

A NEUMANN-NEUMANN METHOD FOR DG DISCRETIZATION OF ELLIPTIC PROBLEMS

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Abstract. A discontinuous Galerkin (DG) discretization of Dirichlet problem for second order elliptic equations with discontinuous coefficients in the 2-D is considered. For this discretization, a Neumann-Neumann (N-N) algorithm is designed and analyzed as an additive Schwarz method (ASM). The coarse spaces is defined using a special partition of unity. The method is almost optimal under the natural assumption on the triangulation. Its rate of convergence is independent of jumps of coefficients. The method is well suited for parallel computations.

Key words. interior penalty discretization, discontinuous Galerkin method, elliptic problems with discontinuous coefficients, finite element method, Neumann-Neumann algorithms, Schwarz methods, preconditioners

AMS subject classifications. 65F10, 65N20, 65N30

1. Introduction. In this paper, discontinuous Galerkin approximation of elliptic problems with discontinuous coefficients is considered. The problem is considered in a polygonal region Ω which is a union of disjoint polygonal subregions Ω_i . The discontinuities of the coefficients occur across $\partial\Omega_i$. The problem is approximated by a conforming finite element method (FEM) on matching triangulation in each Ω_i and nonmatching one across $\partial\Omega_i$. This kind of triangulation and composite discretization are motivated first of all by the regularity of the solution of the problem being discussed. Discrete problems are formulated using DG methods, symmetric and with interior penalty terms on the $\partial\Omega_i$; see [1, 2, 4]. A goal of this paper is to design and analyze Neumann-Neumann (N-N) algorithms for the resulting discrete problem; see [6, 9] and also [10]. The first step, the problem is reduced to the Schur complement problem with respect to unknowns on $\partial\Omega_i$, for $i = 1, \dots, N$. For that discrete harmonic functions defined in a special way are used. The method is designed and analyzed for the Schur complement problem using the general theory of ASMs; see [6, 10]. The local problems are defined on Ω_i and faces of $\partial\Omega_j$ which are common to Ω_i . The coarse space is defined using a special partitioning of unity with respect to Ω_i and introducing master and slave sides of substructures. A side $F_{ij} = \partial\Omega_i \cap \partial\Omega_j$ is master when $\rho_i \geq \rho_j$, otherwise it is slave, so if $F_{ij} \subset \partial\Omega_i$ is master then $F_{ji} \subset \partial\Omega_j$, $F_{ij} = F_{ji}$, is slave. The h_i - and h_j - triangulations on F_{ij} and F_{ji} , respectively, are built in a way that $h_i \geq h_j$ if $\rho_i \geq \rho_j$ where h_i and h_j are the parameters of these triangulations. It is proved that the algorithm is almost optimal and its rate of convergence is independent of h_i and h_j , the number of subdomains Ω_i and the jumps of coefficients. The algorithm is well suited for parallel computations and it can be straightforwardly extended to the problems in $3 - D$ cases.

DG methods are becoming more and more popular for approximation of PDEs; see [1, 2] and literature therein. There are also several papers devoted to algorithms for solving the resulting discrete problem, in particular domain decomposition methods. We first mention [7] and [8] where composite discretization similar to those

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discussed in this paper are considered. In these papers overlapping Schwarz and Neumann-Dirichlet methods were proposed and analyzed for DG discretization of elliptic problems with continuous coefficients. In [4] for the considered discrete problem, a multilevel ASM is designed and analyzed but it is not optimal. In [3] a two-level ASM is proposed and analyzed for DG discretization of fourth order problems. For our knowledge N-N algorithms for DG discretization of elliptic problems with continuous and discontinuous coefficients have not been analyzed in literature.

The paper is organized as follows. In Section 2 the differential problem and its DG discretization are formulated. In Section 3 the Schur complement problem is derived using describe harmonic function in a special way. Sections 4 and 5 are devoted to designing a N-N algorithm while Section 6 is devoted to the proof of the main result, Theorem 5.2. In Section 7 auxiliary results are proved for the used coarse space.

2. Differential and discrete problems.

2.1. Differential problem. Find $u^* \in H_0^1(\Omega)$ such that

$$(2.1) \quad a(u^*, v) = f(v), \quad v \in H_0^1(\Omega)$$

where

$$a(u, v) = \sum_{i=1}^N \int_{\Omega_i} \rho_i \nabla u \nabla v dx, \quad f(v) = \int_{\Omega} f v dx.$$

We assume that $\bar{\Omega} = \cup_{i=1}^N \bar{\Omega}_i$ and the substructures Ω_i are disjoint shaped regular polygonal subregions of diameter H_i and form a geometrical conforming partition of Ω , i.e. $\forall i \neq j$ the intersection $\partial\Omega_i \cap \partial\Omega_j$ is empty or is a common vertex or face of $\partial\Omega_i$ and $\partial\Omega_j$. We assume that $f \in L^2(\Omega)$ and the coefficients ρ_i are constants larger than a positive constant ρ_0 what guarantee that the problem is well posed in $H_0^1(\Omega)$.

2.2. Discrete problem. Let us introduce the shape regular triangulation in each Ω_i with triangular elements and h_i as the mesh parameter. The resulting triangulation on Ω is in general nonmatching across $\partial\Omega_i$. Let $X_i(\Omega_i)$ be a finite element (FE) space of piecewise linear continuous functions Ω_i . Note that we do not assume that functions in $X_i(\Omega_i)$ vanish on $\partial\Omega_i \cap \partial\Omega$; see Remark 5.4 for others variations. Define

$$X_h(\Omega) = X_1(\Omega_1) \times \cdots \times X_N(\Omega_N).$$

A discrete problem obtained by DG method, see [1, 2, 4], is of the form:

Find $u_h^* \in X_h(\Omega)$ such that

$$(2.2) \quad a_h(u_h^*, v) = f(v), \quad v \in X_h(\Omega)$$

where

$$(2.3) \quad a_h(u, v) \equiv \sum_{i=1}^N a_i(u, v) + s_a(u, v) + s_p(u, v).$$

Here for $u = \{u_i\}_{i=1}^N \in X_h(\Omega)$ and $v = \{v_i\}_{i=1}^N \in X_h(\Omega)$

$$(2.4) \quad a_i(u, v) \equiv \int_{\Omega_i} \rho_i \nabla u_i \nabla v_i dx,$$

$$(2.5) \quad s_a(u, v) \equiv \sum_{i=1}^N \sum_{F_{ij} \subset \partial\Omega_i} \frac{1}{l_{ij}} \int_{F_{ij}} \frac{\rho_{ij}}{2} \left(\frac{\partial u_i}{\partial n} + \frac{\partial u_j}{\partial n} \right) (v_j - v_i) ds$$

where $F_{ij} = \partial\Omega_i \cap \partial\Omega_j$ is the common face of $\partial\Omega_i$ and $\partial\Omega_j$ and let $l_{ij} = 2$. We also include $F_{i0} = \partial\Omega_i \cap \partial\Omega$ whenever it has positive measure and let $l_{i0} = 1$. The index l_{ij} says how many subdomains shares F_{ij} . The $\frac{\partial}{\partial n}$ denotes the normal outward derivative on $\partial\Omega_i$ and $\rho_{ij} = 2\rho_i\rho_j/(\rho_i + \rho_j)$ the harmonic average of ρ_i and ρ_j when $j \neq 0$ and $\rho_{i0} = \rho_i$. To make the notation even more compact, when $j = 0$ we take $u_j = 0$ and $v_j = 0$, and $\frac{\partial u_j}{\partial n} = \frac{\partial u_i}{\partial n}$ and $\frac{\partial v_j}{\partial n} = \frac{\partial v_i}{\partial n}$. We note that when ρ_{ij} is given by harmonic average, $\min\{\rho_i, \rho_j\} \leq \rho_{ij} \leq \max\{\rho_i, \rho_j\}$, and also $\rho_{ij} \leq 2\rho_i$ and $\rho_{ij} \leq 2\rho_j$.

The bilinear form $s_a(\cdot, \cdot)$ also can be written as

$$(2.6) \quad s_a(u, v) \equiv \sum_{i=1}^N \frac{\rho_{ij}}{l_{ij}} \sum_{F_{ij} \subset \partial\Omega_i} \left\{ \int_{F_{ij}} \frac{\partial u_i}{\partial n} (v_j - v_i) ds + \int_{F_{ij}} \frac{\partial v_i}{\partial n} (u_j - u_i) ds \right\}$$

where the term $\frac{1}{4} \left(\frac{\partial u_j}{\partial n}, u_j - u_i \right)_{L^2(F_{ij})}$ on $F_{ij} \subset \partial\Omega_j$ has been added ($F_{ji} = F_{ij}$) to $\frac{1}{4} \left(-\frac{\partial u_j}{\partial n}, v_i - v_j \right)_{L^2(F_{ji})}$ and replacing $\frac{\partial}{\partial n}$ to $\partial\Omega_i$ by $-\frac{\partial}{\partial n}$ to $\partial\Omega_j$. In a similar way we proceed with the term $\frac{1}{4} \left(\frac{\partial v_j}{\partial n}, u_j - u_i \right)_{L^2(F_{ji})}$. The penalty term is given as

$$(2.7) \quad s_p(u, v) \equiv \sum_{i=1}^N \sum_{F_{ij} \subset \partial\Omega_i} \int_{F_{ij}} \frac{\delta}{l_{ij}} \frac{\rho_{ij}}{h_i} (u_j - u_i) (v_j - v_i) ds$$

where δ is a penalty positive parameter. It is known that there is $\delta_0 = O(1) > 0$ such that for $\delta \geq \delta_0$ the problem (2.2) has a unique solution. An error bound of the method is optimal for $\rho_i = 1$, see [1, 2], but is not for discontinuous coefficients, see [4]. In the later case the error is $O(h^{3/2})$ only in the H^1 -broken norm if the solution of (2.1) $u^* \in H^{3/2+\epsilon}(\Omega)$, with $\epsilon > 0$. On the other hand we cannot expect more regularity of u^* in the case of discontinuous coefficients in a general case. In the discretization of $s_a(\cdot, \cdot)$ and $s_p(\cdot, \cdot)$, see (2.6) and (2.7), we use the harmonic average of ρ_i and ρ_j , $\rho_{ij} = 2\rho_i\rho_j/(\rho_i + \rho_j)$ instead of ρ_i and ρ_j . In the case of jump on the coefficients across interfaces, it is a natural way of using it.

We introduce the so-called broken norm in $X_h(\Omega)$ with weights given by ρ_i and ρ_{ij} . For $u = \{u_i\} \in X_h(\Omega)$ define

$$(2.8) \quad \|u\|_{1,h}^2 \equiv \sum_{i=1}^N \left\{ \rho_i \|\nabla u_i\|_{L^2(\Omega_i)}^2 + \sum_{F_{ij} \subset \partial\Omega_i} \frac{\delta}{l_{ij}} \frac{\rho_{ij}}{h_i} \int_{F_{ij}} (u_i - u_j)^2 ds \right\}.$$

LEMMA 2.1. *There exists $\delta_0 > 0$ such that for $\delta \geq \delta_0$ and $u \in X_h(\Omega)$*

$$(2.9) \quad \gamma \|u\|_{1,h}^2 \leq a_h(u, u) \leq M \|u\|_{1,h}^2$$

where γ and M are positive constants independent of the ρ_i , h_i and H_i .

For the proof see, for example [4].

3. Schur complement problem. In this section we derive a Schur complement problem for the problem (2.2). We first introduce some auxiliary notations.

Let $u = \{u_i\} \in X_h(\Omega)$ be given. We can represent u_i as

$$(3.1) \quad u_i = \mathcal{H}_i u_i + P_i u_i$$

where $\mathcal{H}_i u_i$ is the discrete harmonic part of u_i in the sense of $a_i(\cdot, \cdot)$, see (2.4), i.e.

$$(3.2) \quad a_i(\mathcal{H}_i u_i, v_i) = 0 \quad v_i \in \overset{\circ}{X}_i(\Omega_i)$$

$$(3.3) \quad \mathcal{H}_i u_i = u_i \quad \text{on} \quad \partial\Omega_i,$$

while $P_i u_i$ is the projection of u_i on $\overset{\circ}{X}_i(\Omega_i)$ in the sense of $a_i(\cdot, \cdot)$, i.e.

$$(3.4) \quad a_i(P_i u_i, v_i) = a_i(u_i, v_i), \quad v_i \in \overset{\circ}{X}_i(\Omega_i).$$

Here $\overset{\circ}{X}_i(\Omega_i)$ is a subspace of $X_i(\Omega_i)$ of functions which vanish on $\partial\Omega_i$, and $\mathcal{H}_i u_i$ is the classical discrete harmonic part of u_i . Let us denote $\overset{\circ}{X}_h(\Omega) \equiv \{\overset{\circ}{X}_i(\Omega_i)\}_{i=1}^N$ to be a subspace of $X_h(\Omega)$ and consider the global projections $\mathcal{H}u \equiv \{\mathcal{H}_i u_i\}_{i=1}^N$ and $Pu \equiv \{P_i u_i\}_{i=1}^N : X_h(\Omega) \rightarrow \overset{\circ}{X}_h(\Omega)$ in the sense of $\sum_{i=1}^N a_i(\cdot, \cdot)$. A function $u \in X_h(\Omega)$ can therefore be decomposed as

$$(3.5) \quad u = \mathcal{H}u + Pu.$$

The function $u \in X_h(\Omega)$ can also be represented as

$$(3.6) \quad u = \hat{\mathcal{H}}u + \hat{P}u$$

where $\hat{P}u = \{\hat{P}_i u_i\}_{i=1}^N : X_h(\Omega) \rightarrow \overset{\circ}{X}_h(\Omega)$ is the projection in the sense of $a_h(\cdot, \cdot)$, the original bilinear form of (2.2), see (2.3). Since $\hat{P}_i u_i \in \overset{\circ}{X}_i(\Omega_i)$ and $v_i \in \overset{\circ}{X}_i(\Omega_i)$, we have

$$a_i(\hat{P}_i u, v_i) = a_h(u, v_i).$$

The discrete solution of (2.2) can be decomposed as $u_h^* = \hat{\mathcal{H}}u_h^* + \hat{P}u_h^*$. To find $\hat{P}u_h^*$ we need to solve the following set of usual discrete Dirichlet problems:

Find $\hat{P}_i u_h^* \in \overset{\circ}{X}_i(\Omega)$ such that

$$(3.7) \quad a_i(\hat{P}_i u_h^*, v_i) = f(v_i), \quad v_i \in \overset{\circ}{X}_i(\Omega_i)$$

for $i = 1, \dots, N$. Note that these problems are local and independent, so they can be solved in parallel. This is a precomputational step.

We now formulate the problem for $\hat{\mathcal{H}}u_h^*$. Let $\hat{\mathcal{H}}_i u$ be the discrete harmonic part of u in the sense of $\hat{a}_i(\cdot, \cdot)$, where $\hat{\mathcal{H}}_i u \in X_i(\Omega_i)$ is the solution of

$$(3.8) \quad \hat{a}_i(\hat{\mathcal{H}}_i u, v_i) = 0 \quad v_i \in \overset{\circ}{X}_i(\Omega_i),$$

$$(3.9) \quad u_i \quad \text{on} \quad \partial\Omega_i \quad \text{and} \quad u_j \quad \text{on} \quad F_{ji} \subset \partial\Omega_j \quad \text{are given}$$

where u_j are given on $F_{ji} = \partial\Omega_i \cap \partial\Omega_j$ and

$$(3.10) \quad \hat{a}_i(u_i, v_i) \equiv \rho_i(\nabla u_i, \nabla v_i)_{L^2(\Omega_i)} + \sum_{F_{ij} \subset \partial\Omega_i} \frac{\rho_{ij}}{l_{ij}} \left(\frac{\partial v_i}{\partial n}, u_j - u_i \right)_{L^2(F_{ij})}.$$

Note that (3.8) - (3.9) has a unique solution. To see this, let us rewrite (3.8) in the form

$$(3.11) \quad \rho_i(\nabla \hat{\mathcal{H}}_i u, \nabla \varphi_i^k)_{L^2(\Omega_i)} = - \sum_{F_{ij} \subset \partial \Omega_i} \frac{\rho_{ij}}{l_{ij}} \left(\frac{\partial \varphi_i^k}{\partial n}, u_j - u_i \right)_{L^2(F_{ij})}$$

where φ_i^k are nodal basis functions of $\overset{\circ}{X}_i(\Omega_i)$ associated with interior nodal points x_k of the h_i -triangulation of Ω_i . Note that $\frac{\partial \varphi_i^k}{\partial n}$ does not vanish on $\partial \Omega_i$ when x_k is an interior node close to $\partial \Omega_i$. We see that $\hat{\mathcal{H}}_i u$ is a special extension into Ω_i of u given on $\partial \Omega_i$ and on the F_{ji} and therefore it depends on the values of u_j given on $F_{ji} = \partial \Omega_i \cap \partial \Omega_j$, and on F_{0i} we already had assumed $u_j = 0$ for $j = 0$. Note that $\hat{\mathcal{H}}_i u$ is the discrete harmonic except on nodal points close to $\partial \Omega_i$. We will call sometimes $\hat{\mathcal{H}}_i u$ as discrete harmonic in special sense, i.e. in the sense of $\hat{a}_i(\cdot, \cdot)$ or $\hat{\mathcal{H}}_i$. We set that $\hat{\mathcal{H}}u = \{\hat{\mathcal{H}}_i u\}_{i=1}^N \in X_h(\Omega)$.

Note that (3.8) is obtained from

$$(3.12) \quad a_h(\hat{\mathcal{H}}u, v) = 0$$

for $u \in X_h(\Omega)$ and when taking $v = \{v_i\}_{i=1}^N \in \overset{\circ}{X}_h(\Omega)$. It is easy to see that $\hat{\mathcal{H}}u = \{\hat{\mathcal{H}}_i u\}_{i=1}^N$ and $\hat{P}u = \{\hat{P}_i u_i\}_{i=1}^N$ are orthogonal in the sense of $a_h(\cdot, \cdot)$, i.e.

$$(3.13) \quad a_h(\hat{\mathcal{H}}u, \hat{P}v) = 0, \quad u, v \in X^h(\Omega).$$

In addition,

$$(3.14) \quad \mathcal{H}\hat{\mathcal{H}}u = \mathcal{H}u, \quad \hat{\mathcal{H}}\mathcal{H}u = \hat{\mathcal{H}}u$$

since $\hat{\mathcal{H}}u$ and $\mathcal{H}u$ do not change the values of u on all the nodes on boundaries of the subdomains Ω_i also denoted by

$$(3.15) \quad \Gamma = (\cup_i \partial \Omega_{ih_i}).$$

We note that definition of Γ includes the nodes on both side of $\cup_i \partial \Omega_i$.

We are now in the position to derive a Schur complement problem for (2.2). Let us apply the decomposition (3.6) into (2.2). We get

$$a_h(\hat{\mathcal{H}}u_h^* + \hat{P}u_h^*, \hat{\mathcal{H}}v_h + \hat{P}v_h) = f(\hat{\mathcal{H}}v_h + \hat{P}v_h)$$

or

$$a_h(\hat{\mathcal{H}}u_h^*, \hat{\mathcal{H}}v_h) + 2a_h(\hat{\mathcal{H}}u_h^*, \hat{P}v_h) + a_h(\hat{P}u_h^*, \hat{P}v_h) = f(\hat{\mathcal{H}}v_h) + f(\hat{P}v_h).$$

Using (3.7) and (3.12) we have

$$(3.16) \quad a_h(\hat{\mathcal{H}}u_h^*, \hat{\mathcal{H}}v_h) = f(\hat{\mathcal{H}}v_h), \quad v_h \in X_h(\Omega).$$

This problem is the Schur complement problem for (2.2). We denote the space $V_h(\Gamma)$ or in short notation V as the set of all functions v_h in $X_h(\Omega)$ such $\hat{P}v_h = 0$, i.e. the space of discrete harmonic functions in the sense of the $\hat{\mathcal{H}}_i$. We rewrite the Schur complement problem as:

Find $u_h^* \in V_h(\Gamma)$ such that

$$(3.17) \quad s(u_h^*, v_h) = g(v_h), \quad v_h \in V_h(\Gamma)$$

where here and below $u_h^* \equiv \hat{\mathcal{H}}u_h^*$, and

$$(3.18) \quad s(u_h, v_h) = a_h(\hat{\mathcal{H}}u_h, \hat{\mathcal{H}}v_h), \quad g(v_h) = f(\hat{\mathcal{H}}v_h).$$

This problem has a unique solution.

4. Technical tools. A goal is to design and analyze a Neumann-Neumann (N-N) method for solving (3.17). This will be done in next section. We now introduce some notations and facts used for that. Let $u = \{u_i\}_{i=1}^N \in X_h(\Omega)$ and $v = \{v_i\}_{i=1}^N \in X_h(\Omega)$. Let

$$(4.1) \quad d_i(u_i, v_i) \equiv \rho_i(\nabla u_i, \nabla v_i)_{L^2(\Omega_i)} + \sum_{F_{ij} \subset \partial\Omega_i} \frac{\delta}{l_{ij}} \frac{\rho_{ij}}{h_i} (u_j - u_i, v_j - v_i)_{L^2(F_{ij})}$$

and

$$(4.2) \quad d_h(u, v) = \sum_{i=1}^N d_i(u, v).$$

Note that for $u, v \in \overset{\circ}{X}_h(\Omega)$

$$(4.3) \quad d_i(u, v) = a_i(u, v) = \rho_i(\nabla u_i, \nabla v_i)_{L^2(\Omega_i)}$$

and for $u \in X_h(\Omega)$

$$(4.4) \quad C_0 d_h(u, u) \leq a_h(u, u) \leq C_1 d_h(u, u)$$

in view of Lemma 2.1, where C_0 and C_1 are positive constants independent of h_i , H_i and ρ_i . The next lemma shows the equivalence between discrete harmonic functions in the sense \mathcal{H} and in the sense $\hat{\mathcal{H}}$, and therefore we can take advantage of all the discrete Sobolev results known for \mathcal{H} discrete harmonic extensions.

LEMMA 4.1. For $u \in X_h(\Omega)$

$$(4.5) \quad d_h(\mathcal{H}u, \mathcal{H}u) \leq d_h(\hat{\mathcal{H}}u, \hat{\mathcal{H}}u) \leq C d_h(\mathcal{H}u, \mathcal{H}u)$$

where $\mathcal{H}u = \{\mathcal{H}_i u_i\}_{i=1}^N$ and $\hat{\mathcal{H}}u = \{\hat{\mathcal{H}}_i u_i\}_{i=1}^N$ are defined by (3.2) - (3.3) and (3.8) - (3.9) respectively, where C is a positive constant independent of h_i , u , ρ_i and H_i .

Proof. We note that P and \mathcal{H} are projections in the sense of $d_h(\cdot, \cdot)$ while \hat{P} and $\hat{\mathcal{H}}$ are projections in the sense of $a_h(\cdot, \cdot)$. Therefore, the LHS of (4.5) follows from properties of minimum energy of discrete harmonic extensions in the $d_h(\cdot, \cdot)$ sense. To prove RHS of (4.5) note that

$$(4.6) \quad d_h(\hat{\mathcal{H}}u, \hat{\mathcal{H}}u) = d_h(\hat{\mathcal{H}}u, \mathcal{H}\hat{\mathcal{H}}u + P\hat{\mathcal{H}}u) = d_h(\hat{\mathcal{H}}u, \mathcal{H}u) + d_h(\hat{\mathcal{H}}u, P\hat{\mathcal{H}}u)$$

in view of (3.14). The first term is estimated as

$$(4.7) \quad d_h(\hat{\mathcal{H}}u, \mathcal{H}u) \leq \varepsilon d_h(\hat{\mathcal{H}}u, \hat{\mathcal{H}}u) + \frac{1}{4\varepsilon} d_h(\mathcal{H}u, \mathcal{H}u),$$

with arbitrary $\varepsilon > 0$. To estimate the second term of RHS of (4.6) note that for $v \equiv P\hat{\mathcal{H}}u \in \overset{\circ}{X}(\Omega)$ and using (3.11), we get

$$(4.8) \quad \begin{aligned} d_h(\hat{\mathcal{H}}u, v) &= \sum_{i=1}^N \rho_i (\nabla \hat{\mathcal{H}}_i u_i, \nabla v_i)_{L^2(\Omega_i)} \\ &= - \sum_{i=1}^N \sum_{F_{ij} \subset \partial\Omega_i} \frac{\rho_{ij}}{l_{ij}} \left(\frac{\partial v_i}{\partial n}, u_j - u_i \right)_{L^2(F_{ij})}. \end{aligned}$$

The terms of RHS of (4.8) are estimated as

$$\begin{aligned} |\rho_{ij} \left(\frac{\partial v_i}{\partial n}, u_j - u_i \right)_{L^2(F_{ij})}| &\leq \rho_{ij} \left\| \frac{\partial v_i}{\partial n} \right\|_{L^2(F_{ij})} \|u_i - u_j\|_{L^2(F_{ij})} \\ &\leq C \frac{\rho_{ij}}{h_i^{1/2}} \|\nabla v_i\|_{L^2(\Omega_i)} \|u_i - u_j\|_{L^2(F_{ij})} \\ &\leq C \left\{ \varepsilon \rho_{ij} \|\nabla v_i\|_{L^2(\Omega_i)}^2 + \frac{\rho_{ij}}{4\varepsilon h_i} \|u_i - u_j\|_{L^2(F_{ij})}^2 \right\} \\ &\leq C \left\{ 2\varepsilon \rho_i \|\nabla v_i\|_{L^2(\Omega_i)}^2 + \frac{\rho_{ij}}{4\varepsilon h_i} \|u_i - u_j\|_{L^2(F_{ij})}^2 \right\}, \end{aligned}$$

where we have used that $\rho_{ij} \leq 2\rho_i$. Substituting this into (4.8), we get

$$(4.9) \quad d_h(\hat{\mathcal{H}}u, v) \leq C \sum_{i=1}^N \left\{ 2\varepsilon \rho_i \|\nabla P_i \hat{\mathcal{H}}_i u_i\|_{L^2(\Omega_i)}^2 + \frac{\rho_{ij}}{4h_i \varepsilon} \sum_{F_{ij} \subset \partial\Omega_i} \|u_i - u_j\|_{L^2(F_{ij})}^2 \right\},$$

and using

$$\|\nabla P_i \hat{\mathcal{H}}_i u_i\|_{L^2(\Omega_i)} \leq \|\nabla \hat{\mathcal{H}}_i u_i\|_{L^2(\Omega_i)},$$

we obtain

$$(4.10) \quad d_h(\hat{\mathcal{H}}u, v) \leq C \left\{ \varepsilon d_h(\hat{\mathcal{H}}u, \hat{\mathcal{H}}u) + \frac{1}{4\varepsilon} d_h(\mathcal{H}u, \mathcal{H}u) \right\},$$

and then

$$d_h(\hat{\mathcal{H}}u, \hat{\mathcal{H}}u) \leq C \left\{ \varepsilon d_h(\hat{\mathcal{H}}u, \hat{\mathcal{H}}u) + \frac{1}{4\varepsilon} d_h(\mathcal{H}u, \mathcal{H}u) \right\}.$$

Choosing now ε sufficiently small, the RHS of (4.5) follows. \square

5. Neumann-Neumann method. We design and analyze Neumann-Neumann (N-N) methods for solving (3.17); see [6, 9]. For that we follow the general framework of ASM; see [10], and stated in the next lemma. The operators I_i and T , the bilinear forms b_i and the spaces V_i are defined on the next subsections while the space V and bilinear form a_h are the same as above.

LEMMA 5.1. *Suppose the following three assumptions hold:*

- i) *There exists a constant C_0 such that for all $u \in V$ there exists a decomposition $u = \sum_{i=0}^N I_i u_i$, $u_i \in V_i$ with*

$$\sum_{i=0}^N b_i(u_i, u_i) \leq C_0^2 a_h(u, u).$$

ii) There exist constants $\epsilon_{i,j}, i, j = 1, \dots, N$ such that

$$a_h(I_i u_i, I_j u_j) \leq \epsilon_{i,j} a_h(I_i u_i, I_i u_j)^{1/2} a_h(I_j u_j, I_j u_j)^{1/2}, \quad \forall u_i \in V_i \quad \forall u_j \in V_j.$$

iii) There exists a constant ω such that

$$a_h(I_i u, I_i u) \leq \omega b_i(u, u) \quad \forall u \in V_i, \quad i = 0, \dots, N.$$

Then, T is invertible and

$$C_0^2 a_h(u, u) \leq a_h(Tu, u) \leq (\rho(\epsilon) + 1) \omega a_h(u, u), \quad \forall u \in V.$$

Here, $\rho(\epsilon)$ is the spectral radius of the matrix $\epsilon = \{\epsilon\}_{i,j=1}^N$.

5.1. Local spaces V_i . Let us denote $V_i(\Gamma_i)$, in short notation V_i , as the vector space defined by the nodal values on $\partial\Omega_i$ and by nodal values on the neighboring faces of Ω_i , i.e. on $F_{ji} \subset \partial\Omega_j$, where $F_{ij} = F_{ji} = \partial\Omega_i \cap \partial\Omega_j$. We denote such nodes by Γ_i . We note that we **do include** the nodal values of ∂F_{ji} (which are vertices of Ω_j) as degrees of freedom of V_i . We denote by $u \in V_i$, if $u = \{u_l^{(i)}\}_{l \in \#(i)}$, where $\#(i)$ is the index set composed of i and the j indices where F_{ij} is a face of $\partial\Omega_i$, where the function $u_i^{(i)}$ is u restricted to $\partial\Omega_i$ and the function $u_j^{(i)}$ is u restricted to F_{ji} . To simplify notation we also use $u = \{u_i\} \in V_i$ to refer to a function defined on Γ_i , and $u = \{u_i\} \in V$ to refer to a function defined on all Γ .

Let us define the regular zero extension operator $\tilde{I}_i : V_i \rightarrow V$ as follows: Given $u \in V_i$, let $\tilde{I}_i u$ be equal to u on nodes Γ_i and zero on $\Gamma \setminus \Gamma_i$. Then we associate with each Ω_k , $k = 1, \dots, N$, the discrete harmonic function u_k inside each Ω_k in the sense of \mathcal{H}_k , see (3.8) and (3.9).

5.2. Master and slave sides. We first classify faces $F_{ij} = \partial\Omega_i \cap \partial\Omega_j$, common to Ω_i and Ω_j , as master and slave. The face F_{ij} is master if $h_i \geq h_j$ and denoted by γ_{ij} and slave if $h_i < h_j$ and denoted by δ_{ij} . Here h_i and h_j are parameters of the h_i - and h_j - triangulation of $F_{ij} \subset \partial\Omega_i$ and $F_{ji} \subset \partial\Omega_j$, $F_{ij} = F_{ji}$, respectively. We consider in the analysis F_{i0} as the master side.

ASSUMPTION M: $h_i \geq h_j$ if and only if $\rho_i \geq \rho_j$

5.3. Weighted prolongation operators I_i . We associate with each Ω_i , $i = 1, \dots, N$, the weighting diagonal matrices $D^{(i)} = \{D_l^{(i)}\}_{l \in \#(i)}$ on Γ_i as follows:

- On $\partial\Omega_i$ ($l = i$)

$$(5.1) \quad D_i^{(i)} = \begin{cases} 1 & x \in \gamma_{ijh_i} \subset \partial\Omega_i, \\ 0 & x \in \delta_{ijh_i} \subset \partial\Omega_i, \\ 1 & x \in \nu_i \subset \partial\Omega_i \end{cases}$$

where γ_{ijh_i} and δ_{ijh_i} are the sets of nodal points of $\gamma_{ij} \subset \partial\Omega_i$ and $\delta_{ij} \subset \partial\Omega_i$, respectively; ν_i is the set of vertices of Ω_i .

- On $\partial\Omega_j$ ($l = j$, $F_{ij} = F_{ji} = \partial\Omega_i \cap \partial\Omega_j$)

$$(5.2) \quad D_j^{(i)} = \begin{cases} 0, & x \in \gamma_{jih_j} \subset \partial\Omega_j, \quad \gamma_{ji} = \delta_{ij}, \quad \delta_{ij} \subset \partial\Omega_i, \\ 1, & x \in \delta_{jih_j} \subset \partial\Omega_i, \\ 0, & x \in (\partial\gamma_{jih_j} \cup \partial\delta_{jih_j}) \end{cases}$$

where for $F_{i0} \in \partial\Omega$ we set $D_j^{(i)} = 0$.

The extension operators $I_i : V_i \rightarrow V$, $i = 1, \dots, N$ are defined as

$$(5.3) \quad I_i = \tilde{I}_i D^{(i)}.$$

5.4. Coarse space and subspace decomposition. Note that

$$(5.4) \quad \sum_{i=1}^N I_i \tilde{I}_i^T = I_\Gamma$$

is a partition of unity on every node of Γ , where I_Γ is the identity operator on Γ . The coarse space $V_0 \subset V$ and its coarse basis functions $\Theta^{(i)}$ are introduced as follows:

$$(5.5) \quad V_0 = \text{Span}\{\Theta^{(i)}\}_{i=1}^N,$$

where $\Theta^{(i)} = I_i \Phi^{(i)}$ where $\Phi^{(i)} \in V_i$ is defined as follows: If the substructure Ω_i does not share a face with the boundary of Ω , i.e. when $\partial\Omega_i \cap \partial\Omega$ has measure zero, then we define $\Phi^{(i)}$ to be equal to one at every node of Γ_i . Such substructure we denote by N_I substructure. If not, Ω_i is a N_B -substructure and we define $\Phi^{(i)}$ equal to one on the faces F_{ij} and F_{ji} that do not touch $\partial\Omega$, the linear function decreasing from one to zero on the faces F_{ij} and F_{ji} touching $\partial\Omega$, and equal to zero on F_{i0} . Because of the linearity, the function $\Phi^{(i)}$ matches across F_{ij} and F_{ji} .

Let us denote $I_0 = I_\Gamma$, i.e. the identity operator on Γ . Hence, V can be decomposed as

$$(5.6) \quad V = \sum_{i=0}^N I_i V_i.$$

We now define bilinear form b_0 as

$$(5.7) \quad b_0(u, v) = (1 + \log \frac{H}{h})^{-1} d_h(\mathcal{H}u, \mathcal{H}v), \quad u, v \in V_0.$$

REMARK 5.1. *Other choices of coarse problems can be considered. We can replace the bilinear form (5.7) to*

$$(5.8) \quad b_0(u, v) = (1 + \log \frac{H}{h})^{-1} a_h(\hat{\mathcal{H}}u, \hat{\mathcal{H}}v), \quad u, v \in V_0$$

and the analysis will follow straightforwardly from the analysis for (5.7) and using (4.4) and (4.5).

In the case when Ω_i are triangles, we can replace the space V_0 by conforming continuous piecewise linear functions on the coarse triangulation associated to Γ , i.e. the functions are linear and matching on F_{ij} and F_{ji} and continuous at the vertices of the substructures, and vanishing on $\partial\Omega$. Theorem 5.2, see below, is valid for this variant of method when the coefficient ρ_i are quasimonotonic, see [5]. In the proof $u_0 \in V_0$ is defined by values at common vertices x_k of the substructures which are equal to an algebraic average values of u_i over faces of Ω_i with x_k as common vertex.

5.5. Local bilinear forms. For $i = 1, \dots, N$, and for $u = \{u_i\} \in V_i$ and $v = \{v_i\} \in V_i$ define

$$(5.9) \quad b_i(u, v) = \int_{\Omega_i} \rho_i \nabla \mathcal{H}_i u_i \nabla \mathcal{H}_i v_i dx + \frac{\rho_i}{H_i^2} \int_{\Omega_i} (\mathcal{H}_i u_i)(\mathcal{H}_i v_i) dx + \\ + \sum_{F_{ij} \subset \partial\Omega_i} \delta \frac{\rho_{ij}}{h_{ij}} \int_{F_{ij}} (u_j - u_i)(v_j - v_i) ds,$$

where $h_{ij} = 2h_i h_j / (h_i + h_j)$ is the harmonic average of h_i and h_j . For a face F_{i0} , we let $h_{ij} = h_i$, and again $\rho_{ij} = \rho_i$ and $v_j = u_j = 0$, $v_i - v_j = v_i$ and $u_i - u_j = 0$. Note that $b_i(\cdot, \cdot)$ differs from $d_i(\cdot, \cdot)$ by the $L_2(\Omega_i)$ term and also by the factor multiplying the penalty term, where here we add the factors from neighboring subdomains, see (4.1). The addition of the $L_2(\Omega_i)$ term makes $b_i(u, u)$ a norm also in the case where $\partial\Omega_i$ does not touch the Dirichlet boundary of the original domain $\partial\Omega$, and as a consequence the local problems will be uniquely solvable.

REMARK 5.2. *In this paper we also consider the case where*

$$(5.10) \quad b_i(u, v) = a_i(\mathcal{H}_i u_i, \mathcal{H}_i v_i) + \sum_{F_{ij} \subset \partial\Omega_i} \delta \frac{\rho_{ij}}{h_{ij}} \int_{F_{ij}} (u_j - u_i)(v_j - v_i) ds.$$

To fix the solvability issue of the local problems, where the constant functions might be in the kernel, we replace V_i by the space of functions in V_i with zero average on $\partial\Omega_i$ or in Ω_i . The analysis developed here includes also this case; see Remark 6.1.

REMARK 5.3. *Like in Remark 5.2, a natural question to ask is if we can replace the bilinear form (5.10) to*

$$(5.11) \quad \begin{aligned} b_i(u, v) &= a_i(\hat{\mathcal{H}}_i u_i, \hat{\mathcal{H}}_i v_i) + \\ &+ \frac{\rho_{ij}}{l_{ij}} \sum_{F_{ij} \subset \partial\Omega_i} \left\{ \int_{F_{ij}} \frac{\partial \hat{\mathcal{H}}_i u_i}{\partial n} (v_j - v_i) ds + \int_{F_{ij}} \frac{\partial \hat{\mathcal{H}}_i v_i}{\partial n} (u_j - u_i) ds \right\} + \\ &+ \sum_{F_{ij} \subset \partial\Omega_i} \int_{F_{ij}} \frac{\delta}{l_{ij}} \frac{\rho_{ij}}{h_i} (u_j - u_i)(v_j - v_i) ds \end{aligned}$$

and define a version of balancing domain decomposition as in ([9]). The answer is no because we cannot estimate (6.8) with C independent of the ratio h_i/h_j . In addition, we cannot replace the last term of (5.11) to

$$\sum_{F_{ij} \subset \partial\Omega_i} \int_{F_{ij}} \frac{\delta}{2} \frac{\rho_{ij}}{h_{ij}} (u_j - u_i)(v_j - v_i) ds$$

since the associated bilinear form might not be positive definite whenever $h_i < h_j$, except if we take $\delta \geq 2\delta_0$, where δ_0 is given on Lemma 2.1, since we can use that $h_{ij} \geq h_i$.

5.6. Projection-like operators. For $i = 0, \dots, N$, let $\tilde{T}_i : V \rightarrow V_i$ be defined as

$$(5.12) \quad b_i(\tilde{T}_i u, v) = a_h(u, I_i v), \quad v \in V_i,$$

and let $T_i = I_i \tilde{T}_i$.

5.7. Preconditioner and main theorem. Find $u_h^* \in V$ such that

$$(5.13) \quad T u_h^* = g_h$$

where

$$(5.14) \quad T = \sum_{i=0}^N T_i$$

and

$$g_h = \sum_{i=0}^N g_i \quad g_i = T_i u_h^*,$$

and u_h^* is the solution of (3.17).

THEOREM 5.2. *Assume that Assumption M holds. Then there exist positive constants C_0 and C_1 independent of h_i, H_i and the jumps of ρ_i such that*

$$(5.15) \quad C_0 a_h(u, u) \leq a_h(Tu, u) \leq C_1 \left(1 + \log \frac{H}{h}\right)^2 a_h(u, u) \quad \forall u \in V.$$

Here $\log(H/h) = \max_i \log(H_i/h_i)$.

REMARK 5.4.

Two other possible discretizations rather the one defined in Section 2 can be considered: In the first discretization, for the case where Ω_i is a N_B substructure, we modify the space $X_i(\Omega_i)$ as the discrete functions vanishing on F_{i0} . In the second discretization, for the case Ω_i is such that $\partial\Omega_i \cap \partial\Omega \neq \emptyset$ we modify the space $X_i(\Omega_i)$ as the discrete functions vanishing on $\partial\Omega$. The essential difference of these two discretizations is that the first discretization does not assume that the $X_i(\Omega_i)$ should vanish on $\partial\Omega_i \cap \partial\Omega$ whenever Ω_i touches $\partial\Omega$ at only a vertex. In the second discretization all nodes of $\partial\Omega_{ih_i} \cap \partial\Omega$ are not degrees of freedom of the problem, while in the first discretization, all nodes but those that $\partial\Omega_{ih_i}$ touches $\partial\Omega$ at only a vertex are not degrees of freedom. In both cases, the boundary terms and penalty terms on F_{i0} , see (2.6) and (2.7), do not exist and are not required.

Neumann-Neumann methods can also be developed for those cases. For the first discretization no changes are required for the coarse problem, and for the local problems associated to N_I substructures. For the local problems on N_B substructures Ω_i we simply eliminate all the degrees of freedom associated to the nodes on $\partial\Omega_{ih_i} \cap \partial\Omega_i$ and Theorem 5.2 will hold with a similar proof. For the second discretization more changes are required to design the preconditioner. For N_I substructures that touch $\partial\Omega$ at just one vertex, we modify V_0 considering $\Phi_{(i)}$ to be linear in the coarse triangulation on Γ_i and vanishing at that vertex, i.e. like what was done for N_B substructures. The space V and the nodes Γ now do not have any degrees of freedom on $\partial\Omega$, and the spaces V_i are defined as the space V restricted to Γ_i , where now the Γ_i do not include nodes on $\partial\Omega$. The definition of the $D^{(i)}$ also do not have any entrance associated to nodes on $\partial\Omega$. When proving Theorem 5.2, a technical problem will arise: How to bound \bar{u}_i in (6.26) for the case that Ω_i touches $\partial\Omega$ at only one vertex? There are two possibilities for the analysis: If there exists a N_B substructure Ω_j where $\rho_i \leq \rho_j$ and with a face F_{ij} in common, then \bar{u}_i can be estimated from the energy norm on Ω_i and on Ω_j ; in this case Theorem 5.2 holds. If not, a log factor in the estimation of \bar{u}_i is obtained and therefore, Theorem 5.2 will hold with three-logs.

6. Proof of Theorem 5.2. By the general theorem of ASMs we need to check the three key assumptions of Lemma 5.1.

Assumption(ii). We need to prove that

$$(6.1) \quad a_h(u, u) \leq \omega b_0(u, u), \quad u \in V_0$$

and for $i = 1, \dots, N$

$$(6.2) \quad a_h(I_i u, I_i u) \leq \omega b_i(u, u), \quad u \in V_i$$

with $\omega \leq C(1 + \log \frac{H}{h})^2$ where C is a positive constant independent of h_i , H_i and ρ_i .
By Lemma 2.1 and Lemma 4.1

$$(6.3) \quad a_h(\hat{\mathcal{H}}u, \hat{\mathcal{H}}u) \leq C d_h(\hat{\mathcal{H}}u, \hat{\mathcal{H}}u) \leq C d_h(\mathcal{H}u, \mathcal{H}u).$$

where $d_h(\cdot, \cdot)$ is defined by (4.2). The proofs of (6.1) and (6.2) then reduce to $d_h(\mathcal{H}u, \mathcal{H}u)$ instead of $a_h(\hat{\mathcal{H}}u, \hat{\mathcal{H}}u)$.

The proof of (6.1) follows from the definition of b_0 , see (5.7), where

$$(6.4) \quad a_h(\hat{\mathcal{H}}u, \hat{\mathcal{H}}u) \leq C d_h(\mathcal{H}u, \mathcal{H}u) = C(1 + \log \frac{H}{h}) b_0(\mathcal{H}u, \mathcal{H}u)$$

with $\omega \leq C(1 + \log \frac{H}{h})$.

We now prove (6.2). In order to simplify notations, all the functions are considered as harmonic extensions in the \mathcal{H} sense. Hence, we denote $\mathcal{H}I_i u$ by $I_i u$ and let $u = \{u_l\}_{l \in \#(i)} \in V_i$. Using (4.1), (4.2), (5.3) and (5.9) we have

$$(6.5) \quad d_h(I_i u, I_i u) = d_i(D^{(i)}u, D^{(i)}u) + \sum_j d_j(D^{(i)}u, D^{(i)}u)$$

where the sum is taken over Ω_j with common faces to Ω_i . We now estimate the two RHS terms of (6.5) as follows:

$$(6.6) \quad \begin{aligned} d_i(D^{(i)}u, D^{(i)}u) &= \int_{\Omega_i} \rho_i |\nabla D_i^{(i)} u_i|^2 dx + \\ &+ \sum_{F_{ij} \subset \partial \Omega_i} \frac{\delta}{l_{ij}} \frac{\rho_{ij}}{h_i} \int_{F_{ij}} (D_i^{(i)} u_i - D_j^{(i)} u_j)^2 dx. \end{aligned}$$

We now estimate the first term of (6.6). We have

$$\rho_i \|\nabla D_i^{(i)} u_i\|_{L^2(\Omega_i)}^2 \leq 2\rho_i \{ \|\nabla(D_i^{(i)} u_i - u_i)\|_{L^2(\Omega_i)}^2 + \|\nabla u_i\|_{L^2(\Omega_i)}^2 \}$$

and

$$\rho_i \|\nabla(D_i^{(i)} u_i - u_i)\|_{L^2(\Omega_i)}^2 \leq C \sum_{\delta_{ij} \subset \partial \Omega_i} \rho_i \|\tilde{u}_i\|_{H_{00}^{1/2}(\delta_{ij})}^2,$$

where $\tilde{u}_i = u_i$ at the interior nodal points of δ_{ij} and $\tilde{u}_i = 0$ on $\partial \delta_{ij}$. It can be proved, see for example [10], that

$$(6.7) \quad \rho_i \|\tilde{u}_i\|_{H_{00}^{1/2}(\delta_{ij})}^2 \leq C(1 + \log \frac{H_i}{h_i})^2 \rho_i \|u_i\|_{H^1(\Omega_i)}^2,$$

where we have denoted

$$\|u_i\|_{H^1(\Omega_i)}^2 = \|\nabla u_i\|_{L^2(\Omega_i)}^2 + \frac{1}{H_i^2} \|u_i\|_{L^2(\Omega_i)}^2.$$

REMARK 6.1. In the case we use the approach described in Remark 5.2, we use the fact that u_i has average zero on $\partial \Omega_i$ and then use Friedrich's inequality to obtain semi-norm on the RHS of (6.7). See also (6.8) below and after (6.10).

We now estimate the second term of (6.6) and (6.10). Note that for F_{i0} , i.e. for faces on $\partial\omega$, the estimates of the terms corresponding to F_{i0} follow straightforwardly. On a slave face F_{ij} of $\partial\Omega_i$, i.e. where $h_i < h_j$ and $\rho_i < \rho_j$, or on F_{i0} , we have

$$\|D_i^{(i)}u_i - D_j^{(i)}u_j\|_{L^2(F_{ij})}^2 \leq Ch_i \max_{F_{ij}} |u_i|^2$$

hence,

$$\frac{\rho_{ij}}{h_{ij}} \|D_i^{(i)}u_i - D_j^{(i)}u_j\|_{L^2(F_{ij})}^2 \leq C\rho_i \max_{F_{ij}} |u_i|^2 \leq C(1 + \log \frac{H_i}{h_i})\rho_i \|u_i\|_{H^1(\Omega_i)}^2,$$

where we have used that $\rho_{ij} \leq 2\rho_i$, and since $h_i < h_j$ we also have $h_{ij} > h_i$.

On a master side F_{ij} of $\partial\Omega_i$, i.e. where $h_i \geq h_j$ and $\rho_i \geq \rho_j$, we have

$$\|D_i^{(i)}u_i - D_j^{(i)}u_j\|_{L^2(F_{ij})} \leq \|u_i - u_j\|_{L^2(F_{ij})} + \|u_j(0)\varphi_j^0 + u_j(H)\varphi_j^H\|_{L^2(F_{ij})},$$

where φ_j^0 and φ_j^H are the nodal basis functions on $\partial\Omega_j$ associated to the endpoints of the face $F_{ji} \equiv (0, H)$. Using a triangular inequality we have

$$\|u_j(0)\varphi_j^0\|_{L^2(F_{ij})} \leq C \|u_j\|_{L^2(0, h_j)} \leq C(\|u_i\|_{L^2(0, h_j)} + \|u_i - u_j\|_{L^2(F_{ij})})$$

and

$$\|u_i\|_{L^2(0, h_j)}^2 \leq C \max_{F_{ij}} |u_i|^2 h_j \leq Ch_j(1 + \log \frac{H_i}{h_i}) \|u_i\|_{H^1(\Omega_i)}^2.$$

Using similar arguments for bounding $\|u_j(H)\varphi_j^H\|_{L^2(F_{ij})}$, and using that $\rho_{ij} \leq 2\rho_i$, and $h_i \geq h_j$ which implies $h_{ij} \geq h_j$, we obtain

$$(6.8) \quad \frac{\rho_{ij}}{h_{ij}} \|D_i^{(i)}u_i - D_j^{(i)}u_j\|_{L^2(F_{ij})}^2 \leq C(1 + \log \frac{H_i}{h_i})b_i(u, u),$$

and the estimate

$$(6.9) \quad d_i(I_i u, I_i u) \leq C(1 + \log \frac{H_i}{h_i})^2 b_i(u, u)$$

follows.

We now estimate the second term of (6.6) $d_j(D^{(i)}u, D^{(i)}u)$ by $b_i(u, u)$. For $u = \{u_l\} \in V_i$ we have

$$(6.10) \quad d_j(D^{(i)}u, D^{(i)}u) = \rho_j \|\nabla D_j^{(i)}u_j\|_{L^2(\Omega_j)}^2 + \frac{\delta}{l_{ij}} \frac{\rho_{ij}}{h_j} \int_{F_{ij}} (D_i^{(i)}u_i - D_j^{(i)}u_j)^2 dx.$$

We need to estimate the first term only since the second term has been already estimated, see (6.8). If F_{ij} is a slave side of $\partial\Omega_i$ then $D_j^{(i)}$ vanishes, and so vanishes $\|\nabla D_j^{(i)}u_j\|_{L^2(\Omega_j)}^2$. We now estimate the case where F_{ij} is a master side of $\partial\Omega_i$ and it is not equal to F_{i0} . On F_{ji} we decompose $u_j = w_j + u_j(0)\varphi_j^0 + u_j(H)\varphi_j^H$, where $w_j = D_j^{(i)}u_j$. We have

$$(6.11) \quad \|\nabla w_j\|_{L^2(\Omega_j)}^2 \leq C \|w_j\|_{H_{00}^{1/2}(F_{ji})}^2 = C\{|w_j|_{H^{1/2}(F_{ji})}^2 + \int_{F_{ji}} \frac{w_j^2}{\text{dist}(s, \partial F_{ji})} ds\}.$$

We estimate the first term of RHS of (6.11). Let Q_j be the L_2 - projection on the h_j -triangulation of F_{j_i} . Using this we have

$$(6.12) \quad \begin{aligned} |w_j|_{H^{1/2}(F_{j_i})}^2 &\leq 2\{|w_j - Q_j u_i|_{H^{1/2}(F_{j_i})}^2 + |Q_j u_i|_{H^{1/2}(F_{j_i})}^2\} \\ &\leq C\left\{\frac{1}{h_j} \|w_j - u_i\|_{L^2(F_{j_i})}^2 + \|\nabla u_i\|_{L^2(\Omega_i)}^2\right\} \end{aligned}$$

and

$$(6.13) \quad \|w_j - u_i\|_{L^2(F_{j_i})}^2 \leq 2 \|u_j - u_i\|_{L^2(F_{j_i})}^2 + 2 \|u_j(0)\varphi_j^0 + u_j(H)\varphi_j^H\|_{L^2(F_{j_i})}^2$$

where the second term of the RHS of (6.13) can be bounded as before and using the fact that $\rho_j \leq \rho_i$.

It remains to estimate the second term of (6.11). We have

$$(6.14) \quad \int_{F_{j_i}} \frac{w_j^2}{\text{dist}(s, \partial F_{j_i})} ds \leq C\left\{\int_0^{H/2} \frac{w_j^2}{s} ds + \int_{H/2}^H \frac{w_j^2}{(H-s)} ds\right\}.$$

Let us estimate the first term of RHS of (6.14). We have

$$\begin{aligned} \int_0^{H/2} \frac{w_j^2}{s} ds &= \int_0^{h_j} \frac{w_j^2}{s} ds + \int_{h_j}^{H/2} \frac{u_j^2}{s} ds \\ &\leq C\{u_j^2(h_j) + \int_{h_j}^{H/2} \frac{u_i^2 - u_j^2}{s} ds + \int_{h_j}^{H/2} \frac{u_i^2}{s} ds\} \\ &\leq C\{u_j^2(h_j) + \frac{1}{h_j} \|u_i - u_j\|_{L^2(F_{j_i})}^2 + (1 + \log \frac{H_j}{h_j}) \max_{F_{j_i}} |u_i|^2\} \\ &\leq C\left\{\frac{1}{h_j} \|u_i - u_j\|_{L^2(F_{j_i})}^2 + (1 + \log \frac{H_i}{h_i})(1 + \log \frac{H_j}{h_j}) \|u_i\|_{H^1(\Omega_i)}^2\right\}. \end{aligned}$$

The second term of (6.14) is estimated similarly. Substituting these estimates to (6.14) we get

$$(6.15) \quad \begin{aligned} \int_{F_{j_i}} \frac{u_j^2}{\text{dist}(s, \delta F_{j_i})} ds &\leq C\left\{(1 + \log \frac{H}{h})^2 (\|\nabla u_i\|_{L^2(\Omega_i)}^2 + \right. \\ &\quad \left. + \frac{1}{H_i^2} \|u_i\|_{L^2(\Omega_i)}^2) + \frac{1}{h_j} \|u_i - u_j\|_{L^2(F_{j_i})}^2\right\}. \end{aligned}$$

In turn, substituting (6.12) and (6.15) into (6.11), and the resulting estimate and (6.8) into (6.10) we get

$$(6.16) \quad d_j(D^{(i)}u, D^{(i)}u) \leq C(1 + \log \frac{H}{h})^2 b_i(u, u).$$

Using (6.9) and (6.16) into (6.2), we get

$$d_h(u, u) \leq C(1 + \log \frac{H}{h})^2 b_i(u, u).$$

The proof of Assumption(ii) is complete.

Assumption(iii) We need to prove that

$$(6.17) \quad a_h(I_i u^{(i)}, I_j u^{(j)}) \leq C \varepsilon_{ij} a_h^{1/2}(I_i u^{(i)}, I_i u^{(i)}) a_h^{1/2}(I_j u^{(j)}, I_j u^{(j)})$$

for $u^{(i)} \in V_i$ and $u^{(j)} \in V_j$, $i, j = 1, \dots, N$, and the spectral radius of $\varepsilon = \{\varepsilon_{ij}\}_{i,j=1}^N$, $\varrho(\varepsilon)$, is bounded. In our case $\varrho(\varepsilon) \leq C$ with constant independent of h_i and H_i . This follows from the fact that $u^{(i)}$ and $u^{(j)}$ are different from zero on Ω_i and Ω_j and their neighbor substructures.

Assumption(i) By Lemma 2.1 and Lemma 4.1, we need to prove that for $u = \{u_i\}_{i=1}^N \in V$ there exist $v^{(0)} \in V_0$ and $v^{(i)} \in V_i$ such that

$$(6.18) \quad v^{(0)} + \sum_{i=1}^N I_i v^{(i)} = u$$

and

$$(6.19) \quad b_0(v^{(0)}, v^{(0)}) + \sum_{i=1}^N b_i(v^{(i)}, v^{(i)}) \leq C d_h(u, u)$$

where C is independent of h_i and H_i .

We first set

$$(6.20) \quad v^{(0)} = \sum_{i=1}^N \bar{u}_i \Theta^{(i)}, \quad \bar{u}_i = \frac{1}{|\Omega_i|} \int_{\Omega_i} u_i ds$$

where $u = \{u_i\}_{i=1}^N \in V$. We note that another possibility would be to define \bar{u}_i as the average of u_i on $\partial\Omega_i$ or a face of it. The $v^{(0)}$ also can be represented, see (5.5), as

$$v^{(0)} = \sum_{i=1}^N I_i \bar{u}_i \Phi^{(i)}.$$

Using the partition of unity (5.4) we compute

$$(6.21) \quad w \equiv u - v^{(0)} = \sum_{i=1}^N I_i (\tilde{I}_i^T u - \bar{u}_i \Phi^{(i)}),$$

and define

$$v^{(i)} \equiv \tilde{I}_i^T u - \bar{u}_i \Phi^{(i)},$$

i.e. $v^{(i)} = \{v_l^{(i)}\}_{l \in \#(i)} \in V_i$ is defined as $v_i^{(i)} = u_i - \bar{u}_i \Phi_i^{(i)}$ on $\partial\Omega_i$, $v_j^{(i)} = u_j - \bar{u}_i \Phi_j^{(i)}$ on neighboring faces F_{ji} including also the nodes on ∂F_{ji} .

By Lemma 7.1, see below, we have

$$(6.22) \quad b_0(v^{(0)}, v^{(0)}) = (1 + \log \frac{H}{h})^{-1} d_h(v^{(0)}, v^{(0)}) \leq C d_h(u, u).$$

It remains to estimate $b_i(v^{(i)}, v^{(i)})$ for $i = 1, \dots, N$. We have

$$(6.23) \quad b_i(v^{(i)}, v^{(i)}) \leq C \{ \rho_i \| \nabla \mathcal{H}_i(u_i^{(i)} - \bar{u}_i \Phi_i^{(i)}) \|_{L^2(\Omega_i)}^2 + \frac{\rho_i}{H_i^2} \| \mathcal{H}_i(u_i^{(i)} - \bar{u}_i \Phi_i^{(i)}) \|_{L^2(\Omega_i)}^2 + \sum_{F_{ij} \subset \partial\Omega_i} \delta \frac{\rho_{ij}}{h_{ij}} \| u_i^{(i)} - u_j^{(i)} \|_{L^2(F_{ij})}^2 \},$$

where we note that we have used in the last term of the LHS of (6.23) that $\Phi_i^{(i)} = \Phi_j^{(i)}$ on the faces F_{ij} and F_{ji} and $\Phi_i^{(i)}$ vanishes on faces of $\partial\Omega_i \cap \partial\Omega$. If Ω_i is a N_I substructure, i.e. it does not share a face with $\partial\Omega$, the function $\Phi_i^{(i)}$ is the constant equal to one and using Poincaré's inequality we obtain

$$(6.24) \quad \|\mathcal{H}_i(u_i - \bar{u}_i \Phi_i^{(i)})\|_{L^2(\Omega_i)}^2 \leq CH_i^2 \|\nabla \mathcal{H}_i u_i\|_{L^2(\Omega_i)}^2.$$

When Ω_i is a N_B substructure, then

$$(6.25) \quad \begin{aligned} \|\nabla \mathcal{H}_i(u_i - \bar{u}_i \Phi_i^{(i)})\|_{L^2(\Omega_i)}^2 &\leq 2 \|\nabla \mathcal{H}_i(u_i - \bar{u}_i)\|_{L^2(\Omega_i)}^2 + \\ &+ 2\bar{u}_i^2 \|\nabla \mathcal{H}_i(1 - \Phi_i^{(i)})\|_{L^2(\Omega_i)}^2. \end{aligned}$$

To estimate the second term of (6.25), we use that $1 - \Phi_i^{(i)}$ is linear on the faces of $\partial\Omega_i$ and vanishes in one of them and minimum energy arguments to have

$$\|\mathcal{H}_i(1 - \Phi_i^{(i)})\|_{L^2(\Omega_i)}^2 \leq C.$$

To bound \bar{u}_i , we consider \bar{u}_{i0} the average of u_i on F_{i0} and we use a Poincaré inequality to obtain

$$(6.26) \quad \bar{u}_i^2 \leq C \|\nabla \mathcal{H}_i u_i\|_{L^2(\Omega_i)}^2 + 2\bar{u}_{i0}^2,$$

and using that

$$\bar{u}_{i0}^2 \leq \frac{C}{H_i} \|u_i\|_{L^2(F_{i0})}^2$$

and $H_i \geq h_i$ we obtain

$$(6.27) \quad \|\nabla \mathcal{H}_i(u_i - \bar{u}_i \Phi_i^{(i)})\|_{L^2(\Omega_i)}^2 \leq C \{ \|\nabla \mathcal{H}_i u_i\|_{L^2(\Omega_i)}^2 + \frac{1}{h_i} \|u_i\|_{L^2(F_{i0})}^2 \},$$

and then use Poincaré inequality to bound the first term of the RHS of (6.23). An estimate of the last term of (6.23) is obvious and the proof of Theorem 5.2 is complete.

7. Auxiliary lemma. Let $u_0 \in V_0$ be defined for $u = \{u_i\}_{i=1}^N \in V$ as

$$(7.1) \quad u_0 = \sum_{i=1}^N \bar{u}_i \Theta^{(i)}, \quad \bar{u}_i \equiv \frac{1}{|\Omega_i|} \int_{\Omega_i} u_i ds.$$

LEMMA 7.1. *Assume that Assumption M holds. Then for u_0 defined by (7.1) holds*

$$(7.2) \quad d_h(u_0, u_0) \leq C(1 + \log \frac{H}{h}) d_h(u, u)$$

where C is independent of h_i , H_i and the jumps of ρ_i

Proof By Lemma 4.1 the estimate (7.2) is enough to prove for $\mathcal{H}u_0 = \{\mathcal{H}_i u_i^0\}_{i=1}^N$. Let us below denote $\mathcal{H}u_0$ by u_0 . We have

$$(7.3) \quad d_h(u_0, u_0) = \sum_{i=1}^N \{ \rho_i \|\nabla u_i^0\|_{L^2(\Omega_i)}^2 + \sum_{F_{ij} \subset \partial\Omega_i} \delta \frac{\rho_{ij}}{h_{ij}} \|u_i^0 - u_j^0\|_{L^2(F_{ij})}^2 \}.$$

We estimate the first term. Note that on $\partial\Omega_i$

$$(7.4) \quad u_0 = \bar{u}_i \Theta_i^{(i)} + \sum_{\delta_{ij} \subset \partial\Omega_i} \bar{u}_j \Theta_i^{(j)}$$

and

$$(7.5) \quad \bar{u}_i \Phi_i^{(i)} = \bar{u}_i \Theta_i^{(i)} + \sum_{\delta_{ij} \subset \partial\Omega_i} \bar{u}_i \Theta_i^{(j)}.$$

Note that

$$(7.6) \quad \begin{aligned} & \| \nabla u_i^0 \|_{L^2(\Omega_i)}^2 = \| \nabla (u_i^0 - \bar{u}_i) \|_{L^2(\Omega_i)}^2 \leq \\ & \leq 2 \| \nabla (u_i^0 - \Phi_i^{(i)} \bar{u}_i) \|_{L^2(\Omega_i)}^2 + 2 \bar{u}_i^2 \| \nabla (1 - \Phi_i^{(i)}) \|_{L^2(\Omega_i)}^2. \end{aligned}$$

When Ω_i is a N_I substructure, the second term of (7.6) vanishes, otherwise we can use similar arguments as in (6.27) and show that

$$\bar{u}_i^2 \| \nabla (1 - \mathcal{H}_i \Phi_i^{(i)}) \|_{L^2(\Omega_i)}^2 \leq C \{ \| \nabla \mathcal{H}_i u_i \|_{L^2(\Omega_i)}^2 + \frac{1}{H_i} \| u_i \|_{L^2(F_{i0})}^2 \}.$$

To bound the first term of (7.6), we use (7.4) and (7.5) to have

$$(7.7) \quad \begin{aligned} & \| \nabla (u_i^0 - \Phi_i^{(i)} \bar{u}_i) \|_{L^2(\Omega_i)}^2 \leq C \sum_{\delta_{ij} \subset \partial\Omega_i} (\bar{u}_i - \bar{u}_j)^2 \| \Theta_i^{(j)} \|_{H_{00}^{1/2}(\delta_{ij})}^2 \leq \\ & \leq C (\bar{u}_i - \bar{u}_j)^2 (1 + \log \frac{H_i}{h_i}) \end{aligned}$$

since

$$\| \Theta_i^{(j)} \|_{H_{00}^{1/2}(\delta_{ij})}^2 \leq C (1 + \log \frac{H_i}{h_i}).$$

Let for $F_{ij} = F_{ji}$, $F_{ij} \subset \partial\Omega_i$, $F_{ji} \subset \partial\Omega_j$

$$\bar{u}_{iF_{ij}} = \frac{1}{|F_{ij}|} \int_{F_{ij}} u_i ds, \quad \bar{u}_{jF_{ji}} = \frac{1}{|F_{ji}|} \int_{F_{ji}} u_j ds.$$

Using this we get

$$(7.8) \quad \begin{aligned} & (\bar{u}_i - \bar{u}_j)^2 \leq C \{ (\bar{u}_i - \bar{u}_{iF_{ij}})^2 + (\bar{u}_{iF_{ij}} - \bar{u}_{jF_{ji}})^2 + (\bar{u}_{jF_{ji}} - \bar{u}_j)^2 \} \leq \\ & \leq C \{ \| \nabla u_i \|_{L^2(\Omega_i)}^2 + \frac{1}{h_{ij}} \| u_i - u_j \|_{L^2(F_{ij})}^2 + \| \nabla u_j \|_{L^2(\Omega_j)}^2 \}. \end{aligned}$$

We have used Poincaré' inequality and that $H_i \geq h_{ij}$

$$(\bar{u}_{iF_{ij}} - \bar{u}_{jF_{ji}})^2 \leq C \frac{1}{H_i^2} (u_i - u_j, 1)_{L^2(F_{ij})}^2 \leq C \frac{1}{H_i} \| u_i - u_j \|_{L^2(F_{ij})}^2.$$

Substituting (7.8) into (7.7), and using that on δ_{ij} we have $\rho_i \leq \rho_j$, and we obtain

$$(7.9) \quad \begin{aligned} & \rho_i \| \nabla u_i^0 \|_{L^2(\Omega_i)}^2 \leq C (1 + \log \frac{H_i}{h_i}) \{ \rho_i \| \nabla u_i \|_{L^2(\Omega_i)}^2 + \rho_j \| \nabla u_j \|_{L^2(\Omega_j)}^2 + \\ & + \frac{\rho_{ij}}{h_{ij}} \| u_i - u_j \|_{L^2(F_{ij})}^2 \}. \end{aligned}$$

We now estimate the second term of (7.3). Let $F_{ij} = \gamma_{ij}$, i.e. F_{ij} be the master side. Note that for F_{i0} the estimate is obvious. For the remaining we have

$$(7.10) \quad u_i^0 - u_j^0 = \bar{u}_i \Theta_i^{(i)} - (\bar{u}_j \Theta_j^{(j)} + \bar{u}_i \Theta_j^{(i)}) = (\bar{u}_i - \bar{u}_j) \Theta_j^{(j)},$$

therefore

$$\frac{1}{h_{ij}} \| u_i^0 - u_j^0 \|_{L^2(F_{ij})}^2 = \frac{1}{h_{ij}} (\bar{u}_i - \bar{u}_j)^2 \| \Theta_j^{(j)} \|_{L^2(F_{ij})}^2 \leq C (\bar{u}_i - \bar{u}_j)^2$$

since

$$(7.11) \quad \| \Theta_j^{(j)} \|_{L^2(F_{ij})}^2 \leq h_j$$

and $h_j \leq h_i$ and $h_{ij} \geq h_j$. Using (7.8) and that $\rho_{ij} \leq \rho_i$ and $\rho_{ij} \leq 2\rho_j$, we get

$$(7.12) \quad \begin{aligned} \frac{\rho_{ij}}{h_{ij}} \| u_i^0 - u_j^0 \|_{L^2(F_{ij})}^2 &\leq C \{ \rho_i \| \nabla u_i \|_{L^2(\Omega_i)}^2 + \rho_j \| \nabla u_j \|_{L^2(\Omega_j)}^2 + \\ &+ \frac{\rho_{ij}}{h_{ij}} \| u_i - u_j \|_{L^2(F_{ij})}^2 \}. \end{aligned}$$

Let $F_{ij} = \delta_{ij}$, i.e. F_{ij} be the slave side. In this case (7.10) reduces to

$$u_i^0 - u_j^0 = (\bar{u}_i - \bar{u}_j) \Theta_i^{(i)}$$

therefore we get

$$(7.13) \quad \begin{aligned} \frac{\rho_{ij}}{h_{ij}} \| u_i^0 - u_j^0 \|_{L^2(F_{ij})}^2 &= \frac{\rho_{ij}}{h_{ij}} (\bar{u}_i - \bar{u}_j)^2 \| \Theta_i^{(i)} \|_{L^2(F_{ij})}^2 \leq \\ &\leq C \rho_{ij} (\bar{u}_i - \bar{u}_j)^2 \leq C \{ \rho_i \| \nabla u_i \|_{L^2(\Omega_i)}^2 + \rho_j \| \nabla u_j \|_{L^2(\Omega_j)}^2 + \\ &+ \frac{\rho_{ij}}{h_{ij}} \| u_i - u_j \|_{L^2(F_{ij})}^2 \} \end{aligned}$$

in view of (7.11) for $\delta_{ij} \subset \partial\Omega_i$ and (7.8).

Substituting (7.9), (7.13) into (7.3) we get (7.2). The proof of Lemma 7.1 is complete.

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