On the convergence properties of the projected gradient method for convex optimization

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Abstract

When applied to an unconstrained minimization problem with a convex objective, the steepest descent method has stronger convergence properties than in the noncovex case: the whole sequence converges to an optimal solution under the only hypothesis of existence of minimizers (i.e. without assuming e.g. boundedness of the level sets). In this paper we look at the projected gradient method for constrained convex minimization. Convergence of the whole sequence to a minimizer assuming only existence of solutions has also been already established for the variant in which the stepsizes are exogenously given and square summable. In this paper, we prove the result for the more standard (and also more efficient) variant, namely the one in which the stepsizes are determined through an Armijo search.

Key words: projected gradient method, convex optimization, quasi-Fejér convergence.

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1 Introduction

1.1 The problem

We are concerned in this paper with the following smooth optimization problem:

$$\min f(x) \tag{1}$$

$$\text{s. t. } x \in C, \tag{2}$$

where $f : \mathbb{R}^n \to \mathbb{R}$ is continuously differentiable and $C \subset \mathbb{R}^n$ is closed and convex. Each iteration of the projected gradient method, which we describe formally in subsection 1.3, basically consists of two stages: starting from the k-th iterate $x^k \in \mathbb{R}^n$, first a step is taken in the direction of $-\nabla f(x^k)$, and then the resulting point is projected onto C, possibly with additional one-dimensional searches in either one of the stages. The classical convergence result establishes that cluster points of $\{x^k\}$ (if any) are stationary points for (1)–(2), i.e. they satisfy the first order optimality conditions, but in general neither existence nor uniqueness of cluster points is guaranteed. In this paper we prove a much stronger result for the case in which f is convex, namely that the whole sequence $\{x^k\}$ converges to a solution of (1)–(2) under the only assumption of existence of solutions. An analogous result is known to hold for the steepest descent method for unconstrained optimization, which we describe in the next subsection.

1.2 The steepest descent method

Given a continuously differentiable $f : \mathbb{R}^n \to \mathbb{R}$, the *steepest descent* method generates a sequence $\{x^k\} \in \mathbb{R}^n$ through

$$x^{k+1} = x^k - \beta_k \nabla f(x^k), \tag{3}$$

where β_k is some positive real number. Several choices are available for β_k. The first one is to set the β_k's exogenously, and a relevant option is

$$\beta_k = \frac{\alpha_k}{\|\nabla f(x^k)\|}, \tag{4}$$

with

$$\sum_{k=0}^{\infty} \alpha_k = \infty, \quad \sum_{k=0}^{\infty} \alpha_k^2 < \infty. \tag{5}$$

Other options consist of performing an exact line minimization, i.e.

$$\beta_k = \mathrm{argmin}_{\beta > 0} f(x^k - \beta \nabla f(x^k)), \tag{6}$$

or an inexact linesearch, e.g. following an Armijo rule, namely

$$\beta_k = \bar{\beta} 2^{-\ell(k)} \tag{7}$$

with

$$\ell(k) = \min\left\{ j \in \mathbb{Z}_{\geq 0} : f(x^k - \bar{\beta} 2^{-j} \nabla f(x^k)) \leq f(x^k) - \sigma \bar{\beta} 2^{-j} \left\| \nabla f(x^k) \right\|^2 \right\}, \tag{8}$$

for some $\bar{\beta} > 0$, $\sigma \in (0, 1)$.

The basic convergence result on this method (and in general on descent direction methods), under either exact linesearches or Armijo searches, derives from Zangwill's global convergence theorem (see [13]) and establishes that every cluster points $\bar{x}$ of $\{x^k\}$, if any, is stationary, i.e. such that $\nabla f(\bar{x}) = 0$. In order to ensure existence of cluster points, it is necessary to assume that the starting iterate x^0 belongs to a bounded level set of f (see [12] for this and other related results). The situation is considerably better when f is convex: it is possible to prove convergence of the whole sequence to a minimizer of f under the sole asumption of existence of minimizers (i.e. without any additional assumption on boundedness of level sets). Results of this kind for the convex case can be found in [5], [7] and [11] for the method with exogenously given β_k's satisfying (4)–(5), in [9] for the method with exact lineasearches as in (6), and in [2], [4] and [10] for the method with the Armijo rule (7)–(8). We observe that in the case of β_k's given by (4)–(5) the method is not in general a descent one, i.e. it is not guaranteed that $f(x^{k+1}) \leq f(x^k)$ for all k.

1.3 The projected gradient method

In this subsection we deal with problem (1)–(2). Convexity of C makes it posible to use the orthogonal projection onto C,$P_C : \mathbb{R}^n \to C$, for obtaining feasible directions which are also descent ones; namely a step is taken from x^k in the direction of $-\nabla f(x^k)$, the resulting vector is projected onto C, and the direction from x^k to this projection has the above mentioned properties. A formal description of the algorithm, called the *projected gradient* method, is the following:

Initialization: Take $x^0 \in C$.

Iterative step: If x^k is stationary, i.e. $\nabla f(x^k)^t (x - x^k) \geq 0$ for all $x \in C$, then stop. Otherwise, let

$$z^k = P_C(x^k - \beta_k \nabla f(x^k)), \tag{9}$$

$$x^{k+1} = x^k + \gamma_k (z^k - x^k), \tag{10}$$

where β_k, γ_k are positive stepsizes, for which, again, several choices are possible. Before discussing them, we mention that in the unconstrained case, i.e. $C = \mathbb{R}^n$, then method given by (9)–(10) with $\gamma_k = 1$ for all k reduces to (3). Following [3], we will focus in three strategies for the stepsizes:

i) Armijo search along the feasible direction: $\beta_k = \beta > 0$ for all k and γ_k determined with an Armijo rule, namely

$$\gamma_k = 2^{-\ell(k)} \tag{11}$$

with

$$\ell(k) = \min\left\{j \in \mathbb{Z}_{\geq 0} : f(x^k - 2^{-j}\nabla f(x^k)) \leq f(x^k) - \sigma 2^{-j}\nabla f(x^k)^t(z^k - x^k)\right\}, \tag{12}$$

for some $\sigma \in (0,1)$.

ii) Armijo search along the boundary of C: $\gamma_k = 1$ for all k and β_k determined through (7) and the following two equations instead of (8):

$$\ell(k) = \min\left\{j \in \mathbb{Z}_{\geq 0} : f(z^{k,j}) \leq f(x^k) - \sigma\bar{\beta}2^{-j}\left\|\nabla f(x^k)\right\|^2\right\}, \tag{13}$$

with

$$z^{k,j} = P_C(x^k - \bar{\beta}2^{-j}\nabla f(x^k)). \tag{14}$$

iii) Exogenous stepsize before projecting: β_k given by (4)–(5) and $\gamma_k = 1$ for all k.

Several comments are in order. First, observe that in the unconstrained case ($C = \mathbb{R}^n$) options (i) and (ii) reduce to the steepest descent method (3) with the Armijo rule given by (7)–(8), while option (iii) reduces to (3) with the β_k's given by (4)–(5). Secondly, note that option (ii) requires a projection onto C for each step of the inner loop resulting from the Armijo search, i.e. possibly many projections for each k, while option (i) demands only one projection for each outer step, i.e. for each k. Thus, option (ii) is competitive only when P_C is very easy to compute (e.g. when C is a box or a ball). Third, we mention that option (iii), as its counterpart in the unconstrained case, fails to be a descent method. Finally, it it easy to show that for option (iii) it holds that $\left\|x^{k+1} - x^k\right\| \leq \alpha_k$ for all k, with α_k as in (4). In view of (5), this means that all stepsizes are "small", while options (i) and (ii) allow for occasionally long steps. Thus option (iii) seems rather undesirable. Its redeeming feature is that its good convergence properties hold also in the nonsmooth case, when $\nabla f(x^k)$ is replaced by a subgradient ξ^k of f at x^k. Subgradients do not give raise to descent directions, so that Armijo searches are not ensured to succeed, and therefore exogenous stepsizes seem to be the only available alternative. This is the case analyzed in [1]. We will not be concerned with option (iii) in the sequel.

Without assuming convexity of f, the convergence results for these methods closely mirror the ones for the steepest descent method in the unconstrained case: cluster points may fail to exist, even when (1)–(2) has solutions, but if they exist, they are stationary and feasible, i.e. $\langle\nabla f(\bar{x}), x-\bar{x}\rangle \geq 0$,

$\bar{x} \in C$ for all cluster point $\bar{x}$ of $\{x^k\}$ and all $x \in C$. These results can be found in Section 2.3.2 of [3]; for the case of option (ii), they are based upon the results in [6].

When f is convex, the stronger results for the unconstrained case, with β_k's given by (4)–(5), have also been extended to the projected gradient method under option (iii): it has been proved in [1] that in such a case, the whole sequence $\{x^k\}$ converges to a solution of problem (1)–(2) under the sole assumption of existence of solutions. On the other hand, the current situation is rather worse for options (i) and (ii): as far as we know, neither existence nor uniqueness of cluster points for options (i) and (ii) has ben proved, assuming only convexity of f. We will prove both for option (i) in the following two sections. The corresponding results for the less interesting option (ii) have very similar proofs, and we sketch them in Section 4.

Of course, results of this kind are immediate under stronger hypotheses on the problem: cluster points of $\{x^k\}$ certainly exist if the intersection of C with some level set of f is nonempty and bounded, and strict convexity of f ensures uniqueness of the cluster point.

2 Preliminaries

This section contains some previously established results needed in our analysis. We prove them in order to make the paper closer to being self-contained. We start with the so called quasi-Fejér convergence theorem (see [4], Theorem 1).

Proposition 1. *Let $T \subset \mathbb{R}^n$ be a nonempty set and $\{a^k\} \subset \mathbb{R}^n$ a sequence such that*

$$\left\|a^{k+1} - z\right\|^2 \leq \left\|a^k - z\right\| + \epsilon_k \tag{15}$$

for all $z \in T$ and all k, where $\{\epsilon_k\} \subset \mathbb{R}_+$ is a summable sequence. Then

i) $\{a^k\}$ is bounded.

ii) If a cluster point $\bar{a}$ of $\{a^k\}$ belongs to T, then the whole sequence $\{a^k\}$ converges to $\bar{a}$.

Proof. i) Fix some $z \in T$. Applying iteratively (15) we get

$$\left\|a^k - z\right\|^2 \leq \left\|a^0 - z\right\|^2 + \sum_{j=0}^{k-1} \epsilon_j \leq \left\|a^0 - z\right\|^2 + \sum_{j=0}^{\infty} \epsilon_j.$$

Since $\{\epsilon_k\}$ is summable, it follows that $\{a^k\}$ is bounded.
ii) Let now $\bar{a} \in T$ be a cluster point of $\{a^k\}$ and take $\delta > 0$. Let $\{a^{\ell_k}\}$ be a subsequence of $\{a^k\}$ convergent to $\bar{a}$. Since $\{\epsilon_k\}$ is summable, there exists k_0 such that $\sum_{j=k_0}^{\infty} \epsilon_j < \delta/2$, and, by (15) with $z = \bar{a}$, there exists $k_1 \geq k_0$ such that $\left\|a^{\ell_k} - \bar{a}\right\|^2 < \frac{\delta}{2}$ for any $k \geq k_1$. Then, for any $k \geq k_1$ we have:

$$\left\|a^k - \bar{a}\right\|^2 \leq \left\|a^{\ell_k} - \bar{a}\right\|^2 + \sum_{j=\ell_k}^{k-1} \epsilon_j \leq \left\|a^{\ell_k} - \bar{a}\right\|^2 + \sum_{j=\ell_k}^{\infty} \epsilon_j < \delta/2 + \delta/2 = \delta.$$

We conclude that $\lim_{k\to\infty} a^k = \bar{a}$. $\square$

Next we show that the linesearch for option (i) is always successful. We start with an immediate fact on descent directions.

Proposition 2. *Take $\sigma \in (0,1)$, $x \in C$ and $v \in \mathbb{R}^n$ such that $\nabla f(x)^t v < 0$. Then there exists $\bar{\gamma} < 1$ such that $f(x+\gamma v) < f(x) + \sigma\gamma\nabla f(x)^t v$ for all $\gamma \in (0,\bar{\gamma}]$.*

Proof. The result follows immediately from the continuous differentiability of f. $\square$

Next we prove that the direction $z^k - x^k$ in option (i) is a descent one.

Proposition 3. *Take x^k and z^k as defined by (9)–(12). Then*

i) x^k belongs to C for all k.

ii) If $\nabla f(x^k) \neq 0$, then $\nabla f(x^k)^t(z^k - x^k) < 0$.

Proof. i) By induction. It holds for $k = 0$ by the initialization step. Assume that $x^k \in C$. By (9), $z^k \in C$. By (12), $\gamma_k \in [0,1]$. By (10), $x^{k+1} \in C$.
ii) A well known elementary property of orthogonal projections states that $\langle v - u, P_C(u) - u\rangle \geq 0$ for all $u \in \mathbb{R}^n$, $v \in C$. By (i), $x^k \in C$. Thus, in view of (9),

$$0 \leq \langle x^k - \beta\nabla f(x^k) - x^k, P_C(x^k - \beta\nabla f(x^k)) - x^k + \beta\nabla f(x^k)\rangle =$$

$$-\beta\langle\nabla f(x^k), z^k - x^k\rangle - \beta^2 \left\|\nabla f(x^k)\right\|^2. \tag{16}$$

Since $\beta > 0$ and $\nabla f(x^k) \neq 0$, it follows from (16) that $\nabla f(x^k)^t(z^k - x^k) \leq -\beta\left\|\nabla f(x^k)\right\|^2 < 0$. $\square$

Corollary 1. *If $\nabla f(x^k) \neq 0$, then γ_k is well defined for the algorithm (9)–(12).*

Proof. Consider Proposition 2 with $x = x^k$, $v = z^k - x^k$. By Proposition 3(ii), $\nabla f(x)^t v < 0$. Thus the assumption of Proposition 2 holds, and the announced $\bar{\gamma}$ exists, so that the inequality in (12) holds for all j such that $2^{-j} \leq \bar{\gamma}$. It follows that both $\ell(k)$ and γ_k are well defined. $\square$

Finally, we prove stationarity of the cluster points of $\{x^k\}$, if any.

Proposition 4. *Let $\{x^k\}$ be the sequence defined by (9)-(12). If $\{x^k\}$ is infinite, $\bar{x}$ is a cluster point of $\{x^k\}$ and Problem (1)–(2) has solutions, then $\bar{x}$ is stationary for Problem (1)–(2).*

Proof. Since C is closed, $\bar{x}$ belongs to C by Proposition 3(i). Let $\{x^{j_k}\}$ be a subsequence of $\{x^k\}$ such that $\lim_{k\to\infty} x^{j_k} = \bar{x}$. Since $\{\gamma_k\} \subset [0,1]$ by (11), and Corollary 1, we assume without loss of generality that $\lim_{k\to\infty}\gamma_{j_k} = \widehat{\gamma} \in [0,1]$. By (10), (11) and (12),

$$0 < -\sigma\gamma_k \nabla f(x^k)^t(z^k - x^k) \le f(x^k) - f(x^{k+1}). \tag{17}$$

It follows from (17) that $\{f(x^k)\}$ is a decreasing sequence. Since $\{x^k\} \subset C$ by Proposition 3(i) and Problem (1)–(2) has solutions, $\{f(x^k)\}$ is bounded below, hence convergent, so that $\lim_{k\to\infty}[f(x^k) - f(x^{k+1})] = 0$. Taking limits in (17) along the subsequence, and taking into account (9), we get

$$0 \le -\sigma\widehat{\gamma}\nabla f(\bar{x})^t[P_C(\bar{x} - \beta\nabla f(\bar{x})) - \bar{x}] \le 0, \tag{18}$$

using also continuity of both f and P_C. Now we consider two cases. Suppose first that $\widehat{\gamma} > 0$. Let $\bar{u} = \bar{x} - \beta\nabla f(\bar{x})$. Then, it follows from (18) that

$$0 = \nabla f(\bar{x})^t[P_C(\bar{u}) - \bar{x}] = \beta^{-1}(\bar{x} - \bar{u})^t[P_C(\bar{u}) - \bar{x}], \tag{19}$$

implying that $0 = (\bar{u} - \bar{x})^t[P_C(\bar{u}) - \bar{x}]$. Since $\bar{x}$ belongs to C, an elementary property of orthogonal projections implies that $\bar{x} = P_C(\bar{u}) = P_C(\bar{x} - \beta\nabla f(\bar{x}))$, and it follows easily that $\nabla f(\bar{x})^t(x - \bar{x}) \ge 0$ for all $x \in C$, i.e. $\bar{x}$ is stationary for Problem (1)–(2).

Consider finally the case of $0 = \widehat{\gamma} = \lim_{k\to\infty}\gamma_{j_k}$. Fix $q \in \mathbb{N}$. Since $\gamma_{j_k} = 2^{-\ell(j_k)}$, there exists k such that $\ell(j_k) > q$, so that, in view of (12),

$$f\left(x^{j_k} - 2^{-q}\nabla f(x^{j_k})\right) > f(x^{j_k}) - \sigma 2^{-q}\nabla f(x^{j_k})^t(z^{j_k} - x^{j_k}). \tag{20}$$

Taking limits in (20) with $k \to \infty$, and defining $\bar{z} = P_C(\bar{x} - \beta\nabla f(\bar{x}))$, we get, for an arbitrary $q \in \mathbb{N}$,

$$f(\bar{x} - 2^{-q}\nabla f(\bar{x})) \ge f(\bar{x}) - \sigma 2^{-q}\nabla f(\bar{x})^t(\bar{z} - \bar{x}). \tag{21}$$

Combining (21) with Proposition 2, we conclude that $\nabla f(\bar{x})^t(\bar{z} - \bar{x}) \ge 0$. Using now Proposition 3(ii), we get that $0 = \nabla f(\bar{x})^t(\bar{z} - \bar{x}) = \nabla f(\bar{x})^t(P_C(\bar{u}) - \bar{x})$, i.e. (19) holds also in this case, and the conclusion is obtained with the same argument as in the previous case. □

Two comment are in order. First, no result proved up to this point requires convexity of f. Second, all these results are rather standard and well known (see e.g. Section 2.3.2 in [3] or [13]). The novelty of this paper occurs in the following sections.

3 Convergence properties in the convex case

In this section we prove that when f is convex then the sequence generated by variant (i) of the projected gradient method (i.e. (9)–(12)) converges to a solution of Problem (1)–(2), under the only assumption of existence of solutions.

Theorem 1. *Assume that Problem* (1)–(2) *has solutions. Then, either the algorithm given by* (9)–(12) *stops at some iteration* k*, in which case* x^k *is a solution of Problem* (1)–(2)*, or it generates an infinite sequence* $\{x^k\}$*, which converges to a solution* x^* *of the problem.*

Proof. In the case of finite stopping, the stopping rule states that x^k is stationary. Since f is convex, stationary points are solutions of Problem (1)–(2). We assume in the sequel that the algorithm generates an infinite sequence $\{x^k\}$.

Let $\widehat{x}$ be any solution of Problem (1)–(2). Using (10) and elementary algebra:

$$\left\|x^{k+1}-x^k\right\|^2+\left\|x^k-\widehat{x}\right\|^2-\left\|x^{k+1}-\widehat{x}\right\|^2=2\langle x^k-x^{k+1},x^k-\widehat{x}\rangle=2\gamma_k\langle z^k-x^k,\widehat{x}-x^k\rangle. \quad (22)$$

The already used elementary property of orthogonal projections can be restated as $\langle P_C(u)-u,v-u\rangle\geq 0$ for all $u\in\mathbb{R}^n$ and all $v\in C$. In view of (9)

$$0\leq\langle z^k-x^k+\beta\nabla f(x^k),\widehat{x}-z^k\rangle=\langle z^k-x^k+\beta\nabla f(x^k),\widehat{x}-x^k\rangle+\langle z^k-x^k+\beta\nabla f(x^k),x^k-z^k\rangle. \quad (23)$$

By (23),

$$\langle z^k-x^k,\widehat{x}-x^k\rangle\geq\beta\langle\nabla f(x^k),x^k-\widehat{x}\rangle-\langle z^k-x^k+\beta\nabla f(x^k),x^k-z^k\rangle\geq$$

$$\beta[f(x^k)-f(\widehat{x})]+\langle z^k-x^k+\beta\nabla f(x^k),z^k-x^k\rangle\geq\langle z^k-x^k+\beta\nabla f(x^k),z^k-x^k\rangle=$$

$$\left\|z^k-x^k\right\|^2+\beta\langle\nabla f(x^k),z^k-x^k\rangle, \quad (24)$$

using the gradient inequality for the convex function f in the first inequality, and feasibility of x^k, resulting from Proposition 3(i), together with optimality of $\widehat{x}$ and positivity of β, in the second one. Combining now (22) and (24), and taking into account (10),

$$\left\|x^{k+1}-x^k\right\|^2+\left\|x^k-\widehat{x}\right\|^2-\left\|x^{k+1}-\widehat{x}\right\|^2\geq 2\gamma_k\left[\left\|z^k-x^k\right\|^2+\beta\langle\nabla f(x^k),z^k-x^k\rangle\right]=$$

$$2\gamma_k^{-1}\left\|x^{k+1}-x^k\right\|^2+2\gamma_k\beta\langle\nabla f(x^k),z^k-x^k\rangle. \quad (25)$$

After rearrangement, we obtain from (25),

$$\left\|x^{k+1}-\widehat{x}\right\|^2\leq\left\|x^k-\widehat{x}\right\|^2+(1-2\gamma_k^{-1})\left\|x^{k+1}-x^k\right\|^2-2\gamma_k\beta\langle\nabla f(x^k),z^k-x^k\rangle\leq$$

$$\left\|x^k-\widehat{x}\right\|^2-2\gamma_k\beta\langle\nabla f(x^k),z^k-x^k\rangle, \quad (26)$$

using the fact that γ_k belongs to $[0,1]$ in the second inequality. Now we look at the specific way in which the γ_k's are determined. By (11), (12), for all j,

$$-\sigma\gamma_j \nabla f(x^j)^t(z^j - x^j) \leq f(x^j) - f(x^{j+1}). \tag{27}$$

Multiplying (27) by $(2\beta)/\sigma$, and defining

$$\epsilon_j = -2\beta\gamma_j \nabla f(x^j)^t(z^j - x^j), \tag{28}$$

we get

$$\epsilon_j \leq \frac{2\beta}{\sigma}[f(x^j) - f(x^{j+1})]. \tag{29}$$

Summing (29) with j between 0 and k,

$$\sum_{j=0}^{k} \epsilon_j \leq \frac{2\beta}{\sigma}[f(x^0) - f(x^{k+1})] \leq \frac{2\beta}{\sigma}[f(x^0) - f(\widehat{x})], \tag{30}$$

and it follows from (30) that $\sum_{j=0}^{\infty} \epsilon_j < \infty$. By (26) and (28),

$$\left\| x^{k+1} - \widehat{x} \right\|^2 \leq \left\| x^k - \widehat{x} \right\|^2 + \epsilon_k. \tag{31}$$

Let S^* be the set of solutions of Problem (1)–(2). Since $\widehat{x}$ is an arbitrary element of S^* and the ϵ_k's are summable, (31) means that $\{x^k\}$ is quasi-Fejér convergent to S^*. Since S^* is nonempty by assumption, it follows from Proposition 1(i) that $\{x^k\}$ is bounded, and therefore it has cluster points. By Proposition 4 all such cluster points are stationary. By convexity of f, they are solutions of Problem (1)–(2), i.e. they belong to S^*. By Proposition 1(ii), the whole sequence $\{x^k\}$ converges to a solution of Problem (1)–(2). □

4 Option (ii): search along an arc

We sketch in this section the analysis corresponding to option (ii), which we restate next:

Initialization: Take $x^0 \in C$.

Iterative step: If x^k is stationary, i.e. $\nabla f(x^k)^t(x - x^k) \geq 0$ for all $x \in C$, then stop. Otherwise, take

$$x^{k+1} = P_C(x^k - \beta_k \nabla f(x^k)), \tag{32}$$

where β_k is given by

$$\beta_k = \bar{\beta} 2^{-\ell(k)}, \tag{33}$$

with

$$\ell(k) = \min\left\{ j \in \mathbb{Z}_{\geq 0} : f(z^{k,j}) \leq f(x^k) - \sigma \bar{\beta} 2^{-j} \left\| \nabla f(x^k) \right\|^2 \right\}, \tag{34}$$

and

$$z^{k,j} = P_C(x^k - \bar{\beta} 2^{-j} \nabla f(x^k)). \tag{35}$$

Results for this variant follow closely those for option (i), developed in the previous two sections. Without assuming convexity of f, the following results hold:

Proposition 5. *If $\{x^k\}$ is the sequence generates by* (32)–(35)*, then*

i) $\{x^k\} \subset C$.

ii) β_k *is well defined by* (33)–(35).

iii) If $\nabla f(x^k) \neq 0$*, then* $\langle \nabla f(x^k), P_C(x^k - \beta_k \nabla f(x^k)) - x^k \rangle < 0$.

iv) If Problem (1)–(2) *has solutions and $\bar{x}$ is a cluster point of $\{x^k\}$, then $\bar{x}$ is stationary for Problem* (1)–(2).

Proof. Item (i) follows immediately from (32); for the remaining items see Proposition 2.3.3 and Lemma 2.3.1 in [3]. □

For convex f, we have the following result.

Theorem 2. *Assume that Problem* (1)–(2) *has solutions. Then, either the algorithm given by* (31)–(35) *stops at some iteration k, in which case x^k is a solution of Problem* (1)–(2)*, or it generates an infinite sequence $\{x^k\}$, which converges to a solution x^* of the problem.*

Proof. The result for the case of finite termination follows from the stopping criterion and the convexity of f. For the case of an infinite sequence, we observe that $\{x^k\}$ in this case can also be seen as the sequence for option (i), with $\gamma_k = 1$ for all k and β_k given by (33)-(35) instead of β. Thus, the computations in the proof of Theorem 1 up to (26) hold for the sequence under consideration with the two just mentioned changes, i.e., for all solution $\widehat{x}$ of Problem (1)–(2), we have

$$\left\| x^{k+1} - \widehat{x} \right\|^2 \leq \left\| x^k - \widehat{x} \right\|^2 + \varepsilon_k, \tag{36}$$

with

$$\varepsilon_k = -2\beta_k \langle \nabla f(x^k), P_C(x^k - \beta_k \nabla f(x^k)) - x^k \rangle. \tag{37}$$

Note that $\varepsilon_k \geq 0$ for all k by Proposition 5(iii). We prove next that $\{\varepsilon_k\}$ is summable. By (37),

$$\varepsilon_k \leq 2\beta_k \left\|\nabla f(x^k)\right\| \left\|P_C(x^k - \beta_k \nabla f(x^k)) - x^k\right\| = 2\beta_k \left\|\nabla f(x^k)\right\| \left\|P_C(x^k - \beta_k \nabla f(x^k)) - P_C(x^k)\right\|$$

$$\leq 2\beta_k \left\|\nabla f(x^k)\right\| \left\|x^k - \beta_k \nabla f(x^k) - x^k\right\| = 2\beta_k^2 \left\|\nabla f(x^k)\right\|^2 \leq 2\bar{\beta}\beta_k \left\|\nabla f(x^k)\right\|^2, \tag{38}$$

using Cauchy-Schwartz inequality in the first inequality, Proposition 5(i) in the first equality, nonexpansiveness of orthogonal projections in the second inequality and (33) in the third one. On the other and, it follows from (32)–(35), in particular from the criterion of the arc-search, that

$$\sigma\beta_k \left\|\nabla f(x^k)\right\|^2 \leq f(x^k) - f(x^{k+1}). \tag{39}$$

Combining (38) and (39),

$$\varepsilon_k \leq \frac{2\bar{\beta}}{\sigma}[f(x^k) - f(x^{k+1})]. \tag{40}$$

By (40), $\sum_{k=0}^{\infty} \varepsilon_k \leq \frac{2\bar{\beta}}{\sigma}[f(x^0) - f(\widehat{x})] < \infty$. In view of (36) it follows, as in Theorem 1, that $\{x^k\}$ is quasi-Fejér convergent to the solution set, and then Proposition 1(i) implies that $\{x^k\}$ is bounded, so that it has cluster points. By Proposition 5(iv) and convexity of f, all of them solve Problem (1)–(2). Finally, Proposition 1(ii) implies that the whole sequence $\{x^k\}$ converges to a solution. $\square$

5 Final remarks

1. The purpose of this paper is theoretical, and it consists of detemining the convergence properties of the projected gradient method in the case of a convex objective. We make no claims whatsoever on the advantages and/or drawbacks of this algorithm viz-a-viz others.
2. When ∇f is Lipschitz continuous in C with known Lipschitz constant L, it is well known that the Armijo search can be avoided, by taking, as γ_k in option (i) or β_k in option (ii), a constant $\theta \in (0, 2/L)$, without affecting the convergence properties for the nonconvex case (i.e. Propositions 2–5). It is not difficult to verify that in the convex case Theorems 1 and 2 also remain valid for this choice of the stepsizes (in fact, the proofs are indeed simpler).

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