} \times{ }_{A} \Delta^{\circ} \longrightarrow \mathbb{R}
$$

the natural pairing between $\mathcal{A}$ and $\mathcal{A}^{*}$ :

$$
\bar{F}(\alpha, \eta)=\langle F(\alpha), \eta\rangle_{A} .
$$

It is straightforward to check that if $\Delta$ is a Lie subalgebroid of $\mathcal{A}$ then $\bar{F}$ is a morphism of Lie algebroid, where we are considering $\mathbb{R}$ equipped with the trivial Lie algebroid structure.

Remember that we have canonically associated to a VB algebroid $\mathcal{A}$ the following operators:

- A vector bundle map $\partial: C \longrightarrow E$ (see Equation (1.23))
- A flat connection $\nabla^{1}: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \times \Gamma\left(E^{*}\right) \longrightarrow \Gamma\left(E^{*}\right)$ (see Equation (1.21))
- A flat connection $\nabla^{0}: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \times \Gamma(C) \longrightarrow \Gamma(C)$ (see Equation (1.22)).

Remark 4.19. Throughout this part, we use the notation $\nabla^{1}$ instead $\left(\nabla^{1}\right)^{*}$ for the action of linear sections on $\Gamma\left(E^{*}\right)$ to simplify the equations.

Since the map $\bar{F}: \mathcal{A} \oplus \Delta^{\circ} \longrightarrow \mathbb{R}$ is bilinear with respect to $A$, and also is a Lie algebroid morphism we have the following result as a consequence of Theorem 2.28.
Proposition 4.20. Let $\left(\Delta, \Delta_{M} ; A, M\right)$ be a Lie subalgebroid of $(\mathcal{A}, E ; A, M)$ with core bundle $K$. Then $\partial(K) \subseteq \Delta_{M}$ and there exists an operator

$$
\mathbf{D}: \Gamma_{l i n}(\mathcal{A}, E) \times_{\Gamma(A)} \Gamma_{l i n}\left(\Delta^{\circ}, K^{\circ}\right) \longrightarrow\left(E^{*} \otimes C / K\right)
$$

such that the following equations hold

$$
\begin{align*}
\mathbf{D}([X, Y]) & =X \cdot \mathbf{D}(Y)-Y \cdot \mathbf{D}(X)  \tag{4.8}\\
\iota_{\partial(c)} \mathbf{D}(X) & =\nabla_{X_{2}}^{1} \pi_{C}(c)-\pi_{C}\left(\nabla_{X_{1}}^{0} c\right)  \tag{4.9}\\
\bar{\partial}(\mathbf{D}(X)(e)) & =\left(\nabla_{X_{2}}^{0}\right)^{*} \pi_{E}(e)-\pi_{E}\left(\left(\nabla_{X}^{1}\right)^{*} e\right) \tag{4.10}
\end{align*}
$$

where the action is

$$
\ell_{X \cdot \mathbf{D}(Y)}=\mathcal{L}_{\rho\left(X_{1}, X_{2}\right)} \bar{F}\left(Y_{1}, Y_{2}\right)
$$

for $X=\left(X_{1}, X_{2}\right), Y=\left(Y_{1}, Y_{2}\right) \in \Gamma_{\text {lin }}(\mathcal{A}, E) \times_{\Gamma(A)} \Gamma_{\text {lin }}\left(\Delta^{\circ}, K^{\circ}\right)$, and the map $\bar{\partial}$ : $C / K \longrightarrow E / \Delta_{M}$ is the quotient map.

From the previous section, there is a correspondence between double vector subbundles and certain operators. As our goal is to describe VB-subalgebroids, we will rewrite Proposition 4.20 in terms of the operator $\mathcal{D}$ associated to $\Delta$.

Let $\nabla: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \longrightarrow \Gamma(\operatorname{Hom}(E, C))$ be the associated connection to the double vector subbundle $\Delta$, after the choice of an horizontal lift $h: \Gamma(A) \longrightarrow \Gamma_{\text {lin }}(\mathcal{A}, E)$. Since $\Delta$ is a VB-algebroid, the linear sections are closed by the Lie bracket, so there exists a section $\Omega \in \Gamma\left(\wedge^{2} A\right) \otimes \Gamma(\operatorname{Hom}(E, C))$ such that

$$
\Omega_{a, b}=h([a, b])-[h(a), h(b)]
$$

and since the horizontal lift is adapted follows that $\Omega \in \Gamma\left(\wedge^{2} A\right) \otimes \Gamma\left(\operatorname{Hom}\left(\Delta_{M}, K\right)\right)$. Let $X_{a}, X_{b} \in \Gamma_{\operatorname{lin}}(\mathcal{A}, E)$. By definition we have

$$
\begin{aligned}
S_{\nabla_{X_{a}}} & =h(a)-X_{a} \\
S_{\nabla_{X_{b}}} & =h(b)-X_{b} \\
S_{\nabla_{\left[X_{a}, X_{b}\right]}} & =h([a, b])-\left[X_{a}, X_{b}\right] .
\end{aligned}
$$

On the other hand

$$
\begin{aligned}
{[h(a), h(b)] } & =\left[X_{a}+S_{\nabla_{X_{a}}}, X_{b}+S_{\nabla_{X_{b}}}\right] \\
& =\left[X_{a}, X_{b}\right]+\left[X_{a}, S_{\nabla_{X_{b}}}\right]+\left[S_{\nabla_{X_{a}}}, X_{b}\right]+\left[S_{\nabla_{X_{a}}}, S_{\nabla_{X_{b}}}\right] \\
& =\left[X_{a}, X_{b}\right]+S_{\left(\nabla_{X_{a}}^{0} \circ \nabla_{X_{b}}-\nabla_{X_{b}} \circ \nabla_{X_{a}}^{1}\right)}+S_{\left(\nabla_{X_{a}} \circ \nabla_{X_{b}}^{1}-\nabla_{X_{b}}^{0} \circ \nabla_{X_{a}}\right)} \\
& +S_{\left(\nabla_{X_{a}} \circ \partial \circ \nabla_{X_{b}}-\nabla_{X_{b}} \circ \partial \circ \nabla_{X_{a}}\right)} .
\end{aligned}
$$

Then

$$
\begin{aligned}
\Omega_{a, b}= & \nabla_{\left[X_{a}, X_{b}\right]}-\left(\nabla_{X_{a}}^{0} \circ \nabla_{X_{b}}-\nabla_{X_{b}} \circ \nabla_{X_{a}}^{1}\right)-\left(\nabla_{X_{a}} \circ \nabla_{X_{b}}^{1}-\nabla_{X_{b}}^{0} \circ \nabla_{X_{a}}\right) \\
- & \left(\nabla_{X_{a}} \circ \partial \circ \nabla_{X_{b}}-\nabla_{X_{b}} \circ \partial \circ \nabla_{X_{a}}\right) \\
= & \nabla_{\left[X_{a}, X_{b}\right]}-\nabla_{X_{a}}\left(\nabla_{X_{b}}^{1}+\partial \circ \nabla_{X_{b}}\right)+\nabla_{X_{b}}\left(\nabla_{X_{a}}^{1}+\partial \circ \nabla_{X_{a}}\right) \\
& -\nabla_{X_{a}}^{0} \circ \nabla_{X_{b}}+\nabla_{X_{b}}^{0} \circ \nabla_{X_{a}}
\end{aligned}
$$

Therefore, taking $u \in \Gamma\left(\Delta_{M}\right)$

$$
\begin{aligned}
\pi\left(\nabla_{\left[X_{a}, X_{b}\right]} u\right)= & \pi\left(\nabla_{X_{a}}\left(\nabla_{X_{b}}^{1}+\partial \circ \nabla_{X_{b}}\right) u\right)-\pi\left(\nabla_{X_{b}}\left(\nabla_{X_{a}}^{1}+\partial \circ \nabla_{X_{a}}\right) u\right) \\
& +\pi\left(\nabla_{X_{a}}^{0} \circ \nabla_{X_{b}} u\right)-\pi\left(\nabla_{X_{b}}^{0} \circ \nabla_{X_{a}} u\right)
\end{aligned}
$$

Then, the equation for $\mathcal{D}$ is

$$
\begin{aligned}
\mathcal{D}_{e}([X, Y])= & \pi\left(\nabla_{X}\left(\nabla_{X_{b}}^{1}+\partial \circ \nabla_{Y}\right) u\right)-\pi\left(\nabla_{Y}\left(\nabla_{X}^{1}+\partial \circ \nabla_{X}\right) u\right) \\
& +\pi\left(\nabla_{X}^{0} \circ \nabla_{Y} u\right)-\pi\left(\nabla_{Y}^{0} \circ \nabla_{X} u\right) .
\end{aligned}
$$

We state now the main theorem of this chapter.
Theorem 4.21. Let $(\mathcal{A}, E ; A, M)$ be a VB-algebroid with core bundle $C$, and let $\left(\Delta, \Delta_{M} ; A, M\right)$ be a double vector subbundle with core bundle $K$ and let

$$
\nabla: \Gamma_{l i n}(\mathcal{A}, E) \longrightarrow \Gamma(\operatorname{Hom}(E, C))
$$

be a connection associated to $\Delta$. Then $\Delta \longrightarrow \Delta_{M}$ is a Lie subalgebroid of $\mathcal{A} \longrightarrow E$ if and only if the following equations hold

$$
\begin{align*}
& \partial(K) \subseteq  \tag{4.11}\\
& \iota_{M}  \tag{4.12}\\
& \iota_{\partial(c)} \mathcal{D}(X)=  \tag{4.13}\\
& \bar{\partial}(\mathcal{D}(X)(u))=-\pi\left(\nabla_{X}^{0} c\right) \quad c \in K  \tag{4.14}\\
& \mathcal{D}_{u}([X, Y])= \pi\left(\nabla_{\left(\nabla_{Y}^{1}+\partial\right)}\right) \\
&\left.+\pi\left(\nabla_{X}^{0} \circ \nabla_{u} Y\right)(u) X\right)-\pi\left(\nabla_{Y}^{0} \circ \nabla_{u} X\right)
\end{align*}
$$

where $\bar{\partial}: C / K \longrightarrow E / \Delta_{M}$ is the quotient map.
Proof. We only need to check the converse. Taking $\mathcal{D}=\left.\pi \circ \nabla\right|_{\Delta_{M}}$, it defines a double vector subbundle $\Delta \subseteq \mathcal{A}$. We will prove $\Delta \longrightarrow \Delta_{M}$ is a Lie subalgebroid of $\mathcal{A} \longrightarrow E$. The anchor $\rho_{\Delta}: \Delta \longrightarrow T \Delta_{M}$ has to be the restriction of the anchor $\rho_{\mathcal{A}}$ to $\Delta$. Let $k \in \Gamma(K)$. Then $\rho_{\mathcal{A}}\left(S_{k}\right)=\partial(k)^{\uparrow} \in \mathfrak{X}(E)$. So

$$
\partial(k)^{\uparrow} \in \mathfrak{X}\left(\Delta_{M}\right) \Longleftrightarrow \partial(k) \in \Gamma\left(\Delta_{M}\right) \Longleftrightarrow \partial(K) \subseteq \Delta_{M} .
$$

Consider now a linear section given by $X+S_{\nabla(X)} \in \Gamma\left(\Delta, \Delta_{M}\right)$. Then

$$
\begin{aligned}
\rho_{\mathcal{A}}\left(X+S_{\nabla(X)}\right) \in \mathfrak{X}\left(\Delta_{M}\right) & \left.\Longleftrightarrow \pi_{E}\left(\rho_{\mathcal{A}}(X)(u)\right)+\pi_{E}\left(S_{\nabla(X)}\right)(u)\right)=0 \\
& \Longleftrightarrow \pi_{E}\left(\nabla_{X}^{1} u\right)+\pi_{E}\left(\partial\left(\nabla_{u}(X)\right)\right)=0 \\
& \Longleftrightarrow-\pi_{E}\left(\nabla_{X}^{1} u\right)=\bar{\partial}\left(\pi\left(\nabla_{u}(X)\right)\right) \\
& \Longleftrightarrow-\pi_{E}\left(\nabla_{X}^{1} u\right)=\bar{\partial}\left(\mathcal{D}_{u}(X)\right)
\end{aligned}
$$

Now we check the Lie bracket conditions. Since $K \subseteq C$ follows that $\left[S_{k_{1}}, S_{k_{2}}\right]=0$ for all $k_{1}, k_{2} \in \Gamma(K)$. For linear and core sections we have

$$
\left[X+S_{\nabla(X)}, S_{k}\right]=\left[X, S_{k}\right]+\left[S_{\nabla(X)}, S_{k}\right]=S_{\nabla_{X}^{0} k}+S_{\nabla(X) \circ \partial \circ k}
$$

Then $\left[X+S_{\nabla(X)}, S_{k}\right] \in \Gamma_{\operatorname{cor}}\left(\Delta, \Delta_{M}\right)$ if and only if

$$
\begin{aligned}
\nabla_{X}^{0} k+\nabla(X) \circ \partial \circ k \in \Gamma(K) & \Longleftrightarrow-\pi\left(\nabla_{X}^{0} k\right)=\pi(\nabla(X) \circ \partial \circ k) \\
& \Longleftrightarrow-\pi\left(\nabla_{X}^{0} k\right)=\iota_{\partial(k)} \mathcal{D}(X) .
\end{aligned}
$$

For two linear sections

$$
\begin{aligned}
{\left[X+S_{\nabla_{X}}, Y+S_{\nabla_{Y}}\right] } & =[X, Y]+\left[X, S_{\nabla_{Y}}\right]+\left[S_{\nabla_{X}}, Y\right]+\left[S_{\nabla_{X}}, S_{\nabla_{Y}}\right] \\
& =[X, Y]+S_{\left(\nabla_{X}^{0} \circ \nabla(Y)-\nabla(Y) \circ \nabla_{X}^{1}\right)}+S_{\left(\nabla(X) \circ \nabla_{Y}^{1}-\nabla_{Y}^{0} \circ \nabla(X)\right)} \\
& +S_{(\nabla(X) \circ \partial \circ \nabla(Y)-\nabla(Y) \circ \partial \circ \nabla(X))} .
\end{aligned}
$$

Then $\left[X+S_{\nabla_{X}}, Y+S_{\nabla_{Y}}\right] \in \Gamma_{\operatorname{lin}}\left(\Delta, \Delta_{M}\right)$ if and only if

$$
\nabla([X, Y])-\nabla_{\left(\nabla_{Y}^{1}+\partial \circ \nabla(Y)\right)}(X)+\nabla_{\left(\nabla_{X}^{1}+\partial \circ \nabla(X)\right)}(Y)-\nabla_{X}^{0} \circ \nabla(Y)+\nabla_{Y}^{0} \circ \nabla(X)
$$

is in $\Gamma\left(\operatorname{Hom}\left(\Delta_{M}, K\right)\right)$, if and only if, equation (4.14) holds.

Example 4.22. Linear subalgebroids of $T A$. Consider the tangent VB-algebroid $(T A, T M ; A, M)$. Recall that we have a natural inclusion $\Gamma(A)$ in $\Gamma_{\operatorname{lin}}(T A, T M)$ : $a \longrightarrow T a$. Hence we can rewrite the canonical connections in terms of sections of $\Gamma(A)$ :

- $\nabla^{0}: \Gamma(A) \times \Gamma(A) \longrightarrow \Gamma(A)$ is given by

$$
\nabla_{a}^{0} b=[a, b]
$$

- $\nabla^{1}: \Gamma(A) \times \Gamma(T M) \longrightarrow \Gamma(T M)$ is given by

$$
\nabla_{a}^{1} u=[\rho(a), u] .
$$

Note now that these connections are not flat. And in this context the core anchor map is $\partial=\rho: A \longrightarrow T M$. Recall the operator $\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(\left(\Delta_{M}\right)^{*} \otimes A / C\right)$ and the connection $\widetilde{\nabla}: \Gamma(T M) \times \Gamma(A) \longrightarrow \Gamma(A)$ defined in Subsection 4.1.1. Recall the basic connection associated to a $T M$-connection on $A$ (see Example 2.5 in [17]):

$$
\nabla^{\text {bas }}: \Gamma(A) \times \Gamma(A) \longrightarrow \Gamma(A) \quad \nabla_{a}^{\text {bas }} b=[a, b]+\widetilde{\nabla}_{\rho(b)} a
$$

Then the equation for $\mathbb{D}$ reads

$$
\begin{aligned}
\mathbb{D}_{u}([a, b])= & \pi\left(\widetilde{\nabla}_{\left[\rho_{A}(b), u\right]+\rho_{A}\left(\widetilde{\nabla}_{u} b\right)} a\right)-\pi\left(\widetilde{\nabla}_{\left[\rho_{A}(a), u\right]+\rho_{A}\left(\widetilde{\nabla}_{u} a\right)} b\right) \\
& +\pi\left(\left[a, \widetilde{\nabla}_{u} b\right]\right)-\pi\left(\left[b, \widetilde{\nabla}_{u} a\right]\right) \\
= & \pi\left(\widetilde{\nabla}_{\rho_{A}\left(\widetilde{\nabla}_{u} b\right)} a+\left[a, \widetilde{\nabla}_{u} b\right]\right)-\pi\left(\widetilde{\nabla}_{\rho_{A}\left(\widetilde{\nabla}_{u} a\right)} b+\left[b, \widetilde{\nabla}_{u} a\right]\right) \\
& +\pi\left(\widetilde{\nabla}_{\left[\rho_{A}(b), u\right]} a-\widetilde{\nabla}_{\left[\rho_{A}(b), u\right]} b\right) \\
= & \pi\left(\nabla_{a}^{\text {bas }}\left(\widetilde{\nabla}_{u} b\right)\right)-\pi\left(\nabla_{b}^{\text {bas }}\left(\widetilde{\nabla}_{u} a\right)\right)+\pi\left(\widetilde{\nabla}_{\left[\rho_{A}(b), u\right]} a-\widetilde{\nabla}_{\left[\rho_{A}(b), u\right]} b\right) \\
= & \hat{\nabla}_{a}^{\text {bas }} \mathbb{D}_{u}(b)-\hat{\nabla}_{b}^{\text {bas }} \mathbb{D}_{u}(a)+\pi\left(\widetilde{\nabla}_{\left[\rho_{A}(b), u\right]} a-\widetilde{\nabla}_{\left[\rho_{A}(b), u\right]} b\right)
\end{aligned}
$$

where $\hat{\nabla}^{\text {bas }}$ is the $A$-connection on the quotient $A / C$ given by

$$
\hat{\nabla}_{a}^{\mathrm{bas}} \pi(b)=\pi\left([a, b]+\widetilde{\nabla}_{\rho_{A}(b)} a\right)=\pi\left(\nabla_{a}^{\mathrm{bas}} b\right)
$$

Therefore, the equations of Theorem 4.21 in this case are

- $\rho_{A}(K) \subseteq \Delta_{M}$
- $\iota_{\rho_{A}(b)} \mathbb{D}(a)=-\pi([a, b])$
- $\bar{\rho}\left(\mathbb{D}_{u}(a)\right)=-\pi_{T M}\left(\left[\rho_{A}(a), u\right]\right)$
- $\mathbb{D}_{u}([a, b])=\hat{\nabla}_{a}^{b a s} \mathbb{D}_{u}(b)-\hat{\nabla}_{b}^{\text {bas }} \mathbb{D}_{x}(a)+\pi\left(\nabla_{[\rho(b), u]} a-\nabla_{[\rho(a), u]} b\right)$
which recover the Theorem 5.17 in [17]. And in the case when $\Delta_{M}=T M$, we have that $\pi \circ \widetilde{\nabla}=\mathcal{D}=\mathbb{D}$ for all $u \in \Gamma(T M)$, and observing that we can rewrite the basic connection by $\hat{\nabla}_{a}^{\text {bas }} b=\pi([a, b])+\mathbb{D}_{\rho_{A}(b)}(a)$, then the equation for $\mathbb{D}$ is

$$
\mathbb{D}_{u}([a, b])=\hat{\nabla}_{a}^{\mathrm{bas}} \mathbb{D}_{u}(b)-\hat{\nabla}_{b}^{\mathrm{bas}} \mathbb{D}_{u}(a)+\mathbb{D}_{[\rho(b), u]}(a)-\mathbb{D}_{[\rho(b), u]}(b)
$$

Then, together with the equation

$$
\iota_{\rho_{A}(b)} \mathbb{D}(a)=-\pi([a, b])
$$

we get a Spencer operator relative to $\pi$, which is the infinitesimal description of wide multiplicative distribution given in [14].

Example 4.23. Linear subalgebroids of $T A \oplus T^{*} A$. Let $\mathfrak{L} \longrightarrow U$ be a double vector subbundle of

with core bundle $K \subseteq A \oplus T^{*} M$. Let $\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(U^{*} \otimes\left(A \oplus T^{*} M\right) / K\right)$ and $\widetilde{\nabla}: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma(A) \longrightarrow \Gamma\left(A \oplus T^{*} M\right)$ such that $\left.\pi \circ \widetilde{\nabla}\right|_{U}=\mathbb{D}$ (see Subsection 4.1.2). The structure maps of the VB-algebroid $\left(T A \oplus T^{*} A, T M \oplus A^{*} ; A, M\right)$ are:

- $\partial=\left(\rho_{A}, \rho_{A}^{*}\right): A \oplus T^{*} M \longrightarrow T M \oplus A^{*}$.
- $\nabla^{0}: \Gamma(A) \times \Gamma\left(A \oplus T^{*} M\right) \longrightarrow \Gamma\left(A \oplus T^{*} M\right)$ is given by

$$
\nabla_{a}(b, \theta)=\left([a, b], \mathcal{L}_{\rho_{A}(a)} \theta\right)
$$

- $\nabla^{1}: \Gamma(A) \times \Gamma\left(T M \oplus A^{*}\right) \longrightarrow \Gamma\left(T M \oplus A^{*}\right)$ is given by

$$
\nabla_{a}(X, \alpha)=\left([\rho(a), X], \mathcal{L}_{a} \alpha\right)
$$

where we used the inclusion $\Gamma(A) \ni a \longrightarrow\left(T a, R_{a}\right) \in \Gamma_{\operatorname{lin}}\left(T A \oplus T^{*} A, T M \oplus A^{*}\right)$. Then Theorem 4.21 applied to this case is:

Theorem 4.24. Let $(\mathfrak{L}, U ; A, M)$ be a double vector subbundle of $\left(T A \oplus T^{*} A, T M \oplus\right.$ $\left.A^{*} ; A, M\right)$ with core bundle $K \subseteq A \oplus T^{*} M$, and let $\widetilde{\nabla}: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma(A) \longrightarrow$ $\Gamma\left(A \oplus T^{*} M\right)$ be the associated connection operator (after a choice of an adapted horizontal lift). Then $\mathfrak{L} \longrightarrow U$ is a subalgebroid of $T A \oplus T^{*} A \longrightarrow T M \oplus A^{*}$ if and only if the following equations hold:

$$
\begin{align*}
\left(\rho_{A}, \rho_{A}^{*}\right)(K) \subseteq & U  \tag{4.15}\\
\iota_{\left(\rho_{A}(b), \rho_{A}^{*}(\theta)\right)} \mathbb{D}(a)= & -\pi\left(\nabla_{a}^{0}(b, \theta)\right) \quad \text { for }(b, \theta) \in K  \tag{4.16}\\
\left(\rho_{A}, \rho_{A}^{*}\right)\left(\mathbb{D}_{(X, \alpha)}(a)\right)= & -\pi_{U}\left(\nabla_{a}^{1}(X, \alpha)\right)  \tag{4.17}\\
\mathbb{D}_{(X, \alpha)}([a, b])= & \pi\left(\nabla_{\left(\nabla_{b}^{1}(X, \alpha)+\left(\rho_{A}, \rho_{A}^{*}\right)\left(\nabla_{(X, \alpha)} b\right)\right)} a\right)  \tag{4.18}\\
& -\pi\left(\nabla_{\left(\nabla_{a}^{1}(X, \alpha)+\left(\rho_{A}, \rho_{A}^{*}\right)\left(\nabla_{(X, \alpha)} a\right)\right)} b\right) \\
& +\pi\left(\nabla_{a}^{0} \circ \nabla_{(X, \alpha)} b\right)-\pi\left(\nabla_{b}^{0} \circ \nabla_{(X, \alpha)} a\right) .
\end{align*}
$$

Now we connect this result with Theorem 5.9 in [26]. Given an operator $\widetilde{\nabla}$ : $\Gamma\left(T M \oplus A^{*}\right) \times \Gamma(A) \longrightarrow \Gamma\left(A \oplus T^{*} M\right)$ define two basic connections (see Proposition 5.1 in [26])

- $\nabla_{1}^{\text {bas }}: \Gamma(A) \times \Gamma\left(T M \oplus A^{*}\right) \longrightarrow \Gamma\left(T M \oplus A^{*}\right)$, given by

$$
\left(\nabla_{1}^{\text {bas }}\right)_{a}(X, \alpha)=\left(\rho, \rho^{*}\right)\left(\widetilde{\nabla}_{(X, \alpha)} a\right)+\nabla_{a}^{1}(X, \alpha)
$$

- $\nabla_{0}^{\text {bas }}: \Gamma(A) \times \Gamma\left(A \oplus T^{*} M\right) \longrightarrow \Gamma\left(A \oplus T^{*} M\right)$, given by

$$
\left(\nabla_{0}^{\text {bas }}\right)_{a}(b, \theta)=\widetilde{\nabla}_{\left(\rho, \rho^{*}\right)(b, \theta)} a+\nabla_{a}^{0}(b, \theta)
$$

For $(b, \theta) \in \Gamma(K)$ we have

$$
\begin{aligned}
\left(\nabla_{0}^{\text {bas }}\right)_{a}(b, \theta) \in \Gamma(K) & \Leftrightarrow \widetilde{\nabla}_{\left(\rho, \rho^{*}\right)(b, \theta)} a+\nabla_{a}^{0}(b, \theta) \quad \in \Gamma(K) \\
& \Leftrightarrow \pi\left(\widetilde{\nabla}_{\left(\rho, \rho^{*}\right)(b, \theta)} a\right)=-\pi\left(\nabla_{a}^{0}(b, \theta)\right) \\
& \Leftrightarrow \iota_{\left(\rho, \rho^{*}\right)(b, \theta)} \mathbb{D}(a)=-\pi\left(\nabla_{a}^{0}(b, \theta)\right)
\end{aligned}
$$

For $(X, \alpha) \in \Gamma(U)$ we have

$$
\begin{aligned}
\left(\nabla_{1}^{\text {bas }}\right)_{a}(X, \alpha) \quad \in \Gamma(U) & \Leftrightarrow\left(\rho, \rho^{*}\right)\left(\widetilde{\nabla}_{(X, \alpha)} a\right)+\nabla_{a}^{1}(X, \alpha) \quad \in \Gamma(U) \\
& \Leftrightarrow \pi_{U}\left(\left(\rho, \rho^{*}\right)\left(\widetilde{\nabla}_{(X, \alpha)} a\right)\right)=-\pi_{U}\left(\nabla_{a}^{1}(X, \alpha)\right) \\
& \left.\Leftrightarrow \overline{\left(\rho_{A}, \rho_{A}^{*}\right)}\right)\left(\mathbb{D}_{(X, \alpha)}(a)\right)=-\pi_{U}\left(\nabla_{a}^{1}(X, \alpha)\right)
\end{aligned}
$$

where we used $\pi_{U} \circ\left(\rho, \rho^{*}\right)=\overline{\left(\rho, \rho^{*}\right)} \circ \pi$.
The basic curvature (see Proposition 5.4 in [26]) is an operator

$$
R^{\text {bas }} \in \Omega^{2}\left(A, \operatorname{Hom}\left(T M \oplus A^{*}, A \oplus T^{*} M\right)\right)
$$

given by
$R^{\text {bas }}(a, b)(X, \alpha)=-\widetilde{\nabla}_{(X, \alpha)}[a, b]+\nabla_{a}^{0}\left(\widetilde{\nabla}_{(X, \alpha)}\right)-\nabla_{b}^{0}\left(\widetilde{\nabla}_{(X, \alpha)} a\right)+\widetilde{\nabla}_{\nabla_{b}^{\text {bas }}(X, \alpha)} a-\widetilde{\nabla}_{\nabla_{a}^{\text {bas }}(X, \alpha)} b$. Then for $(X, \alpha) \in \Gamma(U)$ we have that $R^{\text {bas }}(a, b)(X, \alpha) \in \Gamma(K)$ if and only if

$$
\begin{aligned}
\pi\left(\widetilde{\nabla}_{(X, \alpha)}[a, b]\right)= & +\pi\left(\nabla_{a}^{0}\left(\widetilde{\nabla}_{(X, \alpha)} b\right)\right)-\pi\left(\nabla_{b}^{0}\left(\widetilde{\nabla}_{(X, \alpha)} a\right)\right)+\pi\left(\widetilde{\nabla}_{\left(\nabla_{1}^{\text {bas }}\right)_{b}(X, \alpha)} a\right) \\
& -\pi\left(\widetilde{\nabla}_{\left(\nabla_{1}^{\text {bas }}\right)_{a}(X, \alpha)} b\right) \\
= & +\pi\left(\nabla_{a}^{0}\left(\widetilde{\nabla}_{(X, \alpha)} b\right)\right)-\pi\left(\nabla_{b}^{0}\left(\widetilde{\nabla}_{(X, \alpha)} a\right)\right)-\pi\left(\widetilde{\nabla}_{\left(\rho, \rho^{*}\right)\left(\widetilde{\nabla}_{(X, \alpha)} a\right)+\nabla_{a}^{1}(X, \alpha)} b\right) \\
& +\pi\left(\widetilde{\nabla}_{\left(\rho, \rho^{*}\right)\left(\widetilde{\nabla}_{(X, \alpha)} b\right)+\nabla_{b}^{1}(X, \alpha)} a\right)
\end{aligned}
$$

Therefore our Theorem 4.24 is equivalent to Theorem 5.9 in [26].

### 4.2.1 Infinitesimal-global correspondence

Let $\mathcal{E} \rightrightarrows E$ be a VB-groupoid over $\mathcal{G} \rightrightarrows M$ with core bundle $C$, and let $\mathcal{H} \rightrightarrows H$ be a VB-subgroupoid of $\mathcal{E}$ with core bundle $K$ (see Example 1.24).

Lemma 4.25. The Lie algebroid $A_{\mathcal{H}} \longrightarrow H$ of $\mathcal{H}$ is a $V B$-subalgebroid of $A_{\mathcal{E}}$.
Proof. Since $\mathcal{H}$ is a Lie subgroupoid of $\mathcal{E}$, it follows that $A_{\mathcal{H}}$ is a Lie subalgebroid of $A_{\mathcal{E}}$. Moreover, since $\mathcal{H} \rightrightarrows H$ is a VB-groupoid over $\mathcal{G}$, then by Corollary 4.1.2 in [8] $A_{\mathcal{H}} \longrightarrow H$ is a VB-algebroid over $A$. Hence $A_{\mathcal{H}}$ is a VB-subalgebroid of $A_{\mathcal{E}}$.

To integrate IM-subbundles we need first two results from [8]:
Theorem 4.3.4. Let $\mathcal{A} \longrightarrow E$ be a VB-algebroid over $A \longrightarrow M$, so that $\mathcal{A} \longrightarrow E$ is integrable. Then its source-simply-connected integration $\mathcal{E} \rightrightarrows E$ carries a VBgroupoid over the source-simply-connected Lie groupoid $\mathcal{G} \rightrightarrows M$ integrating $A \longrightarrow M$,

uniquely determined by the property that its differentiation is the given VB-algebroid.
Corollary 4.3.7. Let $\mathcal{A}_{1}$ be a $V B$-subalgebroid of $\mathcal{A}_{2}$ defining, at level of basic algebroids, a Lie subalgebroid $\left(A_{1} \longrightarrow M_{1}\right) \hookrightarrow\left(A_{2} \longrightarrow M_{2}\right)$. For $i=1$, 2 , let $\mathcal{E}_{i}$ and $G_{i}$ be source-simply-connected integrations of $\mathcal{A}_{i}$ and $A_{i}$, respectively. Then $\mathcal{E}_{1}$ is a $V B$-subgroupoid of $\mathcal{E}_{2}$ provided $\mathcal{G}_{1}$ is a Lie subgroupoid of $\mathcal{G}_{2}$.

Now applying Theorem 4.21 combined with the previous two results we get the following infinitesimal-global correspondence.

Theorem 4.26. Let $\mathcal{E} \rightrightarrows E$ be a VB-groupoid over a source 1-connected Lie groupoid $\mathcal{G} \rightrightarrows M$. Then there is one-to-one correspondence between VB-subgroupoids $\mathcal{H} \rightrightarrows H$ of $\mathcal{E}$ and operators $\mathcal{D}: \Gamma_{\text {lin }}\left(A_{\mathcal{E}}, E\right) \longrightarrow \Gamma\left(H^{*} \otimes C / K\right)$ satisfying Equations (4.11)(4.14).

### 4.3 IM-Dirac structures

In this section, we apply what we did before to the particular case of IM-Dirac structures on a Lie algebroid $A$, that means, we describe double vector bundles

whit core bundle $K$ such that $\mathfrak{L} \longrightarrow U$ is a Lie subalgebroid of $T A \oplus T^{*} A \longrightarrow$ $T M \oplus A^{*}, \mathfrak{L} \longrightarrow A$ is a Dirac structure. First we study only the case when $\mathfrak{L} \longrightarrow A$ is a Dirac structure, providing a description in terms of $U$ and $K$. Then we combine with the previous section to include the Lie subalgebroid condition. As examples, we consider the cases of closed linear 2 -forms, Poisson structures and involutive distributions.

### 4.3.1 Dirac structures

Let $(q: A \longrightarrow M,[\cdot, \cdot], \rho)$ be a Lie algebroid, and consider the VB-algebroid

with core bundle $A \oplus T^{*} M$, and where the map $\mathbb{T} q=\left(T q, P_{2}\right)$, where $P_{2}: T^{*} A \longrightarrow A^{*}$ is the cotangent prolongation.

The Courant-Dorfman bracket of two sections $(X, \alpha),(Y, \beta) \in \Gamma_{A}\left(T A \oplus T^{*} A\right)$ (see [6]) is

$$
\llbracket(X, \alpha),(Y, \beta) \rrbracket=\left([X, Y], \mathcal{L}_{X} \beta-i_{Y} d \alpha\right)
$$

If $X, Y \in \mathfrak{X}(A)$ are linear vector fields, and $\alpha, \beta \in \Omega^{1}(A)$ are linear forms, then $(X, \alpha)$ and $(Y, \beta)$ are linear sections, as well as their Courant-Dorfman bracket. Let $(u, \eta),(v, \xi) \in \Gamma\left(T M \oplus A^{*}\right)$ and let $(X, \alpha),(Y, \beta) \in \Gamma_{A}\left(T A \oplus T^{*} A\right)$ be any linear sections projectable to $(u, \eta),(v, \xi)$, respectively. This means


Define a bracket in $\Gamma\left(T M \oplus A^{*}\right)$ by:

$$
[(u, \eta),(v, \xi)]=\mathbb{T} q(\llbracket(X, \alpha),(Y, \beta) \rrbracket)
$$

This bracket is well defined. Indeed if $(\widetilde{Y}, \widetilde{\beta})$ is another linear section covering $(v, \xi)$, there exists a core linear section $\nu^{\uparrow}$ such that $(\widetilde{Y}, \widetilde{\beta})=(Y, \beta)+\nu^{\uparrow}$. Then

$$
\llbracket(X, \alpha),(\widetilde{Y}, \widetilde{\beta}) \rrbracket=\llbracket(X, \alpha),(Y, \beta) \rrbracket+\llbracket(X, \alpha), \nu^{\uparrow} \rrbracket,
$$

and the bracket $\llbracket(X, \alpha), \nu^{\uparrow} \rrbracket$ is a core linear section in $T A \oplus T^{*} A$ over $A$, then it projects over $0 \in T M \oplus A^{*}$, and then

$$
\mathbb{T} q(\mathbb{\llbracket}(X, \alpha),(\widetilde{Y}, \widetilde{\beta}) \rrbracket)=\mathbb{T} q(\llbracket(X, \alpha),(Y, \beta) \rrbracket)+\underbrace{\mathbb{T} q\left(\llbracket(X, \alpha), \nu^{\uparrow} \rrbracket\right)}_{=0}=\mathbb{T} q(\mathbb{\llbracket}(X, \alpha),(Y, \beta) \rrbracket),
$$

and hence, the bracket in $\Gamma\left(T M \oplus A^{*}\right)$ is well defined.
Since $u \sim_{q} X$ and $v \sim_{q} Y$ then $[u, v] \sim_{q}[X, Y]$. So the first component of the bracket $[(u, \eta),(v, \xi)]$ is $[u, v] \in \Gamma(T M)$. In order to describe the second component $P_{2}\left(\mathcal{L}_{X} \beta-\iota_{Y} d \alpha\right) \in A^{*}$ we need a little more work.

Let $h: \Gamma(A) \longrightarrow \Gamma_{\operatorname{lin}}\left(T A \oplus T^{*} A, T M \oplus A^{*}\right)$ be a horizontal lift and let $\nabla^{h}$ : $\Gamma\left(T M \oplus A^{*}\right) \times \Gamma(A) \longrightarrow \Gamma\left(A \oplus T^{*} M\right)$ the connection operator such that

$$
h(a)(u, \eta)=\left(T a(u), R_{a}(\eta)\right)-S_{\nabla_{(u, \eta)}^{h}}(u, \eta) .
$$

We define $\Delta_{(u, \eta)}: \Gamma(A) \longrightarrow \Gamma(A)$ by

$$
\Delta_{(u, \eta)} a=\mathrm{P}_{A}\left(\nabla_{(u, \eta)}^{h} a\right),
$$

where $P_{A}: A \oplus T^{*} M \longrightarrow A$ is the projection over $A$. The map $\Delta_{(u, \eta)}$ is a derivation over $u$ :

$$
\begin{aligned}
\Delta_{(u, \eta)}(f a) & =\mathrm{P}_{A}\left(\nabla_{(u, \eta)}^{h}(f a)\right) \\
& =\mathrm{P}_{A}\left(f \nabla_{(u, \eta)}^{h} a+\left(\ell_{\mathrm{d} f} S_{b}, \ell_{-a} \mathrm{~d} f\right)\right) \\
& =f \operatorname{Pr}_{A}\left(\nabla_{(u, \eta)}^{h} a\right)+\mathcal{L}_{u} f a \\
& =f \Delta_{(u, \eta)} a+\mathcal{L}_{u} f a
\end{aligned}
$$

Consider $\sigma_{h}: \Gamma\left(T M \oplus A^{*}\right) \longrightarrow \Gamma_{\operatorname{lin}}\left(T A \oplus T^{*} A, A\right)$ the horizontal lift of the horizontal linear structure of $\left(T A \oplus T^{*} A, T M \oplus A^{*} ; M, A\right)$ associated to $h$ :

$$
\sigma_{h}(u, \eta)\left(a_{p}\right)=h(a)\left(u_{p}, \eta_{p}\right)=\left(T a(u), R_{a}(\eta)\right)-S_{\nabla_{(u, \eta)^{a}}}(u, \eta)
$$

and write $\sigma_{h}(u, \eta)=(X, \alpha)$ and $\sigma_{h}(v, \xi)=(Y, \beta)$. Then

$$
\begin{aligned}
X\left(a_{p}\right)=\operatorname{Pr}_{T A}\left(\sigma_{h}(u, \eta)\left(a_{p}\right)\right) & =\operatorname{Pr}_{T A}\left(\left(T a(u), R_{a}(\eta)\right)-S_{\nabla_{(u, \eta)}} a(u, \eta)\right) \\
& =\operatorname{Ta}\left(u_{p}\right)+\operatorname{Pr}_{T A}\left(S_{-\nabla_{(u, \eta)}^{h}}(u, \eta)\right) \\
& =T a\left(u_{p}\right)+\left(0+\operatorname{Pr}_{A}\left(-\nabla_{(u, \eta)}^{h} a\right)\right) \\
& =T a\left(u_{p}\right)+\left.\frac{d}{d r}\right|_{r=0}\left(a_{p}-r \operatorname{Pr}_{A}\left(\nabla_{(u, \eta)}^{h} a\right)\right) \\
& =T a\left(u_{p}\right)+\left.\frac{d}{d r}\right|_{r=0}\left(a_{p}-r \Delta_{(u, \eta)} a\right) \\
& =\widehat{\Delta_{(u, \eta)}}\left(a_{p}\right) .
\end{aligned}
$$

Now we calculate $P_{2}\left(\mathcal{L}_{X} \beta-\iota_{Y} d \alpha\right)$. For $b \in \Gamma(A)$ we have

$$
\left\langle P_{2}\left(\mathcal{L}_{X} \beta-\iota_{Y} d \alpha\right), b\right\rangle=\left\langle\mathcal{L}_{X} \beta-\iota_{Y} d \alpha, b^{\uparrow}\right\rangle=\left\langle\mathcal{L}_{X} \beta, b^{\uparrow}\right\rangle-\left\langle\iota_{Y} \mathrm{~d} \alpha, b^{\uparrow}\right\rangle .
$$

The first term is equal to

$$
\left\langle\mathcal{L}_{X} \beta-\iota_{Y} d \alpha, b^{\uparrow}\right\rangle=\mathcal{L}_{X}\left\langle\beta, b^{\uparrow}\right\rangle-\left\langle\beta,\left[X, b^{\uparrow}\right]\right\rangle .
$$

The function $\left\langle\beta, b^{\uparrow}\right\rangle$ is basic:

$$
\left\langle\beta, b^{\uparrow}\right\rangle\left(a_{p}\right)=\left\langle\beta\left(a_{p}\right), b^{\uparrow}\left(a_{p}\right)\right\rangle=\left\langle\mathrm{P}_{2}\left(\beta\left(a_{p}\right)\right), b(p)\right\rangle=\langle\xi(p), b(p)\rangle
$$

Hence $\mathcal{L}_{X}\left\langle\beta, b^{\uparrow}\right\rangle=q^{*} \mathcal{L}_{u}\langle\xi, b\rangle$ because $X$ is a linear vector field. Following Lemma B. 2 in [26], we have $\left\langle\beta,\left[X, b^{\uparrow}\right]\right\rangle=\left\langle\xi,\left(\Delta_{(u, \eta)} b\right)^{\uparrow}\right\rangle$. Therefore

$$
\left\langle\mathcal{L}_{X} \beta, b^{\uparrow}\right\rangle=q^{*}\left(\mathcal{L}_{u}\langle\xi, b\rangle\right)-\left\langle\xi,\left(\Delta_{(u, \eta)} b\right)^{\uparrow}\right\rangle
$$

The term $\left\langle\iota_{Y} \mathrm{~d} \alpha, b^{\uparrow}\right\rangle$ is equal to

$$
\left\langle\iota_{Y} \mathrm{~d} \alpha, b^{\uparrow}\right\rangle=\mathcal{L}_{Y}\left\langle\alpha, b^{\uparrow}\right\rangle .-\mathcal{L}_{b^{\uparrow}}\langle\alpha, Y\rangle-\left\langle\alpha,\left[Y, b^{\uparrow}\right]\right\rangle .
$$

As before, we have $\mathcal{L}_{Y}\left\langle\alpha, b^{\uparrow}\right\rangle=q^{*}\left(\mathcal{L}_{v}\langle\eta, b\rangle\right)$. Write $\mathcal{L}_{b \uparrow}\langle\alpha, Y\rangle=\left\langle\mathcal{L}_{b \uparrow} \alpha, Y\right\rangle+\left\langle\alpha,\left[b^{\uparrow}, Y\right]\right\rangle$. Using again Lemma B. 2 in [26], we get

$$
\mathcal{L}_{b \uparrow} \alpha=-q^{*}\left(\mathrm{P}_{T^{*} M}\left(\nabla_{(u, \eta)}^{h} b\right)\right),
$$

where $\mathrm{P}_{T^{*} M}: A \oplus T^{*} M \longrightarrow T^{*} M$ is the projection on the second component. Hence we have

$$
\left\langle\iota_{Y} \mathrm{~d} \alpha, b^{\uparrow}\right\rangle=q^{*}\left(\mathcal{L}_{v}\langle\eta, b\rangle\right)+\left\langle q^{*}\left(\mathrm{P}_{T^{*} M}\left(\nabla_{(u, \eta)}^{h} b\right)\right), Y\right\rangle=q^{*}\left(\mathcal{L}_{v}\langle\eta, b\rangle+\left\langle\mathrm{P}_{T^{*} M}\left(\nabla_{(u, \eta)}^{h} b\right), v\right\rangle\right),
$$

and then

$$
\begin{aligned}
\left\langle P_{2}\left(\mathcal{L}_{X} \beta-\iota_{Y} d \alpha\right), b\right\rangle= & \mathcal{L}_{u}\langle\xi, b\rangle-\left\langle\xi, \operatorname{Pr}_{A}\left(\nabla_{(u, \eta)}^{h} b\right)\right\rangle \\
& -\mathcal{L}_{v}\langle\eta, b\rangle-\left\langle\mathrm{P}_{T^{*} M}\left(\nabla_{(u, \eta)}^{h} b\right), v\right\rangle \\
= & \mathcal{L}_{u}\langle\xi, b\rangle-\mathcal{L}_{v}\langle\eta, b\rangle-\left\langle(v, \xi), \nabla_{(u, \eta)}^{h} b\right\rangle .
\end{aligned}
$$

Therefore, the bracket in $\Gamma\left(T M \oplus A^{*}\right)$ is equal to

$$
\begin{equation*}
\left\langle[(u, \eta),(v, \xi)]_{h},(b, \theta)\right\rangle=\langle[u, v], \theta\rangle+\mathcal{L}_{u}\langle\xi, b\rangle-\mathcal{L}_{v}\langle\eta, b\rangle-\left\langle(v, \xi), \nabla_{(u, \eta)}^{h} b\right\rangle . \tag{4.19}
\end{equation*}
$$

Theorem 4.27. The triple $\left(T M \oplus A^{*}, P_{T M},[\cdot, \cdot]_{h}\right)$ is a Dull algebroid (see [26], Definition 2.2). Moreover, if we denote by $\Lambda^{h}$ the $\left(T M \oplus A^{*}\right)$-Dorfman connection on $A \oplus T^{*} M$ associated to $h$, then $[\cdot, \cdot]_{h}=\llbracket \cdot, \cdot \rrbracket_{\Lambda^{h}}$
Proof. Remember that the Dorfman connection associated to $h$ is

$$
\Lambda_{(u, \eta)}^{h}(b, \theta)=\nabla_{(u, \eta)}^{h} b+\left(0, \mathrm{~d}\langle\eta, b\rangle+\mathcal{L}_{u} \theta\right) .
$$

Then

$$
\begin{aligned}
\left\langle\mathbb{(}(u, \eta),(v, \xi) \rrbracket_{\Lambda^{h}},(b, \theta)\right\rangle= & \mathcal{L}_{u}(\langle(v, \xi),(b, \theta)\rangle)-\left\langle(v, \xi), \Lambda_{(u, \xi)}^{h}(b, \theta)\right\rangle \\
= & \mathcal{L}_{u}\langle v, \theta\rangle+\mathcal{L}_{u}\langle\xi, \beta\rangle \\
& -\left\langle(v, \xi), \nabla_{(u, \xi)}^{h} b+\left(0, \mathrm{~d}\langle\xi, b\rangle+\mathcal{L}_{u} \theta\right)\right. \\
= & \mathcal{L}_{u}\langle v, \theta\rangle+\mathcal{L}_{u}\langle\xi, \beta\rangle-\langle v, \mathrm{~d}\langle\eta, b\rangle \\
& -\left\langle v, \mathcal{L}_{u} \theta\right\rangle-\left\langle(v, \xi), \nabla_{(u, \eta)}^{h} b\right\rangle \\
= & \left\langle[(u, \eta),(v, \xi)]_{h},(b, \theta)\right\rangle .
\end{aligned}
$$

Proposition 4.28. Let $(X, \alpha)=\sigma_{h}(u, \eta) \in \Gamma_{\text {lin }}(\mathfrak{L}, A)$ for $(u, \eta) \in \Gamma(U)$. Then for $a$ $(b, \theta) \in \Gamma\left(A \oplus T^{*} M\right)$

$$
\begin{equation*}
\llbracket(X, \alpha),\left(b^{\uparrow}, q^{*} \theta\right) \rrbracket=\left(\nabla_{(u, \eta)}^{h} b\right)^{\uparrow}+\left(0, q^{*}\left(\mathcal{L}_{u} \theta+d\langle\eta, b\rangle\right)\right) . \tag{4.20}
\end{equation*}
$$

In particular, if $\Gamma(\mathfrak{L}, A)$ is closed by the Courant-Dorfman bracket, then

$$
\nabla_{(u, \eta)}^{h} b+\left(0, \mathcal{L}_{u} \theta+d\langle\eta, b\rangle\right) \in \Gamma(K) \quad \text { for all }(b, \theta) \in \Gamma(K)
$$

Proof. Recall that

$$
\left[X, b^{\uparrow}\right]=\left(\Delta_{(u, \eta)} b\right)^{\uparrow}=\left(\mathrm{P}_{A}\left(\nabla_{(u, \eta)}^{h} b\right)\right)^{\uparrow}
$$

Also we have that

$$
\mathcal{L}_{X} q^{*} \theta-\iota_{b} \uparrow \mathrm{~d} \alpha=q^{*}\left(\mathcal{L}_{u} \theta+\mathrm{P}_{T^{*} M}\left(\nabla_{(u, \eta)}^{h} b\right)+\mathrm{d}\langle\eta, b\rangle\right) .
$$

Therefore

$$
\begin{aligned}
\llbracket(X, \alpha),\left(b^{\uparrow}, q^{*} \theta\right) \rrbracket & =\left(\mathrm{P}_{A}\left(\nabla_{(u, \eta)}^{h} b\right)\right)^{\uparrow}+q^{*}\left(\mathcal{L}_{u} \theta+\mathrm{P}_{T^{*} M}\left(\nabla_{(u, \eta)}^{h} b\right)+\mathrm{d}\langle\eta, b\rangle\right) \\
& \left.=\left(\nabla_{(u, \eta)}^{h} b\right)\right)^{\uparrow}+\left(0, q^{*}\left(\mathcal{L}_{u} \theta+\mathrm{d}\langle\eta, b\rangle\right)\right) .
\end{aligned}
$$

Hence, if $(b, \theta) \in \Gamma(K)$ and $\mathfrak{L}$ is closed by the bracket, then $\llbracket(X, \alpha),\left(b^{\uparrow}, q^{*} \theta\right) \rrbracket$ is a core linear section of $\mathfrak{L}$ over $A$, which implies that $\nabla_{(u, \eta)}^{h} b+\left(0, \mathcal{L}_{u} \theta+\mathrm{d}\langle\eta, b\rangle\right) \in \Gamma(K)$.

With respect to the pairing, if $(b, \theta) \in \Gamma\left(A \oplus T^{*} M\right)$, then

$$
\begin{aligned}
\left\langle(X, \alpha),\left(b^{\uparrow}, q^{*} \theta\right)\right\rangle & =\left\langle q^{*} \theta, X\right\rangle+\left\langle b^{\uparrow}, \alpha\right\rangle \\
& =\left\langle q^{*} \theta+_{A} 0_{a}, X\right\rangle+\left\langle b^{\uparrow}+_{A^{*}} 0, \alpha\right\rangle \\
& =\langle\theta, u\rangle+\langle b, \eta\rangle .
\end{aligned}
$$

Proposition 4.29. $\mathfrak{L}$ is Langrangian if and only if $K^{\circ}=U$ and the bracket defined in $\Gamma\left(T M \oplus A^{*}\right)$ is skew-symmetric for every $(u, \eta),(v, \xi) \in \Gamma(U)$.

Proof. Let $(b, \theta) \in \Gamma(K)$ and take $(u, \eta) \in \Gamma\left(T M \oplus A^{*}\right)$. Consider a linear section $(X, \alpha) \in \Gamma_{A}\left(T A \oplus T^{*} A\right)$ covering $(u, \eta)$. Then

$$
\langle(b, \theta),(u, \eta)\rangle=0 \Leftrightarrow\left\langle(X, \eta),\left(b^{\uparrow}, q^{*} \theta\right)\right\rangle=0 .
$$

Since $(b, \theta) \in \Gamma(K)$, the section $\left(b^{\uparrow}, q^{*} \theta\right) \in \Gamma_{\text {cor }}\left(T A \oplus T^{*} A, A\right)$. If $(X, \alpha) \in \Gamma(\mathfrak{L})$ and $\mathfrak{L}$ is Lagrangian then $\left\langle(X, \eta),\left(b^{\uparrow}, q^{*} \theta\right)\right\rangle=0$. But then $\langle(b, \theta),(u, \eta)\rangle=0$ with $(u, \eta) \in \Gamma(U)$. Hence $U \subseteq K^{\circ}$. Moreover, since $\mathfrak{L}$ is Langrangian we have $(T A \oplus$ $\left.T^{*} A / \mathfrak{L}\right)^{*} \simeq \mathfrak{L}^{\circ}=\mathfrak{L}$ and the following double vector bundle

with core bundle $U^{\circ}$. So, doing what we did before, interchanging $U$ by $K^{\circ}$ and $K$ by $U^{\circ}$, it follows that $K^{\circ} \subseteq U$. Therefore $K^{\circ}=U$. Now take $(u, \eta),(v, \xi) \in \Gamma(U)$ and let $(X, \alpha),(Y, \beta) \in \Gamma_{A}(\mathfrak{L})$ any linear sections projectable to $(u, \eta),(v, \xi)$. Then

$$
[(v, \xi),(u, \eta)]=\left([v, u], P_{2}\left(\mathcal{L}_{Y} \alpha-\iota_{X} \mathrm{~d} \beta\right)\right)
$$

We have $[v, u]=-[u, v]$. For the second component we have

$$
\begin{aligned}
\left\langle P_{2}\left(\mathcal{L}_{Y} \alpha-\iota_{X} \mathrm{~d} \beta\right), b\right\rangle & =\left\langle\mathcal{L}_{Y} \alpha-\iota_{X} \mathrm{~d} \beta, b^{\uparrow}\right\rangle \\
& =\left\langle\mathcal{L}_{Y} \alpha-\mathcal{L}_{X} \beta-\mathrm{d}\langle\beta, X\rangle, b^{\uparrow}\right\rangle \\
& =\left\langle\mathcal{L}_{Y} \alpha-\mathcal{L}_{X} \beta, b^{\uparrow}\right\rangle+\left\langle\mathrm{d}\langle\beta, X\rangle, b^{\uparrow}\right\rangle
\end{aligned}
$$

and in the other hand

$$
\begin{aligned}
\left\langle P_{2}\left(\mathcal{L}_{X} \beta-\iota_{Y} \mathrm{~d} \alpha\right), b\right\rangle & =\left\langle\mathcal{L}_{X} \beta-\iota_{Y} \mathrm{~d} \alpha, b^{\uparrow}\right\rangle \\
& =\left\langle\mathcal{L}_{X} \beta-\mathcal{L}_{Y} \alpha, b^{\uparrow}+\left\langle\mathrm{d}\langle\alpha, Y\rangle, b^{\uparrow}\right\rangle\right.
\end{aligned}
$$

Then the second component is skew-symmetric if and only if

$$
-\left(\left\langle\mathcal{L}_{Y} \alpha-\mathcal{L}_{X} \beta, b^{\uparrow}\right\rangle+\left\langle\mathrm{d}\langle\beta, X\rangle, b^{\uparrow}\right\rangle\right)=\left\langle\mathcal{L}_{X} \beta-\mathcal{L}_{Y} \alpha, b^{\uparrow}\right\rangle+\left\langle\mathrm{d}\langle\alpha, Y\rangle, b^{\uparrow}\right\rangle
$$

if and only if

$$
\mathcal{L}_{b \uparrow}\langle\beta, X\rangle=-\mathcal{L}_{b \uparrow}\langle\alpha, Y\rangle \quad \Longleftrightarrow \quad \mathcal{L}_{b \uparrow}(\langle\beta, X\rangle+\langle\alpha, Y\rangle)=0 .
$$

Then if $\mathfrak{L}$ is Lagrangian, $\langle\beta, X\rangle+\langle\alpha, Y\rangle=0$. Hence the bracket in two elements of $\Gamma(U)$ is skew-symmetric. Conversaly, if the bracket of two elements of $\Gamma(U)$ is skew-symmetric then $\langle\beta, X\rangle+\langle\alpha, Y\rangle=0$ for all linear sections in $\Gamma(\mathfrak{L})$. For linear and core sections, we have

$$
\left\langle(X, \alpha),\left(b^{\uparrow}, q^{*} \theta\right)\right\rangle=\langle\theta, u\rangle+\langle\eta, b\rangle=0 .
$$

And for two core section

$$
\left\langle\left(a^{\uparrow}, q^{*} \omega\right),\left(b^{\uparrow}, q^{*} \theta\right\rangle=\left\langle\left(\rho, \rho^{*}\right)(a, \omega),(b, \theta)\right\rangle=0\right.
$$

because $\left(\rho, \rho^{*}\right)(K) \subseteq U$. Therefore, $\mathfrak{L} \subseteq \mathfrak{L}^{\circ}$. Now if we dualize the double vector bundle $\left(T A \oplus T^{*} A\right) / \mathfrak{L}$ over $A$ we get a double vector bundle $\mathfrak{L}^{\circ}$ with side bundle $U$ and core bundle $U^{\circ}$. Hence we have two double vector bundles over $A$ with the same side and core bundle. This means that the dimension (over $A$ ) is the same. Therefore $\mathfrak{L}=\mathfrak{L}^{\circ}$.

Remark 4.30. This proposition can be found in [26], Theorem 4.15, (2), with a different proof.

Lemma 4.31. If the sections of $\mathfrak{L}$ are closed with respect to the Courant bracket then $\mathfrak{L} \longrightarrow A$ is a VB-algebroid over $U \longrightarrow M$. In particular, $U \longrightarrow M$ inherits $a$ Lie algebroid structure.

Proof. If $\llbracket \Gamma(\mathfrak{L}), \Gamma(\mathfrak{L}) \rrbracket \subseteq \Gamma(\mathfrak{L})$ then with this bracket $\mathfrak{L} \longrightarrow A$ is a Lie algebroid. If $(X, \alpha),(Y, \beta) \in \Gamma_{A}(\mathfrak{L})$ are linear sections then $\llbracket(X, \alpha),(Y, \beta) \rrbracket$ is linear. If $(b, \theta) \in$ $\Gamma(K)$ then

$$
\begin{aligned}
\llbracket(X, \alpha),(b, \theta)^{\uparrow} \rrbracket & =\llbracket(X, \alpha),\left(b^{\uparrow}, q^{*} \theta\right) \rrbracket \\
& =\left(\left[X, b^{\uparrow}\right], \mathcal{L}_{X} q^{*} \theta-\iota_{b \uparrow} \mathrm{~d} \alpha\right) \\
& \left.=\left(\nabla_{(u, \eta)}^{h} b\right)\right)^{\uparrow}+\left(0, q^{*}\left(\mathcal{L}_{u} \theta+\mathrm{d}\langle\eta, b\rangle\right)\right),
\end{aligned}
$$

where $(u, \eta)=\mathbb{T}(q)(X, \alpha)$, which means that $\llbracket \Gamma_{\text {lin }}(\mathfrak{L}), \Gamma_{\text {cor }}(\mathfrak{L}) \rrbracket \subseteq \Gamma_{\text {cor }}(\mathfrak{L})$. For two core sections $(a, \theta),(b, \omega) \in \Gamma(K)$ we have

$$
\llbracket\left(a^{\uparrow}, q^{*} \theta\right),\left(b^{\uparrow}, q^{*} \omega\right) \rrbracket=\left(\left[a^{\uparrow}, b^{\uparrow}\right], \mathcal{L}_{a^{\uparrow}} q^{*} \omega-\iota_{b \uparrow} \mathrm{~d}\left(q^{*} \theta\right)\right)=0 .
$$

Then $\mathfrak{L} \longrightarrow A$ is a VB-algebroid over $U \longrightarrow M$.

Now we can characterize Dirac structures on a Lie algebroid $A$.
Theorem 4.32. Let $\mathfrak{L} \subseteq T A \oplus T^{*} A$ be a double vector subbundle. Let $h: \Gamma(A) \longrightarrow$ $\Gamma_{\text {lin }}\left(T A \oplus T^{*} A, T M \oplus A^{*}\right)$ be an adapted horizontal lift. Then $\mathfrak{L}$ is a Dirac structure if and only if $K^{\circ}=U$ and $\left(U \longrightarrow M,\left.P_{T M}\right|_{U},[\cdot, \cdot]_{h}\right)$ is a Lie algebroid.

Proof. The Lagrangian condition follows by Theorem 4.29, and by the previous lemma, $\Gamma(\mathfrak{L})$ being closed by the Courant-Dorfman bracket implies that $(U \longrightarrow$ $\left.M,\left.\mathrm{P}_{T M}\right|_{U},[\cdot, \cdot]_{h}\right)$ is a Lie algebroid. Hence, it remains to prove that $\left(U \longrightarrow M,\left.\mathrm{P}_{T M}\right|_{U},[\cdot, \cdot]_{h}\right)$ Lie algebroid together $K=U^{\circ}$ imply $\mathfrak{L}$ is closed by the bracket:

$$
\begin{equation*}
\llbracket \tilde{X}, \tilde{Y} \rrbracket \in \Gamma(\mathfrak{L}, A) \tag{4.21}
\end{equation*}
$$

Note that we only need to check equation 4.21 for linear an core sections. If $\widetilde{X}, \widetilde{Y}$ are core sections, then its Courant-Dorfman bracket is 0 . If $\widetilde{X}=(X, \alpha)=\sigma_{h}(u, \eta)$, and $\widetilde{Y}=\left(b^{\uparrow}, q^{*} \theta\right)$, for $(u, \eta) \in \Gamma(U)$ and $(b, \theta) \in \Gamma(K)$, then

$$
\llbracket \sigma_{h}(u, \eta),\left(b^{\uparrow}, q^{*} \theta\right) \rrbracket=\left(\nabla_{(u, \eta)}^{h} b\right)^{\uparrow}+\left(0, q^{*}\left(\mathcal{L}_{u} \theta+\mathrm{d}\langle\eta, b\rangle\right)\right) .
$$

We claim that $\nabla_{(u, \eta)}^{h} b+\left(0, \mathcal{L}_{u} \theta+\mathrm{d}\langle\eta, b\rangle\right) \in \Gamma(K)$. Indeed, since $U$ is a Lie algebroid and since $K=U^{\circ}$ then

$$
\begin{aligned}
0 & =\left\langle[(u, \eta),(v, \xi)]_{h},(b, \theta)\right\rangle \\
& =\langle[u, v], \theta\rangle+\mathcal{L}_{u}\langle b, \xi\rangle-\mathcal{L}_{v}\langle b, \eta\rangle-\left\langle(v, \xi), \nabla_{(u, \eta)}^{h} b\right\rangle \\
& =\mathcal{L}_{u}\langle v, \theta\rangle-\left\langle v, \mathcal{L}_{u} \theta\right\rangle+\mathcal{L}_{u}\langle b, \xi\rangle-\left\langle v, \mathrm{~d}\langle b, \eta\rangle-\left\langle(v, \xi), \nabla_{(u, \eta)}^{h} b\right\rangle\right. \\
& =\mathcal{L}_{u} \underbrace{\langle(v, \xi),(b, \theta)\rangle}_{=0}-\left\langle v, \mathcal{L}_{u} \theta+\mathrm{d}\langle b, \eta\rangle-\left\langle(v, \xi), \nabla_{(u, \eta)}^{h} b\right\rangle\right. \\
& =-\left\langle(v, \xi), \nabla_{(u, \eta)}^{h} b+\left(0, \mathcal{L}_{u} \theta+\mathrm{d}\langle\eta, b\rangle\right)\right\rangle .
\end{aligned}
$$

Hence $\nabla_{(u, \eta)}^{h} b+\left(0, \mathcal{L}_{u} \theta+\mathrm{d}\langle\eta, b\rangle\right) \in \Gamma(K)$. So

$$
\llbracket \sigma_{h}(u, \eta),\left(b^{\uparrow}, q^{*} \theta\right) \rrbracket=\left(\nabla_{(u, \eta)}^{h} b\right)^{\uparrow}+\left(0, q^{*}\left(\mathcal{L}_{u} \theta+\mathrm{d}\langle\eta, b\rangle\right)\right) \in \Gamma(\mathfrak{L}, A) .
$$

Finally, we need to check the Equation 4.21 for linear sections. Let now $\widetilde{Y}=(Y, \beta)=$ $\sigma_{h}(v, \xi)$. By Theorem 4.9 in [26] we have

$$
\llbracket \sigma_{h}(u, \eta), \sigma_{h}(v, \xi) \rrbracket=\sigma_{h}\left([(u, \eta),(v, \xi) \rrbracket)-S_{R_{\Lambda}((u, \eta),(v, \xi))(\cdot, 0)}\right.
$$

where $R_{\Lambda}$ is the curvature of the Dorfman connection $\Lambda$ associated to the horizontal lift $h$ (see Definition 3.3 in [26]). Since $\sigma_{h}([(u, \eta),(v, \xi)]) \in \Gamma(\mathfrak{L}, A)$ it is enough to prove that $S_{R_{\Lambda}((u, \eta),(v, \xi))(\cdot, 0)}$ is a section of $\mathfrak{L}$ over $A$, which is the same that proving $R_{\Lambda}((u, \eta),(v, \xi))(\cdot, 0) \in \Gamma(\operatorname{Hom}(A, K))$. Let $\widetilde{w}=(w, \delta) \in \Gamma(U), a \in \Gamma(A)$, and set $\widetilde{u}=(u, \eta)$ and $\widetilde{v}=(v, \xi)$. Then using Proposition 3.4 in [26] we have

$$
\left\langle R_{\Lambda}(\widetilde{u}, \widetilde{v})(a, 0), \widetilde{w}\right\rangle=\left\langle\left[[\widetilde{u}, \widetilde{v}]_{h}, \widetilde{w}\right]_{h}+\left[[\widetilde{v}, \widetilde{w}]_{h}, \widetilde{u}\right]_{h}+\left[[\widetilde{w}, \widetilde{u}]_{h}, \widetilde{v}\right]_{h},(a, 0)\right\rangle=0
$$

because $U$ is a Lie algebroid. Hence (4.21) is satisfied by linear sections. Therefore Equation 4.21 holds for all sections in $\Gamma(\mathfrak{L}, A)$, and together with the Lagrangian condition, it follows that $\mathfrak{L}$ is a Dirac structure.

Remark 4.33. One can see Theorem 4.15 together with Corollary 4.16 in [26] for a different proof of this result.

### 4.3.2 IM-Dirac structures

An IM-Dirac structure on a Lie algebroid $A$ is a Dirac structure $\mathfrak{L}$ over $A$, such that it is a Lie subalgebroid of $T A \oplus T^{*} A \longrightarrow T M \oplus A^{*}$. Combining the description of subalgebroids with the description of Dirac structures, we get an infinitesimal description of multiplicative Dirac structures.

Theorem 4.34. Let $\mathfrak{L} \subseteq T A \oplus T^{*} A$ be a double vector subbundle. Let $h: \Gamma(A) \longrightarrow$ $\Gamma_{\text {lin }}\left(T A \oplus T^{*} A, T M \oplus A^{*}\right)$ be an adapted horizontal lift. Then $\mathfrak{L}$ is an IM-Dirac structure if and only if $K=U^{\circ},\left(U \longrightarrow M,\left.P_{T M}\right|_{U},[\cdot, \cdot]_{h}\right)$ is a Lie algebroid, and

$$
\begin{align*}
\left(\rho_{A}, \rho_{A}^{*}\right)(K) \subseteq & U  \tag{4.22}\\
\iota_{\left(\rho_{A}(b), \rho_{A}^{*}(\theta)\right)} \mathbb{D}(a)= & -\pi\left(\nabla_{a}^{0}(b, \theta)\right) \quad \text { for }(b, \theta) \in K  \tag{4.23}\\
\left.\mathbb{D}_{(u, \eta)}\right)([a, b])= & \pi\left(\nabla_{\left(\nabla_{b}^{1}(u, \eta)+\left(\rho_{A}, \rho_{A}^{*}\right)\left(\nabla_{(u, \eta)} b\right)\right)} a\right)  \tag{4.24}\\
& -\pi\left(\nabla_{\left(\nabla_{a}^{1}(u, \eta)+\left(\rho_{A}, \rho_{A}^{*}\right)\left(\nabla_{(u, \eta)} a\right)\right)} b\right) \\
& +\pi\left(\nabla_{a}^{0} \circ \nabla_{(u, \eta)} b\right)-\pi\left(\nabla_{b}^{0} \circ \nabla_{(u, \eta)} a\right) .
\end{align*}
$$

Remark 4.35. This theorem is equivalent to Theorem 5.10 in [26].
A multiplicative Dirac structure on a Lie groupoid $\mathcal{G}$ is a Dirac structure $\mathfrak{D}$ such that it is a Lie subgroupoid of $T \mathcal{G} \oplus T^{*} \mathcal{G}$. It was proven in [36] (Theorem 5.1) that every multiplicative Dirac structure on $\mathcal{G}$ induces an IM-Dirac structure on $A$. Moreover when $\mathcal{G}$ is source simply connected this is a one-to-one correspondence. Hence using this result and combining with Theorem 4.34, Theorem 4.3.4 and Corollary 4.3.7 in [7], we have proven

Proposition 4.36. If $\mathcal{G}$ is source simply connected, there is a one-to-one correspondence between multiplicative Dirac structure $\mathfrak{D}$ on $\mathcal{G}$ and subbundles $U \subseteq T M \oplus A^{*}$ whit an operator $\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(U^{*} \otimes U^{*}\right)$ such that $\left(U \longrightarrow M, P_{T M},[\cdot, \cdot]_{h}\right)$ is Lie algebroid, and such that Equations (4.22), (4.23) and (4.24) hold.

Example 4.37. Closed 2-forms. Let $\omega \in \Omega^{2}(A)$ be a closed 2 -form on $A$, and let $\omega^{\sharp}: T A \longrightarrow T^{*} A$ be the map given by

$$
\omega^{\sharp}(X)=i_{X} \omega \quad \text { for } X \in T A .
$$

We know that the graph of $\omega$, graph $\left(\omega^{\sharp}\right)=\left\{\left(X, i_{X} \omega\right): X \in T A\right\} \subseteq T A \oplus T^{*} A$ is a Dirac structure on $A$. Assume too that $\omega$ is linear, i.e., it is a vector bundle map

over some linear map $r: T M \longrightarrow A^{*}$ covering the identity of $M$. We will proof in a different way, using Theorem 4.32, that graph $\left(\omega^{\sharp}\right)$ is a Dirac structure.

Since $\omega^{\sharp}$ is also linear over $A$ we get that $\omega^{\sharp}$ is a morphism of double vector bundles. Define

$$
\mathfrak{L}_{\omega}=\operatorname{graph}\left(\omega^{\sharp}\right)=\left\{\left(X, i_{X} \omega\right): X \in T A\right\} .
$$

Since $\omega^{\sharp}$ is a morphism of double vector bundles, it follows that $\mathfrak{L}_{\omega}$ is a double vector subbundle of $T A \oplus T^{*} A$, and therefore it defines a double vector bundle

with core bundle $K \longrightarrow M$. Now we will describe who are $U$ and $K$. Denote by $\operatorname{Pr}=\left(T q, P_{2}\right): T A \oplus T^{*} A \longrightarrow T M \oplus A^{*}$ the left vertical vector bundle map of the double vector bundle $\left(T A \oplus T^{*} A, T M \oplus A^{*} ; A, M\right)$, where $q: A \longrightarrow M$ and $P_{2}: T^{*} A \longrightarrow A^{*}$. We know that $U=\operatorname{Pr}\left(\mathfrak{L}_{\omega}\right)$. Let

and let $b \in \Gamma(A)$. Then

$$
\begin{aligned}
\left\langle P_{2}\left(i_{X} \omega\right), b\right\rangle & :=\left\langle i_{X} \omega, 0_{a}+_{T M} \bar{b}\right\rangle=\omega\left(X, 0_{a}+_{T M} \bar{b}\right) \\
& =\omega\left(X+T_{M} 0_{u}, 0_{a}+_{T M} \bar{b}\right)=\omega\left(X, 0_{a}\right)+\omega\left(0_{u}, \bar{b}\right) \\
& =\langle r(u), b\rangle .
\end{aligned}
$$

Therefore

$$
U=\operatorname{graph}(r)=\{(u, r(u)): u \in T M\} .
$$

The core bundle is $K=\operatorname{Ker}\left(\operatorname{Pr}_{\mid \mathfrak{L}_{\omega}}\right) \cap \operatorname{Ker}(\pi) \subseteq A \oplus T^{*} M$. If $(a, \theta) \in K$, then

with $i_{\bar{a}} \omega=\bar{\theta}$ (because $(\bar{a}, \bar{\theta}) \in \mathfrak{L}_{\omega}$ ). Let $X \in T A$ with projections $u \in T M$ and $0 \in A$. Then

$$
\begin{aligned}
\left\langle i_{\bar{a}} \omega, X\right\rangle & =\omega(\bar{a}, X)=-\omega(X, \bar{a}) \\
& =-\omega\left(X, 0+_{T M} \bar{a}\right)=-\langle r(u), a\rangle \\
& =\left\langle u,-r^{T}(a)\right\rangle
\end{aligned}
$$

which means that $\overline{-r^{T}(a)}=i_{\bar{a}} \omega$. Defining $\sigma: A \longrightarrow T^{*} M$ as $\sigma=-r^{T}$ we get that

$$
K=\operatorname{graph}(\sigma)=\{(a, \sigma(a)): a \in A\}
$$

And follows that $K^{\circ}=U$ :

$$
\langle(a, \sigma(a)),(u, r(u))\rangle=\langle a, r(u)\rangle+\langle\sigma(a), u\rangle=\langle a, r(u)\rangle-\langle a, r(u)\rangle=0
$$

Proposition 4.38. There is a canonical inclusion $\Gamma(A) \longrightarrow \Gamma_{\text {lin }}(\mathfrak{L}, U)$.
Proof. We look for a map $h(a): U=\operatorname{graph}(r) \longrightarrow \mathfrak{L}_{\omega}=\operatorname{graph}\left(\omega^{\sharp}\right)$. Let $u \in \Gamma(T M)$. We want $h(a)(u, r(u))=(T a(u), \mu(r(u)))$ such that $\iota_{T a(u)} \omega=\mu(r(u))$. The elements $T a(u), R_{a}(r(u)), \iota_{T a(u)} \omega$ have projections


Then

$$
\Phi:=\iota_{T a(u)} \omega-{ }_{A^{*}} R_{a}(r(u)) \longrightarrow{ }_{p}{ }_{p}
$$

which means that $\Phi=0_{r(u)}+_{A} \bar{\varphi}$ where $\varphi \in \Omega^{1}(M)$. On one hand we have

$$
\langle\Phi, T 0(y)\rangle=\left\langle 0_{r(u)}+_{A} \bar{\varphi}, T 0(y)\right\rangle=\langle\alpha, y\rangle \quad \forall y \in T M .
$$

On the other hand

$$
\begin{aligned}
\langle\Phi, T 0(y)\rangle & =\left\langle\iota_{T a(u)} \omega-A^{*} R_{a}(r(u)), T a(y)-T a(y)\right\rangle \\
& =\left\langle\iota_{T a(u)} \omega, T a(y)\right\rangle-\left\langle R_{a}(r(u)), T a(y)\right\rangle \\
& =\omega(T a(u), T a(y)) \\
& =a^{*} \omega(u, y) .
\end{aligned}
$$

Since $\omega$ is closed then $\omega=\left(r^{t}\right)^{*} \omega_{\text {can }}$ (see Example 2.6 in [7]), where $\omega_{\text {can }} \in \Omega^{2}\left(T^{*} M\right)$ is the canonical symplectic form. Using that $\omega_{\text {can }}=-\mathrm{d} \theta_{\text {can }}$, where $\theta_{\text {can }}$ is the tautological 1-form on $T^{*} M$ and the property $\lambda^{*} \theta=\lambda$ for every $\lambda \in \Omega^{1}(M)$, it follows that

$$
a^{*} \omega=a^{*}\left(\left(r^{t}\right)^{*}\left(\omega_{\text {can }}\right)\right)=a^{*}\left(\mathrm{~d} \sigma^{*} \theta_{\text {can }}\right)=\mathrm{d}\left((\sigma \circ a)^{*} \theta_{\text {can }}\right)=\mathrm{d}(\sigma(a)) .
$$

Hence $\varphi=\mathrm{d} \sigma(a)(u)$. Therefore
$h(a)(u, \eta)=\left(T a(u), R_{a}(\eta)+_{A^{*}} S_{\mathrm{d} \sigma(a)(u)}(u, \eta)\right)=\left(T a(u), R_{a}(\eta)\right)-\left(0, S_{-\mathrm{d} \sigma(a)(u)}(u, \eta)\right)$
is an adapted horizontal lift.

The bracket on $\Gamma(U)$ is: let $(u, r(u)),(v \cdot r(v)) \in \Gamma(U)$, and $(b, \theta) \in \Gamma\left(A \oplus T^{*} M\right)$ we have

$$
\begin{aligned}
\langle[(u, r(u)),(v, r(v))],(b, \theta)\rangle= & \langle[u, v], \theta\rangle+\mathcal{L}_{u}\langle r(v), b\rangle-\mathcal{L}_{v}\langle r(u), b\rangle \\
& -\left\langle(v, r(v)), \nabla_{(u, r(u))}^{h} b\right\rangle \\
= & \langle[u, v], \theta\rangle+\mathcal{L}_{u}\langle r(v), b\rangle-\mathcal{L}_{v}\langle r(u), b\rangle \\
& +\langle(v, r(v)), \mathrm{d}(\sigma(b))(u)\rangle \\
= & \langle[u, v], \theta\rangle+\mathcal{L}_{u}\langle r(v), b\rangle-\mathcal{L}_{v}\langle r(u), b\rangle \\
& +\mathcal{L}_{u}\langle v, \sigma(b)\rangle-\mathcal{L}_{v}\langle u, \sigma(b)\rangle-\langle\sigma(b),[u, v]\rangle \\
= & \langle[u, v], \theta\rangle+\mathcal{L}_{u}\langle r(v), b\rangle-\mathcal{L}_{v}\langle r(u), b\rangle \\
& -\mathcal{L}_{u}\langle r(v), b\rangle+\mathcal{L}_{v}\langle r(u), b\rangle+\langle r([u, v]), b\rangle \\
= & \langle([u, v], r([u, v])),(b, \theta)\rangle,
\end{aligned}
$$

which implies that $[(u, r(u)),(v, r(v))]_{h}=([u, v], r([u, v]))$. Hence, this bracket is skew symmetric for sections of $U$, and together with the condition $K^{\circ}=U$, follow that $\mathfrak{L}_{\omega}$ is a Lagrangian subbundle. Moreover, since the bracket is closed for sections of $U$, we have that $U \longrightarrow M$ is a Lie algebroid, and therefore, Theorem 4.32 holds, and we get in another way the known result that $\mathfrak{L}_{\omega}$ is a Dirac structure.

Remark 4.39. We can identify $U \simeq T M$ and $K \simeq A$, and then we get, naturally, that $K^{\circ}=U$ and that $U$ is a Lie algebroid.

Suppose now that conditions (4.22), (4.23) and (4.24) are also satisfied. We will work little more on these equations. The first one says $\left(\rho, \rho^{*}\right)(K) \subseteq U$. So, for $(a, \sigma(a)),(b, \sigma(b)) \in \Gamma(K)$ we have

$$
\begin{aligned}
\left\langle\left(\rho, \rho^{*}\right)(a, \sigma(a)),(b, \sigma(b))\right\rangle & =\langle\rho(a), \sigma(b)\rangle+\left\langle\rho^{*}(\sigma(a)), b\right\rangle \\
& =\langle\rho(a), \sigma(b)\rangle+\langle\rho(b), \sigma(a)\rangle,
\end{aligned}
$$

which means that $\left(\rho, \rho^{*}\right)(K) \subseteq U$ if and only if

$$
\begin{equation*}
\iota_{\rho(a)} \sigma(b)=-\iota_{\rho(b)} \sigma(a) . \tag{4.25}
\end{equation*}
$$

Before to analyze the other two equations, we need to know who is $\pi: A \oplus T^{*} M \longrightarrow$ $\frac{A \oplus T^{*} M}{K}$ and $\mathbb{D}$. Using $K^{\circ}=U$ we get

$$
\frac{A \oplus T^{*} M}{K} \simeq\left(K^{\circ}\right)^{*} \simeq U^{*} \simeq T^{*} M
$$

So for $(a, \theta) \in A \oplus T^{*} M$ and $(u, r(u)) \in U$

$$
\begin{aligned}
\langle\pi(a, \theta),(u, r(u))\rangle & =\langle(a, \theta),(u, r(u))\rangle=\langle\theta, u\rangle+\langle a, r(u)\rangle \\
& =\langle\theta, u\rangle-\langle\sigma(a), u\rangle=\langle\theta-\sigma(a), u\rangle .
\end{aligned}
$$

Therefore we can write $\pi(a, \theta)=\theta-\sigma(a)$. For $\mathbb{D}$ remember that it satisfies $\mathbb{D}=$ $\left.\pi \circ \nabla^{h}\right|_{U}$. Then

$$
\mathbb{D}_{(u, r(u))}(a)=\pi(0,-\mathrm{d} \sigma(a)(u))=-\mathrm{d} \sigma(a)(u) .
$$

Hence the left side of Equation (4.23) is

$$
\left\langle\mathbb{D}(a),\left(\rho, \rho^{*}\right)(b, \sigma(b))\right\rangle=-\left\langle\mathrm{d} \sigma(a),\left(\rho(b), \rho^{*}(\sigma(b))\right)\right\rangle=-\iota_{\rho(b)} \mathrm{d} \sigma(a) .
$$

The right side is

$$
-\pi\left([a, b], \mathcal{L}_{\rho(a)} \sigma(b)\right)=-\left(\mathcal{L}_{\rho(a)} \sigma(b)-\sigma([a, b])\right) .
$$

Therefore, Equation (4.23) is satisfied if and only if

$$
\begin{equation*}
\sigma([a, b])=\mathcal{L}_{\rho(a)} \sigma(b)-\iota_{\rho(b)} \mathrm{d} \sigma(a) . \tag{4.26}
\end{equation*}
$$

Finally, for the last equation, recall the following operators

$$
\nabla^{0}: \Gamma(A) \times \Gamma\left(A \oplus T^{*} M\right) \longrightarrow \Gamma\left(A \oplus T^{*} M\right), \quad \nabla_{a}^{0}(b, \theta)=\left([a, b], \mathcal{L}_{\rho(a)} \theta\right)
$$

and

$$
\nabla^{1}: \Gamma(A) \times \Gamma\left(T M \oplus A^{*}\right) \longrightarrow \Gamma\left(T M \oplus A^{*}\right), \quad \nabla_{a}^{1}(u, \eta)=\left([\rho(a), u], \mathcal{L}_{a} \eta\right) .
$$

The left hand side of Equation (4.24) is

$$
\mathbb{D}_{(u, r(u))}([a, b])=-\mathrm{d}(\sigma([a, b]))(u) .
$$

If the we assume that Equation (4.23) holds, then

$$
\begin{equation*}
\mathbb{D}_{(u, r(u))}([a, b])=\left(\mathcal{L}_{\rho(b)} \mathrm{d} \sigma(a)-\mathcal{L}_{\rho(a)} \mathrm{d} \sigma(b)\right)(u) \tag{4.27}
\end{equation*}
$$

For the right hand side we have that

$$
\begin{aligned}
\pi\left(\nabla_{\left(\nabla_{b}^{1}(u, \eta)+\left(\rho_{A}, \rho_{A}^{*}\right)\left(\nabla_{(u, \eta)} b\right)\right)} a\right) & =\pi\left(\nabla_{\left([\rho(b), u], \mathcal{L}_{b} r(u)-\rho^{*}(\mathrm{~d}(b)(b))\right)}^{h} a\right. \\
& =-\pi(0, \mathrm{~d} \sigma(a)[\rho(b), u]) \\
& =-\mathrm{d} \sigma(a)([\rho(b), u]) .
\end{aligned}
$$

Analogously,

$$
\pi\left(\nabla_{\left(\nabla_{a}^{1}(u, \eta)+\left(\rho_{A}, \rho_{A}^{*}\right)\left(\nabla_{(u, \eta)}\right)\right)} b\right)=-\mathrm{d} \sigma(b)([\rho(a), u]) .
$$

The third term of the right hand side of Equation (4.24) is

$$
\pi\left(\nabla_{a}^{0} \circ \nabla_{(u, \eta)} b\right)=\pi\left(\nabla_{a}^{0}(0,-\mathrm{d} \sigma(b)(u))=\pi\left(0, \mathcal{L}_{\rho(a)}(-\mathrm{d} \sigma(b)(u))\right)=-\mathcal{L}_{\rho(a)}(\mathrm{d} \sigma(b)(u)) .\right.
$$

In the same way we have

$$
\pi\left(\nabla_{b}^{0} \circ \nabla_{(u, \eta)} a\right)=-\mathcal{L}_{\rho(b)}(\mathrm{d} \sigma(a)(u)) .
$$

Therefore the right hand side of the equation is

$$
-\mathrm{d} \sigma(a)([\rho(b), u])+\mathrm{d} \sigma(b)([\rho(a), u])-\mathcal{L}_{\rho(a)}(\mathrm{d} \sigma(b)(u))+\mathcal{L}_{\rho(a)}(\mathrm{d} \sigma(b)(u))
$$

and it is equal to (4.27). Hence, Equation (4.23) implies Equation (4.24).
Therefore, a multiplicative Dirac structure coming from a multiplicative closed linear 2-form, is described infinitesimally by a vector bundle map $\sigma: A \longrightarrow T^{*} M$ over the identity of $M$ satisfying

- $\iota_{\rho(a)} \sigma(b)=-\iota_{\rho(b)} \sigma(a)$,
- $\sigma([a, b])=\mathcal{L}_{\rho(a)} \sigma(b)-\iota_{\rho(b)} \mathrm{d} \sigma(a)$.

Hence with our approach we also obtain the IM 2-forms describing multiplicative closed linear 2-forms (see [7]).

Example 4.40. Poisson Manifolds. Let $\pi \in \Gamma\left(\wedge^{2} T A\right)$ be a bivector on $A$ which is linear in the following sense: there exists a vector bundle map $\sigma: A^{*} \longrightarrow T M$ such that

is a vector bundle, where $\pi^{\sharp}(\alpha)=\iota_{\alpha} \pi$. Note that $\pi^{\sharp}$ is a morphism of double vector bundles between the prolonged tangent bundle and the prolonged cotangent bundle. Let $\mathfrak{L}_{\pi}$ the graph of $\pi^{\sharp}$ :

$$
\mathfrak{L}_{\pi}=\left\{\left(\pi^{\sharp}(\alpha), \alpha\right): \alpha \in T^{*} A\right\} .
$$

Since $\pi^{\sharp}$ is a morphism of double vector bundles we have that $\mathfrak{L}_{\pi}$ is a double vector subbundle of $T A \oplus T^{*} A$ with side bundle $U \subseteq T M \oplus A^{*}$ and core bundle $K \subseteq$ $A \oplus T^{*} M$. The side bundle $U=\mathbb{T} q\left(\mathfrak{L}_{\pi}\right)$, where $\mathbb{T} q=\left(T q, P_{2}\right)$. Then

$$
u=T q\left(\pi^{\sharp}(\alpha)\right)=\left(T q \circ \pi^{\sharp}\right)(\alpha)=\left(\sigma \circ P_{2}\right)(\alpha)=\sigma\left(P_{2}(\alpha)\right)
$$

which implies that $U=\operatorname{graph}(\sigma)=\left\{(\sigma(\xi), \xi): \xi \in A^{*}\right\}$. The core bundle $K$ is the intersection of the kernels of the projections. So for $(a, \theta) \in K$ we have

whit the condition $\bar{a}=\pi^{\sharp}(\bar{\theta})$. If $\alpha \in T^{*} A$ then

$$
\left\langle a, P_{2}(\alpha)\right\rangle=\left\langle\pi^{\sharp}(\bar{\theta}), \alpha\right\rangle=\pi(\bar{\theta}, \alpha)=-\pi(\alpha, \bar{\theta})=-\left\langle\sigma\left(P_{2}(\alpha)\right), \theta\right\rangle=\left\langle P_{2}(\alpha),-\sigma^{T}(\theta)\right\rangle,
$$

which means that $a=-\sigma^{T}(\theta)$. Hence we get $K=\operatorname{graph}\left(-\sigma^{T}\right)$ and note that $K^{\circ}=U$. Therefore $\pi \in \Gamma\left(\wedge^{2} T A\right)$ is a Poisson structure if and only if $\mathfrak{L}_{\pi}$ is a Dirac structure, if and only if $\left(U \longrightarrow M, P_{T M},[,]_{h}\right)$ is a Lie algebroid. Let see more about the Lie algebroid structure of $U$.

Proposition 4.41. There is a canonical inclusion $\Gamma(A) \longrightarrow \Gamma_{\text {lin }}\left(\mathfrak{L}_{\pi}, U\right)$.
Proof. We look for a map $\Phi_{a}: \operatorname{graph}(\sigma) \longrightarrow \operatorname{graph}\left(\pi^{\sharp}\right)$. Let $(\sigma(\xi), \xi) \in \Gamma(U)$. Note that


Let $\Phi_{a}=T a(\sigma(\xi))-_{T M} \pi^{\sharp}\left(R_{a}(\xi)\right)=0_{\sigma(\xi)}+_{A} \bar{b}$ for some $b \in \Gamma(A)$. On one hand, for $\eta \in A^{*}$, we have

$$
\left\langle\Phi_{a}, R_{0}(\eta)\right\rangle=\left\langle 0_{\sigma(\xi)}+{ }_{A} \bar{b}, R_{0}(\eta)\right\rangle=\langle b, \eta\rangle .
$$

On the other hand we have

$$
\begin{aligned}
\left\langle\Phi_{a}, R_{0}(\eta)\right\rangle & =\left\langle T a(\sigma(\xi))-{ }_{T M} \pi^{\sharp}\left(R_{a}(\xi)\right), R_{a}(\eta)-{ }_{A^{*}} R_{a}(\eta)\right\rangle \\
& =\left\langle\pi^{\sharp}\left(R_{a}(\xi)\right), R_{a}(\eta)\right\rangle=\pi\left(R_{a}(\xi), R_{a}(\eta)\right) \\
& =\left(R_{a}^{*} \pi\right)(\xi, \eta)=\left(R_{a}^{*} \pi\right)(\xi)(\eta) .
\end{aligned}
$$

Hence $\Phi_{a}=-S_{\left(R_{a}^{*} \pi\right)(\xi)}$. Define now the map $l: A \longrightarrow \wedge^{2} A$ by $l(a)=R_{a}^{*}(\pi)$. Therefore the map

$$
a \longrightarrow\left(T a+S_{-l(a)}, R_{a}\right)
$$

is an adapted horizontal lift. Moreover the operator $\nabla: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma(A) \longrightarrow$ $\Gamma\left(A \oplus T^{*} M\right)$ is given by

$$
\nabla_{(X, \xi)} a=(l(a)(\xi), 0)
$$

The bracket for elements in $\Gamma(U)$ associated to the horizontal lift $h$ is

$$
\begin{aligned}
\langle[(\sigma(\xi), \xi),(\sigma(\eta), \eta)],(b, \theta)\rangle= & \langle[\sigma(\xi), \sigma(\eta)], \theta\rangle+\mathcal{L}_{\sigma(\xi)}\langle\eta, b\rangle-\mathcal{L}_{\sigma(\eta)}\langle\xi, b\rangle \\
& -\langle(\sigma(\eta), \eta), l(b)(\xi)\rangle \\
= & \langle[\sigma(\xi), \sigma(\eta)], \theta\rangle+\mathcal{L}_{\sigma(\xi)}\langle\eta, b\rangle-\mathcal{L}_{\sigma(\eta)}\langle\xi, b\rangle \\
& -l(b)(\xi, \eta)
\end{aligned}
$$

If we take an element $\left(-\sigma^{T}(\theta), \theta\right) \in \Gamma(K)$ then

$$
\begin{aligned}
(4.28) 0 & =\left\langle[(\sigma(\xi), \xi),(\sigma(\eta), \eta)]_{h},\left(-\sigma^{T}(\theta), \theta\right)\right\rangle \\
& =\langle[\sigma(\xi), \sigma(\eta)], \theta\rangle-\mathcal{L}_{\sigma(\xi)}\langle\sigma(\eta), \theta\rangle+\mathcal{L}_{\sigma(\eta)}\langle\sigma(\xi), \theta\rangle-l\left(-\sigma^{T}(\theta)\right)(\xi, \eta)
\end{aligned}
$$

Proposition 4.42. There is a Lie algebroid structure on $A^{*} \longrightarrow M$ with anchor map $\sigma: A^{*} \longrightarrow T M$.

Proof. Let $\xi, \eta \in \Gamma\left(A^{*}\right)$ and $b \in \Gamma(A)$. Their brackets is determined by:

$$
\begin{equation*}
\left\langle[\xi, \eta]_{A^{*}}, b\right\rangle=\mathcal{L}_{\sigma(\xi)}\langle\eta, b\rangle-\mathcal{L}_{\sigma(\eta)}\langle\xi, b\rangle-l(b)(\xi, \eta) \tag{4.29}
\end{equation*}
$$

The bilinearity and skew-symmetry of the bracket follow immediately. Now we check Jacobi. Note first that by Equation (4.28) and the definition of the bracket we have that

$$
\sigma\left([\xi, \eta]_{A^{*}}\right)=[\sigma(\xi), \sigma(\eta)] .
$$

Then

$$
\begin{aligned}
\langle[[\xi, \eta], \delta], b\rangle= & \mathcal{L}_{\sigma([\xi, \eta])}\langle\sigma(\delta), b\rangle-\mathcal{L}_{\sigma(\delta)}\langle[\xi, \eta], b\rangle-l(b)([\xi, \eta], \delta) \\
= & \mathcal{L}_{[\sigma(\xi), \sigma(\eta)]}\langle\delta, b\rangle-\mathcal{L}_{\sigma(\delta)} \mathcal{L}_{\sigma(\xi)}\langle\eta, b\rangle+\mathcal{L}_{\sigma(\delta)} \mathcal{L}_{\sigma(\eta)}\langle\xi, b\rangle \\
& -\left\langle\left\{\left\{\ell_{\xi}, \ell_{\eta}\right\}, \ell_{\delta}\right\}, a\right\rangle \\
= & \mathcal{L}_{\sigma(\xi)} \mathcal{L}_{\sigma(\eta)}\langle\delta, b\rangle-\mathcal{L}_{\sigma(\eta)} \mathcal{L}_{\sigma(\xi)}\langle\delta, b\rangle-\mathcal{L}_{\sigma(\delta)} \mathcal{L}_{\sigma(\xi)}\langle\eta, b\rangle \\
& +\mathcal{L}_{\sigma(\delta)} \mathcal{L}_{\sigma(\eta)}\langle\xi, b\rangle-\left\langle\left\{\left\{\ell_{\xi}, \ell_{\eta}\right\}, \ell_{\delta}\right\}, a\right\rangle
\end{aligned}
$$

Now it is straightforward to check that

$$
\langle[[\xi, \eta], \delta], b\rangle+\langle[[\eta, \delta], \xi], b\rangle+\langle[[\delta, \xi], \eta], b\rangle=0 .
$$

Therefore $\left(A^{*} \longrightarrow M, \sigma,[,]_{A^{*}}\right)$ is a Lie algebroid.
Hence we get that the bracket in $\Gamma(U)$ is

$$
[(\sigma(\xi), \xi),(\sigma(\eta), \eta)]_{h}=\left(\sigma\left([\xi, \eta]_{A^{*}}\right),[\xi, \eta]_{A^{*}}\right)
$$

Now we assume that $\pi$ is a multiplicative Poisson structure. Note that the condition $\left(\rho, \rho^{*}\right)(K) \subseteq U$ follows by the fact that $\pi^{\sharp}: T^{*} A \longrightarrow T A$ is a morphism of double vector bundles, and means

$$
\begin{aligned}
0 & =\left\langle\left(\rho, \rho^{*}\right)\left(-\sigma^{T}(\theta), \theta\right),\left(-\sigma^{T}(w), w\right)\right\rangle \\
& \left.=-\left\langle\rho\left(\sigma^{T}(\theta)\right), w\right\rangle, \sigma^{T}(w)\right\rangle-\left\langle\rho^{*}(\theta)\right.
\end{aligned}
$$

for every $\theta, w \in T^{*} M$, which holds if and only if $\rho \circ \sigma^{T}=-\sigma \circ \rho^{*}$. For the other two equations of Theorem 4.34, we need to know first who are $\mathbb{D}$ and the projection $\pi: A \oplus T^{*} M \longrightarrow\left(A \oplus T^{*} M\right) / K$. The operator $\mathbb{D}: \Gamma(A) \longrightarrow \Gamma\left(U^{*} \otimes U^{*}\right)$ is in this case given by

$$
\mathbb{D}((\sigma(\xi), \xi),(\sigma(\eta), \eta))=l(a)(\xi, \eta)
$$

For the projection $\pi$ we have

$$
\begin{aligned}
\langle\pi(a, \theta),(\sigma(\xi), \xi)\rangle & =\langle(a, \theta),(\sigma(\xi), \xi)\rangle \\
& =\langle a, \xi\rangle+\langle\theta, \sigma(\xi)\rangle \\
& =\left\langle a+\sigma^{T}(\theta), \xi\right\rangle
\end{aligned}
$$

which means that we can write $\pi(a, \theta)=\sigma^{T}(\theta)+a$. Now the left side of Equation (4.23) is

$$
\iota_{\left(\rho\left(-\sigma^{T}(\theta)\right), \rho^{*}(\theta)\right)} \mathbb{D}(a)=\iota_{\rho^{*}(\theta)} l(a)
$$

while the left side is

$$
-\pi\left(\left[a,-\sigma^{T}(\theta)\right], \mathcal{L}_{\rho(a)} \theta\right)=\left[a, \sigma^{T}(\theta)\right]-\sigma^{T}\left(\mathcal{L}_{\rho(a)} \theta\right)
$$

Therefore Equation (4.23) translates to the condition

$$
\iota_{\rho^{*}(\theta)} l(a)=\left[a, \sigma^{T}(\theta)\right]-\sigma^{T}\left(\mathcal{L}_{\rho(a)} \theta\right) .
$$

Now the left side of Equation (4.24) is $l([a, b])(\xi)$. Lets see the right side. The term third term is

$$
\begin{aligned}
\pi\left(\nabla_{a}^{0}\left(\nabla_{(\sigma(\xi), \xi)} b\right)\right) & =\pi\left(\nabla_{a}^{0}(l(b)(\xi))\right)=\pi([a, l(b)(\xi)], 0) \\
& =[a, l(b)(\xi)] .
\end{aligned}
$$

Analogously we have that $\pi\left(\nabla_{b}^{0}\left(\nabla_{(\sigma(\xi), \xi)} a\right)\right)=[b, l(a)(\xi)]$. The first term of the right side of Equation (4.24) is

$$
\begin{aligned}
\pi\left(\nabla_{\left(\nabla_{b}^{1}(\sigma(\xi), \xi)+\left(\rho, \rho^{*}\right)\left(\nabla_{(\sigma(\xi), \xi)} b\right)\right)} a\right) & =\pi\left(\nabla_{\left(\left([\rho(b), \sigma(\xi)], \mathcal{L}_{b} \xi\right)+\left(\rho, \rho^{*}\right)(l(b)(\xi))\right)} a\right) \\
& =\pi\left(\nabla_{\left(([\rho(b), \sigma(\xi)]+\rho(l(b)(\xi))), \mathcal{L}_{b} \xi\right)} a\right) \\
& =\pi\left(l(a)\left(\mathcal{L}_{b} \xi\right)\right) \\
& =l(a)\left(\mathcal{L}_{b} \xi\right) .
\end{aligned}
$$

In a similar way we get that the second term is $l(b)\left(\mathcal{L}_{a} \xi\right)$. Therefore Equation (4.24) becames

$$
\begin{equation*}
l([a, b])(\xi)=l(a)\left(\mathcal{L}_{b} \xi\right)-l(b)\left(\mathcal{L}_{a} \xi\right)+[a, l(b)(\xi)]-[b, l(a)(\xi)] . \tag{4.30}
\end{equation*}
$$

Hence we get the following description
Proposition 4.43. Let $A \longrightarrow M$ be a Lie algebroid. A linear multiplicative Poisson structure $\pi \in \Gamma\left(\wedge^{2} T A\right)$ on $A$ is in one to one correspondence with the following data: a vector bundle morphism $\sigma: A^{*} \longrightarrow T M$, a linear map $l: \Gamma(A) \longrightarrow \Gamma\left(\wedge^{2} A\right)$ satisfying

$$
\begin{aligned}
\rho \circ \sigma^{T} & =-\sigma \circ \rho^{*} \\
\iota_{\rho^{*}(\theta)} l(a) & =\left[a, \sigma^{T}(\theta)\right]-\sigma^{T}\left(\mathcal{L}_{\rho(a)} \theta\right) \\
l([a, b])(\xi) & =l(a)\left(\mathcal{L}_{b} \xi\right)-l(b)\left(\mathcal{L}_{a} \xi\right)+[a, l(b)(\xi)]-[b, l(a)(\xi)]
\end{aligned}
$$

Corollary 4.44. Let $A \longrightarrow M$ be a Lie algebroid. Suppose that there exist vector bundle morphism $\sigma: A^{*} \longrightarrow T M$, a linear map $l: \Gamma(A) \longrightarrow \Gamma\left(\wedge^{2} A\right)$ satisfying

$$
\begin{align*}
\iota_{\rho^{*}(\theta)} l(a) & =\left[a, \sigma^{T}(\theta)\right]-\sigma^{T}\left(\mathcal{L}_{\rho(a)} \theta\right)  \tag{4.31}\\
l([a, b])(\xi) & =l(a)\left(\mathcal{L}_{b} \xi\right)-l(b)\left(\mathcal{L}_{a} \xi\right)+[a, l(b)(\xi)]-[b, l(a)(\xi)] . \tag{4.32}
\end{align*}
$$

Then there is a Lie algebroid structure on $A^{*} \longrightarrow M$ such that the pair $\left(A, A^{*}\right)$ is a Lie bialgebroid.

Proof. We have proved the $A^{*} \longrightarrow T M$. Define the map $\delta: \Gamma\left(\wedge^{\bullet} A\right) \longrightarrow \Gamma\left(\wedge^{\bullet+1} A\right)$ by: in degree 0

$$
\langle\delta(f), \xi\rangle=\mathcal{L}_{\sigma(\xi)} f \quad \text { for } \quad f \in C^{\infty}(M),
$$

in degree 1 , we define $\delta=l$. The Equation (4.31) implies that $\delta$ is a derivation a that we can extend to all degrees. It follows that $\delta$ is the coboundary operator associated to the Lie algebroid $A^{*}$. Moreover Equation (4.32) means that

$$
\delta([a, b])=[\delta(a), b]+[a, \delta(b)] .
$$

Hence the pair $\left(A, A^{*}\right)$ is a Lie bialgebroid (see [29], Definition 3.12 and Remark 3.14).

## Appendix

## A Linear vector fields

Lemma .45. Let $X \in \Gamma_{\text {lin }}\left(A_{\mathcal{E}}, E\right)$ be a linear section covering some section $a \in \Gamma(A)$. Then the right invariant vector field $\vec{X} \in \mathfrak{X}(\mathcal{E})$ is linear and covers $\vec{a} \in \mathfrak{X}(\mathcal{G})$.
Proof. First we show that $\vec{X}$ covers $\vec{a}$. Let $\eta \in \mathcal{E}_{g}$ and denote by $R^{\mathcal{E}}$ and by $R^{\mathcal{G}}$ the right multiplication in $\mathcal{E}$ and in $\mathcal{G}$, respectively. Since $Q: \mathcal{E} \longrightarrow \mathcal{G}$ is a morphism of Lie groupoids we have

$$
Q\left(R_{\eta}^{\mathcal{E}}(\mu)\right)=Q(\mu \cdot \eta)=Q(\mu) \cdot Q(\eta)=R_{Q(\eta)}^{\mathcal{G}}(Q(\mu)) \quad \Rightarrow \quad Q \circ R_{\eta}^{\mathcal{E}}=R_{Q(\eta)}^{\mathcal{G}} \circ Q .
$$

Then

$$
\begin{aligned}
(T Q)_{\eta}\left(\vec{X}_{\eta}\right) & =(T Q)_{\eta}\left(\left(T R_{\eta}^{\mathcal{E}}\right)\left(X_{\bar{t}(\eta)}\right)\right)=T\left(Q \circ R_{\eta}^{\mathcal{E}}\right)_{\eta}\left(X_{\bar{t}(\eta)}\right) \\
& =T\left(R_{Q(\eta)}^{\mathcal{G}} \circ Q\right)_{\eta}\left(X_{\bar{t}(\eta)}\right)=\left(T R_{g}^{\mathcal{G}}\right)\left(T Q\left(X_{\bar{t}(\eta)}\right)\right) \\
& =\left(T R_{g}^{\mathcal{G}}\right)\left(a_{\mathbf{t}(g))}=\vec{a}_{g} .\right.
\end{aligned}
$$

Now we prove the linearity: $\vec{X}_{\eta+\mathcal{G} \mu}=\vec{X}_{\eta}+_{T \mathcal{G}} \vec{X}_{\mu}$. Let $\gamma(r), \xi(r) \subseteq \mathcal{E}$ curves such that

$$
\begin{array}{lll}
\gamma(0)=\overline{1}(\bar{t}(\eta)), & \gamma^{\prime}(0)=X_{\bar{t}(\eta)}, & \bar{s}(\gamma(r))=\bar{t}(\eta) \\
\xi(0)=\overline{1}(\bar{t}(\mu)), & \xi^{\prime}(0)=X_{\bar{t}(\mu)}, & \bar{s}(\xi(r))=\bar{t}(\mu)
\end{array}
$$

with $Q(\gamma(r))=Q(\xi(r))$. Then

$$
\begin{aligned}
\vec{X}_{\eta+\mathcal{G} \mu} & =\left(T R_{\eta+\mu}\right)_{\overline{\overline{1}}(\bar{t}(\eta+\mu))}\left(X_{\bar{t}(\eta+\mu)}\right) \\
& =\left(T R_{\eta+\mu}\right)_{\overline{1}(\bar{t}(\eta))+\overline{\mathrm{I}}(\bar{t}(\mu))}\left(X_{\bar{t}(\eta)}+{ }_{A} X_{\bar{t}(\mu)}\right) \\
& =\left.\frac{d}{d r}\right|_{r=0}\left(R_{\eta+\mu}(\gamma(r)+\mathcal{G} \xi(r))\right) \\
& =\left.\frac{d}{d r}\right|_{r=0}((\gamma(r)+\mathcal{G} \xi(r)) \cdot(\eta+\mu)) \\
& =\left.\frac{d}{d r}\right|_{r=0}(\gamma(r) \cdot \eta+\xi(r) \cdot \mu) \\
& =\left.\frac{d}{d r}\right|_{r=0}(\gamma(r) \cdot \eta)+\left.\frac{d}{d r}\right|_{r=0}(\xi(r) \cdot \mu) \\
& =\vec{X}_{\eta}+\vec{X}_{\mu} .
\end{aligned}
$$

Let $X$ be a linear section of $A_{\mathcal{E}}$ and consider its corresponding linear right invariant vector field $\vec{X} \in \mathfrak{X}(\mathcal{E})$. We denote by $\bar{D}_{X} \in \operatorname{Der}\left(\mathcal{E}^{*}\right)$ the associated derivation given by:

$$
\ell_{\bar{D}_{X}(\varphi)}=\vec{X}\left(\ell_{\varphi}\right) \quad \text { for } \varphi \in \Gamma\left(\mathcal{E}^{*}\right)
$$

This derivation is $C^{\infty}(M)$-linear in the following sense: if $h \in C^{\infty}(M)$, then the section $\left(h \circ q_{E}\right) X$ is a linear section of $A_{\mathcal{E}}$ over $E$, and its associated right invariant vector field is $\overrightarrow{\left(h \circ q_{E}\right) X}=\bar{t}^{*}\left(h \circ q_{E}\right) \vec{X}$. Then

$$
\begin{equation*}
\ell_{\bar{D}_{\left(h \circ q_{E}\right) X}(\varphi)}=\overrightarrow{\left(h \circ q_{E}\right) X}\left(\ell_{\varphi}\right)=\bar{t}^{*}\left(h \circ q_{E}\right) \vec{X}\left(\ell_{\varphi}\right)=\bar{t}^{*}\left(h \circ q_{E}\right) \ell_{\bar{D}_{X}(\varphi)}, \tag{.33}
\end{equation*}
$$

which means $\bar{D}_{\left(h \circ q_{E}\right) X}(\varphi)=\left(h \circ q_{E} \circ \bar{t}\right) \bar{D}_{X}$.

## B Module structure on the space of linear sections

Let $(\mathcal{A}, E ; A, M)$ be a VB-algebroid with core bundle $C$. Recall the canonical flat connection $\nabla^{0}: \Gamma_{\operatorname{lin}}(\mathcal{A}, E) \times \Gamma(C) \longrightarrow \Gamma(C)$ (see (1.22)) associated to a VB-algebroid characterized by

$$
S_{\nabla_{X c}}=\left[X, S_{c}\right] .
$$

There is a module structure on $\Gamma\left(\wedge^{p} T^{*} M \otimes \wedge^{q} A \otimes C\right)$ over the space $\Gamma_{\operatorname{lin}}\left(\mathcal{A}^{*}, C^{*}\right)$ given by:

$$
\begin{equation*}
X_{a} \cdot(\theta \otimes \phi \otimes c)=\mathcal{L}_{\rho(a)} \theta \otimes \phi \otimes c+\theta \otimes[a, \phi] \otimes c+\theta \otimes \phi \otimes \nabla_{X_{a}}^{0} c \tag{.34}
\end{equation*}
$$

Lemma .46. We have the following equality

$$
\begin{equation*}
c_{X_{a} \cdot(\theta \otimes \phi \otimes c)}=\mathcal{L}_{\rho_{\mathrm{A}}\left(\chi_{a}\right)} c_{\theta \otimes \phi \otimes c c}, \tag{.35}
\end{equation*}
$$

where $\chi_{a}=\left((T a)^{p},\left(R_{a}\right)^{q}, X_{a}\right)$ and $\rho_{\mathbb{A}}$ is the anchor map of the Lie algebroid $\mathbb{A}_{\mathcal{A}}^{(p, q)}$ (see Section 3.2).

Proof. Recall that the anchor map $\rho_{\mathbb{A}}: \mathbb{A}_{\mathcal{A}}^{(p, q)} \longrightarrow \mathbb{M}_{\mathcal{E}}^{(p, q)}$ has by components the corresponding anchor of each VB-algebroid:

$$
\rho_{\mathbb{A}}\left((T a)^{p},\left(R_{a}\right)^{q}, X_{a}\right)=\left(\left(\rho(a)^{T}\right)^{p},\left(H_{a}\right)^{q}, \rho_{\mathcal{A}^{*}}\left(X_{a}\right)\right) .
$$

Note that $\mathcal{L}_{\left(\rho(a)^{T}\right)^{p}} \theta$ where $\theta \in \Omega^{p}(M)$ is the usual Lie derivative of forms along vector fields, i.e., $\mathcal{L}_{\rho(a)} \theta$. Also we have

$$
\mathcal{L}_{\left(H_{a}\right)^{q}} C_{\phi}=c_{[a, \phi]},
$$

where the bracket is the Schouten bracket (see for example [10] for the previous equality and Schouten bracket). We have too that $\mathcal{L}_{\rho_{\mathcal{A}^{*}}\left(X_{a}\right)} c=\nabla_{X_{a}}^{0} c$. Then using these equalities and the Appendix in [10], the lemma follows.

Suppose now that the VB-algebroid comes from a representation $C \longrightarrow M$ of $A$, i.e., we have a flat $A$-connections on $C: \nabla: \Gamma(A) \times \Gamma(C) \longrightarrow \Gamma(C)$. Hence the module structure on $\Gamma\left(\wedge^{p} T^{*} M \otimes C\right)=\Omega^{k}(M, C)$ over $\Gamma(A)$ is

$$
\begin{equation*}
a \cdot(\theta \otimes c)=\mathcal{L}_{\rho(a)} \theta \otimes c+\theta \otimes \nabla_{a} c \tag{.36}
\end{equation*}
$$

Let $\omega=\theta \otimes c \in \Omega^{k}(M, C)$. Recall the Lie derivative operator $\mathcal{L}_{a}$ acting on $\Omega^{k}(M, C)$ defined on [14]

$$
\mathcal{L}_{a} \omega(V)=\nabla_{a} \omega(V)-\sum_{i} \omega\left(v_{1}, \ldots,\left[\rho(a), v_{i}\right], \ldots, v_{k}\right)
$$

for a $V=\left(v_{1}, \ldots, v_{k}\right)$ with $v_{i} \in T M$. Using the local expression $\omega(V)=\theta(V) c \in$ $\Gamma(C)$, we have

$$
\begin{aligned}
\mathcal{L}_{a} \omega(V) & =\nabla_{a} \omega(V)-\sum_{i} \omega\left(v_{1}, \ldots,\left[\rho(a), v_{i}\right], \ldots, v_{k}\right) \\
& =\nabla_{a}(\theta(V) c)-\sum_{i} \theta\left(v_{1}, \ldots,\left[\rho(a), v_{i}\right], \ldots, v_{k}\right) c \\
& =\theta(V) \nabla_{a} c+\mathcal{L}_{\rho(a)} \theta(V) c-\sum_{i} \theta\left(v_{1}, \ldots,\left[\rho(a), v_{i}\right], \ldots, v_{k}\right) c \\
& =\theta(V) \nabla_{a} c+\left(\mathcal{L}_{\rho(a)} \theta(V)-\sum_{i} \theta\left(v_{1}, \ldots,\left[\rho(a), v_{i}\right], \ldots, v_{k}\right)\right) c \\
& =\theta(V) \nabla_{a} c+\left(\mathcal{L}_{\rho(a)} \theta\right)(V) c .
\end{aligned}
$$

Hence the Lie derivative operator $\mathcal{L}_{a}$ acting on $\Omega^{k}(M, C)$ defined on [14] is the same that the modulo structure on $\Omega^{k}(M, C)$ over $\Gamma(A)$ defined here.

## C Compatibility of multiplication

Here we will prove Lemma 3.22:
Lemma .47. 3.22 There is an isomorphism of Lie groupoids between the Lie groupoid $s^{*}\left(C^{*}\right) \oplus \boldsymbol{t}^{*}\left(E^{*}\right)$ obtained by the dual representation $\left(\left(\Delta^{0}\right)^{T},\left(\Delta^{1}\right)^{T}, \partial^{T}, \Omega^{T}\right)$, and the Lie groupoid $s^{*}\left(E^{*}\right) \oplus \boldsymbol{t}^{*}\left(C^{*}\right)$ which is obtained by dualization of the VB-groupoid $\mathcal{E}=s^{*} E \oplus \boldsymbol{t}^{*} C$. Moreover this is an isomorphism of VB-groupoids.

First we recall the structure maps of the VB-groupoids $\mathbf{s}^{*}\left(C^{*}\right) \oplus \mathbf{t}^{*}\left(E^{*}\right)$ and $\mathbf{s}^{*}\left(E^{*}\right) \oplus \mathbf{t}^{*}\left(C^{*}\right)$. Given a representation up to homotopy $\left(\Delta^{0}, \Delta^{1}, \partial, \Omega\right)$ of $\mathcal{G}$, it induces a representation up to homotopy of $\mathcal{G}$ on the graded vector bundle $E_{[0]}^{*} \oplus C_{[1]}^{*}$ as follows:

- The quasi action $\left(\Delta^{T}\right)_{g}^{0}: E_{\mathbf{s}(g)}^{*} \longrightarrow E_{\mathbf{t}(g)}^{*}$ given by:

$$
\left(\Delta^{T}\right)_{g}^{0}(\eta):=\left(\Delta_{g^{-1}}^{1}\right)^{*} \eta, \quad \text { for } \eta \in E_{\mathbf{s}(g)}^{*}
$$

- The quasi actions $\left(\Delta^{T}\right)_{g}^{1}: C_{\mathbf{s}(g)}^{*} \longrightarrow C_{\mathbf{t}(g)}^{*}$ given by:

$$
\left(\Delta^{T}\right)_{g}^{1}(\xi):=\left(\Delta_{g^{-1}}^{0}\right)^{*} \xi, \quad \text { for } \xi \in C_{\mathbf{s}(g)}^{*}
$$

- The vector bundle map $\partial^{T}: E^{*} \longrightarrow C^{*}$ is the dual map $\partial^{*}$.
- The operator $\Omega^{T}$ is given by: $\xi \in C_{\mathbf{s}(g)}^{*}$ we have

$$
\Omega_{(g, h)}^{T}: C_{\mathbf{s}(h)}^{*} \longrightarrow E_{\mathbf{t}(g)}^{*} \quad \Omega_{(g, h)}^{T}(\xi):=\left(\Omega_{\left(h^{-1}, g^{-1}\right)}\right)^{*} \xi
$$

for $(g, h) \in \mathcal{G}^{(2)}$.
Hence we get the VB-groupoid $\mathbf{s}^{*}\left(C^{*}\right) \oplus \mathbf{t}^{*}\left(E^{*}\right)$ with source and target map given by:

- $\widetilde{s}(g, \xi, \eta)=\xi$
- $\widetilde{t}(g, \xi, \eta)=\partial^{*}(\eta)+\left(\Delta_{g^{-1}}^{0}\right)^{*} \xi$
for $\xi \in C_{\mathbf{s}(g)}^{*}$ and $\eta \in E_{\mathbf{t}(g)}^{*}$. The multiplication is defined as

$$
\left(g_{1}, \xi_{1}, \eta_{1}\right) \cdot{ }^{1}\left(g_{2}, \xi_{2}, \eta_{2}\right)=\left(g_{1} g_{2}, \xi_{2}, \eta_{1}+\left(\Delta_{g_{1}^{-1}}^{1}\right)^{*} \eta_{2}-\Omega_{g_{2}^{-1}, g_{1}^{-1}} \xi_{2}\right),
$$

under the compatibility condition

$$
\begin{equation*}
\widetilde{s}\left(g_{1}, \xi_{1}, \eta_{1}\right)=\xi_{1}=\partial^{*}\left(\eta_{2}\right)+\left(\Delta_{g_{2}^{-1}}^{0}\right)^{*} \xi_{2}=\widetilde{t}\left(g_{2}, \xi_{2}, \eta_{2}\right) \tag{.37}
\end{equation*}
$$

On the other hand the dual VB-groupoid of $\mathcal{E}=\mathbf{s}^{*} E \oplus \mathbf{t}^{*} C$ is the VB-groupoid with structure maps given by:

- The source and target maps $\widehat{s}, \widehat{t}: \mathcal{E}^{*}=\mathbf{s}^{*}\left(E^{*}\right) \oplus \mathbf{t}^{*}\left(C^{*}\right) \longrightarrow C^{*}$ are

$$
\begin{aligned}
& \widehat{s}(g, \mu, \delta)=\partial^{*}(\mu)+\left(\Delta_{g}^{0}\right)^{*} \delta \\
& \widehat{t}(g, \mu, \delta)=\delta
\end{aligned}
$$

where $\mu \in E_{\mathbf{s}(g)}^{*}$ and $\delta \in C_{\mathbf{t}(g)}^{*}$. The multiplication is

$$
\left(g_{1}, \mu_{1}, \delta_{1}\right) \cdot{ }^{2}\left(g_{2}, \mu_{2}, \delta_{2}\right)=\left(g_{1} g_{2}, \mu_{2}+\left(\Delta_{g_{2}}^{1}\right)^{*} \mu_{1}-\Omega_{g_{1}, g_{2}}^{*} \delta_{1}, \delta_{1}\right),
$$

under the compatibility condition $\delta_{2}=\partial^{*}\left(\mu_{1}\right)+\left(\Delta_{g}^{0}\right)^{*} \delta_{1}$.
Proof. of Lemma 3.22 Let $(g, \xi, \eta) \in \mathbf{s}^{*}\left(C^{*}\right) \oplus \mathbf{t}^{*}\left(E^{*}\right)$. The inverse of this element is (see [19]):

$$
(g, \xi, \eta)^{-1}=\left(g^{-1},-\left(\Delta^{0}\right)_{g^{-1}}^{T} \eta+\Omega_{g^{-1}, g}^{T} \xi, \partial^{T} \eta+\left(\Delta^{1}\right)_{g}^{T} \xi\right)
$$

Define the map $\varphi: \mathbf{s}^{*}\left(C^{*}\right) \oplus \mathbf{t}^{*}\left(E^{*}\right) \longrightarrow \mathbf{s}^{*}\left(E^{*}\right) \oplus \mathbf{t}^{*}\left(C^{*}\right)$ by

$$
\varphi(g, \xi, \eta)=\left(g,-\left(\Delta^{0}\right)_{g^{-1}}^{T} \eta+\Omega_{g^{-1}, g}^{T} \xi, \partial^{T} \eta+\left(\Delta^{1}\right)_{g}^{T} \xi\right) .
$$

We show now the compatibility of $\varphi$ with the source, target and multiplication. For the source we have

$$
\begin{aligned}
\widehat{s}(\varphi(g, \xi, \eta)) & =\widehat{s}\left(g,-\left(\Delta^{0}\right)_{g^{-1}}^{T} \eta+\Omega_{g^{-1}, g}^{T} \xi, \partial^{T} \eta+\left(\Delta^{1}\right)_{g}^{T} \xi\right) \\
& =\partial^{*}\left(-\left(\Delta_{g}^{1}\right)^{*} \eta+\Omega_{g^{-1}, g}^{*} \xi\right)+\left(\Delta_{g}^{0}\right)^{*}\left(\partial^{*}(\eta)+\left(\Delta_{g^{-1}}^{0}\right)^{*} \xi\right) \\
& =-\left(\Delta_{g}^{1} \circ \partial\right)^{*} \eta+\left(\Omega_{g^{-1}, g} \circ \partial\right)^{*} \xi+\left(\partial \circ \Delta_{g}^{0}\right)^{*}(\eta)+\left(\Delta_{g^{-1}}^{0} \Delta_{g}^{0}\right)^{*} \xi \\
& =\left(\Delta_{g^{-1} g}^{0}\right)^{*} \xi=\xi \\
& =\widetilde{s}(g, \xi, \eta)
\end{aligned}
$$

With respect to the target map

$$
\begin{aligned}
\widehat{t}(\varphi(g, \xi, \eta)) & =\widehat{t}\left(g,-\left(\Delta^{0}\right)_{g^{-1}}^{T} \eta+\Omega_{g^{-1}, g}^{T} \xi, \partial^{T} \eta+\left(\Delta^{1}\right)_{g}^{T} \xi\right) \\
& =\partial^{T} \eta+\left(\Delta^{1}\right)_{g}^{T} \xi \\
& =\widetilde{t}(g, \xi, \eta)
\end{aligned}
$$

Now we check the compatibility of the multiplication. Let $\left(g_{1}, \xi_{1}, \eta_{1}\right),\left(g_{2}, \xi_{2}, \eta_{2}\right) \in$ $\mathbf{s}^{*}\left(C^{*}\right) \oplus \mathbf{t}^{*}\left(E^{*}\right)$ be two composable elements. Then

$$
\begin{aligned}
\varphi\left(g_{1}, \xi_{1}, \eta_{1}\right) \cdot{ }^{2} \varphi\left(g_{2}, \xi_{2}, \eta_{2}\right)= & \left(g_{1} g_{2},\right. \\
& -\left(\Delta_{g_{2}}^{1}\right)^{*} \eta_{2}+\Omega_{g_{2}^{-1}, g_{2}}^{*} \xi_{2}+\left(\Delta_{g_{2}}^{1}\right)^{*}\left(-\left(\Delta_{g_{1}}^{1}\right)^{*} \eta_{1}+\Omega_{g_{1}^{-1}, g_{1}}^{*} \xi_{1}\right) \\
& -\Omega_{g_{1}, g_{2}}^{*}\left(\partial^{*}\left(\eta_{1}\right)+\left(\Delta_{g_{1}^{-1}}^{0}\right)^{*} \xi_{1}\right) \\
& \left.\partial^{*}\left(\eta_{1}\right)+\left(\Delta_{g_{1}^{-1}}^{0}\right)^{*} \xi_{1}\right) .
\end{aligned}
$$

On the other hand

$$
\begin{aligned}
\varphi\left(\left(g_{1}, \xi_{1}, \eta_{1}\right) \cdot \cdot^{1}\left(g_{2}, \xi_{2}, \eta_{2}\right)\right)= & \varphi\left(g_{1} g_{2}, \xi_{2}, \eta_{1}+\left(\Delta_{g_{1}^{-1}}^{1}\right)^{*} \eta_{2}-\Omega_{g_{2}^{-1}, g_{1}^{-1}}^{*} \xi_{2}\right) \\
= & \left(g_{1} g_{2}\right. \\
& -\left(\Delta_{g_{1} g_{2}}^{1}\right)^{*}\left(\eta_{1}+\left(\Delta_{g_{1}^{-1}}^{1}\right)^{*} \eta_{2}-\Omega_{g_{2}^{-1}, g_{1}^{-1}}^{*} \xi_{2}\right) \\
& +\Omega_{g_{2}^{-1} g_{1}^{-1}, g_{1} g_{2}}^{*} \xi_{2} \\
& \left.\partial^{*}\left(\eta_{1}+\left(\Delta_{g_{1}^{-1}}^{1}\right)^{*} \eta_{2}-\Omega_{g_{2}^{-1}, g_{1}^{-1}}^{*} \xi_{2}\right)+\left(\Delta_{g_{2}^{-1} g_{1}^{-1}}^{0}\right)^{*} \xi_{2}\right)
\end{aligned}
$$

Now we have to show that

$$
\begin{aligned}
& -\left(\Delta_{g_{2}}^{1}\right)^{*} \eta_{2}+\Omega_{g_{2}^{-1}, g_{2}}^{*} \xi_{2}+\left(\Delta_{g_{2}}^{1}\right)^{*}\left(-\left(\Delta_{g_{1}}^{1}\right)^{*} \eta_{1}+\Omega_{g_{1}^{-1}, g_{1}}^{*} \xi_{1}\right)-\Omega_{g_{1}, g_{2}}^{*}\left(\partial^{*}\left(\eta_{1}\right)+\left(\Delta_{g_{1}^{-1}}^{0}\right)^{*} \xi_{1}\right) \\
& =-\left(\Delta_{g_{1} g_{2}}^{1}\right)^{*}\left(\eta_{1}+\left(\Delta_{g_{1}^{-1}}^{1}\right)^{*} \eta_{2}-\Omega_{g_{2}^{-1}, g_{1}^{-1}}^{*} \xi_{2}\right)+\Omega_{g_{2}^{-1} g_{1}^{-1}, g_{1} g_{2}}^{*} \xi_{2}
\end{aligned}
$$

and

$$
\partial^{*}\left(\eta_{1}\right)+\left(\Delta_{g_{1}^{-1}}^{0}\right)^{*} \xi_{1}=\partial^{*}\left(\eta_{1}+\left(\Delta_{g_{1}^{-1}}^{1}\right)^{*} \eta_{2}-\Omega_{g_{2}^{-1}, g_{1}^{-1}}^{*} \xi_{2}\right)+\left(\Delta_{g_{2}^{-1} g_{1}^{-1}}^{0}\right)^{*} \xi_{2}
$$

We start for the second one:

$$
\begin{aligned}
\partial^{*}\left(\eta_{1}\right)+\left(\Delta_{g_{1}^{-1}}^{0}\right)^{*} \xi_{1} & =\partial^{*}\left(\eta_{1}\right)+\left(\Delta_{g_{1}^{-1}}^{0}\right)^{*}\left(\partial^{*}\left(\eta_{2}\right)+\left(\Delta_{g_{2}^{-1}}^{0}\right)^{*} \xi_{2}\right) \text { by Eq }(.37) \\
& =\partial^{*}\left(\eta_{1}\right)+\left(\Delta_{g_{1}^{-1}}^{0}\right)^{*} \partial^{*}\left(\eta_{2}\right)+\left(\Delta_{g_{1}^{-1}}^{0}\right)^{*}\left(\Delta_{g_{2}^{-1}}^{0}\right)^{*} \xi_{2} \\
\text { by Eq. }(1.11) & =\partial^{*}\left(\eta_{1}\right)+\partial^{*}\left(\Delta_{g_{1}^{-1}}^{1}\right)^{*}\left(\eta_{2}\right)+\left(\Delta_{g_{1}^{-1}}^{0}\right)^{*}\left(\Delta_{g_{2}^{-1}}^{0}\right)^{*} \xi_{2} \\
\text { by Eq. } 1.12) & =\partial^{*}\left(\eta_{1}\right)+\partial^{*}\left(\Delta_{g_{1}^{-1}}^{1}\right)^{*}\left(\eta_{2}\right)-\partial^{*} \Omega_{g_{2}^{-1}, g_{1}^{-1}}^{*} \xi_{2}+\left(\Delta_{g_{2}^{-1} g_{1}^{-1}}^{0}\right)^{*} \xi_{2} .
\end{aligned}
$$

Now we show the first equality. We expand the two sides and we get

$$
\begin{aligned}
(\mathrm{I})= & -\left(\Delta_{g_{2}}^{1}\right)^{*} \eta_{2}+\Omega_{g_{2}^{-1}, g_{2}}^{*} \xi_{2}-\left(\Delta_{g_{1}}^{1} \Delta_{g_{2}}^{1}\right)^{*} \eta_{1}+\left(\Omega_{g_{1}^{-1}, g_{1}} \Delta_{g_{2}}^{1}\right)^{*} \xi_{1} \\
& -\left(\partial \Omega_{g_{1}, g_{2}}\right)^{*} \eta_{1}-\left(\Delta_{g_{1}^{-1}}^{0} \Omega_{g_{1}, g_{2}}\right)^{*} \xi_{1} \\
= & -\left(\Delta_{g_{2}}^{1}\right)^{*} \eta_{2}+\Omega_{g_{2}^{-1}, g_{2}}^{*} \xi_{2}-\left(\Delta_{g_{1}}^{1} \Delta_{g_{2}}^{1}+\partial \Omega_{g_{1}, g_{2}}\right)^{*} \eta_{1} \\
& +\left(\Omega_{g_{1}^{-1}, g_{1}} \Delta_{g_{2}}^{1}-\Delta_{g_{1}^{-1}}^{0} \Omega_{g_{1}, g_{2}}\right)^{*} \xi_{1} \\
(\mathrm{II})= & -\left(\Delta_{g_{1} g_{2}}^{1}\right)^{*} \eta_{1}-\left(\Delta_{g_{1}^{-1}}^{1} \Delta_{g_{1} g_{2}}^{1}\right)^{*} \eta_{2}+\left(\Omega_{g_{2}^{-1}, g_{1}^{-1}}^{*} \Delta_{g_{1} g_{2}}^{1}+\Omega_{g_{2}^{-1} g_{1}^{-1}, g_{1} g_{2}}\right)^{*} \xi_{2}
\end{aligned}
$$

By Equation (1.13) we have $-\left(\Delta_{g_{1}}^{1} \Delta_{g_{2}}^{1}+\partial \Omega_{g_{1}, g_{2}}\right)^{*} \eta_{1}=-\left(\Delta_{g_{1} g_{2}}^{1}\right)^{*} \eta_{1}$ and $-\left(\Delta_{g_{2}}^{1}-\right.$ $\left.\Delta_{g_{1}^{-1}}^{1} \Delta_{g_{1} g_{2}}^{1}\right)^{*} \eta_{2}=-\Omega_{g_{1}^{-1}, g_{1} g_{2}}^{*} \partial^{*}\left(\eta_{2}\right)$. By Equation (1.14) we have

$$
\left(\Omega_{g_{2}^{-1}, g_{1}^{-1}}^{*} \Delta_{g_{1} g_{2}}^{1}+\Omega_{g_{2}^{-1} g_{1}^{-1}, g_{1} g_{2}}\right)^{*} \xi_{2}=\left(\Delta_{g_{2}^{-1}}^{0} \Omega_{g_{1}^{-1}, g_{1} g_{2}}+\Omega_{g_{2}^{-1}, g_{2}}\right)^{*} \xi_{2}
$$

Then, putting all together we have to show that

$$
\begin{equation*}
-\Omega_{g_{1}^{-1}, g_{1} g_{2}}^{*}\left(\partial^{*}\left(\eta_{2}\right)+\left(\Delta_{g_{2}^{-1}}^{0}\right)^{*} \xi_{2}\right)+\left(\Omega_{g_{1}^{-1}, g_{1}} \Delta_{g_{2}}^{1}-\Delta_{g_{1}^{-1}}^{0} \Omega_{g_{1}, g_{2}}\right)^{*} \xi_{1}=0 \tag{.38}
\end{equation*}
$$

Remember that $\xi_{1}=\partial^{*}\left(\eta_{2}\right)+\left(\Delta_{g_{2}^{-1}}^{0}\right)^{*} \xi_{2}$ (see Equation (.37)) and together with the Equation (1.14), the left hand side of (.38) is $\Omega_{g_{1}^{-1} g_{1}, g_{2}}^{*} \xi_{1}$, and it is zero because the operator $\Omega$ is normalized (see [19], Theorem 2.13). Then (I) $=$ (II), and therefore, the map $\varphi$ is compatible with the multiplication, and hence, it is and isomorphism of Lie groupoids. Moreover, since $\varphi$ is also linear with respect to the vector bundle structure over $\mathcal{G}$, it is actually an isomorphism of VB-groupoids.

## D Dull algebroids and Dorfman connections

In this section we recall the definitions of Dull algebroids and Dorfman connections. The reference for this part is [26].

Definition .48. A dull algebroid is a vector bundle $Q \longrightarrow M$ endowed with an anchor, i.e. a vector bundle morphism $\rho_{Q}: Q \longrightarrow T M$ over the identity on $M$ and a bracket $[,]_{Q}$ on $\Gamma(Q)$ with

$$
\rho_{Q}\left[q_{1}, q_{2}\right]_{Q}=\left[\rho_{Q}\left(q_{1}\right), \rho_{Q}\left(q_{2}\right)\right]
$$

for all $q_{1}, q_{2} \in \Gamma(Q)$, and satisfying the Leibniz identity in both terms

$$
\left[f_{1} q_{1}, f_{2} q_{2}\right]_{Q}=f_{1} f_{2}\left[q_{1}, q_{2}\right]_{Q}+f_{1} \rho_{Q}\left(q_{1}\right)\left(f_{2}\right) q_{2}-f_{2} \rho_{Q}\left(q_{2}\right)\left(f_{1}\right) q_{1}
$$

for all $f_{1}, f_{2} \in C^{\infty}(M), q_{1}, q_{2} \in \Gamma(Q)$.
Definition .49. Let $\left(Q \longrightarrow M, \rho_{Q},[,]_{Q}\right)$ be a dull algebroid. Let $B \longrightarrow M$ be a vector bundle with a fiberwise pairing $\langle\cdot, \cdot\rangle: Q \times_{M} B \longrightarrow \mathbb{R}$ and a map $\mathbf{d}_{B}$ : $C^{\infty}(M) \longrightarrow \Gamma(B)$ such that

$$
\left\langle q, \mathbf{d}_{B} f\right\rangle=\rho_{Q}(q)(f)
$$

for all $q \in \Gamma(Q)$ and $f \in C^{\infty}(M)$. Then $\left(B, \mathbf{d}_{B},\langle\cdot, \cdot\rangle\right)$ is called a pre-dual of $Q$ and $Q$ and $B$ are said to be paired by $\langle\cdot, \cdot\rangle$.

Definition .50. Let $\left(Q \longrightarrow M, \rho_{Q},[,]_{Q}\right)$ be a dull algebroid and $\left(B \longrightarrow M, \mathbf{d}_{B},\langle\cdot, \cdot\rangle\right)$ be a pre-dual of Q .

1. A Dorfman $(Q-)$ connection on $B$ is an $\mathbb{R}$-bilinear map

$$
\nabla: \Gamma(Q) \times \Gamma(B) \longrightarrow \Gamma(B)
$$

such that
(a) $\nabla_{f q} b=f \nabla_{q} b+\langle q, b\rangle \mathbf{d}_{B} f$
(b) $\nabla_{q}(f b)=f \nabla_{q} b+\rho_{Q}(q) f b$
(c) $\nabla_{q}\left(\mathbf{d}_{B} f\right)=\mathbf{d}_{B}\left(\mathcal{L}_{\rho(q)} f\right)$ for all $f \in C^{\infty}(M), q \in \Gamma(Q), b \in \Gamma(B)$.
2. The curvature of $\nabla$ is the map

$$
R_{\nabla}: \Gamma(Q) \times \Gamma(Q) \longrightarrow \Gamma\left(B^{*} \otimes B\right)
$$

defined on $q_{1}, q_{2} \in \Gamma(Q)$ by: $R_{\nabla}\left(q_{1}, q_{2}\right)=\nabla_{q_{1}} \nabla_{q_{2}}-\nabla_{q_{2}} \nabla_{q_{1}}-\nabla_{\left[q_{1}, q_{2}\right]_{Q}}$
Recall Proposition 4.17:
Proposition .51. 4.17 There is one-to-one correspondence between horizontal lifts $h: \Gamma(A) \longrightarrow \Gamma\left(T A \oplus T^{*} A\right)$ and $\left(T M \oplus A^{*}\right)$-Dorfman connection on $A \oplus T^{*} M$

$$
\Lambda: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma\left(A \oplus T^{*} M\right) \longrightarrow \Gamma\left(A \oplus T^{*} M\right)
$$

via the relation

$$
\begin{equation*}
\Lambda_{(u, \xi)}(a, \theta)=\nabla_{(u . \xi)}^{h} a+\left(0, d\langle\xi, a\rangle+\mathcal{L}_{u} \theta\right) . \tag{.39}
\end{equation*}
$$

Moreover, if $(\mathfrak{L}, U ; A, M)$ be a double vector subbundle of $\left(T A \oplus T^{*} A, T M \oplus A^{*} ; A, M\right)$ with core bundle $K \subseteq A \oplus T^{*} M$, then $h$ is adapted to $\mathfrak{L}$ if and only if $\Lambda$ is adapted to $\mathfrak{L}$.

Proof. Let $h: \Gamma(A) \longrightarrow \Gamma_{\operatorname{lin}}\left(T A \oplus T^{*} A, T M \oplus A^{*}\right)$ be a horizontal lift. Recall that the linear section $R_{a}: A^{*} \longrightarrow T^{*} A$ is given by

$$
R_{a}(\xi)=\left(d \ell_{\xi}\right)_{a}-q^{*}(\mathrm{~d}\langle\xi, a\rangle) .
$$

Then

$$
\begin{aligned}
-S_{\nabla_{(u, \xi)}^{h}(a)}\left(u_{p}, \xi_{p}\right) & =h(a)\left(u_{p}, \xi_{p}\right)-\left(T a\left(u_{p}\right), R a\left(\xi_{p}\right)\right) \\
& =h(a)\left(u_{p}, \xi_{p}\right)-\left(T a\left(u_{p}\right),\left(\mathrm{d} \ell_{\xi}\right)_{a_{p}}-q^{*}(\mathrm{~d}\langle\xi, a\rangle)\right) \\
& =h(a)\left(u_{p}, \xi_{p}\right)-\left(T a\left(u_{p}\right),\left(\mathrm{d} \ell_{\xi}\right)_{a_{p}}\right)+\left(0, q^{*}(d\langle\xi, a\rangle)\right) \\
& =-\left(\delta_{(u, \xi)}(a)\right)^{\uparrow}\left(a_{p}\right)+q^{*}(\mathrm{~d}\langle\xi, a\rangle)
\end{aligned}
$$

which implies that

$$
\begin{equation*}
\nabla_{(u, \xi)}^{h}(a)=\delta_{(u, \xi)}(a)-(0, \mathrm{~d}\langle\xi, a\rangle) \tag{.40}
\end{equation*}
$$

where

$$
\delta: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma(A) \longrightarrow \Gamma\left(A \oplus T^{*} M\right)
$$

is defined by

$$
\begin{equation*}
\left(\delta_{(u, \xi)}(a)\right)^{\uparrow}\left(a_{p}\right)=\left(T a\left(u_{p}\right),\left(\mathrm{d} \ell_{\xi}\right)_{a_{p}}\right)-h(a)\left(u_{p}, \xi_{p}\right) \tag{.41.}
\end{equation*}
$$

Define the map $\Lambda: \Gamma\left(T M \oplus A^{*}\right) \times \Gamma\left(A \oplus T^{*} M\right) \longrightarrow \Gamma\left(A \oplus T^{*} M\right)$ by

$$
\begin{equation*}
\Lambda_{(u, \xi)}(a, \theta)=\delta_{(u, \xi)}(a)+\left(0, \mathcal{L}_{u} \theta\right)=\nabla_{(u, \xi)}^{h} a+\left(0, \mathrm{~d}\langle\xi, a\rangle+\mathcal{L}_{u} \theta\right) . \tag{.42}
\end{equation*}
$$

Then using Theorem 4.1 in [26] and the relation (.42) follows the first part of the proposition. The second part of the proposition follows by Proposition 4.12 in [26].

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