# CONVERGENCE ANALYSIS FOR THE NUMERICAL BOUNDARY CORRECTOR FOR ELLIPTIC EQUATIONS WITH RAPIDLY OSCILLATING COEFFICIENTS 

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#### Abstract

We develop the convergence analysis for a numerical scheme proposed for approximating the solution of the elliptic problem $$
L_{\epsilon} u_{\epsilon}=-\frac{\partial}{\partial x_{i}} a_{i j}(x / \epsilon) \frac{\partial}{\partial x_{j}} u_{\epsilon}=f \text { in } \Omega, \quad u_{\epsilon}=0 \text { on } \partial \Omega
$$ where the matrix $a(y)=\left(a_{i j}(y)\right)$ is symmetric positive definite and periodic with period $Y$. The major goal is to develop a numerical scheme capturing the solution oscillations in the $\epsilon$ scale on a mesh size $h>\epsilon($ or $h \gg \epsilon)$. The proposed method is based on asymptotic analysis and on numerical treatments for the boundary corrector terms, and the convergence analysis is based on asymptotic expansion estimates and finite elements analysis. We obtain discretization errors of $O\left(h^{2}+\epsilon^{3 / 2}+\epsilon h\right)$ and $O(h+\epsilon)$ in the $L^{2}$ norm and the broken $H^{1}$ semi-norm, respectively.


Key words. Finite elements, homogenization, elliptic equations, multiscaling, boundary layer, mixed finite elements.

AMS subject classifications. 65N30, 35B27,

1. Introduction. This paper develops the convergence analysis of the numerical scheme proposed in [43] to approximate $u_{\epsilon}$, the solution of the problem:

$$
\begin{equation*}
L_{\epsilon} u_{\epsilon}=-\frac{\partial}{\partial x_{i}}\left(a_{i j}(x / \epsilon) \frac{\partial}{\partial x_{j}} u_{\epsilon}\right)=f \text { in } \Omega, \quad u_{\epsilon}=0 \text { on } \partial \Omega, \tag{1.1}
\end{equation*}
$$

where $a(y)=\left(a_{i j}(y)\right)$ is a positive symmetric definite matrix and $\epsilon \in(0,1)$ is the periodicity parameter. We assume the $a_{i j} \in L_{\text {per }}^{\infty}(Y)$, i.e. $a_{i j} \in L^{\infty}\left(\mathbb{R}^{2}\right)$ and $Y$-periodic, $Y=(0,1)^{2}$, and there exists a positive constant $\gamma_{a}$ such that $a_{i j}(y) \xi_{i} \xi_{j} \geq \gamma_{a}\|\xi\|^{2}$ for all $\xi \in \mathbb{R}^{2}$ and $y \in Y$. We always use the Einstein summation convention, i.e. repeated indices indicate summation, except for the index $k$, which refers to variables or functions associated to edges of the polygonal domain $\Omega$.

We note that when the mesh size $h>\epsilon$, standard finite element methods do not yield good numerical approximations; see [27]. Recently, new numerical methods have been proposed for solving the Problem (1.1) such as the multi-scale finite element methods [23, 26, 4, 13, 21], the residual-free bubble function methods [11, 5, 6, 38, 12], and the generalized FEM for homogenization problems [39]. There are also related methods for the case the homogenized equation is not known; see the heterogeneous multiscale method $[18,19,2]$ and $[22,20]$. The numerical method considered here, opposed to the methods in $[5,26,38,4,11]$ is based strongly on the asymptotic expansion of $u_{\epsilon}$. We also explore the periodicity of the matrix $a$ to obtain a very efficient method for approximating $u_{\epsilon}$.

One of the first mathematical tools used to handle this problem was homogenization theory $[8,9]$. Based on this theory a first order expansion of $u_{\epsilon}$ plus a boundary corrector term is considered and then each term is numerically approximated in

[^0][42, 43]. These methods were designed to work with a mesh size $h>\epsilon($ or $h \gg \epsilon)$, however they also work in the case $h<\epsilon$. The article [42] presents the numerical algorithm when the domain $\Omega$ is a rectangular region, while [43] generalizes the method to the case where the domain $\Omega$ is a convex polygon with rational boundary normals. This generalization is possible due to the Lagrange multiplier space introduced to approximate $\partial_{\eta} u_{0}$ on $\partial \Omega$.

The convergence analysis for the numerical method is performed in two parts. First we estimate the error between $u_{\epsilon}$ and $u_{0}+\epsilon u_{1}+\epsilon \phi_{\epsilon}$ in $L^{2}$ and $H^{1}$ norms, where $\phi_{\epsilon}$ denotes the theoretical approximation for the boundary corrector term $\theta_{\epsilon}$. The theory developed for approximating $\theta_{\epsilon}$ is similar to the one proposed in [3, 34]. We note that Propositions 6.1 and 6.4 , which estimates the error between $u_{\epsilon}$ and $u_{0}+\epsilon u_{1}+\epsilon \theta_{\epsilon}$ on the $H^{1}$ and $L^{2}$ norms, respectively, extend the results in [3, 34]. More specifically, Proposition 6.1 gives the same error estimate of Theorem 2.2 in [3], however here we assume $u_{0} \in W^{2, p}(\Omega)$ and $\chi^{j} \in W_{p e r}^{1, q}(\Omega)$ for $1 / p+1 / q \leq 1 / 2$ while in Theorem 2.2 in [3] it is assumed $u_{0} \in W^{2, \infty}(\Omega)$ and $\chi^{j} \in H_{p e r}^{1}(\Omega)$. We also note that Propositions 6.1 and 6.4 generalize respectively, Propositions 2.1 and 2.3 from [34]. In Proposition 6.1 we assume $a_{i j} \in L_{p e r}^{\infty}(Y), u_{0} \in W^{2, p}(\Omega)$ and $\chi^{j} \in W_{p e r}^{1, q}(\Omega)$ for $1 / p+1 / q \leq 1 / 2$, and $\Omega \subset \mathbb{R}^{2,3}$, while in Proposition 2.1 from [34] it is assumed $a_{i j} \in C_{p e r}^{1, \beta}(Y), u_{0} \in H^{2}(\Omega)$ and $\Omega \subset \mathbb{R}^{2}$. In Proposition 6.4 we assume $a_{i j} \in L_{p e r}^{\infty}(Y)$, $u_{0} \in W^{3, p}(\Omega), \chi^{j}$ and $\chi^{i j} \in W_{p e r}^{1, q}(\Omega)$ for $1 / p+1 / q \leq 1 / 2$, and $\Omega \subset \mathbb{R}^{2,3}$, while in Proposition 2.3 from [34] it is assumed $a_{i j} \in C_{p e r}^{1, \beta}(Y), u_{0} \in H^{3}(\Omega)$ and $\Omega \subset \mathbb{R}^{2}$. The importance of considering a theory that handles the case $a_{i j} \in L_{p e r}^{\infty}(Y)$ comes from applications to composite materials where the coefficients $a_{i j}$ are often piecewise constant; see also Theorem 1.1 from [32] which gives conditions on the discontinuities of the functions $a_{i j}$ so that $\chi^{j}$ and $\chi^{i j} \in W_{p e r}^{1, \infty}(Y)$. We also observe that Proposition 2.1 from [34] is used in the convergence analysis of the numerical methods presented in [23, 27, 38], and therefore the analysis presented here can be helpful for extending the convergence proofs of these numerical methods assuming less regularity on $a$ or $u_{0}$. In the second part of the convergence analysis we use finite elements theory to estimate the error due to the discrete approximation. The main difficulty here lies in the fact that we use a discrete approximation of $\partial_{\eta} u_{0}$ as Dirichlet boundary condition for the boundary corrector problem. We observe that if $u_{0}^{h}$ is a finite element approximation for $u_{0}$, then $\partial_{\eta} u_{0}^{h}$ does not necessarily belong to the trace of the finite element space used to obtain $u_{0}^{h}$, hence we introduce the Lagrange multiplier space to approximate $\partial_{\eta} u_{0}$ and we develop error estimates between $\partial_{\eta} u_{0}$ and its discrete approximation in $W^{1,1-1 / p}$ spaces; see Lemma 4.3.

To simplify the exposition we perform the analysis in the case $\Omega=(0,1)^{2}$, although the same theory holds in the case $\Omega=\prod_{i=1}^{2}\left(a_{i}, b_{i}\right), a_{i}<b_{i} \in \mathbb{R}$. We note that Propositions 6.1 and 6.4 are proved in the case $\Omega \subset \mathbb{R}^{d} d=2,3$, is a convex domain and $Y=(0,1)^{d}$. The analysis presented here can also be extended to the case where the domain $\Omega$ is a convex polygon with rational boundary normals; see [41].

We now introduce some norms and semi-norms. Let $B \subset \mathbb{R}^{2}$ be an open set and define

$$
\begin{aligned}
\|v\|_{m, \infty, B} & =\max _{|\alpha| \leq m}\left\{\text { ess. } \sup _{x \in B}\left|\partial^{\alpha} v(x)\right|\right\}, \\
|v|_{m, \infty, B} & =\max _{|\alpha|=m}\left\{\text { ess. } \sup _{x \in B}\left|\partial^{\alpha} v(x)\right|\right\},
\end{aligned}
$$

and for $1 \leq q<\infty$

$$
\begin{aligned}
\|v\|_{m, q, B} & =\left(\int_{B} \sum_{|\alpha| \leq m}\left|D^{\alpha} v\right|^{q} d x\right)^{1 / q} \\
|v|_{m, q, B} & =\left(\int_{B} \sum_{|\alpha|=m}\left|D^{\alpha} v\right|^{q} d x\right)^{1 / q}
\end{aligned}
$$

We also define the non-conforming norms related to a partition $\mathcal{T}_{h}=K_{1}, K_{2}, \ldots, K_{N}$ of $B$ by

$$
\|v\|_{m, h}=\sqrt{\sum_{K_{j} \in \mathcal{T}_{h}}\|v\|_{H^{m}\left(K_{j}\right)}^{2}}
$$

Throughout this paper we do not make reference to the domain $B$, or to the coefficient $q$ when $B=\Omega$, or $q=2$, respectively. In what follows $c$ denotes a generic constant independent of $\epsilon$ and mesh parameters.

This paper is organized as follows. Section 2 introduces the asymptotic expansion of $u_{\epsilon}$ considered in [42, 43], describes a theoretical approximation for the boundary corrector term, and presents the main theorems for estimating the errors due to the asymptotic expansion approximation. Section 3 describes the numerical algorithm, Section 4 treats the discretization errors due to the finite element approximation, and Section 5 presents the numerical experiments. The Appendix contains the proofs of the main results from Section 2.

## 2. Theoretical Approximation.

2.1. The Asymptotic Expansion. Consider the following anzats

$$
\begin{equation*}
u_{\epsilon}(x)=u_{0}(x, x / \epsilon)+\epsilon u_{1}(x, x / \epsilon)+\epsilon^{2} u_{2}(x, x / \epsilon)+\cdots \tag{2.1}
\end{equation*}
$$

where the functions $u_{j}(x, y)$ are $Y$ periodic in y . Using (2.1) in Equation (1.1) and matching the terms with the same order in $\epsilon$, one may define functions $u_{j}$ such that $u_{0}(x, x / \epsilon)+\epsilon u_{1}(x, x / \epsilon)+\epsilon^{2} u_{2}(x, x / \epsilon)$ approximates $u_{\epsilon}$, for instance if $u_{0} \in C^{2}(\Omega)$ and $\chi^{j} \in W^{1, \infty}(Y)$ we have

$$
\left\|u_{\epsilon}(x)-u_{0}(x, x / \epsilon)-\epsilon u_{1}(x, x / \epsilon)\right\|_{1} \leq c \epsilon^{1 / 2}\left\|u_{0}\right\|_{2, \infty}
$$

where the constant $c$ depends on $a, \chi^{j}$ and $\Omega$. These terms are defined below; for more details, including the proof of the above inequality see [9, 29].

Let $\chi^{j} \in H_{\text {per }}^{1}(Y)$, i.e. $\chi^{j} \in H_{l o c}^{1}\left(\mathbb{R}^{2}\right)$ and $Y$-periodic, be the weak solution with zero average over $Y$ of

$$
\begin{equation*}
\nabla_{y} \cdot a(y) \nabla_{y} \chi^{j}=\nabla_{y} \cdot a(y) \nabla_{y} y_{j}=\frac{\partial}{\partial y_{i}} a_{i j}(y) \tag{2.2}
\end{equation*}
$$

and define the matrix

$$
\begin{equation*}
A_{i j}=\frac{1}{|Y|} \int_{Y} a_{l m}(y) \frac{\partial}{\partial y_{l}}\left(y_{i}-\chi^{i}\right) \frac{\partial}{\partial y_{m}}\left(y_{j}-\chi^{j}\right) d y \tag{2.3}
\end{equation*}
$$

It is easy to check that the matrix $A$ is symmetric positive definite. Define $u_{0} \in H_{0}^{1}(\Omega)$ as the weak solution of

$$
\begin{equation*}
-\nabla \cdot A \nabla u_{0}=f \text { in } \Omega, \quad u_{0}=0 \text { on } \partial \Omega \tag{2.4}
\end{equation*}
$$

and let

$$
\begin{equation*}
u_{1}\left(x, \frac{x}{\epsilon}\right)=-\chi^{j}\left(\frac{x}{\epsilon}\right) \frac{\partial u_{0}}{\partial x_{j}}(x) \tag{2.5}
\end{equation*}
$$

Note that $u_{0}+\epsilon u_{1}$ does not satisfy the zero Dirichlet boundary condition on $\partial \Omega$ imposed for $u_{\epsilon}$. In order to overcome this, the boundary corrector term $\theta_{\epsilon} \in H^{1}(\Omega)$ is introduced as the solution of

$$
\begin{equation*}
-\nabla \cdot a(x / \epsilon) \nabla \theta_{\epsilon}=0 \text { in } \Omega, \quad \theta_{\epsilon}=-u_{1}\left(x, \frac{x}{\epsilon}\right) \text { on } \partial \Omega \tag{2.6}
\end{equation*}
$$

hence $u_{0}+\epsilon u_{1}+\epsilon \theta_{\epsilon} \in H_{0}^{1}(\Omega)$. Propositions 6.1 and 6.6 provide error estimates between $u_{\epsilon}$ and $u_{0}+\epsilon u_{1}+\epsilon \theta_{\epsilon}$ in the norms $\|\cdot\|_{1}$ and $\|\cdot\|_{0}$, respectively.

We also define the term $u_{2}$, which is used in the proof of Proposition 6.4. Set

$$
b_{i j}=-a_{i j}+a_{i m} \frac{\partial \chi^{j}}{\partial y_{m}}+\frac{\partial}{\partial y_{m}}\left(a_{m i} \chi^{j}\right)
$$

and observe that $\bar{b}_{i j}=A_{i j}$, where $\bar{b}_{i j}=\int_{Y} b_{i j} d y$. Define $\chi^{i j} \in H_{p e r}^{1}(Y)$ as the weak solution with zero average over $Y$ of

$$
\begin{equation*}
\nabla_{y} \cdot a \nabla_{y} \chi^{i j}=b_{i j}-\bar{b}_{i j} \tag{2.7}
\end{equation*}
$$

and let

$$
\begin{equation*}
u_{2}\left(x, \frac{x}{\epsilon}\right)=-\chi^{i j}\left(\frac{x}{\epsilon}\right) \frac{\partial^{2} u_{0}}{\partial x_{i} \partial x_{j}}(x) . \tag{2.8}
\end{equation*}
$$

2.2. Boundary Corrector Approximation. The coefficients $a_{i j}(x / \epsilon)$ and the boundary values $-u_{1}\left(x, \frac{x}{\epsilon}\right)$ in the Equation (2.6) are highly oscillatory, hence it is not a trivial problem to obtain a good discrete approximation for $\theta_{\epsilon}$. We propose an analytical approximation for $\theta_{\epsilon}$, denoted by $\phi_{\epsilon}$, which satisfies the oscillating boundary condition and is suitable for numerical approximation. The approximation for $\theta_{\epsilon}$ proposed here is similar to the one used in [3, 34].

Note that $u_{0}$ vanishes on $\partial \Omega$, therefore $\left.\nabla u_{0}\right|_{\partial \Omega}=\eta \partial_{\eta} u_{0}$, where $\eta$ denotes the unity outward normal vector to $\partial \Omega$ and $\partial_{\eta} u_{0}$ denotes the unity outward derivative of $u_{0}$ on $\partial \Omega$. Hence in order to obtain the approximation $\phi_{\epsilon}$ for $\theta_{\epsilon}$, we introduce the following decomposition $\theta_{\epsilon}=\tilde{\theta}_{\epsilon}+\bar{\theta}_{\epsilon}$, where

$$
\begin{equation*}
-\nabla \cdot a(x / \epsilon) \nabla \tilde{\theta}_{\epsilon}=0 \quad \text { in } \Omega, \quad \tilde{\theta}_{\epsilon}=\left(\chi^{j}\left(\frac{x}{\epsilon}\right) \eta_{j}-\chi^{*}\right) \partial_{\eta} u_{0} \quad \text { on } \partial \Omega \tag{2.9}
\end{equation*}
$$

and

$$
\begin{equation*}
-\nabla \cdot a(x / \epsilon) \nabla \bar{\theta}_{\epsilon}=0 \text { in } \Omega, \quad \bar{\theta}_{\epsilon}=\chi^{*} \partial_{\eta} u_{0} \quad \text { on } \quad \partial \Omega \tag{2.10}
\end{equation*}
$$

where $\left.\chi^{*}\right|_{\Gamma_{k}}=\chi_{k}^{*}, k \in\{e, w, n, s\}$ are properly chosen constants defined in Subsection 2.2.1, and $\Gamma_{e}=\{1\} \times[0,1], \Gamma_{w}=\{0\} \times[0,1], \Gamma_{n}=[0,1] \times\{1\}$, and $\Gamma_{s}=[0,1] \times\{0\}$. In Remark 2.1 we show that $\chi^{*} \partial_{\eta} u_{0}$ and $\chi^{j}\left(\frac{x}{\epsilon}\right) \eta_{j} \partial_{\eta} u_{0} \in H^{1 / 2}(\partial \Omega)$, therefore the Problems (2.9) and (2.10) are well posed. Later in this section we define the functions $\tilde{\phi}_{\epsilon}$ and $\bar{\phi}_{\epsilon}$, which are the approximations for $\tilde{\theta}_{\epsilon}$ and $\bar{\theta}_{\epsilon}$ respectively, and define $\phi_{\epsilon}=$ $\tilde{\phi}_{\epsilon}+\bar{\phi}_{\epsilon}$.

REMARK 2.1. Let $\Omega \subset \mathbb{R}^{2}$ be a convex polygon and assume $u_{0} \in H^{2}(\Omega) \cap H_{0}^{1}(\Omega)$. We have by Theorem A.2 [37] that $\left.\partial_{\eta} u_{0}\right|_{\Gamma_{k}} \in H_{00}^{1 / 2}\left(\Gamma_{k}\right)$ and $\left\|\partial_{\eta} u_{0}\right\|_{H_{00}^{1 / 2}\left(\Gamma_{k}\right)} \leq c\left\|u_{0}\right\|_{2}$, therefore

$$
\left\|\chi^{*} \partial_{\eta} u_{0}\right\|_{H^{1 / 2}(\partial \Omega)} \leq c\left(\chi^{*}\right)\left\|u_{0}\right\|_{2}
$$

Note also that $u_{1}\left(x, \frac{x}{\epsilon}\right)=-\chi^{j}\left(\frac{x}{\epsilon}\right) \frac{\partial u_{0}}{\partial x_{j}}(x)$ and $\frac{\partial u_{1}}{\partial x_{l}}=-\left(\frac{\partial \chi^{j}}{\partial x_{l}}\right) \frac{\partial u_{0}}{\partial x_{j}}-\chi^{j}\left(\frac{\partial^{2} u_{0}}{\partial x_{l} \partial x_{j}}\right)$. If we assume $u_{0} \in W^{2, p}(\Omega)$ and $\chi^{j} \in W_{p e r}^{1, q}(Y)$, for $p \geq 2$ and $q>2$ or $p>2$ and $q \geq 2$, by a direct application of Sobolev embedding Theorem (5.4 [1]) we obtain $u_{1} \in H^{1}(\Omega)$. In addition, from regularity theory of elliptic equations we obtain $\chi^{j} \in L^{\infty}(Y) \cap H^{1}(Y)$ (see Theorem 13.1 [30] and 4.28 [15]), hence we also have $\left.u_{1}\right|_{\Gamma_{k}} \in H_{00}^{1 / 2}\left(\Gamma_{k}\right)$.
2.2.1. Calculating the Constants $\chi_{k}^{*}$. We define the constants $\chi_{k}^{*}$ such that the function $\tilde{\phi}_{\epsilon}$ decays exponentially to zero away from the boundary and satisfies the Dirichlet boundary condition $\tilde{\phi}_{\epsilon}(x)=-u_{1}\left(x, \frac{x}{\epsilon}\right)-\chi^{*} \partial_{\eta} u_{0}(x)$ for $x \in \partial \Omega$.

Associated to each side of $\Omega$ define the functions $v_{k}, k \in\{e, w, n, s\}$ as

1. Let $G_{e}=\{(-\infty, 0] \times[0,1]\}$ and $v_{e}$ the solution of

$$
\begin{aligned}
& -\nabla_{y} \cdot a\left(y_{1}, y_{2}\right) \nabla_{y} v_{e}=0 \text { in } G_{e}, \\
& v_{e}\left(0, y_{2}\right)=\chi^{1}\left(1 / \epsilon, y_{2}\right) \text { for } 0<y_{2}<1, \\
& v_{e}\left(y_{1}, \cdot\right)[0,1] \text {-periodic for }-\infty<y_{1}<0, \\
& \text { and } \partial_{y_{i}} v_{e} \exp \left(-\gamma y_{1}\right) \in L^{2}\left(G_{e}\right) \quad i=1,2 .
\end{aligned}
$$

2. Let $G_{w}=\{[0, \infty) \times[0,1]\}$ and $v_{w}$ the solution of

$$
\begin{aligned}
& -\nabla_{y} \cdot a\left(y_{1}, y_{2}\right) \nabla_{y} v_{w}=0 \text { in } G_{w} \\
& v_{w}\left(0, y_{2}\right)=-\chi^{1}\left(0, y_{2}\right) \text { for } 0<y_{2}<1 \\
& v_{w}\left(y_{1}, \cdot\right)[0,1] \text {-periodic for } 0<y_{1}<\infty \\
& \text { and } \partial_{y_{i}} v_{w} \exp \left(\gamma y_{1}\right) \in L^{2}\left(G_{w}\right) \quad i=1,2
\end{aligned}
$$

3. Let $G_{n}=\{[0,1] \times(-\infty, 0]\}$ and $v_{n}$ the solution of

$$
\begin{aligned}
& -\nabla_{y} \cdot a\left(y_{1}, y_{2}\right) \nabla_{y} v_{n}=0 \text { in } G_{n} \\
& v_{n}\left(y_{1}, 0\right)=\chi^{2}\left(y_{1}, 1 / \epsilon\right) \text { for } 0<y_{1}<1 \\
& v_{n}\left(\cdot, y_{2}\right)[0,1] \text {-periodic for }-\infty<y_{2}<0 \\
& \text { and } \partial_{y_{i}} v_{n} \exp \left(-\gamma y_{2}\right) \in L^{2}\left(G_{n}\right) \quad i=1,2
\end{aligned}
$$

4. Let $G_{s}=\{[0,1] \times[0, \infty)\}$ and $v_{s}$ the solution of

$$
\begin{aligned}
& -\nabla_{y} \cdot a\left(y_{1}, y_{2}\right) \nabla_{y} v_{s}=0 \text { in } G_{s} \\
& v_{s}\left(y_{1}, 0\right)=-\chi^{2}\left(y_{1}, 0\right) \text { for } 0<y_{1}<1 \\
& v_{s}\left(\cdot, y_{2}\right)[0,1] \text {-periodic for } 0<y_{2}<\infty \\
& \text { and } \partial_{y_{i}} v_{n} \exp \left(\gamma y_{2}\right) \in L^{2}\left(G_{s}\right) \quad i=1,2
\end{aligned}
$$

The above problems have been studied by several authors, see [36, 33, 29, 34]. Theorem 10.1 in Section 10.4 from [33] guarantees the existence of a unique solution for each of the above equations. In addition, by Theorem 3 [36] there exists constants $\chi_{k}^{*}$, such that

$$
\left|v_{k}(y)-\chi_{k}^{*}\right| \leq c \exp \left(\gamma y \cdot \eta_{k}\right) \text { as } y \cdot \eta_{k} \rightarrow-\infty
$$

where $\eta_{k}$ denotes the unity outward normal on $\Gamma_{k}$.
2.2.2. Approximating $\tilde{\theta}_{\epsilon}$. We note by Remark 2.1 that $\left.\left(u_{1}\left(x, \frac{x}{\epsilon}\right)-\chi^{*} \partial_{\eta} u_{0}\right)\right|_{\Gamma_{k}} \in$ $H_{00}^{1 / 2}\left(\Gamma_{k}\right)$. Thus, we can split $\tilde{\theta}_{\epsilon}=\sum_{k \in\{e, w, n, s\}} \tilde{\theta}_{\epsilon}^{k}$ where

$$
L_{\epsilon} \tilde{\theta}_{\epsilon}^{k}=0 \text { in } \Omega, \quad \text { and } \quad \tilde{\theta}_{\epsilon}^{k}= \begin{cases}-u_{1}\left(x, \frac{x}{\epsilon}\right)-\chi^{*} \partial_{\eta} u_{0} & \text { on } \Gamma_{k}  \tag{2.11}\\ 0 & \text { on } \partial \Omega \backslash \Gamma_{k} .\end{cases}
$$

We approximate $\tilde{\theta}_{\epsilon}^{k}$ by $\tilde{\phi}_{\epsilon}^{k}$ given as

$$
\begin{align*}
& \tilde{\phi}_{\epsilon}^{e}\left(x_{1}, x_{2}\right)=\varphi_{e}\left(x_{1}\right)\left(v_{e}\left(\frac{x_{1}-1}{\epsilon}, \frac{x_{2}}{\epsilon}\right)-\chi_{e}^{*}\right) \frac{\partial u_{0}}{\partial x_{1}}\left(x_{1}, x_{2}\right),  \tag{2.12}\\
& \tilde{\phi}_{\epsilon}^{w}\left(x_{1}, x_{2}\right)=-\varphi_{w}\left(x_{1}\right)\left(v_{w}\left(\frac{x_{1}}{\epsilon}, \frac{x_{2}}{\epsilon}\right)-\chi_{w}^{*}\right) \frac{\partial u_{0}}{\partial x_{1}}\left(x_{1}, x_{2}\right), \\
& \tilde{\phi}_{\epsilon}^{n}\left(x_{1}, x_{2}\right)=\varphi_{n}\left(x_{2}\right)\left(v_{n}\left(\frac{x_{1}}{\epsilon}, \frac{x_{2}-1}{\epsilon}\right)-\chi_{n}^{*}\right) \frac{\partial u_{0}}{\partial x_{2}}\left(x_{1}, x_{2}\right), \\
& \tilde{\phi}_{\epsilon}^{s}\left(x_{1}, x_{2}\right)=-\varphi_{s}\left(x_{2}\right)\left(v_{s}\left(\frac{x_{1}}{\epsilon}, \frac{x_{2}}{\epsilon}\right)-\chi_{s}^{*}\right) \frac{\partial u_{0}}{\partial x_{2}}\left(x_{1}, x_{2}\right),
\end{align*}
$$

where $\varphi_{k}$ are nonnegative smooth functions satisfying

$$
\varphi_{e}(s)=\varphi_{n}(s)=\left\{\begin{array}{lll}
1 & \text { if } s \in[2 / 3,1] \\
0 & \text { if } s \in[0,1 / 3],
\end{array} \quad \varphi_{w}(s)=\varphi_{s}(s)=\left\{\begin{array}{lll}
0 & \text { if } s \in[2 / 3,1] \\
1 & \text { if } s \in[0,1 / 3]
\end{array}\right.\right.
$$

Hence

$$
\begin{equation*}
\tilde{\phi}_{\epsilon}=\sum_{k \in\{e, w, n, s\}} \tilde{\phi}_{\epsilon}^{k} \tag{2.13}
\end{equation*}
$$

approximates $\tilde{\theta}_{\epsilon}$, and $\tilde{\phi}_{\epsilon}=\tilde{\theta}_{\epsilon}$ on the boundary of $\Omega$.
2.2.3. Approximating $\bar{\theta}_{\epsilon}$. The boundary condition imposed on Equation (2.10) does not depend on $\epsilon$. An effective approximation for $\bar{\theta}_{\epsilon}$ is given by $\bar{\phi} \in H^{1}(\Omega)$ the weak solution of

$$
\begin{equation*}
-\nabla \cdot A \nabla \bar{\phi}=0 \text { in } \Omega, \quad \bar{\phi}=\chi^{*} \partial_{\eta} u_{0} \quad \text { on } \partial \Omega \tag{2.14}
\end{equation*}
$$

By Propositions 6.3 and 6.5 , we have that $\bar{\phi}$ is a good approximation for $\bar{\theta}_{\epsilon}$ only on the $L^{2}$ norm, since $\left\|\bar{\phi}-\bar{\theta}_{\epsilon}\right\|_{0}$ is $O(\epsilon)$ and $\left\|\bar{\phi}-\bar{\theta}_{\epsilon}\right\|_{1}$ is $O(1)$. We note, however, that the asymptotic expansion considered here to approximate $u_{\epsilon}$ is given by $u_{0}+\epsilon u_{1}+\epsilon \bar{\theta}_{\epsilon}+\epsilon \tilde{\theta}_{\epsilon}$, and by a triangular inequality we obtain $\left\|u_{\epsilon}-u_{0}-\epsilon u_{1}-\epsilon \bar{\phi}-\epsilon \tilde{\theta}_{\epsilon}\right\|_{1} \leq$ $c \epsilon+\left\|u_{\epsilon}-u_{0}-\epsilon u_{1}-\epsilon \theta_{\epsilon}\right\|_{1}$. Hence, when estimating the error on the $H^{1}$ norm between $u_{\epsilon}$ and its theoretical approximation, the contribution due to the approximation of $\bar{\theta}_{\epsilon}$ by $\bar{\phi}$ is $O(\epsilon)$.
2.2.4. Approximating $u_{\epsilon}$. We finally define the theoretical approximation for $u_{\epsilon}$ as $u_{0}+\epsilon u_{1}+\epsilon \phi_{\epsilon}$, where

$$
\begin{equation*}
\phi_{\epsilon}=\tilde{\phi}_{\epsilon}+\bar{\phi} \tag{2.15}
\end{equation*}
$$

Note that $\left.\phi_{\epsilon}\right|_{\partial \Omega}=\left.\theta_{\epsilon}\right|_{\partial \Omega}$, therefore $u_{0}+\epsilon u_{1}+\epsilon \phi_{\epsilon}=0$ on $\partial \Omega$.
2.2.5. Error estimates. The following theorems provide error estimates between $u_{\epsilon}$ and $u_{0}-\epsilon u_{1}-\epsilon \phi_{\epsilon}$ on the $H^{1}$ and $L^{2}$ norms. Theorem 2.1 estimates the error on the $H^{1}$ norm, while Theorems 2.2 and 2.3 estimate the error on the $L^{2}$ norm. Theorem 2.2 assumes more regularity on $u_{0}$ and less regularity on $a$ that is assumed in Theorem 2.3.

Theorem 2.1. Let $u_{\epsilon}$ be the solution of the Problem (1.1), $u_{0}, u_{1}$ and $\phi_{\epsilon}$ defined by Equations (2.4), (2.5) and (2.15), respectively. Assume $a_{i j} \in L_{p e r}^{\infty}(Y), u_{0} \in$ $W^{2, p}(\Omega), \chi^{j} \in W_{p e r}^{1, q}(Y), v_{e}$ and $\nabla\left(v_{e}-\chi_{e}^{*}\right) \exp \left(-\gamma y_{1}\right) \in L^{s}\left(G_{e}\right)$, for $1 / s+3 / p \leq 1$, $s \geq 2$ and $1 / p+1 / q \leq 1 / 2$. We also assume similar hypothesis for the other functions $v_{k}$. Then there exists a constant $c$ independent of $\epsilon$ such that

$$
\left\|u_{\epsilon}(\cdot)-u_{0}(\cdot)-\epsilon u_{1}(\cdot, \cdot / \epsilon)-\epsilon \phi_{\epsilon}(\cdot)\right\|_{1} \leq c \epsilon\left\|u_{0}\right\|_{2, p} .
$$

Proof. See Subsection 6.1 ㅁ
Theorem 2.2. Let $u_{\epsilon}$ be the solution of Problem (1.1), $u_{0}, u_{1}, \phi_{\epsilon}, \bar{\phi}$ and $\chi^{i j}$ defined by Equations (2.4), (2.5), (2.15), (2.14) and (2.7), respectively. Assume $a_{i j} \in L_{p e r}^{\infty}(Y), u_{0} \in W^{3, p}(\Omega)$, and $\bar{\phi} \in W^{2, p}(\Omega)$ and $\chi^{i j} \in W_{p e r}^{1, q}(Y)$, for $p>2$ and $1 / p+1 / q \leq 1 / 2$. Assume also $\chi^{j} \in W^{1, \infty}(Y)$, $v_{e}$ and $\nabla\left(v_{e}-\chi_{e}^{*}\right) \exp \left(-\gamma y_{1}\right) \in L^{\infty}\left(G_{e}\right)$. We also assume similar hypothesis for the other functions $v_{k}$. Then there exists a constant $c$ independent of $\epsilon$ such that

$$
\left\|u_{\epsilon}(\cdot)-u_{0}(\cdot)-\epsilon u_{1}(\cdot, \cdot / \epsilon)-\epsilon \phi_{\epsilon}(\cdot)\right\|_{0} \leq c \epsilon^{3 / 2}\left\|u_{0}\right\|_{3, p} .
$$

Proof. See Subsection 6.2 प
Theorem 2.3. Let $u_{\epsilon}$ be the solution of Problem (1.1), $u_{0}, u_{1}$ and $\phi_{\epsilon}$ be defined by Equations (2.4), (2.5) and (2.15), respectively. Assume $a_{i j} \in C_{p e r}^{1, \beta}(Y), \beta>0$, $u_{0} \in H^{3}(\Omega)$. Then there exists a constant $c$ independent of $\epsilon$ such that

$$
\left\|u_{\epsilon}(\cdot)-u_{0}(\cdot)-\epsilon u_{1}(\cdot, \cdot / \epsilon)-\epsilon \phi_{\epsilon}(\cdot)\right\|_{0} \leq c \epsilon^{3 / 2}\left\|u_{0}\right\|_{3} .
$$

Proof. See Subsection 6.3 口
Remark 2.2. Due to the Proposition 6.2, which under the hypothesis of Theorems 2.2 and 2.3 gives that $\left\|\tilde{\theta}_{\epsilon}-\tilde{\phi}_{\epsilon}\right\|_{0}$ is $O\left(\epsilon^{1 / 2}\right)$, we obtain a factor $\epsilon^{3 / 2}$ in these theorems, rather than $\epsilon^{2}$ as in Propositions 6.4 and 6.6.
3. Finite Element Approximation. We now describe how to approximate the terms $u_{0}, u_{1}, \tilde{\phi}_{\epsilon}$ and $\bar{\phi}$ numerically.

- Approximate the solution of Problem (2.2) with a second order accurate conforming finite element on a partition $\mathcal{T}_{\hat{h}}(Y)$. Denote these solutions by $\chi_{\hat{h}}^{j}$.
- Define $A_{i j}^{\hat{h}}=\frac{1}{|Y|} \int_{Y} a_{l m}(y) \frac{\partial}{\partial y_{l}}\left(y_{i}-\chi_{\hat{h}}^{i}\right) \frac{\partial}{\partial y_{m}}\left(y_{j}-\chi_{\hat{h}}^{j}\right) d y$.
- Let $V^{h}(\Omega)$ be a conforming second order accurate finite element space on a mesh $\mathcal{T}_{h}(\Omega)$ and let $V_{0}^{h}(\Omega)=V^{h}(\Omega) \cap H_{0}^{1}(\Omega)$. Define $u_{0}^{h, \hat{h}} \in V_{0}^{h}(\Omega)$ as the solution of

$$
\int_{\Omega} A^{\hat{h}} \nabla u_{0}^{h, \hat{h}} \cdot \nabla v^{h} d x=\int_{\Omega} f v^{h} d x, \quad \forall v^{h} \in V_{0}^{h}(\Omega) .
$$

- Since $\partial_{\eta} u_{0}$ appears as boundary condition imposed in Equation (2.14), it is important to obtain a good discrete approximation for it. In oder to approximate $\partial_{\eta} u_{0}$ we define $Y^{h}=\left.V^{h}(\Omega)\right|_{\partial \Omega}, Y_{k}^{h}=\left.Y^{h}\right|_{\Gamma_{k}}$ and $Y_{0, k}^{h}=\left\{\lambda^{h} \in\right.$ $Y_{k}^{h} ; \lambda^{h}=0$ at $\left.\partial \Gamma_{k}\right\}$. Let $\lambda_{k}^{h, \hat{h}} \in Y_{0, k}^{h}$ be the solution of

$$
\begin{equation*}
\int_{\Gamma_{k}} \lambda_{k}^{h, \hat{h}} \phi^{h} d \sigma=\int_{\Omega} A_{i j}^{\hat{h}} \partial_{i} u_{0}^{h, \hat{h}} \partial_{j} \phi^{h} d x-\int_{\Omega} f \phi^{h} d x \tag{3.1}
\end{equation*}
$$

$\forall \phi^{h} \in V^{h}(\Omega)$, such that $\left.\phi^{h}\right|_{\partial \Omega \backslash \Gamma_{k}}=0$. Later in Proposition 4.3 we show that $\lambda_{k}^{h, \hat{h}}$ is a good approximation for $A \nabla u_{0} \cdot \eta_{k}$ on $\Gamma_{k}$, hence we approximate $\partial_{\eta} u_{0}$ by $\mu^{h, \hat{h}}$ where

$$
\left.\mu^{h, \hat{h}}\right|_{\Gamma_{k}}=\lambda_{k}^{h, \hat{h}} / A_{l_{k} l_{k}}^{\hat{h}}, l_{k}=\left\{\begin{array}{lll}
1 & \text { if } & k=e, w \\
2 & \text { if } & k=n, s
\end{array}\right.
$$

- We observe that we use $\mu^{h, \hat{h}}$ as the approximation for $\partial_{\eta} u_{0}$ in Equation (3.5), hence in order to guarantees that the final numerical approximation for $u_{\epsilon}$ satisfies the zero Dirichlet boundary condition we define the approximation for $\nabla u_{0}$ as

$$
\begin{equation*}
\Psi^{h, \hat{h}}=\nabla u_{0}^{h, \hat{h}}+\sum_{k \in\{e, w, n, s\}} E_{k}^{h}\left(\mu^{h, \hat{h}}-\nabla u_{0}^{h, \hat{h}} \cdot \eta^{k}\right) \eta^{k} \tag{3.2}
\end{equation*}
$$

Here $E_{k}^{h}(\cdot)$ denotes a non-conforming discrete extension of $\mu^{h, \hat{h}}-\nabla u_{0}^{h, \hat{h}} \cdot \eta^{k}$ by zero on $\Omega$. More specifically, $E_{k}^{h}\left(\mu^{h, \hat{h}}-\nabla u_{0}^{h, \hat{h}} \cdot \eta^{k}\right)(z)=0$, if $z$ is a vertex of $\mathcal{T}_{h}(\bar{\Omega}) \backslash \Gamma_{k}, E_{k}^{h}\left(\mu^{h, \hat{h}}-\nabla u_{0}^{h, \hat{h}} \cdot \eta^{k}\right)(z)=\mu^{h, \hat{h}}-\nabla u_{0}^{h, \hat{h}} \cdot \eta^{k}(z)$, if $z$ is a vertex of $\Gamma_{k}$, and $\left.\left.E_{k}^{h}\left(\mu^{h, \hat{h}}-\nabla u_{0}^{h, \hat{h}} \cdot \eta^{k}\right)\right|_{K_{i}} \in V^{h}(\Omega)\right|_{K_{i}}, \forall K_{i} \in \mathcal{T}_{h}(\Omega)$.

- Define

$$
\begin{equation*}
u_{1}^{h, \hat{h}}(x, x / \epsilon)=-\Psi_{j}^{h, \hat{h}}(x) \chi_{\hat{h}}^{j}(x / \epsilon) . \tag{3.3}
\end{equation*}
$$

Note that this leads to a nonconforming approximation for $u_{1}$ in the partition $\mathcal{T}_{h}(\Omega)$.

- Let $\tau$ be a positive integer and $G_{e}^{\tau}=\left\{y \in \mathbb{R}^{2} ;-\tau \leq y_{1} \leq 0\right.$ and $\left.0 \leq y_{2} \leq 1\right\}$. Define $\tilde{v}_{e} \in H^{1}\left(G_{e}^{\tau}\right)$ as the weak solution of

$$
\begin{aligned}
& -\nabla_{y} \cdot a(y) \nabla_{y} \tilde{v}_{e}=0 \text { in } G_{e}^{\tau} \\
& \tilde{v}_{e}(y)=\chi_{\hat{h}}^{1}\left(1 / \epsilon, y_{2}\right) \text { on }\left\{y \in G_{e}^{\tau}, y_{1}=0\right\} \\
& \partial_{\eta} \tilde{v}_{e}=0 \text { on }\left\{y \in G_{e}^{\tau} ; y_{1}=-\tau\right\} \\
& \text { and } v_{e}\left(y_{1}, 0\right)=v_{k}\left(y_{1}, 1\right) \text { for }-\tau \leq y_{1} \leq 0 .
\end{aligned}
$$

Let $v_{e}^{\hat{h}, \tau}$ be a numerical approximation of $\tilde{v}_{e}$ using a second order accurate conforming finite element on a mesh $\mathcal{T}_{\hat{h}}\left(G_{e}^{\tau}\right)$, and define

$$
\chi_{e}^{*, \hat{h}, \tau}=\int_{0}^{1} v_{e}^{\hat{h}, \tau}\left(-\tau, y_{2}\right) d y_{2} .
$$

The other cases $k \in\{w, n, s\}$ are treated similarly.

- Observe that the term $v_{e}\left(\frac{x_{1}-1}{\epsilon}, \frac{x_{2}}{\epsilon}\right)$ appears in Equation (2.12). The approximation $v_{e}^{\hat{h}, \tau}$ is defined in $G_{e}^{\tau}$, hence we have defined $v_{e}^{\hat{h}, \tau}\left(\frac{x_{1}-1}{\epsilon}, \frac{x_{2}}{\epsilon}\right)$ only when $x_{1} \geq 1-\epsilon \tau$. Since the functions $v_{e}-\chi_{e}^{*}$ decays exponentially to zero in the $-\eta_{e}$ direction, its is natural to define the following approximation

$$
\tilde{\phi}_{\epsilon}^{e, h, \hat{h}, \tau}\left(x_{1}, x_{2}\right)= \begin{cases}\left(v_{e}^{\hat{h}, \tau}\left(\frac{x_{1}-1}{\epsilon}, \frac{x_{2}}{\epsilon}\right)-\chi_{e}^{*, \hat{h}, \tau}\right) \Psi^{h, \hat{h}} & \text { if } x_{1}>1-\epsilon \tau \\ 0 & \text { otherwise } .\end{cases}
$$

- Let

$$
\begin{equation*}
\tilde{\phi}_{\epsilon}^{h, \hat{h}, \tau}=\sum_{k \in\{e, w, n, s\}} \tilde{\phi}_{\epsilon}^{k, h, \hat{h}, \tau}, \tag{3.4}
\end{equation*}
$$

where the others terms $\tilde{\phi}_{\epsilon}^{k, h, \hat{h}, \tau}$ are defined in a similar way.

- Let $\bar{\phi}^{h, \hat{h}, \tau}$ be a second order accurate finite element approximation on a mesh of size $h$ for the following equation (for the well posedness of the equation bellow see Remark 3.1)

$$
\begin{equation*}
-\nabla \cdot A^{\hat{h}} \nabla \psi=0 \text { in } \Omega, \quad \text { and } \quad \psi=\chi^{*, \hat{h}, \tau} \mu^{h, \hat{h}} \text { on } \partial \Omega \text {. } \tag{3.5}
\end{equation*}
$$

- Approximate $\theta_{\epsilon}$ by $\phi_{\epsilon}^{h, \hat{h}, \tau}=\tilde{\phi}_{\epsilon}^{h, \hat{h}, \tau}+\bar{\phi}^{h, \hat{h}, \tau}$ and finally define the numerical solution for Equation (1.1) as

$$
\begin{equation*}
u_{\epsilon}^{h, \hat{h}, \tau}=u_{0}^{h, \hat{h}}+\epsilon u_{1}^{h, \hat{h}}+\epsilon \phi_{\epsilon}^{h, \hat{h}, \tau} . \tag{3.6}
\end{equation*}
$$

Remark 3.1. By construction $\mu^{h, \hat{h}}$ vanishes at the corners of $\Omega$, therefore $\chi^{*, \hat{h}, \tau} \mu^{h, \hat{h}} \in H^{1 / 2}(\partial \Omega)$. This implies that Equation (3.5) is well posed. In addition $\left.\chi^{*, \hat{h}, \tau} \mu^{h, \hat{h}} \in V^{h}\right|_{\partial \Omega}$, hence we can look for a numerical solution of Equation (3.5) in $V^{h}(\Omega)$.
4. Finite Element Approximation Error Analysis. For the discrete error analysis we assume $\hat{h}=0$ and $\tau=\infty$, i.e. $v_{k}^{\hat{h}, \tau}=v_{k}, \chi_{\hat{h}}^{j}=\chi^{j}$ and $A^{\hat{h}}=A$, and for this reason we will note make reference to the indices $\tau$ and $\hat{h}$ when we make reference to the the numerical approximation for $u_{0}, \nabla u_{0}, \bar{\phi}, \tilde{\phi}_{\epsilon}$ and $u_{\epsilon}$, i.e. $u_{\epsilon}^{h}=u_{\epsilon}^{h, \hat{h}, \tau}$ and similar for the other terms; an error analysis including the error due to the numerical approximation of the functions $v_{k}$ and $\chi^{j}$, and the matrix $A$ is currently work under progress. We also assume that linear or bilinear finite elements are used to approximate $u_{0}$. Theorems 4.1 and 4.2 give the main results of this section. Theorem 4.1 provides error estimates for the broken $H^{1}$ semi-norm and the $L^{2}$ norm between the exact solution $u_{\epsilon}$ and its numerical approximation $u_{\epsilon}^{h}$. Theorem 4.2 assumes more regularity from $u_{0}$ resulting in a better error estimate on the $L^{2}$ norm.

Theorem 4.1. Let $u_{\epsilon}$ be the solution of the Problem (1.1), $u_{0}, \chi^{j}$ and $u_{\epsilon}^{h}$ be defined by Equations (2.2), (2.4) and (3.6), respectively, and the functions $v_{k}$ and the
constants $\chi_{k}^{*}$ be defined as in Subsection 2.2.1. Assume $a_{i j} \in L_{p e r}^{\infty}(Y), u_{0} \in W^{2, p}(\Omega)$, $\chi^{j} \in W_{p e r}^{1, q}(Y), v_{e}$ and $\nabla\left(v_{e}-\chi_{e}^{*}\right) \exp \left(-\gamma y_{1}\right) \in L^{s}\left(G_{e}\right)$, for $1 / p+1 / q \leq 1 / 2$ and $1 / s+3 / p \leq 1$. We also assume similar hypothesis for the other functions $v_{k}$. Then there exists a constant $c$ independent of $\epsilon$ and $h$ such that

$$
\left|u_{\epsilon}-u_{\epsilon}^{h}\right|_{1, h} \leq c(h+\epsilon)\left\|u_{0}\right\|_{2, p}
$$

and

$$
\left\|u_{\epsilon}-u_{\epsilon}^{h}\right\|_{0} \leq c\left(h^{2}+\epsilon+\epsilon h\right)\left\|u_{0}\right\|_{2, p} .
$$

Proof. By the triangular inequality we have

$$
\begin{aligned}
\left|u_{\epsilon}-u_{\epsilon}^{h}\right|_{1, h} \leq & \left|u_{\epsilon}-u_{0}-u_{1}-\phi_{\epsilon}\right|_{1}+\left|u_{0}-u_{0}^{h}\right|_{1, h}+\epsilon\left|u_{1}-u_{1}^{h}\right|_{1, h} \\
& +\epsilon\left|\bar{\phi}-\bar{\phi}^{h}\right|_{1, h}+\epsilon\left|\tilde{\phi}_{\epsilon}-\tilde{\phi}_{\epsilon}^{h}\right|_{1, h},
\end{aligned}
$$

and the theorem follows from Theorem 2.1, the approximation error (4.1), and Propositions 4.2, 4.3 and 4.4.

Theorem 4.2. Let $u_{\epsilon}$ be the solution of the Problem (1.1), $\chi^{j}, u_{0}, \chi^{i j}, \bar{\phi}$ and $u_{\epsilon}^{h}$ be defined by Equations (2.2), (2.4), (2.7), (2.14) and (3.6), respectively, and the functions $v_{k}$ and the constants $\chi_{k}^{*}$ be defined as in Subsection 2.2.1. Assume $a_{i j} \in L_{p e r}^{\infty}(Y), u_{0} \in W^{3, p}(\Omega), \bar{\phi} \in W^{2, p}(\Omega)$ and $\chi^{i j} \in W_{\text {per }}^{1, q}(Y)$, for $p>2$ and $1 / p+1 / q \leq 1 / 2$. Also assume $\chi^{j} \in W^{1, \infty}(Y)$, and $v_{e}$ and $\nabla\left(v_{e}-\chi_{e}^{*}\right) \exp \left(-\gamma y_{1}\right) \in$ $L^{\infty}\left(G_{e}\right)$. We also assume similar hypothesis for the other functions $v_{k}$. Then there exists a constant $c$ independent of $\epsilon$ and $h$ such that

$$
\left\|u_{\epsilon}-u_{\epsilon}^{h}\right\|_{0} \leq c\left(h^{2}+\epsilon^{\frac{3}{2}}+\epsilon h\right)\left\|u_{0}\right\|_{3, p} .
$$

Furthermore, if $a_{i j} \in C_{p e r}^{1, \beta}(Y)$ and $u_{0} \in H^{3}(\Omega)$, then

$$
\left\|u_{\epsilon}-u_{\epsilon}^{h}\right\|_{0} \leq c\left(h^{2}+\epsilon^{\frac{3}{2}}+\epsilon h\right)\left\|u_{0}\right\|_{3} .
$$

Proof. The same proof of Theorem 4.1 holds here, except that (4.1) is replaced by (4.2) and Theorem 2.1 is replaced by Theorems 2.3 and 2.2 .

We now prove the propositions used in the proofs of Theorems 4.1 and 4.2.
For the approximation error of the term $u_{0}$ we use standard finite element analysis to obtain

$$
\begin{align*}
& \left\|u_{0}-u_{0}^{h}\right\|_{1, p} \leq c h\left\|u_{0}\right\|_{2, p}, \text { for } 2 \leq p \leq \infty  \tag{4.1}\\
& \left\|u_{0}-u_{0}^{h}\right\|_{0, p} \leq c h^{2}\left\|u_{0}\right\|_{2, p}, \text { for } 2 \leq p<\infty \tag{4.2}
\end{align*}
$$

and

$$
\begin{equation*}
\left\|u_{0}-u_{0}^{h}\right\|_{0, \infty} \leq c h^{2} \ln (h)\left\|u_{0}\right\|_{2, \infty} \tag{4.3}
\end{equation*}
$$

see Corollary 7.1.2, Theorem 4.4.20 and inequality (7.5.4) from [10]. Let $\mathcal{I}^{h}$ be the usual local point-wise $\mathcal{P}_{1}$ or $\mathcal{Q}_{1}$ interpolate and $K \in \mathcal{T}_{h}(\Omega)$, then

$$
\left|u_{0}-u_{0}^{h}\right|_{2, p, K} \leq\left|u_{0}-\mathcal{I}^{h} u_{0}\right|_{2, p, K}+\left|\mathcal{I}^{h} u_{0}-u_{0}^{h}\right|_{2, p, K}
$$

Using an interpolation error estimate, see Theorem 4.4.20 [10], we obtain

$$
\begin{equation*}
\left|u_{0}-\mathcal{I}^{h} u_{0}\right|_{s, p, h} \leq c h^{m-s}\left|u_{0}\right|_{m, p, h}, \text { for } 0 \leq s \leq m, \tag{4.4}
\end{equation*}
$$

and from an inverse inequality, see Lemma 4.5.3 [10], we have

$$
\begin{equation*}
\left|\mathcal{I}^{h} u_{0}-u_{0}^{h}\right|_{2, p, K} \leq c h^{-1}\left\|\mathcal{I}^{h} u_{0}-u_{0}^{h}\right\|_{1, p, K} . \tag{4.5}
\end{equation*}
$$

Finally from (4.4), (4.5) and (4.1) we obtain

$$
\begin{equation*}
\left\|u_{0}-u_{0}^{h}\right\|_{2, p, h} \leq c\left\|u_{0}\right\|_{2, p} . \tag{4.6}
\end{equation*}
$$

In order to estimate the $L^{2}$ and the broken $H^{1}$ semi-norm of $u_{1}-u_{1}^{h}$, (see Proposition 4.2) we note that $u_{1}-u_{1}^{h}=\left(\partial_{x_{j}} u_{0}-\Psi_{j}^{h}\right) \chi^{j}$ hence by a Cauchy inequality and the Sobolev embedding Theorem we obtain $\left\|u_{1}-u_{1}^{h}\right\|_{0} \leq c\left\|\partial_{x_{j}} u_{0}-\Psi_{j}^{h}\right\|_{0, p}\left\|\chi^{j}\right\|_{0, q}$ for $1 / p+1 / q \leq 1 / 2$. Therefore we have to estimate the error between $\Psi^{h}$ and $\nabla u_{0}$ on the $L^{p}$ and on the broken $W^{1, p}$ semi-norm, (see Proposition 4.1) this is done by first estimating the error between $A \nabla u_{0} \cdot \eta$ and $\lambda^{h}$ in the trace space of $W^{1, p}(\Omega)$ over $\Gamma_{k}$ in different norms; see Lemma 4.3. Lemmas 4.1 and 4.2 are auxiliary results used for obtaining Lemma 4.3.

Consider the following spaces:
Case $2<p<\infty$ : Since $W^{1-1 / p, p}\left(\Gamma_{k}\right) \hookrightarrow C^{0}\left(\Gamma_{k}\right)$, we define the spaces
$W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)=\left\{\varphi \in W^{1-1 / p, p}\left(\Gamma_{k}\right) ; \varphi=0\right.$ on $\left.\partial \Gamma_{k}\right\}$ equipped with the norm $\|\cdot\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)}=\|\cdot\|_{W^{1-1 / p, p}\left(\Gamma_{k}\right)}$.

Case $p=2$ : We set $W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)=H_{00}^{1 / 2}\left(\Gamma_{k}\right)$ and $\|\cdot\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)}=\|\cdot\|_{H_{00}^{1 / 2}\left(\Gamma_{k}\right)} ;$ see [31] for the definition of $H_{00}^{1 / 2}\left(\Gamma_{k}\right)$.

Case $1<p<2$ : We define $W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)=W^{1-1 / p, p}\left(\Gamma_{k}\right)$ equipped with the norm $\|\cdot\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)}=\|\cdot\|_{W^{1-1 / p, p}\left(\Gamma_{k}\right)}$.

These spaces have the following important feature. Denote by $\tilde{\varphi}$ the extension by zero to $\partial \Omega \backslash \Gamma_{k}$ of a given function $\varphi \in W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)$. Then by the Trace Theorem and the Lift Theorem 1.5.2.3 from [24] there exists a function $\psi_{\varphi} \in W^{1, p}(\Omega)$ such that $\left.\psi_{\varphi}\right|_{\partial \Omega}=\tilde{\varphi}$ and

$$
\begin{equation*}
c_{1}\|\varphi\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)} \leq\left\|\psi_{\varphi}\right\|_{1, p} \leq c\|\tilde{\varphi}\|_{W^{1-\frac{1}{p}, p}(\partial \Omega)} \leq c_{2}\|\varphi\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)} . \tag{4.7}
\end{equation*}
$$

We also introduce the dual space of $W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)$, denoted by $W^{-1+1 / p, p^{\prime}}\left(\Gamma_{k}\right)$, where $1 / p+1 / p^{\prime}=1$.

The following inverse inequality is required in the proof of Lemma 4.3.
Lemma 4.1. Let $1<p<\infty$ and $v^{h} \in Y_{0, k}^{h}$. Then

$$
\begin{equation*}
\left\|v^{h}\right\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)} \leq c h^{-1}\left\|v^{h}\right\|_{W^{-1+1 / p^{\prime}, p\left(\Gamma_{k}\right)}} . \tag{4.8}
\end{equation*}
$$

Proof. Consider the following inverse inequality (see Theorem 4.5.11 [10])

$$
\begin{equation*}
\left\|v^{h}\right\|_{s, q, \partial \Omega} \leq c h^{-s}\left\|v^{h}\right\|_{0, q, \partial \Omega}, \quad \forall v^{h} \in Y^{h}, \quad 1 \leq q \leq \infty \text { and } 0 \leq s \leq 1 . \tag{4.9}
\end{equation*}
$$

Given $v^{h} \in Y_{0, k}^{h}$ let $\tilde{v}^{h} \in Y^{h}$ be the extension of $v^{h}$ to $\partial \Omega \backslash \Gamma_{k}$ by zero. Using (4.7) and (4.9) we obtain

$$
\begin{align*}
\left\|v^{h}\right\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)} & \leq c\left\|\tilde{v}^{h}\right\|_{W^{1-1 / p, p}(\partial \Omega)} \\
& \leq c h^{-1+1 / p}\left\|\tilde{v}^{h}\right\|_{L^{p}(\partial \Omega)}=c h^{-1+1 / p}\left\|v^{h}\right\|_{L^{p}\left(\Gamma_{k}\right)} . \tag{4.10}
\end{align*}
$$

Let $\mathcal{P}_{0, k}$ denote the $L^{2}$ projector to $Y_{0, k}^{h}$ and assume that $v^{h} \in Y_{0, k}^{h}$. Then

$$
\left\|v^{h}\right\|_{L^{p}\left(\Gamma_{k}\right)}=\sup _{\phi \in L^{p^{\prime}}\left(\Gamma_{k}\right)} \frac{\left\langle v^{h}, \phi\right\rangle}{\|\phi\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}}=\sup _{\phi \in L^{p^{\prime}}\left(\Gamma_{k}\right)} \frac{\left\langle v^{h}, \mathcal{P}_{0, k} \phi\right\rangle}{\|\phi\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}} .
$$

By Theorem 1 in [17] we have

$$
\begin{equation*}
\left\|\mathcal{P}_{0, k} \phi\right\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)} \leq c\|\phi\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)} 1 \leq p^{\prime} \leq \infty \tag{4.11}
\end{equation*}
$$

Hence

$$
\begin{align*}
\left\|v^{h}\right\|_{L^{p}\left(\Gamma_{k}\right)} & \leq c \sup _{\phi \in L^{p^{\prime}}\left(\Gamma_{k}\right)} \frac{\left\|v^{h}\right\|_{W^{-1+\frac{1}{p^{\prime}, p}\left(\Gamma_{k}\right)}}\left\|\mathcal{P}_{0, k} \phi\right\|_{W_{00}^{1-\frac{1}{p^{\prime}, p^{\prime}}}{ }_{\left(\Gamma_{k}\right)}}^{\left\|\mathcal{P}_{0, k} \phi\right\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}}}{} \leq c h^{-1+\frac{1}{p^{\prime}}}\left\|v^{h}\right\|_{W^{-1+\frac{1}{p^{\prime}, p}}\left(\Gamma_{k}\right)},
\end{align*}
$$

where on the last inequality we have used (4.10) for bounding $\left\|\mathcal{P}_{0, k} \phi\right\|_{W_{00}^{1-1 / p^{\prime}, p^{\prime}}\left(\Gamma_{k}\right)}$. Combining inequalities (4.10) and (4.12) we obtain (4.8).

The following lemma provide stability and error estimates concerning $\mathcal{P}_{0, k}$, the $L^{2}$ projector to $Y_{0, k}^{h}$. These results are required in the proof of Lemma 4.3.

Lemma 4.2. Let $2 \leq p<\infty$ and $\mathcal{P}_{0, k}: W^{-1+\frac{1}{p}, p^{\prime}}\left(\Gamma_{k}\right) \rightarrow Y_{0, k}^{h}$ be the $L^{2}$ projector to $Y_{0, k}^{h}$. Then we have

$$
\begin{gather*}
\left\|\mathcal{P}_{0, k} \phi\right\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)} \leq c\|\phi\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)} \quad \forall \phi \in W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right),  \tag{4.13}\\
\left\|\phi-\mathcal{P}_{0, k} \phi\right\|_{L^{p}\left(\Gamma_{k}\right)} \leq c h^{1-\frac{1}{p}}\|\phi\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)} \quad \forall \phi \in W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right),  \tag{4.14}\\
\left\|\phi-\mathcal{P}_{0, k} \phi\right\|_{W^{-1+\frac{1}{p}, p^{\prime}}\left(\Gamma_{k}\right)} \leq \operatorname{ch}^{1-\frac{1}{p}}\|\phi\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)} \quad \forall \phi \in L^{p^{\prime}}\left(\Gamma_{k}\right) \tag{4.15}
\end{gather*}
$$

and

$$
\begin{equation*}
\left\|\mathcal{P}_{0, k} \phi\right\|_{W^{-1+\frac{1}{p}, p^{\prime}}\left(\Gamma_{k}\right)} \leq c\|\phi\|_{W^{-1+\frac{1}{p}, p^{\prime}}\left(\Gamma_{k}\right)} \quad \forall \phi \in W^{-1+\frac{1}{p}, p^{\prime}}\left(\Gamma_{k}\right) . \tag{4.16}
\end{equation*}
$$

Proof of (4.13):
Case $p>2$ : Observe that $\mathcal{P}_{0, k}: L^{p}\left(\Gamma_{k}\right) \rightarrow Y_{0, k}^{h}$ is stable in $L^{p}$ and $W^{1, p}$, i.e. $\left\|\mathcal{P}_{0, k} \phi\right\|_{L^{p}\left(\Gamma_{k}\right)} \leq c\|\phi\|_{L^{p}\left(\Gamma_{k}\right)} \forall \phi \in L^{p}\left(\Gamma_{k}\right)$, and $\left\|\mathcal{P}_{0, k} \phi\right\|_{W^{1, p}\left(\Gamma_{k}\right)} \leq c\|\phi\|_{W^{1, p}\left(\Gamma_{k}\right)}$ $\forall \phi \in W^{1, p}\left(\Gamma_{k}\right)$, respectively; see Theorems 1 and 2 in [17]. Since $W^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)=$ $\left[L^{p}\left(\Gamma_{k}\right), W^{1, p}\left(\Gamma_{k}\right)\right]_{1-1 / p, p}$; see Theorem 12.2 .3 in $[10]$, we obtain the stability of $\mathcal{P}_{0, k}$ in $W^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)$ by the real interpolation method, see Proposition 12.1.5 in [10], and the inequality (4.13) follows.

Case $p=2$ : By definition $H_{00}^{1 / 2}\left(\Gamma_{k}\right)=\left[L^{2}\left(\Gamma_{k}\right), H_{0}^{1}\left(\Gamma_{k}\right)\right]_{1 / 2}$ and the proof is analogue to the case $p>2$.

Proof of (4.14):

Case $p>2$ : Let $\mathcal{I}^{h}:\left.L^{p}\left(\Gamma_{k}\right) \rightarrow V^{h}(\Omega)\right|_{\Gamma_{k}}$ denote the standard $\mathcal{P}_{1}$ or $\mathcal{Q}_{1}$ interpolation operator. Then we have

$$
\begin{align*}
\left\|\phi-\mathcal{P}_{0, k} \phi\right\|_{L^{p}\left(\Gamma_{k}\right)} & \leq\left\|\phi-\mathcal{I}^{h} \phi\right\|_{L^{p}\left(\Gamma_{k}\right)}+\left\|\mathcal{P}_{0, k}\left(\phi-\mathcal{I}^{h} \phi\right)\right\|_{L^{p}\left(\Gamma_{k}\right)} \\
& \leq c\left\|\phi-\mathcal{I}^{h} \phi\right\|_{L^{p}\left(\Gamma_{k}\right)}, \text { by }(4.11) \\
& \leq c h^{1-\frac{1}{p}}\|\phi\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)}, \text { by }(4.4) \tag{4.17}
\end{align*}
$$

Case $p=2$ : Follows similarly to the case $p>2$ by replacing $\mathcal{I}^{h}$ by the Clement interpolation operator defined by (2.13) in [40] and use the real interpolation method to obtain (4.17).

Proof of (4.15):

$$
\begin{align*}
\left\|\phi-\mathcal{P}_{0, k} \phi\right\|_{W^{-1+\frac{1}{p}, p^{\prime}}\left(\Gamma_{k}\right)} & =\sup _{v \in W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)} \frac{\left\langle\phi-\mathcal{P}_{0, k} \phi, v\right\rangle}{\|v\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)}} \\
= & \sup _{v \in W_{00}^{1-\frac{1}{p}, p}} \frac{\left\langle\phi-\mathcal{P}_{0, k} \phi, v-\mathcal{P}_{0, k} v\right\rangle}{\|v\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)}} \\
= & \sup _{v \in W_{00}^{1-\frac{1}{p}, p}} \frac{\left\langle\phi, v-\mathcal{P}_{0, k} v\right\rangle}{\|v\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)}} \\
\leq & \sup _{v \in W_{00}^{1-\frac{1}{p}, p}} \frac{\|\phi\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}\left\|v-\mathcal{P}_{0, k} v\right\|_{L^{p}\left(\Gamma_{k}\right)}}{\|v\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)}} \\
\leq & c h^{1-\frac{1}{p}}\|\phi\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}, \tag{4.18}
\end{align*}
$$

where we have used (4.14) to obtain the last inequality.
Proof of (4.16):

$$
\begin{aligned}
&\left\|\mathcal{P}_{0, k} \phi\right\|_{W^{-1+\frac{1}{p}, p^{\prime}}{ }_{\left(\Gamma_{k}\right)}} \sup _{v \in W_{00}^{1-\frac{1}{p}, p}{ }_{\left(\Gamma_{k}\right)}} \frac{\left\langle\mathcal{P}_{0, k} \phi, v\right\rangle}{\|v\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)}} \\
& \leq c \sup _{v \in W_{00}^{1-\frac{1}{p}, p}{ }_{\left(\Gamma_{k}\right)}} \frac{\left\langle\mathcal{P}_{0, k} \phi, \mathcal{P}_{0, k} v\right\rangle}{\left\|\mathcal{P}_{0, k} v\right\|_{W_{00}}^{1-\frac{1}{p}, p}{ }_{\left(\Gamma_{k}\right)}}, \text { by (4.13) } \\
& \leq c \sup _{v \in W_{00}^{1-\frac{1}{p}, p}{ }_{\left(\Gamma_{k}\right)}}^{\left\|\mathcal{P}_{0, k} v\right\|_{W_{00}}^{1-\frac{1}{p}, p}{ }_{\left(\Gamma_{k}\right)}} \leq c\|\phi\|_{W^{-1+\frac{1}{p}, p^{\prime}}\left(\Gamma_{k}\right)} .
\end{aligned}
$$

The following lemma estimate the error between $A \nabla u_{0} \cdot \eta$ and its numerical approximation $\lambda^{h}$. This lemma is used in the proof of Proposition 4.1.

Lemma 4.3. Let $\lambda^{h}$ be defined by Equation (3.1) and $\lambda=\partial_{\eta_{A}} u_{0}=A_{i j} \partial_{j} u_{0} \eta_{i}$, where $\eta_{i}$ is the ith component of the normal vector to $\Gamma_{k}$. Assume that $u_{0} \in W^{2, p}(\Omega)$. Then we have

$$
\begin{equation*}
\left\|\lambda-\lambda^{h}\right\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)} \leq c\left\|u_{0}\right\|_{2, p} \quad \text { for } \quad 2 \leq p<\infty \tag{4.19}
\end{equation*}
$$

$$
\begin{equation*}
\left\|\lambda-\lambda^{h}\right\|_{L^{p}\left(\Gamma_{k}\right)} \leq c h^{1-\frac{1}{p}}\left\|u_{0}\right\|_{2, p} \quad \text { for } \quad 2 \leq p \leq \infty \tag{4.20}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|\lambda-\lambda^{h}\right\|_{W^{-1+1 / p, p^{\prime}}\left(\Gamma_{k}\right)} \leq c h\left\|u_{0}\right\|_{2, p} \quad \text { for } \quad 2 \leq p<\infty \tag{4.21}
\end{equation*}
$$

Proof of (4.19): From Remark 2.1 if $p=2$, or from the Sobolev embedding theorem if $p>2$, we have

$$
\begin{equation*}
\|\lambda\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)} \leq c\left\|u_{0}\right\|_{2, p} \tag{4.22}
\end{equation*}
$$

In order to prove inequality (4.19) observe that

$$
\left\|\lambda-\lambda^{h}\right\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)} \leq\|\lambda\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)}+\left\|\lambda^{h}\right\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)}
$$

and

$$
\left\|\lambda^{h}\right\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)}=\sup _{\phi \in W^{-1+\frac{1}{p}, p^{\prime}}\left(\Gamma_{k}\right)} \frac{\left\langle\lambda^{h}, \phi\right\rangle}{\|\phi\|_{W^{-1+1 / p, p^{\prime}}\left(\Gamma_{k}\right)} .}
$$

Since $\lambda^{h} \in Y_{0, k}^{h}$ then $\left\langle\lambda^{h}, \phi\right\rangle=\left\langle\lambda^{h}, \mathcal{P}_{0, k} \phi\right\rangle$, and using (4.16) we obtain

$$
\begin{equation*}
\left\|\lambda^{h}\right\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)} \leq c \sup _{\phi \in W^{-1+\frac{1}{p}, p^{\prime}}\left(\Gamma_{k}\right)} \frac{\left\langle\lambda^{h}, \mathcal{P}_{0, k} \phi\right\rangle}{\left\|\mathcal{P}_{0, k} \phi\right\|_{W^{-1+\frac{1}{p}, p^{\prime}}{ }_{\left(\Gamma_{k}\right)}} . . . ~} \tag{4.23}
\end{equation*}
$$

Now we recall the discrete extension operator, $E_{h}: Y^{h} \rightarrow V^{h}(\Omega)$ defined by (5.5) in [40], which satisfies

$$
\left\|E_{h} g\right\|_{1, p^{\prime}} \leq c\|g\|_{W^{1-1 / p^{\prime}, p^{\prime}}(\partial \Omega)}
$$

for $g \in Y^{h}$. Hence if $g^{h} \in Y_{0, k}^{h}$ and $\tilde{g}^{h}$ denotes the extension of $g^{h}$ by zero to $\partial \Omega \backslash \Gamma_{k}$ it follows

$$
\begin{equation*}
\left\|E_{h} \tilde{g}^{h}\right\|_{1, p^{\prime}} \leq c\left\|g^{h}\right\|_{W_{00}^{1-1 / p^{\prime}, p^{\prime}}\left(\Gamma_{k}\right)} \tag{4.24}
\end{equation*}
$$

Let $\tilde{\mathcal{P}}_{0, k} \phi$ denote the discrete extension of $\mathcal{P}_{0, k} \phi$ to $\partial \Omega \backslash \Gamma_{k}$ by zero. From the definition of $\lambda^{h}$ and inequalities (4.24) and (4.1), we obtain

$$
\begin{aligned}
\left\langle\lambda^{h}, \mathcal{P}_{0, k} \phi\right\rangle & =\left\langle\lambda, \mathcal{P}_{0, k} \phi\right\rangle+a\left(u_{0}^{h}-u_{0}, E_{h} \tilde{\mathcal{P}}_{0, k} \phi\right) \\
& \leq\|\lambda\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)}\left\|\mathcal{P}_{0, k} \phi\right\|_{W^{-1+1 / p, p^{\prime}\left(\Gamma_{k}\right)}}+c h\left\|u_{0}\right\|_{2, p}\left\|\mathcal{P}_{0, k} \phi\right\|_{W_{00}^{1-1 / p^{\prime}, p^{\prime}}\left(\Gamma_{k}\right)} \\
& \leq c\left(\|\lambda\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)}+c\left\|u_{0}\right\|_{2, p}\right)\left\|\mathcal{P}_{0, k} \phi\right\|_{W^{-1+1 / p, p^{\prime}}\left(\Gamma_{k}\right)} .
\end{aligned}
$$

Here we used the inverse estimate (4.8) applied to $\mathcal{P}_{0, k} \phi$ to obtain (4.25) . Inequality (4.19) follows from (4.25), (4.23) and (4.22).

Proof of (4.21): We observe that

$$
\begin{align*}
& \left\|\lambda-\lambda^{h}\right\|_{W^{-1+1 / p, p^{\prime}}\left(\Gamma_{k}\right)}=\sup _{\phi \in W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)} \frac{\left\langle\lambda-\lambda^{h}, \phi\right\rangle}{\|\phi\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)}} \\
& \leq c \sup _{\phi \in W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)} \frac{\left\langle\lambda-\lambda^{h}, \phi-\mathcal{P}_{0, k} \phi\right\rangle}{\|\phi\|_{\left.W_{00}^{1-\frac{1}{p}, p}{ }^{1}{ }^{2} \Gamma_{k}\right)}}+c \sup _{\phi \in W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)} \frac{\left\langle\lambda-\lambda^{h}, \mathcal{P}_{0, k} \phi\right\rangle}{\left\|\mathcal{P}_{0, k} \phi\right\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)}} . \tag{4.26}
\end{align*}
$$

In order to estimate the second term on the right hand side of (4.26) we use the definition of $\lambda$ and $\lambda^{h}$, and the inequality (4.24) to obtain

$$
\begin{align*}
\left\langle\lambda-\lambda^{h}, \mathcal{P}_{0, k} \phi\right\rangle & =a\left(u_{0}^{h}-u_{0}, E_{h} \tilde{\mathcal{P}}_{0, k} \phi\right) \\
& \leq c h\left\|u_{0}\right\|_{2, p}\left\|\mathcal{P}_{0, k} \phi\right\|_{W_{00}^{1-1 / p^{\prime}, p^{\prime}}\left(\Gamma_{k}\right)} \\
& \leq c h\left\|u_{0}\right\|_{2, p}\left\|\mathcal{P}_{0, k} \phi\right\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)} \text { since } p>p^{\prime} \tag{4.27}
\end{align*}
$$

For estimating the first term on the right hand side of (4.26) we note that

$$
\begin{align*}
\left\|\phi-\mathcal{P}_{0, k} \phi\right\|_{W^{-1+\frac{1}{p}, p^{\prime}}\left(\Gamma_{k}\right)} & =\sup _{v \in W_{00}^{1-\frac{1}{p}, p}{ }_{\left(\Gamma_{k}\right)}} \frac{\left\langle\phi-\mathcal{P}_{0, k} \phi, v-\mathcal{P}_{0, k} v\right\rangle}{\|v\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)}} \\
& \leq \sup _{v \in W_{00}^{1-\frac{1}{p}, p}{ }_{\left(\Gamma_{k}\right)}} \frac{\left\|\phi-\mathcal{P}_{0, k} \phi\right\|_{L^{2}\left(\Gamma_{k}\right)}\left\|v-\mathcal{P}_{0, k} v\right\|_{L^{2}\left(\Gamma_{k}\right)}}{\|v\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)}} \\
& \leq c h\|\phi\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)} . \tag{4.28}
\end{align*}
$$

In the last inequality we used (4.14) and the fact that $W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right) \hookrightarrow H_{00}^{1 / 2}\left(\Gamma_{k}\right)$ for $p>2$. Hence,

$$
\begin{align*}
\left\langle\lambda-\lambda^{h}, \phi-\mathcal{P}_{0, k} \phi\right\rangle & \leq\left\|\lambda-\lambda^{h}\right\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)}\left\|\phi-\mathcal{P}_{0, k} \phi\right\|_{W^{-1+1 / p, p^{\prime}}\left(\Gamma_{k}\right)} \\
& \leq c h\left\|u_{0}\right\|_{2, p}\|\phi\|_{W_{00}^{1-1 / p, p}\left(\Gamma_{k}\right)}, \text { by }(4.19) \text { and }(4.28) \tag{4.29}
\end{align*}
$$

and the inequality (4.21) follows from (4.26), (4.27) and (4.29).
Proof of (4.20):
Case $2 \leq p<\infty$ : We have

$$
\begin{equation*}
\left\|\lambda-\lambda^{h}\right\|_{L^{p}\left(\Gamma_{k}\right)} \leq \sup _{\phi \in L^{p^{\prime}}\left(\Gamma_{k}\right)} \frac{\left\langle\lambda-\lambda^{h}, \phi-\mathcal{P}_{0, k} \phi\right\rangle}{\|\phi\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}}+\sup _{\phi \in L^{p^{\prime}}\left(\Gamma_{k}\right)} \frac{\left\langle\lambda-\lambda^{h}, \mathcal{P}_{0, k} \phi\right\rangle}{\|\phi\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}} \tag{4.30}
\end{equation*}
$$

The first term on the right hand side of (4.30) is bounded as follows:

$$
\begin{align*}
\sup _{\phi \in L^{p^{\prime}}\left(\Gamma_{k}\right)} \frac{\left\langle\lambda-\lambda^{h}, \phi-\mathcal{P}_{0, k} \phi\right\rangle}{\|\phi\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}} & \leq \sup _{\phi \in L^{p^{\prime}}\left(\Gamma_{k}\right)} \frac{\left\|\lambda-\lambda^{h}\right\|_{W_{00}^{1-\frac{1}{p}, p}\left(\Gamma_{k}\right)}\left\|\phi-\mathcal{P}_{0, k} \phi\right\|_{W^{-1+\frac{1}{p}, p^{\prime}}\left(\Gamma_{k}\right)}}{\|\phi\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}} \\
& \leq c h^{1-\frac{1}{p}}\left\|u_{0}\right\|_{2, p} . \tag{4.31}
\end{align*}
$$

Here we have used (4.15) and (4.19) to arrive in (4.31). In order to estimate the second term on the right hand side of (4.30) we use the definition of $\lambda$ and $\lambda^{h}$ to obtain

$$
\begin{aligned}
\sup _{\phi \in L^{p^{\prime}}\left(\Gamma_{k}\right)} \frac{\left\langle\lambda-\lambda^{h}, \mathcal{P}_{0, k} \phi\right\rangle}{\|\phi\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}} & \leq \sup _{\phi \in L^{p^{\prime}}\left(\Gamma_{k}\right)} \frac{\int_{Y} a_{i j} \partial_{i}\left(u_{0}-u_{0}^{h}\right) \partial_{j}\left(E_{h} \tilde{\mathcal{P}}_{0, k} \phi\right) d y}{\left\|\mathcal{P}_{0, k} \phi\right\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}} \\
& \leq c h \sup _{\phi \in L^{p^{\prime}}\left(\Gamma_{k}\right)} \frac{\left\|u_{0}\right\|_{2, p}\left\|\mathcal{P}_{0, k} \phi\right\|_{W_{00}^{1-\frac{1}{p^{\prime}, p^{\prime}}}}}{\left\|\mathcal{P}_{0, k} \phi\right\|_{L^{p^{\prime}}\left(\Gamma_{k}\right)}} \\
& \leq c h^{1-\frac{1}{p}}\left\|u_{0}\right\|_{2, p}, \text { by }(4.10) .
\end{aligned}
$$

Case $p=\infty$ : Let $z \in \Gamma_{k}$, then

$$
\begin{equation*}
\left|\lambda(z)-\lambda^{h}(z)\right| \leq\left|\lambda(z)-\mathcal{P}_{0, k} \lambda(z)\right|+\left|\lambda^{h}(z)-\mathcal{P}_{0, k} \lambda(z)\right| \tag{4.32}
\end{equation*}
$$

For the first term of (4.32), by Theorem 3.1 in [44] there exists a positive constant $c$ such that

$$
\begin{equation*}
\left|\lambda(z)-\mathcal{P}_{0, k} \lambda(z)\right| \leq c\left\|\lambda-v^{h}\right\|_{0, \infty, \Gamma_{k}}+c \exp (-c h)\left\|\lambda-v^{h}\right\|_{0,1, \Gamma_{k}}, \forall v^{h} \in Y_{0, k} \tag{4.33}
\end{equation*}
$$

The use of $\mathcal{Q}_{1}$ elements to approximate $u_{0}$ implies $\left.A \nabla u_{0}^{h} \cdot \eta_{k}\right|_{\Gamma_{k}} \in Y_{0, k}$, therefore we can take $v^{h}=A \nabla u_{0}^{h} \cdot \eta_{k}$ in (4.33) and use (4.1) to obtain

$$
\begin{equation*}
\left\|\lambda-\mathcal{P}_{0, k} \lambda\right\|_{0, \infty} \leq c h\left\|u_{0}\right\|_{2, \infty} \tag{4.34}
\end{equation*}
$$

When $\mathcal{P}_{1}$ elements are used $A \nabla u_{0}^{h} \cdot \eta_{k}$ is piecewise constant, hence $\left.A \nabla u_{0}^{h} \cdot \eta_{k}\right|_{\Gamma_{k}} \notin Y_{0, k}$. We then consider a rectangular mesh $\tilde{\mathcal{T}}^{h}(\Omega)$ such that the approximation $\tilde{u}_{0}^{h}$ using bilinear elements on $\tilde{\mathcal{T}}^{h}(\Omega)$ for $u_{0}$ satisfies $\left.A \nabla \tilde{u}_{0}^{h} \cdot \eta_{k}\right|_{\Gamma_{k}} \in Y_{0, k}$. Hence we take $v^{h}=A \nabla \tilde{u}_{0}^{h} \cdot \eta_{k}$ in (4.33) and use (4.1) to obtain (4.34).

To estimate the second term on the right hand side of (4.32) we follow ideas from [44]. Let $E_{z} \subset \Gamma_{k}$ denote an edge of an element $K_{z} \in \mathcal{T}^{h}(\Omega)$ such that $z \in E_{z}$, and define $\delta_{z}$ as the polynomial of degree 1 on $E_{z}$ such that

$$
\int_{E_{z}} \delta_{z}(s) v(s) d s=v(z), \text { for any } v \text { polynomial of degree } 1
$$

Regard $\delta_{z}$ as extended by zero to $\Gamma_{k} \backslash E_{z}$ and denote by $\tilde{\delta}_{z}^{h} \in V^{h}(\Omega)$ the extension by zero of $\mathcal{P}_{0, k} \delta_{z}$ to $\Omega$. Then we have

$$
\begin{align*}
\lambda^{h}(z)-\mathcal{P}_{0, k} \lambda(z) & =\int_{\Gamma_{k}} \mathcal{P}_{0, k}\left(\lambda^{h}-\lambda\right) \delta_{z} d s=\int_{\Gamma_{k}}\left(\lambda^{h}-\lambda\right) \mathcal{P}_{0, k} \delta_{z} d s \\
& =\int_{\Omega} A_{i j} \partial_{i}\left(u_{0}-u_{0}^{h}\right) \partial_{j}\left(\tilde{\delta}_{z}^{h}\right) d x \tag{4.35}
\end{align*}
$$

where we have used the definition of $\lambda^{h}$ to obtain (4.35). From (4.1) and (4.35) follows

$$
\left|\lambda^{h}(z)-\mathcal{P}_{0, k} \lambda(z)\right| \leq c h\left\|u_{0}\right\|_{2, \infty}\left\|\tilde{\delta}_{z}^{h}\right\|_{1,1}
$$

Using an inverse estimate followed by a Poincare inequality we have

$$
\left\|\tilde{\delta}_{z}^{h}\right\|_{1,1} \leq c h^{-1}\left\|\tilde{\delta}_{z}^{h}\right\|_{0,1} \leq c\left\|\mathcal{P}_{0, k} \delta_{z}\right\|_{0,1, \Gamma_{k}}
$$

Finally, we use the fact that $\left\|\mathcal{P}_{0, k} \delta_{z}\right\|_{0,1, \Gamma_{k}} \leq c$, see Lemma 3.5 in [44], and (4.20) follows.

Proposition 4.1 estimates the error between $\nabla u_{0}$ and its proposed numerical approximation $\Psi^{h}$. This Proposition is required in the proof of Proposition 4.2.

Proposition 4.1. Let $u_{0}$ and $\Psi^{h}$ be defined by Equations (2.4) and (3.2), respectively. Assume $u_{0} \in W^{2, p}(\Omega)$ and that linear or bilinear finite elements are used to approximate $u_{0}$. Then for $2 \leq p \leq \infty$ we have

$$
\begin{equation*}
\left\|\left(\nabla u_{0}-\Psi^{h}\right) \cdot \nu\right\|_{0, p} \leq \operatorname{ch}\left\|u_{0}\right\|_{2, p}, \quad \forall \nu \in \mathbb{R}^{2} \text { with }|\nu|=1 \tag{4.36}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|\left(\nabla u_{0}-\Psi^{h}\right) \cdot \nu\right\|_{1, p, h} \leq c\left\|u_{0}\right\|_{2, p}, \quad \forall \nu \in \mathbb{R}^{2} \text { with }|\nu|=1 \tag{4.37}
\end{equation*}
$$

Proof of (4.36): From the triangular inequality we have

$$
\begin{equation*}
\left\|\left(\nabla u_{0}-\Psi^{h}\right) \cdot \nu\right\|_{0, p} \leq\left\|\left(\nabla u_{0}-\nabla u_{0}^{h}\right) \cdot \nu\right\|_{0, p}+\left\|\left(\nabla u_{0}^{h}-\Psi^{h}\right) \cdot \nu\right\|_{0, p} . \tag{4.38}
\end{equation*}
$$

Use (4.1) to estimate the first term on the right hand side of (4.38). For the second term, by the definition of $\Psi^{h}$, we have

$$
\left\|\left(\nabla u_{0}^{h}-\Psi^{h}\right) \cdot \nu\right\|_{0, p} \leq c \sum_{k \in\{e, w, n, s\}}\left\|E_{k}^{h}\left(\mu^{h}-\nabla u_{0}^{h} \cdot \eta^{k}\right)\right\|_{0, p}
$$

Consider $k=e$ and that bilinear elements are used to approximate $u_{0}$; the other cases, $k \in\{w, n, s\}$ or when $\mathcal{P}_{1}$ elements are used, follow in a similar way. From definition, the function $E_{e}^{h}\left(\mu^{h}-\frac{\partial u_{0}^{h}}{\partial x_{1}}\right)$ is linear in the $x_{1}$ direction and equal to zero in $x_{1} \leq 1-h$, hence

$$
\left\|E_{e}^{h}\left(\mu^{h}-\nabla u_{0}^{h} \cdot \eta^{k}\right)\right\|_{0, p} \leq h^{1 / p}\left\|\partial_{x_{1}} u_{0}^{h}-\mu^{h}\right\|_{0, p, \Gamma_{e}}, \quad \text { if } 2 \leq p<\infty
$$

or

$$
\left\|E_{e}^{h}\left(\mu^{h}-\nabla u_{0}^{h} \cdot \eta^{k}\right)\right\|_{0, \infty} \leq\left\|\partial_{x_{1}} u_{0}^{h}-\mu^{h}\right\|_{0, \infty, \Gamma_{e}}, \quad \text { if } p=\infty
$$

Case $2 \leq p<\infty$ : The triangular inequality gives

$$
\begin{equation*}
\left\|\partial_{x_{1}} u_{0}^{h}-\mu^{h}\right\|_{0, p, \Gamma_{e}} \leq\left\|\partial_{x_{1}} u_{0}^{h}-\partial_{x_{1}} u_{0}\right\|_{0, p, \Gamma_{e}}+\left\|\partial_{x_{1}} u_{0}-\mu^{h}\right\|_{0, p, \Gamma_{e}} \tag{4.39}
\end{equation*}
$$

In order to estimate the first term on the right hand side of (4.39), let $K \in \mathcal{T}_{h}(\Omega)$ containing an edge $E \subset \Gamma_{k}$. Applying a Trace Theorem we have

$$
\begin{aligned}
& \left\|\partial_{x_{1}} u_{0}^{h}-\partial_{x_{1}} u_{0}\right\|_{0, p, E} \leq \\
& 0) \quad c\left(h^{-1}\left\|\partial_{x_{1}} u_{0}^{h}-\partial_{x_{1}} u_{0}\right\|_{0, p, K}^{p}+h^{p-1}\left\|\partial_{x_{1}} u_{0}^{h}-\partial_{x_{1}} u_{0}\right\|_{1, p, K}^{p}\right)^{1 / p} .
\end{aligned}
$$

From (4.1), (4.6) and (4.40) we obtain

$$
\begin{equation*}
\left\|\partial_{x_{1}} u_{0}^{h}-\partial_{x_{1}} u_{0}\right\|_{0, p, \Gamma_{e}} \leq c h^{1-1 / p}\left\|u_{0}\right\|_{2, p} \tag{4.41}
\end{equation*}
$$

For second term on the right hand side of (4.39), we apply the definition of $\lambda$ and $\lambda^{h}$ to obtain $\left\|\partial_{x_{1}} u_{0}-\mu^{h}\right\|_{0, p, \Gamma_{e}}=A_{11}\left\|\lambda-\lambda^{h}\right\|_{0, p, \Gamma_{e}}$, and therefore from (4.20) we have

$$
\begin{equation*}
\left\|\partial_{x_{1}} u_{0}-\mu^{h}\right\|_{0, p, \Gamma_{e}} \leq c h^{1-1 / p}\left\|u_{0}\right\|_{2, p} \tag{4.42}
\end{equation*}
$$

From (4.39), (4.41) and (4.42) we obtain

$$
\left\|E_{e}\left(\mu^{h}-\nabla u_{0}^{h} \cdot \eta^{e}\right)\right\|_{0, p} \leq c h\left\|u_{0}\right\|_{2, p}
$$

and hence estimate (4.36) holds for $p<\infty$.

Case $2=\infty$ : We have

$$
\left\|\partial_{x_{1}} u_{0}^{h}-\mu^{h}\right\|_{0, \infty, \Gamma_{e}} \leq\left\|\partial_{x_{1}} u_{0}^{h}-\partial_{x_{1}} u_{0}\right\|_{0, \infty, \Gamma_{e}}+\left\|\partial_{x_{1}} u_{0}-\mu^{h}\right\|_{0, \infty, \Gamma_{e}}
$$

and applying (4.20) and (4.1) we have

$$
\left\|\partial_{x_{1}} u_{0}-\mu^{h}\right\|_{0, \infty, \Gamma_{e}} \leq c h\left\|u_{0}\right\|_{2, \infty}
$$

and hence estimate (4.36) follows for $p=\infty$.
Proof of (4.37): We have

$$
\begin{align*}
\left\|\left(\nabla u_{0}^{h}-\Psi^{h}\right) \cdot \nu\right\|_{0, p} & \leq c\left\|\left(\nabla u_{0}-\Psi^{h}\right) \cdot \nu\right\|_{0, p}+\left\|\left(\nabla u_{0}-\nabla u_{0}^{h}\right) \cdot \nu\right\|_{0, p} \\
& \leq c h\left\|u_{0}\right\|_{2, p}, \quad \text { by }(4.1) \text { and }(4.36) \tag{4.43}
\end{align*}
$$

and from an inverse inequality, see Lemma 4.5.3 from [10], follows that

$$
\left\|\left(\nabla u_{0}^{h}-\Psi^{h}\right) \cdot \nu\right\|_{1, p, h} \leq c\left\|u_{0}\right\|_{2, p}
$$

Since

$$
\left\|\left(\nabla u_{0}-\Psi^{h}\right) \cdot \nu\right\|_{1, p, h} \leq c\left(\left\|\left(\nabla u_{0}^{h}-\nabla u_{0}\right) \cdot \nu\right\|_{1, p, h}+\left\|\left(\nabla u_{0}^{h}-\Psi^{h}\right) \cdot \nu\right\|_{1, p, h}\right)
$$

we obtain (4.37) from (4.6).
The following proposition estimates the error between $u_{1}$ and $u_{1}^{h}$. These estimates are required in the proof of Theorems 4.1 and 4.2.

Proposition 4.2. Let $u_{1}$ and $u_{1}^{h}$ be defined by (2.5) and (3.3), respectively. Assume that $u_{0} \in W^{2, p}(\Omega)$ and $\chi^{i} \in W_{p e r}^{1, q}(Y)$, for $1 / p+1 / q \leq 1 / 2$. Then there exists a constant $c$ independent of $\epsilon$ and $h$ such that

$$
\begin{equation*}
\left|u_{1}-u_{1}^{h}\right|_{1, h} \leq c\left\|u_{0}\right\|_{2, p}\|\chi\|_{1, q, Y}\left(\frac{h^{2}}{\epsilon^{2}}+1\right)^{1 / 2} \tag{4.44}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|u_{1}-u_{1}^{h}\right\|_{0} \leq c h\left\|u_{0}\right\|_{2, p}\|\chi\|_{1, q, Y} \tag{4.45}
\end{equation*}
$$

where $\|\chi\|_{1, q, Y}=\sum_{i}\left\|\chi^{i}\right\|_{1, q, Y}$.
Proof of (4.44): We have
(4.46) $\left|u_{1}-u_{1}^{h}\right|_{1, h}^{2} \leq$

$$
2 \sum_{K_{j} \in \mathcal{T}_{h}(\Omega)} \int_{K_{j}} \sum_{j \in 1,2}\left(\left(\partial_{x_{i}} u_{0}-\Psi_{i}^{h}\right) \partial_{x_{j}} \chi^{i}(\cdot / \epsilon)\right)^{2}+\left(\chi^{i}(\cdot / \epsilon) \cdot \partial_{x_{j}}\left(\partial_{x_{i}} u_{0}-\Psi_{i}^{h}\right)\right)^{2} d x
$$

For the first term on the right hand side of (4.46) we have

$$
\begin{array}{r}
\sum_{K_{j} \in \mathcal{T}_{h}(\Omega)} \int_{K_{j}} \sum_{j \in 1,2}\left(\left(\partial_{x_{i}} u_{0}-\Psi_{i}^{h}\right) \partial_{x_{j}} \chi^{i}(\cdot / \epsilon)\right)^{2} d x \leq\left|\partial_{x_{i}} u_{0}-\Psi_{i}^{h}\right|_{0, p}^{2}\left\|\partial_{x_{j}} \chi^{i}(\cdot / \epsilon)\right\|_{0, q}^{2} \\
\leq \epsilon^{-2}\left|\partial_{x_{i}} u_{0}-\Psi_{i}^{h}\right|_{0, p}^{2}\|\chi\|_{1, q, Y}^{2} \leq c \epsilon^{-2} h^{2}\left\|u_{0}\right\|_{2, p}^{2}\|\chi\|_{1, q, Y}^{2} \tag{4.47}
\end{array}
$$

where we have used (4.36) to obtain (4.47).

The second term on the right hand side of (4.46) is bounded by a Cauchy inequality, $\left\|\chi^{i} \partial_{j}\left(\partial_{i} u_{0}-\Psi_{i}^{h}\right)\right\|_{0}^{2} \leq\|\chi\|_{0, q}^{2}\left|\partial_{i} u_{0}-\Psi_{i}^{h}\right|_{1, p, h}^{2}$.

Proof of (4.45): It follows from a direct application of Cauchy inequality and the approximation error estimate (4.1).

The following proposition estimates the error between $\tilde{\phi}_{\epsilon}$ and $\tilde{\phi}_{\epsilon}^{h}$. This Proposition is required in the proof of Theorems 4.1 and 4.2.

Proposition 4.3. Let $\tilde{\phi}_{\epsilon}$ and $\tilde{\phi}_{\epsilon}^{h}$ be defined by (2.13) and (3.4), respectively. Assume that $u_{0} \in W^{2, p}(\Omega)$ and $v_{k} \in W^{1, q}\left(G_{k}\right)$, for $1 / p+1 / q \leq 1 / 2$. Then

$$
\begin{equation*}
\left|\tilde{\phi}_{\epsilon}-\tilde{\phi}_{\epsilon}^{h}\right|_{1, h} \leq c\left(\frac{h^{2}}{\epsilon^{2}}+1\right)^{1 / 2} \max _{k}\left\|v_{k}\right\|_{1, q, G_{k}}\left\|u_{0}\right\|_{2, p} \tag{4.48}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|\tilde{\phi}_{\epsilon}-\tilde{\phi}_{\epsilon}^{h}\right\|_{0} \leq c h \max _{k}\left\|v_{k}-\chi_{k}^{*}\right\|_{0, q, G_{k}}\left\|u_{0}\right\|_{2, p} \tag{4.49}
\end{equation*}
$$

Proof. From definition of $\tilde{\phi}_{\epsilon}$ and $\tilde{\phi}_{\epsilon}^{h}$ we have

$$
\left|\tilde{\phi}_{\epsilon}-\tilde{\phi}_{\epsilon}^{h}\right|_{1, h} \leq \sum_{k \in\{e, w, n, s\}}\left|\tilde{\phi}_{\epsilon}^{k}-\tilde{\phi}_{\epsilon}^{k, h}\right|_{1, h}
$$

and the proposition follows from arguments similar to the ones given in the proof of Proposition 4.2. [

Finally, we prove the last proposition used in the proof of Theorems 4.1 and 4.2. Proposition 4.4 estimates the error between $\bar{\phi}$ and $\bar{\phi}^{h}$.

Proposition 4.4. Let $\bar{\phi}$ be defined by Equation (2.14), $\bar{\phi}^{h}$ be the finite element approximation to the Equation (3.5), and assume that $u_{0} \in H^{2}(\Omega)$. Then we have

$$
\begin{equation*}
\left\|\bar{\phi}-\bar{\phi}^{h}\right\|_{1} \leq c\left\|u_{0}\right\|_{2} \tag{4.50}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|\bar{\phi}-\bar{\phi}^{h}\right\|_{0} \leq c h\left\|u_{0}\right\|_{2} \tag{4.51}
\end{equation*}
$$

Proof of (4.50): We note that $\chi^{*} \mu^{h} \in H^{1 / 2}(\partial \Omega)$, see Remark 3.1, hence we define $\psi \in \overline{H^{1}(\Omega) \text { as the solution of }}$

$$
\begin{equation*}
\nabla \cdot A \nabla \psi=0 \text { in } \Omega \quad \psi=\chi^{*} \mu^{h} \text { on } \partial \Omega \tag{4.52}
\end{equation*}
$$

From regularity theory and (4.19) we have

$$
\begin{equation*}
\|\psi\|_{1} \leq \sum_{k} c\left\|\chi^{*} \mu^{h}\right\|_{H_{00}^{1 / 2}\left(\Gamma_{k}\right)} \leq c\left\|u_{0}\right\|_{2} \tag{4.53}
\end{equation*}
$$

and from triangular inequality

$$
\left\|\bar{\phi}-\bar{\phi}^{h}\right\|_{1} \leq\|\bar{\phi}-\psi\|_{1}+\left\|\bar{\phi}^{h}-\psi\right\|_{1} .
$$

Since $\chi^{*} \mu^{h} \in V^{h}(\Omega)$, the problem of finding $\bar{\phi}$ reduces to a conforming finite element problem, hence standard finite element analysis and (4.53) gives

$$
\left|\bar{\phi}^{h}-\psi\right|_{1} \leq c\left\|u_{0}\right\|_{2}
$$

Finally, from regularity theory and Lemma 4.3 we obtain

$$
\begin{aligned}
|\bar{\phi}-\psi|_{1} & \leq\left\|\chi^{*} \mu^{h}-\chi^{*} \partial_{\eta} u_{0}\right\|_{H^{1 / 2}(\partial \Omega)} \\
& \leq \sum_{k}\left\|\chi^{*} \mu^{h}-\chi^{*} \partial_{\eta} u_{0}\right\|_{H_{00}^{1 / 2}\left(\Gamma_{k}\right)} \leq c\left\|u_{0}\right\|_{2}
\end{aligned}
$$

Proof of (4.51): From the triangular inequality

$$
\left\|\bar{\phi}-\bar{\phi}^{h}\right\|_{0} \leq c\|\bar{\phi}-\psi\|_{0}+\left\|\bar{\phi}^{h}-\psi\right\|_{0}
$$

and from standard finite element analysis and (4.53) we obtain

$$
\left\|\bar{\phi}^{h}-\psi\right\|_{0} \leq \operatorname{ch}\|\psi\|_{1} \leq \operatorname{ch}\left\|u_{0}\right\|_{2}
$$

Theorem 6.1 from [37] states

$$
\begin{aligned}
\|\bar{\phi}-\psi\|_{0} & \leq c\left(\sum_{k}\left\|\chi^{*} \partial_{\eta} u_{0}-\chi^{*} \mu^{h}\right\|_{H^{-1 / 2}\left(\Gamma_{k}\right)}^{2}\right)^{1 / 2} \\
& \leq c h\left\|u_{0}\right\|_{2} \quad \text { by }(4.21)
\end{aligned}
$$

5. Numerical Results. As in [26] we consider the case

$$
a(x)=\left(\frac{2+1.8 \sin \left(2 \pi x_{1} / \epsilon\right)}{2+1.8 \cos \left(2 \pi x_{2} / \epsilon\right)}+\frac{2+\sin \left(2 \pi x_{2} / \epsilon\right)}{2+1.8 \sin \left(2 \pi x_{1} / \epsilon\right)}\right) I_{2 \times 2}, \quad \text { and } \quad f(x)=-1
$$

We compare the solution obtained by our method with the solution obtained by a second order accurate finite element method on a fine mesh with size $h_{f}$, which we call $u_{\epsilon}^{*}$. Table 5.1 provide absolute errors estimates for $u_{\epsilon}^{*}-u_{\epsilon}^{h, \hat{h}, \tau}$. We have used $\tau=2, \hat{h}=1 / 128, h_{f}=1 / 2048$, and a triangular mesh with continuous piecewise linear functions to approximate $\chi_{\hat{h}}^{j}$ and $v_{k}^{\hat{h}, p}$.

> TABLE 5.1
> $u_{\epsilon}^{*}-u_{\epsilon}^{h, \tilde{h}, \tau}$ error

| $\\|\cdot\\|_{0}$ error |  |  |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\epsilon \downarrow \quad h \rightarrow$ |  |  |  |  |  |  |  |
| $1 / 8$ |  |  |  |  | $1 / 16$ | $1 / 32$ | $1 / 64$ |
| $1 / 16$ |  |  |  |  |  |  |  |$\left.| 2.7085 \mathrm{e}-04 \quad 7.7993 \mathrm{e}-05\right)$

From Table 5.1, we see that for $\epsilon \ll h$ we have errors of order $O\left(h^{2}\right)$ and $O(h)$ for the $L^{2}$ norm and $H^{1}$ semi norm, respectively. We observe that when we fix $h$ and decrease $\epsilon$ the errors almost do not change. This is evidence that in this case the dominant error term is $O(h)$. Also looking at the diagonal values in this table we see clearly that the numerical error agrees with the theoretical rates from Theorems 4.1 and 4.2.

| $\epsilon=1 / 64, h=1 / 32, h_{f}=1 / 1024$ |  |  |
| :--- | :--- | :--- |
| $u_{\epsilon}^{*}-u_{0}^{h, \hat{h}}$ | $\\|\cdot\\|_{0}$ | $\left.\cdot\right\|_{1, h}$ |
| $u_{\epsilon}^{*}-u_{0}^{h, \hat{h}}-\epsilon u_{1}^{h, \hat{h}}$ | 0.0287 | 0.0215 |
| $u_{\epsilon}^{*}-u_{0}^{h, h}-\epsilon u_{1}^{h, h}-\epsilon \bar{\phi}^{h, \hat{h}, \tau}$ | 0.0213 | 0.0026 |
| $u_{\epsilon}^{*}-u_{0}^{h, \hat{h}}-\epsilon u_{1}^{h, h}-\epsilon\left(\bar{\phi}^{h, \hat{h}, \tau}+\tilde{\phi}_{\epsilon}^{h, \hat{h}, \tau}\right)$ | $5.1865 \mathrm{e}-05$ | 0.0025 |

Table 5.2 shows the improvement obtained in the final approximation when the term $\phi_{\epsilon}^{h, \hat{h}, \tau}$ is taken into account. It can be appreciated from this table that a better improvement on the $\|\cdot\|_{0}$ norm rather than on $|\cdot|_{1, h}$ semi norm is clearly seen. The improvement on the $L^{2}$ norm is an evidence that we were able to obtain, through the proper calculation of $\chi^{*}$, the asymptotic $L^{2}$ behavior of the boundary corrector $\theta_{\epsilon}$ in the interior of the domain $\Omega$. We also note that the term $\tilde{\phi}_{\epsilon}$ primarily forces the final approximation $u_{\epsilon}^{h, \hat{h}, \tau}$ to satisfy the zero Dirichlet boundary condition, and since it has support only in a thin boundary layer of $\partial \Omega$, then no much error improvement is obtained on the $|\cdot|_{1, h}$ semi norm.

We also consider the following example:

$$
a(y)=\left\{\begin{array}{ll}
2 & \text { if } 2 / 5<y_{1}<3 / 5 \text { or } 2 / 5<y_{2}<3 / 5 \\
1 & \text { otherwise } .
\end{array} \quad \text { and } f=-1\right.
$$

TABLE 5.3
$u_{\epsilon}^{*}-u_{\epsilon}^{h, \hat{h}, \tau}$ error

| $\\|\cdot\\|_{0}$ error, $h_{f}=1 / 2000$ |  |  |  |
| :--- | :--- | :--- | :--- |
| $\epsilon \downarrow \quad h \rightarrow$ | $1 / 10$ | $1 / 20$ | $1 / 40$ |
| $1 / 20$ | $4.8318 \mathrm{e}-04$ | $1.3043 \mathrm{e}-04$ |  |
| $1 / 40$ | $4.7578 \mathrm{e}-04$ | $1.1954 \mathrm{e}-04$ | $3.0805 \mathrm{e}-05$ |
| $1 / 64$ | $2.5388 \mathrm{e}-04$ | $5.9446 \mathrm{e}-05$ | $1.4414 \mathrm{e}-05$ |

TABLE 5.4
$u_{\epsilon}^{*}-u_{\epsilon}^{h, \hat{h}, \tau}$ error

| $\|\cdot\|_{1, h}$ error, $h_{f}=1 / 2000$ |  |  |  |
| :--- | :--- | :--- | :--- |
| $\epsilon \downarrow \quad h \rightarrow$ | $1 / 10$ | $1 / 20$ | $1 / 40$ |
| $1 / 20$ | 0.0180 | 0.0092 |  |
| $1 / 40$ | 0.0179 | 0.0090 | 0.0046 |
| $1 / 64$ | 0.0086 | 0.0045 | 0.0026 |

We compare the solution obtained by our method with the solution obtained by a second order accurate finite element method in a fine mesh of size $h_{f}$, which we call $u_{\epsilon}^{*}$. Tables 5.3 and 5.4 provide absolute errors estimates for $u_{\epsilon}^{*}-u_{\epsilon}^{h, \hat{h}, \tau}$, on the $\|\cdot\|_{0}$ norm and $|\cdot|_{1, h}$ semi norm for different values of $h$ and $\epsilon$. We have used $\tau=2, \hat{h}=1 / 128$, and a triangular mesh with continuous piecewise linear functions to approximate $\chi_{\hat{h}}^{j}$ and $v_{e}^{\hat{h}, \tau}$.

Although the convergence analysis presented here are not intended for the quasi periodic case $a_{i j}(x, x / \epsilon)$ the numerical approximation presented here can be generalized for this case. This would be done by approximating matrix $a(x, x / \epsilon)$ by $\sum_{j} a^{j}(x / \epsilon) I_{K_{j}}(x)$, where $I_{K_{J}}$ is the characteristic function for $K_{j} \in \mathcal{I}_{k}(\Omega)$, and then solving a cell problem in each sub-domain $K_{j}$.

## 6. Appendix.

6.1. Proof of Theorem 2.1. By the triangular inequality we have

$$
\begin{aligned}
\left|u_{\epsilon}-u_{0}-u_{1}-\phi_{\epsilon}\right|_{1, h} \leq & \left|u_{\epsilon}-u_{0}-u_{1}-\theta_{\epsilon}\right|_{1} \\
& +\epsilon\left|\bar{\theta}_{\epsilon}-\bar{\phi}\right|_{1}+\epsilon\left|\tilde{\theta}_{\epsilon}-\tilde{\phi}_{\epsilon}\right|_{1}
\end{aligned}
$$

and the theorem follows from Propositions 6.1, 6.2 and 6.3.
We now prove the propositions used in the proof of Theorem 2.1. The following proposition gives the same error estimate of Theorem 2.2 in [3], however here we assume $u_{0} \in W^{2, p}(\Omega)$ and $\chi^{j} \in W_{p e r}^{1, q}(\Omega)$ for $1 / p+1 / q \leq 1 / 2$ while in Theorem 2.2 in [3] it is assumed $u_{0} \in W^{2, \infty}(\Omega)$ and $\chi^{j} \in H_{p e r}^{1}(\Omega)$. It also generalizes Proposition 2.1 from [34] where it is assumed $a_{i j} \in C_{p e r}^{1, \beta}(Y), u_{0} \in H^{2}(\Omega)$ and $\Omega \subset \mathbb{R}^{2}$. We note here that Theorem 1.1 from [32] gives conditions concerning the discontinuities of the functions $a_{i j}$ such that $\chi^{j} \in W_{p e r}^{1, \infty}(Y)$. Finally, we observe that in the case $a_{i j} \in C_{p e r}^{1, \beta}(Y)$ a error estimate similar to Proposition 6.1 can be obtained in the case a zero Neumann boundary condition is used to define $u_{\epsilon}$; see [35].

Proposition 6.1. Let $\Omega \subset \mathbb{R}^{d}$, $d=2,3$ be a convex domain, $u_{\epsilon}$ be the solution of Problem (1.1) and $u_{0}, u_{1}$, and $\theta_{\epsilon}$ be defined by Equations (2.4), (2.5) and (2.6), respectively. Assume $a_{i j} \in L_{p e r}^{\infty}(Y), u_{0} \in W^{2, p}(\Omega)$, and $\chi^{j} \in W_{\text {per }}^{1, q}(Y)$ for $1 / p+1 / q \leq$ $1 / 2$. Then there exists a constant $c$ independent of $u_{0}$ and $\epsilon$, such that

$$
\left\|u_{\epsilon}(\cdot)-u_{0}(\cdot)-\epsilon u_{1}(\cdot, \cdot / \epsilon)-\epsilon \theta_{\epsilon}(\cdot)\right\|_{1} \leq c \epsilon\left\|u_{0}\right\|_{2, p} .
$$

Proof. Define
(6.1) $v_{0}(x, y)=a(y) \nabla_{x} u_{0}(x)+a(y) \nabla_{y} u_{1}(x, y)=a(y)\left(\nabla_{y} y_{j}-\nabla_{y} \chi^{j}(y)\right) \frac{\partial u_{0}}{\partial x_{j}}(x)$.

From the definition of $\chi^{j}$ we have

$$
\int_{Y}\left(a(y)\left(e_{j}-\nabla_{y} \chi^{j}(y)\right)-A e_{j}\right) \nabla_{y} \phi(y) d y=0, \quad \forall \phi \in H_{p e r}^{1}(Y)
$$

Since the vector $a(y)\left(e_{j}-\nabla_{y} \chi^{j}(y)\right)-A e_{j}$ is $Y$ periodic and has zero average entries over $Y$, by Lemma 6.1 there exists $\phi_{j}(y) \in H_{p e r}^{1}(Y)$ with zero average over $Y$ such that

$$
\begin{equation*}
a(y)\left(\nabla_{y} y_{j}-\nabla_{y} \chi^{j}(y)\right)-A e_{j}=-\operatorname{curl}_{y} \phi_{j}(y) \tag{6.2}
\end{equation*}
$$

Let

$$
\begin{equation*}
\phi=\phi_{j}(y) \frac{\partial u_{0}}{\partial x_{j}}(x) \tag{6.3}
\end{equation*}
$$

and define

$$
\begin{aligned}
v_{1}(x, y) & =-\operatorname{curl}_{x} \phi(x, y) \\
& =\binom{-\phi_{j}(y) \frac{\partial^{2} u_{0}}{\partial x_{2} \partial x_{j}}(x)}{\phi_{j}(y) \frac{\partial^{2} u_{0}}{\partial x_{1} \partial x_{j}}(x)} .
\end{aligned}
$$

In the case $d=2$ we have $\left|\operatorname{curl}_{y} \phi_{j}\right|_{0, q}=\left|\phi_{j}\right|_{1, q}$. Since $\chi^{j} \in W_{p e r}^{1, q}(Y)$ and $\phi_{j}$ has zero average over $Y$, we apply a Poincare inequality to obtain

$$
\left\|\phi_{j}\right\|_{1, q, Y} \leq c\left|\operatorname{curl}_{y} \phi_{j}\right|_{0, q, Y} \leq c\left(\left\|\chi^{1}\right\|_{1, q, Y}+\left\|\chi^{2}\right\|_{1, q, Y}\right)
$$

In the case $d=3$ by the Remark 3.11 in [25] we also obtain that $\phi_{j} \in W_{p e r}^{1, q}(Y)^{3}$ if $\chi^{j} \in W_{p e r}^{1, q}(Y)$. From hypothesis $u_{0} \in W^{2, p}(\Omega)$ for $1 / p+1 / q \leq 1 / 2$, hence $v_{1}(x, x / \epsilon) \in$ $L^{2}(\Omega)$ and $\left\|v_{1}\right\|_{0} \leq c\left(\left\|\chi^{1}\right\|_{1, q, Y}+\left\|\chi^{2}\right\|_{1, q, Y}\right)\left\|u_{0}\right\|_{2, p}$. Moreover, by Lemma 6.1,

$$
\begin{equation*}
\nabla_{x} \cdot v_{1}(x, y)=0 \tag{6.4}
\end{equation*}
$$

and simple calculations give

$$
\begin{align*}
\nabla_{y} \cdot v_{1}(x, y) & =\nabla_{y} \cdot \operatorname{curl}_{x}\left(\phi_{j}(y) \partial_{x_{j}} u_{0}(x)\right) \\
& =-\nabla_{x} \cdot \operatorname{curl}_{y}\left(\phi_{j}(y) \partial_{x_{j}} u_{0}(x)\right) \\
& =-\nabla_{x} \cdot v_{0}(x, y)-f . \tag{6.5}
\end{align*}
$$

Let

$$
z_{\epsilon}(x)=u_{\epsilon}(x)-u_{0}(x)-\epsilon u_{1}(x, x / \epsilon)
$$

and

$$
\eta_{\epsilon}(x)=a(x / \epsilon) \nabla u_{\epsilon}(x)-v_{0}(x, x / \epsilon)-\epsilon v_{1}(x, x / \epsilon)
$$

Then

$$
\begin{aligned}
& a(x / \epsilon) \nabla z_{\epsilon}(x)-\eta_{\epsilon}(x) \\
& \quad=a(x / \epsilon) \nabla u_{\epsilon}(x)-a(x / \epsilon) \nabla_{x} u_{0}(x)-\epsilon a(x / \epsilon) \nabla_{x} u_{1}(x, x / \epsilon) \\
& \quad-a(x / \epsilon) \nabla_{y} u_{1}(x, x / \epsilon)-a(x / \epsilon) \nabla u_{\epsilon}(x)+v_{0}(x, x / \epsilon)+\epsilon v_{1}(x, x / \epsilon) \\
& \quad=\epsilon\left(v_{1}(x, x / \epsilon)-a(x / \epsilon) \nabla_{x} u_{1}(x, x / \epsilon)\right)
\end{aligned}
$$

and so

$$
\begin{equation*}
\left\|a(\cdot / \epsilon) \nabla z_{\epsilon}-\eta_{\epsilon}\right\|_{0} \leq \epsilon\left\|v_{1}(\cdot, \cdot / \epsilon)-a(\cdot / \epsilon) \nabla_{x} u_{1}(\cdot, \cdot / \epsilon)\right\|_{0} \tag{6.6}
\end{equation*}
$$

Given $g \in L^{2}(\Omega)$, let $w_{\epsilon} \in H_{0}^{1}(\Omega)$ be the solution of

$$
\begin{equation*}
\int_{\Omega} a(x / \epsilon) \nabla w_{\epsilon}(x) \nabla \psi(x) d x=\int_{\Omega} g(x) \psi(x) d x, \quad \forall \psi \in H_{0}^{1}(\Omega) \tag{6.7}
\end{equation*}
$$

hence

$$
\begin{align*}
\int_{\Omega} g\left(z_{\epsilon}-\epsilon \theta_{\epsilon}\right) d x & =\int_{\Omega} a(\cdot / \epsilon) \nabla w_{\epsilon} \cdot \nabla\left(z_{\epsilon}-\epsilon \theta_{\epsilon}\right) d x \\
& =\int_{\Omega} a(\cdot / \epsilon) \nabla w_{\epsilon} \cdot \nabla z_{\epsilon} d x-\epsilon \int_{\Omega} a(\cdot / \epsilon) \nabla w_{\epsilon} \cdot \nabla \theta_{\epsilon} d x \\
& =\int_{\Omega} a(\cdot / \epsilon) \nabla w_{\epsilon} \cdot \nabla z_{\epsilon} d x \tag{6.8}
\end{align*}
$$

Now observe that

$$
\begin{equation*}
\int_{\Omega} a(\cdot / \epsilon) \nabla w_{\epsilon} \cdot \nabla z_{\epsilon} d x=\int_{\Omega} a(\cdot / \epsilon) \nabla w_{\epsilon} \cdot\left(\nabla z_{\epsilon}-\eta_{\epsilon}\right) d x+\int_{\Omega} \eta_{\epsilon} \cdot \nabla w_{\epsilon} d x \tag{6.9}
\end{equation*}
$$

In order to estimate the second term on the right hand side of (6.9) we apply the definition of $\eta_{\epsilon}$ to obtain

$$
\begin{align*}
\int_{\Omega} \eta_{\epsilon} \cdot \nabla w_{\epsilon} d x & =\int_{\Omega}\left(a(x / \epsilon) \nabla u_{\epsilon}(x)-v_{0}(x, x / \epsilon)-\epsilon v_{1}(x, x / \epsilon)\right) \cdot \nabla w_{\epsilon}(x) d x \\
& =\int_{\Omega} f w_{\epsilon} d x-\int_{\Omega}\left(v_{0}(x, x / \epsilon)-\epsilon v_{1}(x, x / \epsilon)\right) \cdot \nabla w_{\epsilon}(x) d x \tag{6.10}
\end{align*}
$$

We note that

$$
\begin{align*}
\int_{\Omega} v_{1}(x, x / \epsilon) \cdot \nabla w_{\epsilon}(x) d x & =\int_{\Omega} \nabla \cdot v_{1}(x, x / \epsilon) w_{\epsilon}(x) d x \\
& =\left.\int_{\Omega}\left(\nabla_{x}+1 / \epsilon \nabla_{y}\right) \cdot v_{1}(x, y)\right|_{(y=x / \epsilon)} w_{\epsilon}(x) d x \\
& =-\frac{1}{\epsilon} \int_{\Omega}\left(\nabla_{x} \cdot v_{0}+f\right) w_{\epsilon} d x \tag{6.11}
\end{align*}
$$

where we have used (6.4) and (6.5) to obtain (6.11). Using the definition of $v_{0}$ we have

$$
\int_{\Omega} v_{0}(x, x / \epsilon) \cdot \nabla w_{\epsilon}(x) d x=\int_{\Omega} a(x / \epsilon)\left(e_{j}-\nabla_{y} \chi^{j}(x / \epsilon)\right) \frac{\partial u_{0}}{\partial x_{j}}(x) \cdot \nabla w_{\epsilon}(x) d x
$$

and by the chain rule we obtain

$$
\begin{aligned}
(6.12) \int_{\Omega} v_{0}(x, x / \epsilon) \cdot \nabla w_{\epsilon} d x= & \int_{\Omega} a(x / \epsilon)\left(e_{j}-\nabla_{y} \chi^{j}(x / \epsilon)\right) \cdot \nabla\left(\frac{\partial u_{0}}{\partial x_{j}} w_{\epsilon}(x)\right) d x \\
& -\int_{\Omega} a(x / \epsilon)\left(e_{j}-\nabla_{y} \chi^{j}(x / \epsilon)\right) \cdot\left(w_{\epsilon} \nabla \frac{\partial u_{0}}{\partial x_{j}}(x)\right) d x
\end{aligned}
$$

In this paragraph we evaluate the first term on the right hand side of (6.12). Let $\left(\frac{\epsilon}{3} Y_{i}\right)_{i=1, \ldots, i_{m}}$ be a finite set of translated cells of $\frac{\epsilon}{3} Y$, recovering $\bar{\Omega}$, and consider a partition of unity $\rho_{i}$, such that $\operatorname{supp} \rho_{i} \subset \frac{2 \epsilon}{3} Y_{i}$, where $\frac{2 \epsilon}{3} Y_{i}$ denotes the cell $\frac{2 \epsilon}{3} Y$ centered in $\frac{\epsilon}{3} Y_{i}$. We note that

$$
\begin{equation*}
\operatorname{supp}\left(\rho_{i} w_{\epsilon}\right) \subset \frac{2 \epsilon}{3} Y_{i} \cap \bar{\Omega} \subset \epsilon Y_{i} \tag{6.13}
\end{equation*}
$$

hence

$$
\begin{align*}
& \int_{\Omega} a(x / \epsilon)\left(e_{j}-\nabla_{y} \chi^{j}(x / \epsilon)\right) \cdot \nabla\left(\frac{\partial u_{0}}{\partial x_{j}} w_{\epsilon}(x)\right) d x= \\
& \sum_{i=1: i_{m}} \int_{\epsilon Y_{i}} a(x / \epsilon)\left(e_{j}-\nabla_{y} \chi^{j}(x / \epsilon)\right) \cdot \nabla\left(\rho_{i} \frac{\partial u_{0}}{\partial x_{j}} w_{\epsilon}(x)\right) d x=0 . \tag{6.14}
\end{align*}
$$

Here to obtain (6.14) we first note that $u_{0}$ has a stable extension to $W^{2, p}\left(\mathbb{R}^{2}\right)$, which we also denote $u_{0}$ applying (6.13) we obtain that the function $\rho_{i} \partial_{x_{j}} u_{0} w_{\epsilon}$ is defined
uniquely as zero outside of $\Omega$ and since $1 / p+1 / q \leq 1 / 2$ we obtain $\rho_{i} \partial_{x_{j}} u_{0} w_{\epsilon} \in$ $W^{1, q^{\prime}}\left(\mathbb{R}^{2}\right)$ for $1 / q^{\prime}=1-1 / q$. We then observe that $\chi^{j} \in W_{p e r}^{1, q}(Y), H_{p e r}^{1}(Y) \hookrightarrow$ $W_{p e r}^{1, q^{\prime}}(Y)$ and (2.2) implies

$$
\int_{Y} a_{i j}(y) \partial_{y_{l}}\left(\chi^{j}-y_{j}\right) \partial_{y_{m}} \psi=0, \quad \forall \psi \in W_{p e r}^{1, q^{\prime}}(Y)
$$

Finally, since $\rho_{i} \partial_{x_{j}} u_{0} w_{\epsilon}$ has a compact support contained in the interior of $\epsilon Y_{i}$, see (6.13), then $\rho_{i} \partial_{x_{j}} u_{0} w_{\epsilon} \in W_{p e r}^{1, q^{\prime}}\left(\epsilon Y_{i}\right)$ and (6.14) follows.

For the second term on the right hand side of equation (6.12), we use the definition of $v_{0}$ and it follows that

$$
-\int_{\Omega} a(x / \epsilon)\left(e_{j}-\nabla_{y} \chi^{j}(x / \epsilon)\right) \cdot\left(w_{\epsilon} \nabla \frac{\partial u_{0}}{\partial x_{j}}(x)\right) d x=-\int_{\Omega} \nabla_{x} \cdot v_{0}(x, x / \epsilon) w_{\epsilon}(x) d x
$$

Hence

$$
\begin{equation*}
\int_{\Omega} v_{0}(x, x / \epsilon) \cdot \nabla w_{\epsilon}(x) d x=-\int_{\Omega} \nabla_{x} \cdot v_{0}(x, x / \epsilon) w_{\epsilon}(x) d x \tag{6.15}
\end{equation*}
$$

From Equations (6.10), (6.11) and (6.15) we obtain

$$
\int_{\Omega} \eta_{\epsilon} \cdot \nabla w_{\epsilon} d x=0
$$

and from (6.9)

$$
\begin{equation*}
\left.\int_{\Omega} a(\cdot / \epsilon) \nabla w_{\epsilon} \cdot \nabla z_{\epsilon} d x=\int_{\Omega} a(\cdot / \epsilon)\left(\nabla z_{\epsilon}-\eta_{\epsilon}\right) \cdot \nabla w_{\epsilon}\right) d x \tag{6.16}
\end{equation*}
$$

From Equations (6.8) and (6.16) we have

$$
\begin{aligned}
\left|\int_{\Omega} g\left(z_{\epsilon}-\epsilon \theta_{\epsilon}\right) d x\right| & \leq c\left\|a(\cdot / \epsilon) \nabla z_{\epsilon}-\eta_{\epsilon}\right\|_{0}\left\|w_{\epsilon}\right\|_{1} \\
& \leq \epsilon\left\|v_{1}(\cdot, \cdot / \epsilon)-a(\cdot / \epsilon) \nabla_{x} u_{1}(\cdot, \cdot / \epsilon)\right\|_{0}\|g\|_{-1} \quad \text { by } \quad(6.6)
\end{aligned}
$$

Dividing by $\|g\|_{-1}$ and taking the supremum for $g \neq 0$ we get

$$
\begin{aligned}
\left\|z_{\epsilon}(x)-\epsilon \theta_{\epsilon}\right\|_{1} & \leq c \epsilon\left\|v_{1}(\cdot, \cdot / \epsilon)-a(\cdot / \epsilon) \nabla_{x} u_{1}(\cdot, \cdot / \epsilon)\right\|_{0} \\
& \leq c \epsilon\left(\left\|\chi^{1}\right\|_{1, q, Y}+\left\|\chi^{2}\right\|_{1, q, Y}\right)\left\|u_{0}\right\|_{2, p}
\end{aligned}
$$

The following remark is used in the proof of Proposition 6.5.
Remark 6.1. Let $f \in H^{-1}(\Omega), g \in H^{1 / 2}(\partial \Omega)$ and define $u_{\epsilon} \in H^{1}(\Omega)$ as the weak solution of the following problem

$$
L_{\epsilon} u_{\epsilon}=f \quad \text { in } \Omega, \quad u_{\epsilon}=g \quad \text { on } \partial \Omega
$$

It is easy to see that Proposition 6.1 extends immediately to this case if $u_{0}$, defined as the solution of

$$
-\nabla \cdot A \nabla u_{0}=f \quad \text { in } \Omega, \quad u_{0}=g \quad \text { on } \quad \partial \Omega
$$

belongs to $W^{2, p}(\Omega)$.
The following corollary follows from Proposition 6.1 and is used in the proof of Proposition 6.5.

Corollary 6.1. Let $\Omega \subset \mathbb{R}^{d}$, $d=2,3$, be a convex domain, $u_{\epsilon}$ and $u_{0}$ be defined by Equations (1.1) and (2.4), respectively. Assume $a_{i j} \in L_{p e r}^{\infty}(Y), u_{0} \in W^{m, p}(\Omega)$ and $\chi^{j} \in W_{\text {per }}^{1, q}(Y)$ for $(m-1) p>2$ and $1 / p+1 / q \leq 1 / 2$. Then there exists a constant $c$ independent of $u_{0}$ and $\epsilon$ such that

$$
\left\|u_{\epsilon}-u_{0}\right\|_{0} \leq c \epsilon\left\|u_{0}\right\|_{m, p}
$$

Proof. The hypothesis $u_{0} \in W^{m, p}(\Omega),(m-1) p>d$ implies $\partial_{x_{i}} u_{0} \in C(\Omega)$, and $\chi^{j} \in C(Y)$ see Remark 2.1, therefore $\left\|u_{1}\right\|_{0} \leq c\left\|u_{0}\right\|_{m, p}$. From the maximum principle $\left\|\theta_{\epsilon}\right\|_{0, \infty} \leq\left\|\partial_{x_{i}} u_{0}\right\|_{0, \infty, \partial \Omega}\left\|\chi^{i}\right\|_{0, \infty, \partial \Omega}$, and hence the corollary follows from Proposition 6.1. $\square$

The following proposition estimates the $H^{1}$ norm of $\tilde{\theta}_{\epsilon}-\tilde{\phi}_{\epsilon}$, and is used in the proof of Theorem 6.1.

Proposition 6.2. Let $u_{0}, \tilde{\theta}_{\epsilon}$ and $\tilde{\phi}_{\epsilon}$ be defined by Equations (2.4), (2.9) and (2.13), respectively, and the functions $v_{k}$ be defined as in Subsection 2.2.1. Assume $u_{0} \in W^{2, p}(\Omega)$, and $v_{e}$ and $\nabla\left(v_{e}-\chi_{e}^{*}\right) \exp \left(-\gamma y_{1}\right) \in L^{s}\left(G_{e}\right)$ for $s \geq 2$ and $1 / s+3 / p \leq 1$. We also assume similar hypothesis for the other functions $v_{k}$. Then there exists positive constants $0<\delta(p, s) \leq 1 / 2$, and $c(\delta, \gamma)$ independent of $\epsilon$ such that

$$
\begin{aligned}
\left\|\tilde{\theta}_{\epsilon}-\tilde{\phi}_{\epsilon}\right\|_{1} \leq & c(\delta, \gamma) \epsilon^{\delta}\|a\|_{0, \infty}\left\|u_{0}\right\|_{2, p} \max _{k}\left(\left\|\nabla\left(v_{k}-\chi_{k}^{*}\right) \exp \left(-\gamma y \cdot \eta^{k}\right)\right\|_{0, s, G_{k}}\right. \\
& \left.+\left\|v_{k}-\chi_{k}^{*}\right\|_{1, s, G_{k}}\right)
\end{aligned}
$$

In addition, when $p, s \rightarrow \infty$ then $\delta \rightarrow 1 / 2$ with $c(\delta, \gamma)$ bounded independent of $\delta$.
Proof. By definition

$$
\left\|\tilde{\theta}_{\epsilon}-\tilde{\phi}_{\epsilon}\right\|_{1} \leq \sum_{k \in\{e, w, n, s\}}\left\|\tilde{\theta}_{\epsilon}^{k}-\tilde{\phi}_{\epsilon}^{k}\right\|_{1}
$$

Consider the case $k=e$, the other cases are treated in a similar way. We denote $v_{e}^{\epsilon}(x)=v_{e}\left(\frac{x_{1}-1}{\tilde{\omega}^{\epsilon}}, \frac{x_{2}}{\epsilon}\right)$ and $a^{\epsilon}(x)=a(x / \epsilon)$, and let $g \in H_{0}^{1}(\Omega)$. Then applying the definition of $\phi_{\epsilon}^{e}$ we obtain

$$
\begin{aligned}
& \int_{\Omega} a^{\epsilon} \nabla\left(\tilde{\theta}_{\epsilon}^{e}-\tilde{\phi}_{\epsilon}^{e}\right) \nabla g d x=\int_{\Omega}-a^{\epsilon} \nabla\left(\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right) \varphi_{e} \frac{\partial u_{0}}{\partial x_{1}}\right) \nabla g d x \\
& (6.17)=-\int_{\Omega}\left(\varphi_{e} \frac{\partial u_{0}}{\partial x_{1}} a^{\epsilon} \nabla\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right)\right) \nabla g d x-\int_{\Omega}\left(\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right) a^{\epsilon} \nabla\left(\varphi_{e} \frac{\partial u_{0}}{\partial x_{1}}\right)\right) \nabla g d x
\end{aligned}
$$

We note that due to the Sobolev embedding Theorem 5.4 from [1], the integrals above are well defined. For the first term on the right hand side of Equation (6.17) we have

$$
\begin{align*}
& \int_{\Omega}\left(\varphi_{e} \frac{\partial u_{0}}{\partial x_{1}} a^{\epsilon} \nabla\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right)\right) \nabla g d x= \\
& \quad \int_{\Omega} a^{\epsilon} \nabla\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right) \nabla\left(\varphi_{e} \frac{\partial u_{0}}{\partial x_{1}} g\right) d x-\int_{\Omega} a^{\epsilon} \nabla\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right) \cdot g \nabla\left(\varphi_{e} \frac{\partial u_{0}}{\partial x_{1}}\right) d x \tag{6.18}
\end{align*}
$$

We now estimate the first term of the right hand side of (6.18). Let $I_{i}=\{(i-$ 1) $\left.\epsilon / 6-\epsilon / 6<x_{2}<i \epsilon / 6+\epsilon / 6,\right\}, i_{m}=1+\sup _{i \in \mathbb{N}}(i 3 / \epsilon<1)$, and consider a partition of unity $\rho_{i}$ of $\Omega$, subject to $(0,1) \times I_{i}$. Let $I_{i}^{\epsilon}$ be the interval centered in $I_{i}$ with $\left|I_{i}^{\epsilon}\right|=\epsilon$. Since $\operatorname{supp}\left(\rho_{i} g\right) \subset[0,1] \times I_{i}^{\epsilon}$ we have

$$
\begin{align*}
& \int_{\Omega} a^{\epsilon} \nabla\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right) \nabla\left(\varphi_{e} \frac{\partial u_{0}}{\partial x_{1}} g\right) d x=  \tag{6.19}\\
& \sum_{i=0: i_{m}} \int_{0}^{1} \int_{I_{i}^{\epsilon}} a^{\epsilon} \nabla\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right) \nabla\left(\rho_{i} \varphi_{e} \frac{\partial u_{0}}{\partial x_{1}} g\right) d x_{2} d x_{1}=0
\end{align*}
$$

where to arrive in (6.19) we have used the definition of $v_{e}$ and arguments similar to the ones used to obtain (6.14).

For the second term on the right hand side of Equation (6.18), we apply a Cauchy inequality to obtain

$$
\begin{align*}
& \left|\int_{\Omega} a^{\epsilon} \nabla\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right) \cdot \nabla\left(\varphi_{e} \frac{\partial u_{0}}{\partial x_{1}}\right) g d x\right| \leq  \tag{6.20}\\
& \|a\|_{\infty}\left|\varphi_{e} \nabla u_{0}\right|_{1, p}\left\|\nabla v_{e}^{\epsilon} \exp \left(-\gamma \frac{x_{1}-1}{\epsilon}\right)\right\|_{0, s}\left(\frac{\epsilon}{\gamma}\right)^{1 / l}\left\|(\gamma / \epsilon)^{1 / l} \exp \left(\gamma \frac{x_{1}-1}{\epsilon}\right) g\right\|_{0, l},
\end{align*}
$$

where $1 / l=1-1 / p-1 / s$. Taking $y_{1}=\left(x_{1}-1\right) / \epsilon$ and $y_{2}=x_{2} / \epsilon$, and exploring the [0,1]-periodicity of $v_{e}\left(y_{1}, \cdot\right)$ we have

$$
\begin{align*}
\left\|\nabla\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right) \exp \left(-\gamma \frac{x_{1}-1}{\epsilon}\right)\right\|_{0, s}^{s} & \leq\left(\frac{1}{\epsilon}+1\right) \int_{-1 / \epsilon}^{0} \int_{0}^{1}\left|\nabla_{y} v_{e} \exp \left(-\gamma y_{1}\right)\right|^{s} \epsilon^{2-s} d y_{2} d y_{1} \\
& \leq c \epsilon^{(1-s)}\left\|\nabla_{y} v_{e} \exp \left(-\gamma y_{1}\right)\right\|_{0, s, G_{e}}^{s} \tag{6.21}
\end{align*}
$$

Let $g_{n} \in C_{0}^{\infty}(\Omega), g_{n} \rightarrow g$ in $H^{1}$ and $I_{n}=(0,1) \cap\left|g_{n}\right|>0$, then integrating by parts in $x_{1}$

$$
\begin{align*}
\left\|(\gamma / \epsilon)^{1 / l} \exp \left(\gamma \frac{x_{1}-1}{\epsilon}\right) g_{n}\right\|_{0, l} & =\left(\int_{0}^{1} \int_{I_{n}} \frac{\gamma}{\epsilon} \exp \left(l \gamma \frac{x_{1}-1}{\epsilon}\right)\left|g_{n}\right|^{l} d x_{1} d x_{2}\right)^{1 / l} \\
& =\left(-\int_{0}^{1} \int_{I_{n}} \frac{1}{l} \exp \left(l \gamma \frac{x_{1}-1}{\epsilon}\right) \frac{\partial\left|g_{n}\right|^{l}}{\partial x_{1}} d x_{1} d x_{2}\right)^{1 / l}  \tag{6.22}\\
6.23) & \leq c\left(\left\|\exp \left(l \gamma \frac{x_{1}-1}{\epsilon}\right)\right\|_{0, r^{\prime}}\left\|g_{n}\right\|_{0, s^{\prime}(l-1)}^{l-1}\left\|\frac{\partial g_{n}}{\partial x_{1}}\right\|_{0}\right)^{1 / l}  \tag{6.23}\\
6.24) & \leq c(\Omega)\left(s^{\prime}(l-1)\right)^{(l-1) / l}\left(\frac{\epsilon}{r^{\prime} l \gamma}\right)^{1 /\left(r^{\prime} l\right)}\left|g_{n}\right|_{1}^{2} . \tag{6.24}
\end{align*}
$$

To obtain (6.23) we have used a Cauchy inequality with $1 / r^{\prime}+1 / s^{\prime}=1 / 2$. In order to obtain (6.24), we note that the last inequality in the proof of Lemma 5.10 in [1] states

$$
\begin{aligned}
\left\|g_{n}\right\|_{0, s^{\prime}(l-1)} & \leq 2^{(t-1) / t}\left(\frac{2 t-t}{2-t}\right)\left\|g_{n}\right\|_{1, t}, \text { for } 2 t /(2-t)=s^{\prime}(l-1), 1 \leq t<2 \\
& \leq 2^{(t-1) / t}\left(\frac{2 t-t}{2-t}\right) \operatorname{vol}(\Omega)^{(1 / t-1 / 2)}\left\|g_{n}\right\|_{1}, \text { by Theorem } 2.8 \text { in }[1] \\
& \leq c(\Omega)\left(\frac{2 t-t}{2-t}\right)\left|g_{n}\right|_{1}, \text { by a Poincare inequality. }
\end{aligned}
$$

Hence (6.24) follows from (6.23). Taking the limit $n \rightarrow \infty$ we obtain inequality (6.24) for $g$.

Since $1 / s+3 / p<1$, there exists $r^{\prime}>2$ such that $1 / l r^{\prime}+1 / l+1 / s-1>0$, and hence from $(6.18),(6.19),(6.20),(6.21)$, and (6.24) it follows

$$
\begin{align*}
\int_{\Omega} \varphi_{e} \frac{\partial u_{0}}{\partial x_{1}} a^{\epsilon} \nabla\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right) \nabla g d x \leq & c(\Omega, \gamma)\left(s^{\prime}(l-1)\right)^{(l-1) / l} \epsilon^{\delta^{\prime}}\|a\|_{\infty}\left|\varphi_{e} \nabla u_{0}\right|_{1, p} \\
& \left\|\nabla\left(v_{e}-\chi_{e}^{*}\right) \exp \left(-\gamma y_{1}\right)\right\|_{0, s, G_{e}}|g|_{1} \tag{6.25}
\end{align*}
$$

where $\delta^{\prime}=1 / l r^{\prime}+1 / l+1 / s-1$.
For estimating the second term on the right hand side of (6.17), we apply a Cauchy inequality with $1 / r+1 / p=1 / 2$ to obtain

$$
\begin{align*}
\left|\int_{\Omega}\left(v_{e}^{\epsilon}-\chi_{e}^{*}\right) a^{\epsilon} \nabla\left(\varphi_{e} \frac{\partial u_{0}}{\partial x_{1}}\right) \cdot \nabla g d x\right| & \leq\|a\|_{0, \infty}\left|\varphi_{e} \frac{\partial u_{0}}{\partial x_{1}}\right|_{1, p}\left(\epsilon \int_{G_{e}}\left(v_{e}-\chi_{e}^{*}\right)^{r} d y\right)^{1 / r}|g|_{1} \\
& \leq c(r) \epsilon^{1 / r}\|a\|_{0, \infty}\left|\varphi_{e} \frac{\partial u_{0}}{\partial x_{1}}\right|_{1, p}\left\|v_{e}^{\epsilon}-\chi_{e}^{*}\right\|_{1, G_{e}}|g|_{1} \tag{6.26}
\end{align*}
$$

where we have used the Sobolev embedding Theorem 5.4 in [1] to obtain the last inequality.

Taking $g=\tilde{\theta}_{\epsilon}^{e}-\tilde{\phi}_{\epsilon}^{e}$ and using the ellipticity of $a$

$$
\begin{aligned}
\left|\tilde{\theta}_{\epsilon}^{e}-\tilde{\phi}_{\epsilon}^{e}\right|_{H_{0}^{1}(\Omega)}^{2} \leq & \gamma_{a}^{-1} \int_{\Omega}\left(a^{\epsilon} \nabla\left(\tilde{\theta}_{\epsilon}^{e}-\tilde{\phi}_{\epsilon}^{e}\right)\right) \cdot \nabla\left(\tilde{\theta}_{\epsilon}^{e}-\tilde{\phi}_{\epsilon}^{e}\right) d x \\
\leq & \frac{c(r)}{\gamma_{a}} \epsilon^{\delta}\|a\|_{0, \infty}\left|\varphi_{e} \nabla u_{0}\right|_{1, p}\left(\left\|\nabla\left(v_{e}-\chi_{e}^{*}\right) \exp \left(-\gamma y_{1}\right)\right\|_{0, s, G_{e}}\right. \\
& \left.+\left\|\nabla\left(v_{e}-\chi_{e}^{*}\right)\right\|_{1, G_{e}}\right)\left|\tilde{\theta}_{\epsilon}^{e}-\tilde{\phi}_{\epsilon}^{e}\right|_{H_{0}^{1}(\Omega)}
\end{aligned}
$$

where $\delta=\min \left\{\delta^{\prime}, 1 / r\right\}$.
Observe that $s, p \rightarrow \infty$ implies $l \rightarrow 1$. Choosing $s^{\prime}=1 /(l-1)$ in Inequality (6.24) we have that $\left(s^{\prime}(l-1)\right)^{(l-1) / l}\left(\epsilon /\left(r^{\prime} l \gamma\right)\right)^{1 /\left(r^{\prime} l\right)} \rightarrow \epsilon^{1 / 2} /(2 \gamma)$. In inequality $(6.26) p \rightarrow \infty$ implies $1 / r \rightarrow 1 / 2$ and $c(r) \epsilon^{1 / r} \rightarrow c \epsilon^{1 / 2}$.

Finally, we prove the last proposition used in the proof of Theorem 6.1. Proposition 6.3 estimates the $H^{1}$ norm of $\bar{\phi}-\bar{\theta}_{\epsilon}$,

Proposition 6.3. Let $\Omega$ be a convex polygon, and the functions $u_{0}, \bar{\theta}_{\epsilon}$ and $\bar{\phi}$ be defined by Equations (2.4), (2.10) and (2.14), respectively. Assume that $u_{0} \in H^{2}(\Omega)$, then there exists a positive constant $c$ independent of $\epsilon$ and $u_{0}$ such that

$$
\left\|\bar{\phi}-\bar{\theta}_{\epsilon}\right\|_{1} \leq c \frac{\|a\|_{0, \infty, Y}}{\gamma_{a}}\left\|u_{0}\right\|_{2}
$$

Proof. Consider the notation $a^{\epsilon}(x)=a(x / \epsilon)$, the same will be used for $a_{i j}$. Since $\left(\bar{\phi}-\bar{\theta}_{\epsilon}\right)=0$ on $\partial \Omega$ we have

$$
\begin{aligned}
\int_{\Omega} a_{i j}^{\epsilon} \frac{\partial\left(\bar{\phi}-\bar{\theta}_{\epsilon}\right)}{\partial x_{i}} \frac{\partial\left(\bar{\phi}-\bar{\theta}_{\epsilon}\right)}{\partial x_{j}} d x & =\int_{\Omega} a_{i j}^{\epsilon} \frac{\partial \bar{\phi}}{\partial x_{i}} \frac{\partial\left(\bar{\phi}-\bar{\theta}_{\epsilon}\right)}{\partial x_{j}} d x \\
& \leq\|a\|_{0, \infty, Y}\left(\int_{\Omega}|\nabla \bar{\phi}|^{2} d x\right)^{1 / 2}\left(\int_{\Omega}\left|\nabla\left(\bar{\phi}-\bar{\theta}_{\epsilon}\right)\right|^{2} d x\right)^{1 / 2}
\end{aligned}
$$

and from the ellipticity of $a$ we obtain

$$
\left|\bar{\phi}-\bar{\theta}_{\epsilon}\right|_{1} \leq \frac{\|a\|_{0, \infty, Y}}{\gamma_{a}}|\bar{\phi}|_{1} .
$$

The regularity theory gives that $|\bar{\phi}|_{1} \leq c\left\|\chi^{*} \partial_{\eta} u_{0}\right\|_{H^{1 / 2}(\partial \Omega)}$, and since $\Omega$ is a convex polygon by Remark 2.1

$$
\left|\bar{\phi}-\bar{\theta}_{\epsilon}\right|_{1} \leq c\left\|u_{0}\right\|_{2}
$$

The proposition follows from a Poincare inequality.
6.2. Proof of Theorem 2.2. Use a triangular inequality similar to the one used in the proof of Theorem 2.1 and Propositions 6.4, 6.2 and 6.5.

We now prove the propositions used in the proof of Theorem 2.2. The following proposition generalizes Proposition 2.3 from [34], where it is assumed $a_{i j} \in C_{p e r}^{1, \beta}(Y)$, $u_{0} \in H^{3}(\Omega)$ and $\Omega \subset \mathbb{R}^{2}$. We note here that Theorem 1.1 from [32] gives conditions concerning the discontinuities of the functions $a_{i j}$ such that $\chi^{j}$ and $\chi^{i j} \in W_{p e r}^{1, \infty}(Y)$.

Proposition 6.4. Let $\Omega \subset \mathbb{R}^{d}$, $d=2,3$ be a convex domain, $u_{\epsilon}$ be the solution of Problem (1.1), and $\chi^{j}, u_{0}, u_{1}, \theta_{\epsilon}$ and $\chi^{i j}$ be defined by Equations (2.2), (2.4), (2.5), (2.6) and (2.7), respectively. Assume $a_{i j} \in L_{p e r}^{\infty}(Y), u_{0} \in W^{3, p}(\Omega)$, $\chi^{j}$ and $\chi^{i j} \in W_{\text {per }}^{1, q}(Y)$, for $p, q>d$ and $1 / p+1 / q \leq 1 / 2$. Then there exists a constant $c$ independent of $u_{0}$ and $\epsilon$ such that

$$
\left\|u_{\epsilon}(\cdot)-u_{0}(\cdot)-\epsilon u_{1}(\cdot, \cdot / \epsilon)-\epsilon \theta_{\epsilon}(\cdot)\right\|_{0} \leq C \epsilon^{2}\left\|u_{0}\right\|_{3, p}\left(\max _{j}\left\|\chi^{j}\right\|_{0, q}+\max _{k j}\left\|\chi^{k j}\right\|_{1, q}\right)
$$

Proof.
Define the field $v_{1}$ by

$$
\begin{equation*}
\left(v_{1}(x, y)\right)_{k}=-a_{k i}(y) \chi^{j} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}}(x)+a_{k l}(y) \frac{\partial \chi^{i j}}{\partial y_{l}} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}}(x) \tag{6.27}
\end{equation*}
$$

hence

$$
\begin{equation*}
a(y) \nabla_{x} u_{1}(x, y)+a(y) \nabla_{y} u_{2}(x, y)=v_{1}(x, y) \tag{6.28}
\end{equation*}
$$

Let $q(y)=\phi(y), \phi$ defined by Equation (6.3) and let $\psi_{i j} \in W_{\mathrm{per}}^{1, q}(Y)$ such that

$$
\begin{aligned}
& \operatorname{curl}_{y} \psi_{1 j}=\tilde{\psi}_{1 j}=\left(\begin{array}{l}
-a_{11} \chi^{j}+a_{1 l} \partial_{l} \chi^{1, j}-c_{1 j}^{1} \\
-a_{21} \chi^{j}+a_{2 l} \partial_{l} \chi^{1, j}-\phi_{j}^{(3)}-c_{1 j}^{2} \\
-a_{31} \chi^{j}+a_{3 l} \partial_{l} \chi^{1, j}+\phi_{j}^{(2)}-c_{1 j}^{3}
\end{array}\right), \\
& \operatorname{curl}_{y} \psi_{2 j}=\tilde{\psi}_{2 j}=\left(\begin{array}{l}
-a_{12} \chi^{j}+a_{1 l} \partial_{l} \chi^{2, j}+\phi_{j}^{(3)}-c_{2 j}^{1} \\
-a_{22} \chi^{j}+a_{2 l} \partial_{l} \chi^{2, j}-c_{2 j}^{2} \\
-a_{32} \chi^{j}+a_{3 l} \partial_{l} \chi^{2, j}-\phi_{j}^{(1)}-c_{2 j}^{3}
\end{array}\right)
\end{aligned}
$$

and

$$
\operatorname{curl}_{y} \psi_{1 j}=\tilde{\psi}_{3 j}=\left(\begin{array}{l}
-a_{13} \chi^{j}+a_{1 l} \partial_{l} \chi^{3, j}-\phi_{j}^{(2)}-c_{3 j}^{1} \\
-a_{23} \chi^{j}+a_{2 l} \partial_{l} \chi^{3, j}+\phi_{j}^{(1)}-c_{3 j}^{2} \\
-a_{33} \chi^{j}+a_{3 l} \partial_{l} \chi^{3, j}-c_{3 j}^{3}
\end{array}\right)
$$

where the constants $c_{i j}^{l}$ are chosen such that each entry of the vectors $\tilde{\psi}_{i j}$ has integral zero over $Y$, e.g. $c_{1 j}^{1}=\int_{Y}-a_{11} \chi^{j}+a_{1 l} \partial_{l} \chi^{1, j} d y$. It is easy to check that $\nabla_{y} \cdot \tilde{\psi}_{k j}=0$, what guarantees by Lemma 6.1 the existence of such functions $\psi_{k j}$, and by Remark 3.11 in [25] we have

$$
\begin{equation*}
\left\|\psi_{k j}\right\|_{1, q} \leq c\left(\left\|\chi^{j}\right\|_{0, q}+\left\|\chi^{k j}\right\|_{1, q}\right) \tag{6.29}
\end{equation*}
$$

Define

$$
\begin{equation*}
p(x, y)=\psi_{k j}(y) \frac{\partial^{2} u_{0}}{\partial x_{k} \partial x_{j}}(x) \tag{6.30}
\end{equation*}
$$

and let

$$
v_{2}(x, y)=-\operatorname{curl}_{x} p(x, y)
$$

and a simple calculation gives

$$
\begin{equation*}
\nabla_{y} \cdot v_{2}=-\nabla_{x} \cdot v_{1}, \quad \nabla_{x} \cdot v_{2}=0 \tag{6.31}
\end{equation*}
$$

and

$$
\begin{align*}
\left\|v_{2}(\cdot, \cdot / \epsilon)\right\|_{0} & \leq c\left\|u_{0}\right\|_{3, p} \max _{k j}\left\|\psi_{k j}\right\|_{1, q, Y} \\
& \leq c\left\|u_{0}\right\|_{3, p}\left(\left\|\chi^{j}\right\|_{0, q}+\left\|\chi^{k j}\right\|_{1, q}\right) \quad \text { by } \quad(6.29) \tag{6.32}
\end{align*}
$$

Define

$$
\psi_{\epsilon}(x)=u_{\epsilon}(x)-u_{0}(x)-\epsilon u_{1}(x, x / \epsilon)-\epsilon^{2} u_{2}(x, x / \epsilon)
$$

and

$$
\xi_{\epsilon}(x)=a(x / \epsilon) \nabla u_{\epsilon}(x)-v_{0}(x, x / \epsilon)-\epsilon v_{1}(x, x / \epsilon)-\epsilon^{2} v_{2}(x, x / \epsilon)
$$

where $v_{0}$ is defined by (6.1). Then

$$
\begin{aligned}
a(x / \epsilon) \nabla \psi_{\epsilon}-\xi_{\epsilon}(x)= & a(x / \epsilon) \nabla u_{\epsilon}(x)-a(x / \epsilon) \nabla u_{0}(x)-\epsilon a(x / \epsilon) \nabla u_{1}(x, x / \epsilon) \\
& -\epsilon^{2} a(x / \epsilon) \nabla u_{2}(x, x / \epsilon) \\
& -a(x / \epsilon) \nabla u_{\epsilon}(x)+v_{0}(x, x / \epsilon)+\epsilon v_{1}(x, x / \epsilon)+\epsilon^{2} v_{2}(x, x / \epsilon) \\
= & -a(x / \epsilon) \nabla_{x} u_{0}(x)-\epsilon a(x / \epsilon) \nabla_{x} u_{1}(x, x / \epsilon)-a(x / \epsilon) \nabla_{y} u_{1}(x, x / \epsilon) \\
& -\epsilon^{2} a(x / \epsilon) \nabla_{x} u_{2}(x, x / \epsilon)-\epsilon a(x / \epsilon) \nabla_{y} u_{2}(x, x / \epsilon) \\
& +v_{0}(x, x / \epsilon)+\epsilon v_{1}(x, x / \epsilon)+\epsilon^{2} v_{2}(x, x / \epsilon) \\
= & \epsilon^{2}\left(v_{2}(x, x / \epsilon)-a(x / \epsilon) \nabla_{x} u_{2}(x, x / \epsilon)\right), \text { by (6.1), and (6.28). }
\end{aligned}
$$

From the definition of $u_{2}$ and (6.32) we obtain

$$
\begin{equation*}
\left\|a(x / \epsilon) \nabla \psi_{\epsilon}-\xi_{\epsilon}\right\|_{0} \leq c \epsilon^{2}\left\|u_{0}\right\|_{3, p} \max _{k j}\left(\left\|\chi^{j}\right\|_{0, q}+\left\|\chi^{k j}\right\|_{1, q}\right) \tag{6.33}
\end{equation*}
$$

Define $\varphi_{\epsilon} \in H^{1}(\Omega)$ as the weak solution of

$$
\begin{equation*}
-\nabla \cdot a(x / \epsilon) \nabla \varphi_{\epsilon}=0 \text { in } \Omega, \quad \text { and } \varphi_{\epsilon}(x)=u_{2}(x, x / \epsilon) \text { on } \partial \Omega \tag{6.34}
\end{equation*}
$$

We observe that the Sobolev embedding theorem and the hypothesis $p, q>d$, implies the function $u_{2}$ is continuous. Therefore, we use the maximum principle to obtain

$$
\begin{align*}
\left\|\varphi_{\epsilon}\right\|_{0} & \leq c\left\|\varphi_{\epsilon}\right\|_{0, \infty} \\
& \leq c \max _{i j}\left\|\chi^{i j}\right\|_{0, \infty, Y}\left\|\partial_{x_{i} x_{j}} u_{0}\right\|_{0, \infty} \\
& \leq c \max _{i j}\left\|\chi^{i j}\right\|_{1, q, Y}\left\|u_{0}\right\|_{3, p} . \tag{6.35}
\end{align*}
$$

Given $g \in L^{2}(\Omega)$, let $w_{\epsilon} \in H^{1}(\Omega)$ denotes the solution of

$$
\begin{equation*}
\int_{\Omega} a(x / \epsilon) \nabla w_{\epsilon}(x) \nabla \psi(x) d x=\int_{\Omega} g(x) \psi(x) d x, \quad \forall \psi \in H_{0}^{1}(\Omega) \tag{6.36}
\end{equation*}
$$

Since $\psi_{\epsilon}+\epsilon \theta_{\epsilon}+\epsilon^{2} \varphi_{\epsilon} \in H_{0}^{1}(\Omega)$ we obtain

$$
\begin{align*}
\int_{\Omega} g\left(\psi_{\epsilon}+\epsilon \theta_{\epsilon}+\epsilon^{2} \varphi_{\epsilon}\right) d x & =\int_{\Omega} a(x / \epsilon)\left(\nabla \psi_{\epsilon}+\epsilon \nabla \theta_{\epsilon}+\epsilon^{2} \nabla \varphi_{\epsilon}\right) \nabla w_{\epsilon}(x) d x \\
& =\int_{\Omega} a(x / \epsilon) \nabla \psi_{\epsilon} \nabla w_{\epsilon}(x) d x \tag{6.37}
\end{align*}
$$

where we have used the definition of $\theta_{\epsilon}$ and $\varphi_{\epsilon}$ to obtain (6.37). We observe that

$$
\begin{equation*}
\int_{\Omega} a^{\epsilon} \nabla \psi_{\epsilon} \nabla w_{\epsilon} d x=\int_{\Omega}\left(a^{\epsilon} \nabla \psi_{\epsilon}-\xi_{\epsilon}\right) \cdot \nabla w_{\epsilon} d x+\int_{\Omega} \xi_{\epsilon} \cdot \nabla w_{\epsilon} d x \tag{6.38}
\end{equation*}
$$

and we estimate the second term on the right hand side of (6.38) as follows

$$
\begin{align*}
\int_{\Omega} \xi_{\epsilon} \cdot \nabla w_{\epsilon} d x= & \int_{\Omega}\left(a(x / \epsilon) \nabla u_{\epsilon}(x)-v_{0}(x, x / \epsilon)-\epsilon v_{1}(x, x / \epsilon)\right. \\
& \left.-\epsilon^{2} v_{2}(x, x / \epsilon)\right) \cdot \nabla w_{\epsilon}(x) d x \\
= & \int_{\Omega} f w_{\epsilon}(x)+\nabla_{x} \cdot v_{0}(x, x / \epsilon) w_{\epsilon}(x) \\
& -\epsilon v_{1}(x, x / \epsilon) \cdot \nabla w_{\epsilon}(x)+\epsilon \nabla_{x} v_{1}(x, x / \epsilon) w_{\epsilon}(x) d x \tag{6.39}
\end{align*}
$$

here we used the definition of $u_{\epsilon},(6.15)$, integration by parts and (6.31) to obtain (6.39). Using (6.27) we have

$$
\begin{align*}
\int_{\Omega} v_{1}(x, x / \epsilon) \cdot \nabla w_{\epsilon}(x)= & \int_{\Omega}\left(-a_{k i}^{\epsilon} \chi_{\epsilon}^{j} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}}(x)\right. \\
& \left.+a_{k l}^{\epsilon} \frac{\partial \chi_{\epsilon}^{i j}}{\partial y_{l}} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}}(x)\right) \frac{\partial w_{\epsilon}}{\partial x_{k}}(x) d x \tag{6.40}
\end{align*}
$$

Consider the partition of unit $\rho_{i}$ defined in the proof of Proposition 6.1, then

$$
\begin{aligned}
& \int_{\Omega} a_{k l}^{\epsilon} \frac{\partial \chi_{\epsilon}^{i j}}{\partial y_{l}} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}} \frac{\partial w_{\epsilon}}{\partial x_{k}}(x) d x= \\
= & \sum_{1}^{i_{m}} \int_{\epsilon Y_{i}} a_{k l}^{\epsilon} \frac{\partial \chi_{\epsilon}^{i j}}{\partial y_{l}} \rho_{i} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}} \frac{\partial w_{\epsilon}}{\partial x_{k}} d x
\end{aligned}
$$

$$
\begin{align*}
&= \sum_{1}^{i_{m}} \int_{\epsilon Y_{i}} a_{k l}^{\epsilon} \frac{\partial \chi_{\epsilon}^{i j}}{\partial y_{l}} \frac{\partial}{\partial x_{k}}\left(\rho_{i} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}} w_{\epsilon}(x)\right)-a_{k l}^{\epsilon} \frac{\partial \chi_{\epsilon}^{i j}}{\partial y_{l}} w_{\epsilon}(x) \frac{\partial}{\partial x_{k}}\left(\rho_{i} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}}\right) d x \\
&= \sum_{1}^{i_{m}} \int_{\epsilon Y_{i}} \epsilon^{-1}\left(a_{i j}^{\epsilon}-a_{i k}^{\epsilon} \frac{\partial \chi_{\epsilon}^{j}}{\partial_{y_{k}}}+A_{i j}\right) \rho_{i} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}} w_{\epsilon} \\
&+a_{k i}^{\epsilon} \chi_{\epsilon}^{j}\left(\frac{\partial}{\partial_{x_{k}}}\left(\rho_{i} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}}(x)\right) w_{\epsilon}(x)+\rho_{i} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}}(x) \frac{\partial w_{\epsilon}}{\partial_{x_{k}}}(x)\right) d x \\
& \quad-\int_{\Omega} a_{k l} \frac{\partial \chi_{\epsilon}^{i j}}{\partial y_{l}} w_{\epsilon}(x) \frac{\partial}{\partial x_{k}}\left(\frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}}\right) d x \\
& \begin{array}{l}
\text { 1) } \\
=\int_{\Omega} \epsilon^{-1}\left(\nabla_{x} v_{0} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}}(x)-f\right) w_{\epsilon}(x) d x \\
2) \\
\quad-\int_{\Omega} a_{k i}^{\epsilon} \chi_{\epsilon}^{j} \frac{\partial^{2} u_{0}}{\partial x_{j} \partial x_{i}} \frac{\partial w_{\epsilon}}{\partial_{x_{k}}}(x) d x-\int_{\Omega} \nabla_{x} \cdot v_{1} d x .
\end{array}
\end{align*}
$$

Here we used the definition of $\chi^{i j}$ to arrive in (6.41), and from (6.39), (6.40) and (6.42) we obtain

$$
\int_{\Omega} \xi_{\epsilon} \cdot \nabla w_{\epsilon}(x) d x=0
$$

and hence from (6.33) and (6.38)

$$
\begin{aligned}
\left|\int_{\Omega} g\left(\psi_{\epsilon}+\epsilon \theta_{\epsilon}+\epsilon^{2} \varphi_{\epsilon}\right) d x\right| & \left.\leq \| a^{\epsilon} \nabla \psi_{\epsilon}-\xi_{\epsilon}\right)\left\|_{0}\right\| w_{\epsilon} \|_{1} \\
& \leq c \epsilon^{2}\left\|u_{0}\right\|_{3, p}\left(\left\|\chi^{j}\right\|_{0, q, Y}+\left\|\chi^{k j}\right\|_{1, q, Y}\right)\|g\|_{-1} .
\end{aligned}
$$

Dividing by $g$ and taking the supremum over $g$, we have

$$
\left\|u_{\epsilon}-u_{0}-\epsilon u_{1}-\epsilon \theta_{\epsilon}-\epsilon^{2} u_{2}-\epsilon^{2} \varphi_{\epsilon}\right\| \leq c \epsilon^{2}\left\|u_{0}\right\|_{3, p} \max _{k j}\left(\left\|\chi^{j}\right\|_{0, q}+\left\|\chi^{k j}\right\|_{1, q}\right) .
$$

Observe that $u_{2}(x, x / \epsilon)$ and $\varphi_{\epsilon}(x)$ are bounded in $L^{2}(\Omega)$ by $\left\|u_{0}\right\|_{3, p} \max _{k j}\left\|\chi^{k j}\right\|_{1, q}$, independent of $\epsilon$, see (6.35). Hence

$$
\left\|u_{\epsilon}-u_{0}-\epsilon u_{1}-\epsilon \theta_{\epsilon}\right\| \leq c \epsilon^{2}\left\|u_{0}\right\|_{3, p}\left(\max _{j}\left\|\chi^{j}\right\|_{0, q}+\max _{k j}\left\|\chi^{k j}\right\|_{1, q}\right) .
$$

The following proposition estimates the $L^{2}$ norm of $\bar{\phi}-\bar{\theta}_{\epsilon}$, and it is used in the proof of Theorem 2.2

Proposition 6.5. Let $u_{0}, \chi^{j}, \bar{\theta}_{\epsilon}$ and $\bar{\phi}$ be defined by (2.4), (2.2), (2.10) and (2.14), respectively. Assume that $u_{0} \in W^{3, p}(\Omega), \bar{\phi} \in W^{2, p}(\Omega)$ and $\chi^{j} \in W_{p e r}^{1, q}(Y)$, for $1 / p+1 / q \leq 1 / 2$. Then we have

$$
\left\|\bar{\theta}_{\epsilon}-\bar{\phi}\right\|_{0} \leq c \epsilon\left\|u_{0}\right\|_{3, p}
$$

Proof. Observe that $\bar{\phi} \in W^{2, p}(\Omega)$ and $p \geq 2$, hence from Corollary 6.1 and Remark 6.1 we obtain

$$
\left\|\bar{\theta}_{\epsilon}-\bar{\phi}\right\|_{0} \leq c \epsilon\|\bar{\phi}\|_{2, p} .
$$

Since

$$
\left.\bar{\phi}\right|_{\partial \Omega}=\left.\sum_{k} \varphi_{k} \chi_{k}^{*} \nabla u_{0} \cdot \eta_{k}\right|_{\partial \Omega}
$$

by regularity theory, see Theorems 4.3.1.4 and 4.3.2.4 [24], $\|\bar{\phi}\|_{2, p} \leq c\left(\chi^{*}\right)\left\|u_{0}\right\|_{3, p}$, and the proposition follows.
6.3. Proof of Theorem 2.3. Use a triangular inequality similar to the one used in the Proof of Theorem 2.1 and Propositions 6.6, 6.2 and 6.5. Observe that if $a_{i j} \in C_{p e r}^{1, \beta}(Y), \beta>0$, by regularity theory $\chi^{j} \in C_{p e r}^{1, \beta}, v_{e} \in C^{1, \beta}$ and $\nabla\left(v_{e}-\right.$ $\left.\chi_{e}^{*}\right) \exp \left(-\gamma y_{1}\right) \in L^{\infty}\left(G_{e}\right)$; see Theorem 15.1 in [30] and Remark 6.4 in [34]. By the Sobolev embedding theorem $u_{0} \in W^{2, \infty}(\Omega)$, hence Proposition 6.2 holds for $\delta=1 / 2$.

The following proposition is used in the proof of Theorem 2.3. Proposition 6.6 generalizes Proposition 2.3 from [34] to the case $\Omega \subset \mathbb{R}^{3}$.

Proposition 6.6. Let $\Omega \subset \mathbb{R}^{d}$, $d=2,3$ be a convex domain, $u_{\epsilon}$ be the solution of Problem (1.1), and $u_{0}, u_{1}$, and $\theta_{\epsilon}$ be defined by Equations (2.4), (2.5) and (2.6), respectively. Assume $a_{i j} \in C^{1, \beta}(Y), \beta>0$ and $u_{0} \in H^{3}(\Omega)$. Then there exists $a$ constant $c$ independent of $u_{0}$ and $\epsilon$, such that

$$
\left\|u_{\epsilon}(\cdot)-u_{0}(\cdot)-\epsilon u_{1}(\cdot, \cdot / \epsilon)-\epsilon \theta_{\epsilon}(\cdot)\right\|_{0} \leq C \epsilon^{2}\left\|u_{0}\right\|_{3} .
$$

Proof. Since $a_{i j} \in C^{1, \beta}(Y)$ by regularity theory $\chi^{i} \in C^{2, \beta}(Y), \chi^{i j} \in C^{1}(Y)$ and by Theorem 3 in [7] we obtain

$$
\left\|\varphi_{\epsilon}\right\|_{0} \leq c\left\|u_{2}(\cdot, \cdot / \epsilon)\right\|_{0, \partial \Omega} \leq c\left\|u_{0}\right\|_{3}\left\|\chi^{i} j\right\|_{0, \infty}
$$

where the function $\varphi_{\epsilon}$ is defined by (6.34) and we have used the trace theorem in the last inequality. The rest of the proof of follows exactly as the proof of Proposition 6.4.
6.4. Auxiliary Result . The following lemma is used in the proof of Propositions 6.1 and 6.4.

Lemma 6.1. A function $\mathbf{v} \in L_{\text {per }}^{2}(Y)^{2},\left(\mathbf{v} \in L_{\text {per }}^{2}(Y)^{3}\right)$ satisfies

$$
\begin{equation*}
\nabla \cdot \mathbf{v}=\mathbf{0} \tag{6.43}
\end{equation*}
$$

and $\int_{Y} v_{i} d y=0$ iff there exists a function $\phi \in H_{p e r}^{1}(Y)\left(\phi \in H_{p e r}^{1}(Y)^{3}\right)$ such that:

$$
\begin{equation*}
\mathbf{v}=\operatorname{curl} \phi \tag{6.44}
\end{equation*}
$$

Proof. Similar to the proof of Theorem 3.4 from [25] using discrete Fourier transforms rather than continuous Fourier transforms, see [41]. [
7. Conclusions. We perform the convergence analysis for the proposed numerical method for approximating the solution of Equation (1.1). The error estimates obtained in the numerical experiments agree with the theoretical errors estimates from Theorems 4.1 and 4.2. The method presented here is strongly based on the periodicity of the coefficients $a_{i j}$, and for this reason it has relative low computational cost with optimal error convergence rate.

We generalize results found in the literature for estimating the error between $u_{\epsilon}$ and its first order asymptotic expansion $u_{0}+\epsilon u_{1}$ approximation plus the boundary corrector term $\theta_{\epsilon}$. Such generalization permit us to develop sharp finite element error estimates with very weak assumptions on the regularity of $a(y)$, including composite materials applications.

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